MATROIDS ON EIGHT ELEMENTS WITH THE HALF-PLANE PROPERTY AND RELATED CONCEPTS

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ABSTRACT. We classify all matroids with at most 8 elements that have the half-plane property, and we provide a list of some matroids on 9 elements that have, and that do not have the half-plane property. Furthermore, we prove that several classes of matroids and polynomials that are motivated by the theory of semidefinite programming are closed under taking minors and under passing to faces of the Newton polytope.

1. INTRODUCTION

A multivariate polynomial is said to have the *half-plane property* (HPP) if it does not vanish whenever we plug in for each variable a complex number from the open right half-plane. One of the initial motivations for this property comes from electrical networks; the theory suggests that the spanning tree polynomial of any graph should have the half-plane property by Kirchhoff's matrix tree theorem. Later on, in their seminal paper Choe, Oxley, Sokal and Wagner [10] generalized this setup to arbitrary, not necessarily graphic, matroids by showing that the support of every homogeneous multiaffine polynomial with the half-plane property must be the collection of bases of a matroid. Conversely, they define a matroid to have the half-plane property if its basis generating polynomial has the half-plane property, and they initiate a thorough investigation of which matroids have the half-plane property. These matroids generalize graphic matroids, and they have several combinatorially interesting properties. In particular, they share a plethora of so-called negative dependence properties that are not satisfied by arbitrary matroids, see e.g. [3, 30]. Moreover, non-negativity of the Rayleigh difference

$$\Delta_{ij}(h) := \frac{\partial h}{\partial x_i} \cdot \frac{\partial h}{\partial x_j} - \frac{\partial^2 h}{\partial x_i \partial x_j} \cdot h$$

of the basis generating polynomial of such matroids for all indices i, j is one of their characteristics. The class of matroids with the half-plane property has several desirable properties such as being closed under minors, duality, direct sums, 2-sums [10]. Furthermore, it includes several families of matroids like uniform, regular and $\sqrt[6]{1}$ -matroids. On the other hand, it is rather difficult to determine whether a given matroid has the half-plane property. Oxley, for instance, asks for a "practically feasible algorithm for testing whether a matroid is HPP" in his book [27, Problem 15.8.10]. One of the main results of this paper is a complete classification of which matroids on at most 8 elements have the half-plane property. This is achieved by checking theoretical criteria on the Rayleigh differences due to Brändén [4] and Wagner–Wei [32] by computational means using state-of-the-art software packages like the packages "SumsOfSquares" [12] and "Matroids" [9] for Macaulay2 [17] and the Julia package "HomotopyContinuation.jl" [6]. Even though these methods are mostly numerical, our heuristical algorithm produces for each matroid with at most

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8 elements a symbolic certificate for whether it has the half-plane property or not. Our classification yields a list of 32 matroids with at most 8 elements that are minor-minimal with respect to not having the half-plane property. These include the ten forbidden minors of rank 3 on 7 elements that were already found in [32], namely the Fano matroid, three of its relaxations, the free extension of $M(K_4)$ by one element and their duals. All other forbidden minors are sparse paving matroids of rank 4 on 8 elements. These include the self-dual matroid P_8 and three of its relaxations as well as the co-extension of P_7 and its dual. Moreover, we conduct tests on the half-plane property on matroids on 9 elements of rank 3 and 4. Our tests confirm that the Pappus, non-Pappus and (non-Pappus\9)+e matroids are the only forbidden minors for the half-plane property that are on 9 elements with rank 3. Among those of rank 4, we provide a list of 4125 matroids that have the half-plane property, and a list of 1218 matroids that are forbidden (minimal) minors for the half-plane property.

There is also ample interest in the half-plane property from the point of view of convex optimization. Consider for instance, the feasible sets of *semidefinite* programming (SDP) that are so-called spectrahedral cones. These are semi-algebraic convex sets that can (up to a linear change of coordinates) be described as the closure of the connected component of $C_f = \{x \in \mathbb{R}^n : f(x) \neq 0\}$ that contains the positive orthant for a suitable homogeneous polynomial f with the half-plane property. The question whether, conversely, the set C_f is a spectrahedral cone for every homogeneous f with the half-plane property is the content of the *generalized* Lax conjecture, a fundamental open question in this context [29]. In [5] Brändén showed that the basis generating polynomial of the Vámos matroid V_8 constitutes a counter-example to some stronger predecessor of the generalized Lax conjecture. Further such examples were given in [7, 1] and will be given in Section 5.1 of this article (on the other hand, see [20] for some positive result). This indicates that basis generating polynomials of matroids might be a good testing ground for the (current version of the) generalized Lax conjecture as well. We say that a matroid is spectrahedral if its basis generating polynomial f has the half-plane property and if the set C_f defined as above is a spectrahedral cone. For example it is not known whether the Vámos matroid is spectrahedral, although this is true for a related polynomial [19]. In Section 3 we will show that the class of spectrahedral matroids is minor-closed. More generally, we show in Section 4 that given f such that C_f is spectrahedral, the same is true for the polynomial that constitutes of all terms of f whose monomial lies in a fixed face of the Newton polytope of f.

2. The half-plane property and related concepts

Let M be a matroid of rank r on the ground set E = [n] and let \mathcal{B} be the collection of its bases. The *basis generating polynomial* of M is defined to be

$$h_M = \sum_{B \in \mathcal{B}} \prod_{i \in B} x_i.$$

Note that the basis generating polynomial of a matroid is *multiaffine* in the sense that it has degree at most one in every variable. We denote by $\mathrm{rk}: 2^E \to \mathbb{N}$ the rank function of M. See [27] for an introduction to matroid theory.

Definition 2.1. A polynomial $0 \neq f \in \mathbb{C}[x_1, \ldots, x_n]$ is said to have the *half-plane* property if $f(x_1, \ldots, x_n) \neq 0$ whenever the real part of each $x_i \in \mathbb{C}$ is positive.

Remark 2.2. For homogeneous polynomials, having the half-plane property is equivalent to being *stable*. A polynomial $0 \neq f \in \mathbb{C}[x_1, \ldots, x_n]$ is stable if

$$f(x_1,\ldots,x_n)\neq 0$$

whenever $\text{Im}(x_i) > 0$ for all $i \in [n]$. A univariate *real* polynomial $f \in \mathbb{R}[t]$ is stable if and only if it has only real roots.

Definition 2.3. A matroid is said to have the *half-plane property* if its basis generating polynomial is stable.

Remark 2.4. If $f, g \in \mathbb{C}[x_1, \ldots, x_n]$ are both non-zero, then the product $f \cdot g$ is stable if and only if both f and g are stable. Since for matroids M_1 and M_2 we have $h_{M_1 \oplus M_2} = h_{M_1} \cdot h_{M_2}$ [10, Proposition 4.5], we can often restrict our attention to connected matroids when studying the half-plane property.

Definition 2.5. Consider a polynomial $f \in \mathbb{C}[x_1, \ldots, x_n]$ with support $S \subseteq \mathbb{Z}_{\geq 0}^n$ given as

$$f = \sum_{\alpha \in \mathcal{S}} c_{\alpha} x^{\alpha}$$

for $c_{\alpha} \in \mathbb{C} \setminus \{0\}$. The Newton polytope Newt(f) of f is the convex hull in \mathbb{R}^n of all α with $c_{\alpha} \neq 0$. Let F be a face of Newt(f). We denote

$$f_F = \sum_{\alpha \in \mathcal{S} \cap F} c_\alpha x^\alpha$$

A standard argument shows that passing to a face of the Newton polytope preserves the half-plane property.

Proposition 2.6. Let $f \in \mathbb{C}[x_1, \ldots, x_n]$ be stable and F a face of Newt(f). Then f_F is stable as well.

Proof. Let $f = \sum_{\alpha \in \mathcal{S}} c_{\alpha} x^{\alpha}$ with support $\mathcal{S} \subseteq \mathbb{Z}_{\geq 0}^{n}$ for $c_{\alpha} \in \mathbb{C}$. Let $a \in \mathbb{R}^{n}$ and $c \in \mathbb{R}$ such that $\langle a, x \rangle \geq c$ for all $x \in \text{Newt}(f)$ with equality exactly when $x \in F$. For all $\epsilon > 0$ the polynomial

$$f_{\epsilon} := \epsilon^{-c} \cdot f(\epsilon^{a_1} x_1, \dots, \epsilon^{a_n} x_n) = \sum_{\alpha \in \mathbb{Z}^n \cap \operatorname{Newt}(f)} \epsilon^{\langle a, \alpha \rangle - c} c_{\alpha} x^{\alpha}$$

is also stable. It follows that $f_F = \lim_{\epsilon \to 0} f_{\epsilon}$ is stable by Hurwitz's theorem. \square

For any $f \in \mathbb{C}[x_1, \ldots, x_n]$ we denote by $f^{\#}$ and $f_{\#}$ its leading form resp. its initial form, i.e., the sum of all terms of largest or lowest degree respectively. If fis stable, then both $f^{\#}$ and $f_{\#}$ are stable. This has been proved in [10, §2.2] but it also follows from applying Proposition 2.6 to the face of Newt(f) that maximizes resp. minimizes the all-ones vector.

The standard way of calculating the basis generating polynomial of a minor of the matroid M is to delete and contract one element at a time. If $i \in E$ is not a coloop of M, then $h_{M\setminus\{e\}} = h_M|_{x_i=0}$ and $h_{M\setminus\{e\}} = \frac{\partial h_M}{\partial x_i}$ otherwise. If $i \in E$ is not a loop of M, then $h_{M/\{e\}} = \frac{\partial h_M}{\partial x_i}$ and $h_{M/\{e\}} = h_M$ otherwise. Since these operations preserve the half-plane property, this property is minor-closed [10, §4.1]. The basis generating polynomials of minors can also be expressed in terms of certain initial and leading forms.

Lemma 2.7. For any $S \subseteq E$ we have:

- (1) $h_{M/S} = c \cdot (h_M|_{x_i=1 \text{ for } i \in S})_{\#}$ for some constant c. (2) $h_{M\setminus S} = c' \cdot (h_M|_{x_i=1 \text{ for } i \in S})^{\#}$ for some constant c'.

Proof. We first prove (1). By [27, Cor. 3.1.8] a subset $I \subseteq E \setminus S$ is a basis of M/S if and only if there is a basis B of M such that $B \setminus I$ is a basis of $M|_S$, i.e., a maximal independent subset of S. This shows that the support of $h_{M/S}$ agrees with the support of $f := (h_M|_{x_i=1 \text{ for } i \in S})_{\#}$. It also follows from [27, Cor. 3.1.8] that the coefficient of each monomial in f is the number of bases of $M|_S$.

By the same argument we see that the support of $h_{M\setminus S}$ agrees with the support of $g := (h_M|_{x_i=1 \text{ for } i\in S})^{\#}$ and that the coefficient of every monomial in g is the number of bases of $M/(E\setminus S)$. This shows (2).

We will now study some concepts related to the half-plane property that have been of recent interest.

Definition 2.8. A real homogeneous polynomial $h \in \mathbb{R}[x_1, \ldots, x_n]$ of degree d is said to have a *determinantal representation* if there are positive semi-definite matrices A_1, \ldots, A_n of size $d \times d$ such that

$$h = \det(x_1 A_1 + \dots + x_n A_n).$$

We say that f is weakly determinantal if f^r has a determinantal representation for some suitable $r \in \mathbb{N}$. A matroid is called weakly determinantal if its basis generating polynomial is weakly determinantal.

Every polynomial that has a determinantal representation is stable. The same is true for weakly determinantal polynomials. Furthermore, the basis generating polynomial of a matroid M has a determinantal representation if and only if Mis a regular matroid [10, §8]. The class of weakly determinantal matroids is less well understood. We know that it includes all $\sqrt[6]{1}$ -matroids by [10, §8]. The main result of [5] says that the Vámos matroid is not weakly determinantal although it has the half-plane property by [32]. Further such matroids were found in [1] and in Section 5 we will also give some new examples. Of course, being regular is a minor-closed property. More generally, we have:

Theorem 2.9 (Cor. 5.8 in [22]). Let $f \in \mathbb{R}[x_1, \ldots, x_n]$ be a multiaffine stable polynomial. If f has a determinantal representation, then $\frac{\partial f}{\partial x_k}$ and $f|_{x_k=0}$ also have determinantal representations.

We will prove the analogous statement for weakly determinantal polynomials in Corollary 3.13. The following characterization of multiaffine stable polynomials is due to Brändén.

Theorem 2.10 (Thm. 5.6 in [4]). Let $h \in \mathbb{R}[x_1, \ldots, x_n]$ be multiaffine. The following are equivalent:

(1) h is stable,

(2) for all $1 \leq i, j \leq n$, the Rayleigh difference

$$\Delta_{ij}(h) := \frac{\partial h}{\partial x_i} \cdot \frac{\partial h}{\partial x_j} - \frac{\partial^2 h}{\partial x_i \partial x_j} \cdot h$$

is nonnegative on \mathbb{R}^n .

Definition 2.11. A multiaffine polynomial $h \in \mathbb{R}[x_1, \ldots, x_n]$ is called *SOS-Rayleigh* if for all $1 \leq i, j \leq n$, the Rayleigh difference $\Delta_{ij}(h)$ is a sum of squares (of polynomials). A matroid is called *SOS-Rayleigh* if its basis generating polynomial is SOS-Rayleigh.

For us the notion of being SOS-Rayleigh is important for several reasons. It follows directly from the definition and Theorem 2.10 that SOS-Rayleigh implies the half-plane property. However, it is easier to test whether a polynomial is a sum of squares than checking for global nonnegativity. Namely, the former can be done efficiently by running a semidefinite program [2]. Moreover, it was shown in [22] that being weakly determinantal implies SOS-Rayleigh. Via testing for the SOS-Rayleigh property we can thus find new examples of matroids with the half-plane property that are not weakly determinantal. Finally, polynomials with the half-plane property that are not SOS-Rayleigh are of interest in the context of Saunderson's approach to certifying the global nonnegativity of multivariate polynomials using *hyperbolic programming* [28]. We first show that in the multiaffine case being SOS-Rayleigh is preserved under taking derivatives.

Theorem 2.12. Let $f \in \mathbb{R}[x_1, \ldots, x_n]$ be a multiaffine stable polynomial. If f is SOS-Rayleigh, then $\frac{\partial f}{\partial x_k}$ and $f|_{x_k=0}$ are SOS-Rayleigh as well.

Proof. Let $g = \frac{\partial f}{\partial x_k}$ and $h = f|_{x_k=0}$. One calculates

h i

 $\Delta_{ij}f = x_k^2 \cdot \Delta_{ij}g + x_k \cdot p + \Delta_{ij}h$

for some $p \in \mathbb{R}[x_1, \ldots, x_n]$ that does not depend on x_k . By assumption $\Delta_{ij}f = \sum_{l=1}^m s_l^2$ is a sum of squares. Comparing degrees on both sides we get that $s_l = a_l x_k + b_l$ for some polynomials a_l, b_l that do not depend on x_k . It follows that $\Delta_{ij}g = \sum_{l=1}^m a_l^2$ and $\Delta_{ij}h = \sum_{l=1}^m b_l^2$.

Corollary 2.13. The class of SOS-Rayleigh matroids is minor-closed.

Let $h \in \mathbb{R}[x_1, \ldots, x_n]$ be a homogeneous multiaffine polynomial. We can summarize the relations between the properties we defined so far as follows:

$$\begin{array}{ccc} h \text{ has a determinantal} & \stackrel{[22]}{\longleftrightarrow} & \Delta_{ij}h \text{ is a square} \\ \text{ representation} & & \stackrel{for all }{\longleftrightarrow} & i, j \in [n] \end{array}$$

$$\begin{array}{c} h \text{ is weakly} \\ \text{determinantal} & \Longrightarrow & h \text{ has HPP} \iff & h \text{ is hyperbolic} \\ \text{with resp. to all } e \in \mathbb{R}^{n}_{\geq 0} \\ \\ \downarrow [22] & & \uparrow [4] \end{array}$$

$$s \text{ SOS-Rayleigh} \implies & \Delta_{ij}h \geq 0 \\ \text{ for all } i, j \in [n] \end{array}$$

3. Hyperbolic polynomials and spectrahedra

Definition 3.1. A polynomial h is called *hyperbolic* with respect to $e \in \mathbb{R}^n$ if $h(e) \neq 0$ and for all $v \in \mathbb{R}^n$, the univariate polynomial $h(v - te) \in \mathbb{R}[t]$ has only real roots. The hyperbolicity cone of h at e is

$$C_h(e) = \{ v \in \mathbb{R}^n : h(v - te) = 0 \Rightarrow t \in \mathbb{R}_{>0} \}.$$

Every homogeneous stable polynomial $f \in \mathbb{R}[x_1, \ldots, x_n]$ is hyperbolic with respect to the all-ones vector and one can study the associated hyperbolicity cone. One can show that it always contains the positive orthant. Conversely, if the hyperbolicity cone of a hyperbolic polynomial contains the postive orthant, then it is stable. Moreover, if the non-zero coefficients of a homogeneous polynomial have no sign variation, then being hyperbolic with respect to the all-ones vector implies that the associated hyperbolicity cone contains the positive orthant. In particular, the basis generating polynomials of a matroid is stable if and only if it is hyperbolic with respect to the all-ones vector.

Definition 3.2. A spectrahedral cone is a cone of the form

 $C = \{ v \in \mathbb{R}^n : A(v) = v_1 A_1 + \ldots + v_n A_n \succeq 0 \}$

for some real symmetric matrices A_1, \ldots, A_n of size $d \times d$, where $A(v) \succeq 0$ means that A(v) is positive semi-definite. We say that a matroid is *spectrahedral* if it has the half-plane property and the hyperbolicity cone at the all-ones vector of its basis generating polynomial is a spectrahedral cone.

Recall the following criterion for a hyperbolicity cone to be spectrahedral.

6

Theorem 3.3 (Thm. 2.1 in [29]). Let $h \in \mathbb{R}[x_1, \ldots, x_n]$ be a homogeneous stable polynomial and $e = (1, \ldots, 1)$ the all-ones vector. The hyperbolicity cone $C_h(e)$ is spectrahedral if and only if there is another homogeneous stable polynomial $g \in \mathbb{R}[x_1, \ldots, x_n]$, such that $C_h(e) \subseteq C_g(e)$ and $h \cdot g$ has a determinantal representation.

Lemma 3.4. Let f, g be two polynomials that are hyperbolic with respect to $e \in \mathbb{R}^n$. For $v \in \mathbb{R}^n$ let $g_{\min}(v)$ be the smallest root of g(te - v) and $f_{\min}(v)$ be the smallest root of f(te - v) respectively. Then we have $f_{\min}(v) \leq g_{\min}(v)$ for all $v \in \mathbb{R}^n$ if and only if $C_f(e) \subseteq C_g(e)$.

Proof. \Leftarrow : Assume that $C_f(e) \subseteq C_g(e)$. Then for all $v \in \mathbb{R}^n$ the smallest root of

 $f((t+f_{\min}(v))e-v)$

is zero. Thus $f(te - (-f_{\min}(v)e + v))$ has only non-negative zeros. By definition of $C_f(e)$ this implies that $-f_{\min}(v)e + v \in C_f(e) \subseteq C_g(e)$. By the definition of $C_g(e)$ this shows that $g(te - (-f_{\min}(v)e + v)) = g((t + f_{\min}(v))e - v)$ has only non-negative zeros. Thus $f_{\min}(v) \leq g_{\min}(v)$.

⇒: For $v \in C_f(e)$ we have by definition that $f_{\min}(v) \ge 0$. If $f_{\min}(v) \le g_{\min}(v)$, then $g_{\min}(v) \ge 0$ and thus $v \in C_g$.

Lemma 3.5. Let $(h_i)_{i\in\mathbb{N}}, (g_i)_{i\in\mathbb{N}}$ two sequences of polynomials that are hyperbolic with respect to $e \in \mathbb{R}^n$. Assume that we have $h = \lim_{i\to\infty} h_i$ and $g = \lim_{i\to\infty} g_i$ for polynomials g, h that are hyperbolic with respect to e. If $C_{h_i}(e) \subseteq C_{g_i}(e)$ for all $i \in \mathbb{N}$, then $C_h(e) \subseteq C_g(e)$.

Proof. For every $v \in \mathbb{R}^n$ and $i \in \mathbb{N}$ the smallest root of $h_i(te - v)$ is at most the smallest root of $g_i(te - v)$ by Lemma 3.4. Since the roots of a univariate polynomial depend continuously on the coefficients, we have the same for h and g. Thus, again by Lemma 3.4 $C_h(e) \subseteq C_g(e)$.

Lemma 3.6. Let $h \in \mathbb{R}[x_1, \ldots, x_n]$ be a homogeneous polynomial that does not depend on x_k . Let $h' := x_k^m h$ for a positive integer m, and assume that h' (and thus h) is hyperbolic with respect to $e \in \mathbb{R}^n$. Then

$$C_h(e) = \{ v \in \mathbb{R}^n : v + \lambda e_k \in C_{h'}(e) \text{ for some } \lambda \in \mathbb{R} \}.$$

Proof. We have $C_{h'}(e) = C_h(e) \cap C_{x_k}(e) \subseteq C_h(e)$. For every $v \in C_h(e)$ we have $v + \lambda e_k \in C_h(e)$ since h does not depend on x_k . This shows the inclusion \supset .

On the other hand, if $v \in C_h(e)$, then for $\lambda = -v_k$, the polynomial $h'(te - (v + \lambda e_k))$ equals $c \cdot t^m \cdot h(te - v)$ for some non-zero constant $c \in \mathbb{R}$ and thus has only nonnegative roots. This shows the other inclusion.

Corollary 3.7. Let $h_1, h_2 \in \mathbb{R}[x_1, \ldots, x_n]$ be homogeneous polynomials that do not depend on x_k . Let $h'_i := x_k^{m_i}h$ and assume that h'_i (and thus h_i) is hyperbolic with respect to $e \in \mathbb{R}^n$ for i = 1, 2. If $C_{h'_1}(e) \subseteq C_{h'_2}(e)$, then $C_{h_1}(e) \subseteq C_{h_2}(e)$.

Proof. This follows from the description of $C_{h_i}(e)$ given in Lemma 3.6.

Corollary 3.8. Let $h_1, h_2 \in \mathbb{R}[x_1, \ldots, x_n]$ be homogeneous stable polynomials and $e = (1, \ldots, 1)$ the all-ones vector. Let $C_{h_1}(e) \subseteq C_{h_2}(e)$ and $h'_i = (h_i|_{x_k=1})_{\#}$ for i = 1, 2. Then $C_{h'_1}(e) \subseteq C_{h'_2}(e)$.

Proof. Let d_i be the degree of h_i and r_i be the smallest degree of a monomial of $h_i|_{x_k=1}$. For $\gamma > 0$ let T_{γ} the linear map defined by

$$T_{\gamma}(x_1,\ldots,x_n)=(\gamma x_1,\ldots,\gamma x_{k-1},x_k,\gamma x_{k+1},\ldots,\gamma x_n).$$

For i = 1, 2 the polynomial $h_{i,\gamma} = \gamma^{-r_i} h_i(T_{\gamma}x)$ is stable. Since $T_{\gamma}^{-1}e$ is in the positive orthant and thus in the interior of $C_{h_i,\gamma}(e)$, we have

$$C_{h_{i,\gamma}}(e) = C_{h_{i,\gamma}}(T_{\gamma}^{-1}e) = \{ v \in \mathbb{R}^n : h_i(T_{\gamma}v - te) = 0 \Rightarrow t \ge 0 \} = T_{\gamma}^{-1}(C_{h_i}(e)),$$

where the first equality is [14, Theorem 2]. In particular $C_{h'_1}(e) \subseteq C_{h'_2}(e)$ implies $T_{\gamma}^{-1}(C_{h'_1}(e)) \subseteq T_{\gamma}^{-1}(C_{h'_2}(e))$ and therefore $C_{h_{1,\gamma}}(e) \subseteq C_{h_{2,\gamma}}(e)$. Since h_i is homogeneous, the limit $\lim_{\gamma\to 0} h_{i,\gamma}$ kills all the monomials, except those that are divisible by $x_k^{d_i-r_i}$. Thus, we have

$$\lim_{\gamma \to 0} h_{i,\gamma} = x_k^{d_i - r_i} (h_i|_{x_k = 1})_{\#}$$

Now the claim follows from Lemma 3.5 and Corollary 3.7.

Theorem 3.9. Let $h \in \mathbb{R}[x_1, \ldots, x_n]$ be a homogeneous, multiaffine and stable polynomial and $e = (1, \ldots, 1)$ the all-ones vector. If $\frac{\partial h}{\partial x_k} \neq 0$ and the hyperbolicity cone $C_h(e)$ is spectrahedral, then the hyperbolicity cone of $\frac{\partial h}{\partial x_k}$ is also spectrahedral.

Proof. Let $h \in \mathbb{R}[x_1, \ldots, x_n]$ be hyperbolic with respect to $e \in \mathbb{R}^n$ and assume that $C_h(e)$ is spectrahedral. Then, by Theorem 3.3, there exists a stable polynomial $g \in \mathbb{R}[x_1, \ldots, x_n]$ such that $C_h(e) \subseteq C_g(e)$ and $p := h \cdot g$ has a determinantal representation. We can assume that k = 1 and that

$$0 \neq p = \det(x_1 A_1 + \ldots + x_n A_n)$$

where A_i is positive semidefinite of rank $r_i \ge 1$. Please note that p does not need to be multiaffine. Let us write each A_i as the sum of rank 1 matrices:

$$A_i = A_{i1} + \ldots + A_{ir_i},$$

where A_{ij} are positive semidefinite matrices of rank 1, $i \in [n]$, $j \in [r_i]$. Let us define a new polynomial

$$\tilde{p} = \det(x_{11}A_{11} + x_{12}A_{12} + \dots + x_{1r_1}A_{1r_1} + \dots + x_{nr_n}A_{nr_n})$$

in $\sum_{i=1}^{n} r_i$ variables. The degree of each variable x_{ij} in \tilde{p} is the rank of A_{ij} so that \tilde{p} is multiaffine. Moreover, since the rank of A_i is r_i , there are monomials of \tilde{p} that are divisible by $x_{i1} \cdots x_{ir_i}$, see e.g. [5, p. 1206]. By Theorem 2.9 the polynomial

$$\frac{\partial'^{1}p}{\partial x_{11}\cdots\partial x_{1r_1}} = (\tilde{p}|_{x_{1j}=1 \text{ for } j\in[r_1]})_{\#}$$

has a determinantal representation. The same is thus true for the polynomial \hat{p} that we obtain from $\frac{\partial^{r_1}\tilde{p}}{\partial x_{11}\cdots\partial x_{1r_1}}$ by setting $x_{ir_1} = \cdots = x_{ir_k} = x_i$ for all $i \in [n]$. By construction we have that

$$\hat{p} = (p|_{x_1=1})_{\#} = (h|_{x_1=1} \cdot g|_{x_1=1})_{\#} = (h|_{x_1=1})_{\#} \cdot (g|_{x_1=1})_{\#}.$$

Since h is multiaffine, we have $(h|_{x_1=1})_{\#} = \frac{\partial h}{\partial x_1}$. Thus in order to prove the claim it remains to show that the hyperbolicity cone of $(h|_{x_1=1})_{\#}$ is contained in the hyperbolicity cone of $(g|_{x_1=1})_{\#}$. This is the content of Corollary 3.8.

Remark 3.10. The proof of Theorem 3.9 crucially relies on the assumption that h is multiaffine and it is not known whether one can drop this assumption. A related result was proved in [21]: If h (not necessarily multiaffine) has a determinantal representation, then the hyperbolicity cone of any iterated derivative in direction e of h is spectrahedral.

Lemma 3.11. Let $h \in \mathbb{R}[x_1, \ldots, x_n]$ be a homogeneous, multiaffine and stable polynomial, and let $e = (1, \ldots, 1)$ the all-ones vector. If $h|_{x_k=0} \neq 0$ and the hyperbolicity cone $C_h(e)$ is spectrahedral, then the hyperbolicity cone of $h|_{x_k=0}$ is also spectrahedral.

Proof. The hyperbolicity cone of $h|_{x_k=0}$ is the intersection of $C_h(e)$ with the hyperplane $x_k = 0$ and thus spectrahedral.

Corollary 3.12. The class of spectrahedral matroids is minor-closed.

Proof. If a matroid is spectrahedral, then the same is true for its contractions by Theorem 3.9 and for its deletions by Lemma 3.11. \Box

Corollary 3.13. Let $h \in \mathbb{R}[x_1, \ldots, x_n]$ be multiaffine, stable and weakly determinantal. Then $\frac{\partial h}{\partial x_k}$ and $h|_{x_k=0}$ are also weakly determinantal.

Proof. For $\frac{\partial h}{\partial x_k}$ we can apply the proof of Theorem 3.9 to the case $g = h^r$ for some $r \geq 0$. The claim for $h|_{x_k=0}$ follows directly from the definition.

Corollary 3.14. The class of weakly determinantal matroids is minor-closed.

4. MATROID POLYTOPES

Definition 4.1. The matroid polytope P(M) of a matroid M is defined as

$$P(M) = \operatorname{conv}\left\{\sum_{i\in B} e_i : B \in \mathcal{B}\right\}$$

where $e_i \in \mathbb{R}^n$ denotes the *i*th unit vector.

Remark 4.2. The matroid polytope of a matroid is the Newton polytope of its basis generating polynomial.

Remark 4.3. It follows for example from [25, §4.4] that there is the following description of P(M) by means of inequalities:

$$P(M) = \left\{ x \in r \cdot \Delta_n : \sum_{i \in S} x_i \le \operatorname{rk}(S) \text{ for all flats } S \subseteq E \right\}$$

where $r \cdot \Delta_n \subseteq \mathbb{R}^n$ denotes r-fold dilation of the standard n-simplex $\Delta_n \subseteq \mathbb{R}^n$. It follows from [15, Thm. 4.1] that any face F of P(M) is the matroid polytope of a suitable uniquely determined matroid M_F itself. For a face $F \neq \emptyset$ of P(M) of codimension 1 there are two possibilities. Either there is a flat S of M such that F consists of all points $x \in r \cdot \Delta_n$ that satisfy $\sum_{i \in S} x_i = \operatorname{rk}(S)$. In this case we have $M_F = M|_S \oplus M/S = M \setminus (E \setminus S) \oplus M/S$ by [16, Thm. 2]. Otherwise F is the intersection of $r \cdot \Delta_n$ with a coordinate hyperplane $x_i = 0$. Letting $S = E \setminus \{i\}$ we have $\operatorname{rk}(S) = r$ since $F \neq \emptyset$ and F consists of all points $x \in r \cdot \Delta_n$ that satisfy $\sum_{i \in S} x_i = \operatorname{rk}(S)$. Again we have $M_F = M|_S \oplus M/S$ although S is not a flat.

Corollary 4.4. Let M be a matroid and F a face of its matroid polytope. Let P be a property that is minor-closed and preserved under taking the direct sum of matroids. If M has property P, then M_F has property P.

This applies to the half-plane property, being weakly determinantal, spectrahedral and SOS-Rayleigh.

Proof. It suffices to show the claim for facets F of the matroid polytope. Then it follows from the description $M_F = M|_S \oplus M/S$ from Remark 4.3.

The second claim is true for the half-plane property by Proposition 2.6. The other three properties are minor-closed and it remains to show that these are preserved under taking the direct sums. For being weakly determinantal and spectrahedral this follows from taking suitable block matrices. For being SOS-Rayleigh it follows from the identity $\Delta_{ij}(f \cdot g) = f^2 \Delta_{ij}g + g^2 \Delta_{ij}f$.

MATROIDS ON EIGHT ELEMENTS WITH HPP

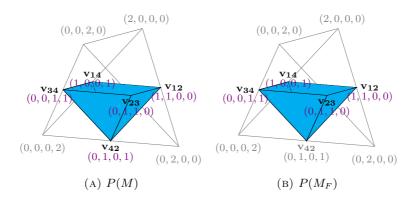


FIGURE 1. Matroid polytopes P(M) and $P(M_F)$

Corollary 4.5. Let M be a matroid and F be a facet of P(M). There is a subset $S \subseteq E$ and a constant c such that

$$h_{M_F} = c \cdot (h_M|_{x_i=1 \text{ for } i \in E \setminus S})_{\#} \cdot (h_M|_{x_i=1 \text{ for } i \in S})^{\#}.$$

Proof. By Remark 4.3 we have $M_F = M|_S \oplus M/S$ and thus the claim follows from Lemma 2.7.

Example 4.6. Let M be the matroid with basis generating polynomial

$$h_M = x_1 x_2 + x_2 x_3 + x_1 x_4 + x_2 x_4 + x_3 x_4.$$

Its matroid polytope P(M) is depicted in Figure 1a. The nonempty proper flats of M are $S_1 = \{2\}$, $S_2 = \{4\}$ and $S_3 = \{1,3\}$. Thus P(M) has the following representation in terms of inequalities:

$$P(M) = \left\{ x \in 2\Delta_4 : \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \le \begin{pmatrix} 1 \\ 1 \\ 1 \\ 2 \end{pmatrix} \right\}.$$

Consider for instance the flat $\{1,3\}$, the hyperplane $H = \{x \in \mathbb{R}^4 : x_1 + x_3 = 1\}$ and the face $F = P(M) \cap H$. The matroid M_F is the matroid whose bases are encoded by the vertices of the face F that is illustrated in Figure 1b. Its basis generating polynomial is

$$h_{M_F} = x_1 x_2 + x_2 x_3 + x_1 x_4 + x_3 x_4 = (x_1 + x_3) (x_2 + x_4).$$

which is consistent with Corollary 4.5.

For the rest of the section we will extend these results to arbitrary stable polynomials. In Proposition 2.6 we have already seen that given a stable polynomial f and a face F of its Newton polytope, the polynomial f_F is also stable.

Lemma 4.7. Let $f \in \mathbb{R}[x_1, \ldots, x_n]$ be homogeneous and multiaffine. Let F be a face of Newt(f). If f has a determinantal representation, then f_F has a determinantal representation as well.

Proof. Without loss of generality, we can assume that F is a facet of P := Newt(f). Since f is multiaffine, we can write

$$f = \det(x_1 A_1 + \ldots + x_n A_n)$$

for some positive semidefinite matrices of rank at most 1, i.e., we have $A_i = a_i \cdot a_i^t$ for some $a_i \in \mathbb{R}^d$ [5, §3]. Let M be the matroid represented by the vectors a_1, \ldots, a_n . Then we have P = P(M). By Remark 4.3 there is a subset S of the ground set of M such that F consists of all $p \in d \cdot \Delta_n$ that satisfy $\sum_{i \in S} p_i = \operatorname{rk}(S) =: r$. After replacing the A_i by $N^t A_i N$ for some invertible matrix N, we can assume that the span of all a_i with $i \in S$ is spanned by the first r standard unit vectors. This means that in the matrix $A := x_1 A_1 + \ldots + x_n A_n$ the variables x_i for $i \in S$ only show up in the upper left $r \times r$ block R_1 of A. Let R_2 be the lower right $(d - r) \times (d - r)$ block. By applying Laplace expansion to the determinant of A we see that f_F , which is the sum of terms of f that have maximal degree in the $x_i, i \in S$, is exactly the determinant of the block matrix

$$\begin{pmatrix} R_1|_{x_j=0,\,j\notin S} & 0\\ 0 & R_2 \end{pmatrix}.$$

This shows that f_F has a determinantal representation.

Lemma 4.8. Let $f \in \mathbb{R}[x_1, \ldots, x_n]$ be homogeneous. Let F be a face of Newt(f). If f has a determinantal representation, then f_F has a determinantal representation as well.

Proof. As in the proof of Theorem 3.9 we can find a multiaffine homogeneous polynomial $p \in \mathbb{R}[x_{11}, \ldots, x_{1r_1}, \ldots, x_{nr_n}]$ which has a determinantal representation such that $f = p|_{x_{ij}=x_i}$. In particular, the polytope Newt(f) is the image of Newt(p) under a linear map. There is a face F' of Newt(p) such that $f_F = (p_{F'})|_{x_{ij}=x_i}$. Thus the claim follows from Lemma 4.7.

Corollary 4.9. Let $f \in \mathbb{R}[x_1, \ldots, x_n]$ be homogeneous and stable. Let F be a face of Newt(f). If f is weakly determinantal or spectrahedral, then f_F is weakly determinantal resp. spectrahedral as well.

Proof. Let $a \in \mathbb{R}^n$ and $c \in \mathbb{R}$ such that $\langle a, p \rangle \geq c$ for all $p \in \text{Newt}(f)$ with equality exactly when $p \in F$. If f is spectrahedral, then by Theorem 3.3 there is a stable polynomial g whose hyperbolicity cone contains the one of f such that $f \cdot g$ has a determinantal representation. Let F' and F'' be the faces of Newt(g) and $\text{Newt}(f \cdot g)$ where $\langle a, - \rangle$ attains its minimum. Then we have $(f \cdot g)_{F''} = f_F \cdot g_{F'}$ and this polynomial has a determinantal representation by Lemma 4.8. Writing f_F and $g_{F'}$ as limits as in the proof of Proposition 2.6, it follows from Lemma 3.5 that the hyperbolicity cone of $g_{F'}$ contains the one of f_F . Thus we conclude that f_F is spectrahedral. If f is weakly determinantal, then we can proceed in the same way by letting $g = f^r$ for some $r \geq 0$.

5. Classification of Matroids on Eight Elements with Respect to the Half-plane Property

In this section we classify all matroids on a ground set E with $|E| \leq 8$ that have the half-plane property. Matroids with the half-plane property on at most seven elements were classified in [10], so it remains to consider ground sets of exactly eight elements.

Let M be a matroid on the ground set [n] with basis generating polynomial h_M . Recall from Theorem 2.10 that M has the half-plane property if and only if $\Delta_{ij}h_M(x) \geq 0$ for all $x \in \mathbb{R}^n$ and $1 \leq i, j \leq n$. We will make use of this criterion. Wagner and Wei proved that when all proper minors of M have the half-plane property, it suffices to find *one* Rayleigh difference which is nonnegative.

Theorem 5.1 (Thm. 3 in [32]). Let M be a matroid all of whose proper minors have the half-plane property. If there exist distinct indices $i, j \in [n]$ such that $\Delta_{ij}h_M(x) \ge 0$ for all $x \in \mathbb{R}^n$, then M has the half-plane property.

Theorem 5.1 will be the main criterion that we will use to prove that a certain matroid has the half-plane property. But first we narrow down the set of matroids

that have to be considered. By [10, Prop. 4.2] having the half-plane property is closed under taking the dual of the matroid. Thus it is enough to consider matroids on eight elements with rank at most four. Further the half-plane property is preserved by direct sums, by adjoining loops or parallel elements [10, §4]. Therefore, we can restrict attention to simple connected matroids on eight elements of rank at most four. Finally, all rank-1 and rank-2 matroids have the half-plane property by [10, Cor. 5.5]. Thus we can restrict attention to matroids on eight elements of rank three and four.

We will use the Macaulay2 [17] package "Matroids" by Chen [8, 9] where a list of all matroids on at most eight elements is implemented: The command allMatroids(8) yields a list of all matroids on 8 elements. In the following, we will denote by \mathcal{M}_i the *i*th element of this list (counting starts from zero). We obtain that the number of non-isomorphic matroids on 8 elements with rank 3 or 4 is 1265. While 685 of them are simple, 659 of them are simple and connected. In [10] it was shown that all matroids on at most seven elements have the half-plane property, except for the Fano matroid F_7 , Non-Fano matroid F_7^- , F_7^{--} , F_7^{-3} , $M(K_4) + e$ and their duals. Since the half-plane property is minor-closed, we can exclude all matroids that have one of these matroids as a minor. Then we are left with 309 simple and connected matroids all of whose proper minors have the half-plane property. By Theorem 5.1, for each of these 309 matroids, if we can prove that one Rayleigh difference is nonnegative, the matroid in question has the half-plane property.

For doing this, we run a sums of squares test using the Macaulay2 package "SumsOfSquares" by Cifuentes, Kahle, Parrilo, and Peyrl [11, 12] on all Rayleigh differences of the basis generating polynomials of all these 309 matroids. We obtain that for 287 matroids from this list there exists some indices i, j such that $\Delta_{ij}(h_M)$ is a sum of squares. Among them 256 matroids are SOS-Rayleigh, i.e., for those matroids *all* Rayleigh differences are a sum of squares. Moreover, for each of the 287 matroids, there were some indices i, j for which the SDP solver could find a Gram matrix with *rational* entries. Thus we even obtain a *symbolic* certificate for being a sums of squares, and thus for the corresponding matroid to have the half-plane property. For more information on the source code of the tests and symbolic certificates, please see the ancillary files Appendix.pdf, M2Code.m2 and SageCode.sage. For more information on SDP solvers and the "SumsOfSquares" package in Macaulay2, we refer to [2, 11, 12].

We thus note that only 22 matroids are left for which we do not know whether they have the half-plane property: the fact that for those 22 matroids there are no i, j for which the Rayleigh difference is a sum of squares does not imply that these matroids do not have the half-plane property as there are nonnegative polynomials that are not a sum of squares. All these 22 matroids have rank 4. This implies that among the matroids on eight elements with rank 3 there are no new forbidden minors for the half-plane property.

In order to investigate the half-plane property of those remaining 22 matroids, recall that the homogeneous polynomial h_M has the half-plane property if and only if it is hyperbolic with respect to e = (1, ..., 1) and $\mathbb{R}^n_{\geq 0} \subseteq C_{h_M}(e)$. Since the roots of a polynomial depend continuously on their coefficients, finding points $e, v \in \mathbb{R}^n_{\geq 0}$ for which $h_M(et - v)$ has not only real zeros proves that h_M does not have the half-plane property. Thus, testing whether $h_M(et - v)$ has only real roots for $e, v \in \{0, 1\}^8$ provides a quick way to eliminate some more matroids. We obtain that 15 of the 22 matroids do not pass this test, and the remaining 7 matroids require more tests to prove or disprove that they have the half-plane property. For the list of these 15 matroids whose basis generating polynomials fail this test and for the corresponding points e, v, we refer to Table 1.

	Number of pairs (e, v) for which	
Matroids	$\mathbf{h}_{\mathbf{M}}(\mathbf{et} - \mathbf{v})$	One of the pairs (e, v)
	has non-real roots	
\mathcal{M}_{435}	4	((1, 1, 1, 1, 1, 1, 0, 1), (1, 1, 0, 0, 0, 0, 1, 1))
\mathcal{M}_{437}	8	((0, 0, 0, 0, 1, 1, 1, 1), (1, 1, 1, 1, 1, 1, 0, 1))
\mathcal{M}_{439}	4	((1, 0, 1, 1, 1, 1, 1, 1), (1, 1, 1, 1, 0, 0, 0, 0))
\mathcal{M}_{443}	2	((1, 1, 1, 1, 0, 1, 1, 1), (0, 0, 0, 0, 1, 1, 1, 1))
\mathcal{M}_{450}	4	((0, 1, 1, 1, 1, 1, 1, 1), (1, 1, 0, 0, 1, 1, 0, 0))
\mathcal{M}_{455}	2	((1, 1, 0, 1, 0, 1, 0, 1), (0, 1, 1, 0, 1, 0, 1, 1))
\mathcal{M}_{460}	2	((0, 0, 1, 1, 1, 1, 1, 1), (1, 1, 0, 0, 0, 0, 1, 1))
\mathcal{M}_{461}	12	((1, 1, 1, 1, 0, 1, 1, 1), (0, 0, 1, 1, 1, 1, 0, 0))
\mathcal{M}_{465}	10	((0, 1, 1, 1, 1, 1, 1, 1), (1, 1, 0, 0, 0, 0, 1, 1))
\mathcal{M}_{466}	38	((0, 0, 1, 1, 1, 1, 0, 1), (1, 1, 0, 0, 0, 0, 1, 1))
\mathcal{M}_{467}	62	((1, 1, 0, 1, 1, 0, 1, 1), (0, 0, 1, 1, 1, 1, 0, 0))
\mathcal{M}_{548}	6	((1, 1, 1, 1, 0, 0, 0, 1), (0, 0, 0, 0, 1, 1, 1, 1))
\mathcal{M}_{549}	4	((1, 1, 1, 1, 0, 0, 1, 1), (1, 1, 1, 1, 0, 0, 1, 1))
\mathcal{M}_{570}	78	((1, 1, 0, 0, 1, 1, 1, 1), (0, 0, 1, 1, 1, 1, 0, 0))
\mathcal{M}_{575}	158	((1, 1, 1, 1, 1, 1, 0, 1), (0, 0, 0, 1, 1, 0, 1, 1))

TABLE 1. 15 matroids and a sample of directions for which they fail the hyperbolicity test.

Matroids	$\mathbf{x} \in \mathbb{R}^{6} ext{ s.t. } \mathbf{\Delta_{6,7}(h_M)(x)} < 0$
\mathcal{M}_{424}	(4, 30, 1, 7, -32, -4)
\mathcal{M}_{430}	(80, 19, -31, -31, -17, -4)
\mathcal{M}_{431}	(60, 27, -90, -22, 27, 5)
\mathcal{M}_{436}	(40, 309, -40, -306, 9, 73)
\mathcal{M}_{462}	(20, 55, -11, -4, -52, -19)
\mathcal{M}_{463}	(30, 399, -111, -10, -368, -28)
\mathcal{M}_{550}	(50, -25, 94, -45, -142, 66)

TABLE 2. Seven matroids and points $x \in \mathbb{R}^6$ at which one of their Rayleigh differences is negative.

For each of the remaining 7 matroids M, using the Julia package "Homotopy-Continuation.jl" by Breiding and Timme [6], we found a point $x \in \mathbb{R}^6$ for which $\Delta_{67}(h_M)(x) < 0$ which confirms that they do not have the half-plane property as well. More precisely, we computed all critical points of the Rayleigh difference and plugged in nearby rational points. For the list of points where the Rayleigh difference is negative, see Table 2. This gives us the following main result of this section.

Theorem 5.2. There are exactly 22 matroids on 8 elements all of whose minors have the half-plane property but which do not have the half-plane property themselves. These 22 matroids are the matroids \mathcal{M}_k for k in the following list:

 $\{424, 430, 431, 435, 436, 437, 439, 443, 450, 455, 460, 461, 462, 463, 465,$

466, 467, 548, 549, 550, 570, 575.

All of them are sparse paving matroids of rank 4. Furthermore, all of these matroids are self-dual except for the following dual pairs: $\mathcal{M}_{424} = \mathcal{M}_{436}^*$, $\mathcal{M}_{430} = \mathcal{M}_{548}^*$, $\mathcal{M}_{450} = \mathcal{M}_{549}^*$ and $\mathcal{M}_{455} = \mathcal{M}_{550}^*$.

We now take a closer look at some of the 22 matroids from Theorem 5.2. In the following, we will mostly stick to the catalog of [27] regarding special matroids. Further Ext(M) of a matroid M refers to the free extension of M by an element e, see [27, page 270]. The co-extension CoExt(M) of M refers to the dual of the extension of M^* , such that CoExt/e = M. Note that Ext(M) and CoExt(M) can be obtained by using the SageMath commands M.extension() and M.coextension() respectively.

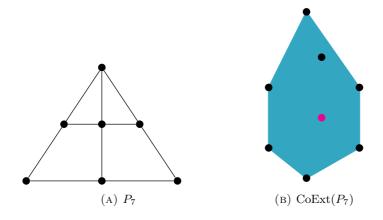


FIGURE 2. The matroids P_7 and $\mathcal{M}_{430} = \text{CoExt}(P_7)$.

Example 5.3. The matroid \mathcal{M}_{430} is the co-extension $\operatorname{CoExt}(P_7)$ of the ternary 3-spike P_7 . Both are depicted in Figure 2. Further minors of \mathcal{M}_{430} include P_6 , Q_6 , R_6 , $\operatorname{CoExt}(R_6)$ and $\operatorname{Ext}(Q_6)$ which all have the half-plane property. Its dual is the matroid \mathcal{M}_{548} .

Example 5.4. The rank-4 matroid P_8 is represented over \mathbb{Q} by the matrix:

1	0	0	0	0	1	1	2
0	1	0	0	1	0	1	1
0	0	1	0	1	1	0	$\begin{pmatrix} 2 \\ 1 \\ 1 \\ 0 \end{pmatrix}$
$\setminus 0$	0	0	1	2	1	1	0/

The circuit hyperplanes of P_8 are $\{1, 2, 3, 8\}$, $\{1, 2, 4, 7\}$, $\{1, 3, 4, 6\}$, $\{2, 3, 4, 5\}$, $\{1, 4, 5, 8\}$, $\{2, 3, 6, 7\}$, $\{1, 5, 6, 7\}$, $\{2, 5, 6, 8\}$, $\{3, 5, 7, 8\}$ and $\{4, 6, 7, 8\}$. We denote by P'_8 , P''_8 and P'''_8 the matroids obtained by relaxing the first, the first and the second, resp. all three of the following circuit hyperplanes: $\{1, 4, 5, 8\}$, $\{2, 3, 6, 7\}$ and $\{4, 6, 7, 8\}$. It was shown in [10, Ex. 11.8] that P_8 , P'_8 and P''_8 do not have the half-plane property. In our list, these are the matroids \mathcal{M}_{575} , \mathcal{M}_{570} and \mathcal{M}_{467} . Furthermore, the matroid \mathcal{M}_{466} is the relaxation P''_8 which does not have the halfplane property as well. In [24, Prop. 4] the matroid P''_8 is denoted by P_3 and it is shown that it is not representable over any field. Further note that in [27] the matroid P''_8 is denoted by $P^=_8$. It is an excluded minor for being representable over the field of 4 elements.

Example 5.5. The matroid \mathcal{M}_{431} has only four circuit hyperplanes: $\{1, 2, 3, 4\}$, $\{1, 2, 5, 6\}$, $\{1, 3, 5, 7\}$ and $\{2, 3, 5, 8\}$.

Any matroid having one of our 22 matroids as a minor does not have the halfplane property.

Example 5.6. The *Extended Ternary Golay code* is the matroid represented by the following generating matrix of the Extended Ternary Golay code over the field \mathbb{F}_3

1	1	0	0	0	0	0	1	1	1	2	2	0 `	\
1	0	1	0	0	0	0	1	1	2	1	0	2	
	0	0	1	0	0	0	1	2	1	0	1	2	
						0							
	0	0	0	0	1	0	1	0	2	2	1	1	
	0	0	0	0	0	1	0	1	1	1	1	1	/

The supports of the codewords form a Steiner System S(5, 6, 12), i.e., a 12 element set with a collection \mathcal{D} of 6 element subsets (called blocks) such that every 5 element subset of S is contained in exactly one block. Here, a ground set E with 12 elements with the collection \mathcal{D} of hyperplanes define a matroid. It does not have the halfplane property since it has P_8 as a minor.

Further matroids having one of our 22 matroids as a minor include the coextensions $\text{CoExt}(P_8)$, CoExt(J), $\text{CoExt}(T_8)$, $\text{CoExt}(S_8)$, CoExt(N1), CoExt(N2), CoExt(AG(2,3)), the extensions $\text{Ext}(P_8)$, $\text{Ext}(T_8)$, Ext(J), Ext(N1) and the matroid AG(3,3). These all do not have the half-plane property.

Example 5.7. The Pappus and the non-Pappus matroid are of rank 3 on 9 elements [27, Ex. 1.5.15]. They do not have the half-plane property by [10, Ex. 11.9]. Their only two non-isomorphic deletions were proven to have the half-plane property in [32]. Thus these two matroids are minor-minimal with respect to the half-plane property. In [10, Ex. 11.10] it is shown that the matroid (non-Pappus \setminus 9) + e obtained by adding a new element freely to the contraction of the non-Pappus matroid by an element contained in two circuits does not have the half-plane property either. The authors of [10] suspect that this matroid is also minor-minimal with respect to the half-plane property. This is indeed the case: By Theorem 5.2 there are no minor-minimal matroids of rank 3 on 8 elements. Thus minor-minimality follows from the fact that none of the five matroids of rank 3 on 7 elements that do not have the half-plane property is a minor of (non-Pappus \setminus 9) + e. In Section 6, we confirm that they are the only minimal forbidden minors for the half-plane property of rank 3 on 9 elements.

Remark 5.8. A binary matroid has the half-plane property if and only if it is a regular matroid and, similarly, a ternary matroid has the half-plane property if and only if it is a $\sqrt[6]{1}$ -matroid [27, §15.8]. In particular, the list of excluded minors for the classes of binary and ternary matroids with the half-plane property is finite. In this context Oxley poses the problem of finding all excluded minors for the class of quaternary matroids with the half-plane property [27, Prob. 15.8.8]. In addition to the excluded minors for quaternary matroids, see [27, Thm. 6.5.9], this list contains the Fano matroid F_7 , its relaxation F_7^{--} , their duals and the matroid P'_8 from Example 5.4. Any quaternary matroid on at most 8 elements that does not have the half-plane property has one of these 5 matroids as a minor. Further excluded minors for the class of quaternary matroids with the half-plane property are the Pappus matroid and its dual.

Remark 5.9. A matroid M with ground set E is called *Rayleigh*, if $\Delta_{ij}(h_M)(x) \ge 0$ for all $i, j \in E$ and all x in the *nonnegative orthant*. It is clear from Theorem 2.10 that the half-plane property implies Rayleigh. The converse is not true. For instance every matroid of rank 3 is Rayleigh [31]. When searching for critical points of Rayleigh differences using the Julia package "HomotopyContinuation.jl", we found that the matroids \mathcal{M}_k for k from the following list are not Rayleigh:

 $\{768, 816, 821, 825, 878, 879, 882, 883, 891, 894, 895, 896, 910, 911, 912\}.$

Note that the matroid \mathcal{M}_{912} is the matroid S_8 [27, p. 648].

Furthermore, for fixed indices i, j, we can express h_M as $h_M = ax_ix_j + bx_i + cx_j + d$ where $a, b, c, d \in \mathbb{R}[x_1, \ldots, x_n]$ are polynomials that do not depend on x_i and x_j . Then we have $\Delta_{i,j}h_M = ad - bc$, and the supremum of the ratio $\frac{bc}{ad}(x)$ over all x in the nonnegative orthant and all i, j is called the *correlation constant* of the matroid M. If M is not Rayleigh, then the correlation constant is larger than 1. It was conjectured in [18] that the correlation constant cannot exceed $\frac{8}{7}$. Our computations support their conjecture, see also the ancillary file Appendix.pdf. 5.1. SOS-Rayleigh and weakly determinantal matroids. In a celebrated article Brändén [5] disproved a predecessor of the generalized Lax Conjecture by showing that the Vámos matroid V_8 is not weakly determinantal although it has the half-plane property [32]. Further such matroids were constructed in [1, 7]. In this section we will add some further examples to this list. The examples from the literature rely on the following criterion:

Theorem 5.10 (Brändén [5]). Let M be a weakly determinantal matroid on the ground set [n]. Then its rank function rk satisfies the Ingleton inequalities:

 $\operatorname{rk}(P_1 \cup P_2) + \operatorname{rk}(P_1 \cup P_3) + \operatorname{rk}(P_1 \cup P_4) + \operatorname{rk}(P_2 \cup P_3) + \operatorname{rk}(P_2 \cup P_4)$

$$\geq \operatorname{rk}(P_1) + \operatorname{rk}(P_2) + \operatorname{rk}(P_1 \cup P_2 \cup P_3) + \operatorname{rk}(P_1 \cup P_2 \cup P_4) + \operatorname{rk}(P_3 \cup P_4)$$

for all $P_1, P_2, P_3, P_4 \subseteq [n]$.

For the Vámos matroid there exist disjoint subsets $P_1, P_2, P_3, P_4 \subseteq [8]$ of size 2 that violate this inequality. This motivates the following definition.

Definition 5.11. A sparse paying matroid M on a ground set E of rank r is called Vámos-like if there exist pairwise disjoint sets P_1, P_2, P_3, P_4, K where $|P_1| = |P_2| = |P_3| = |P_4| = 2$ and |K| = r - 4 such that $K \cup P_i \cup P_j$ for $i < j, (i, j) \neq (3, 4)$ are non-bases, while $K \cup P_3 \cup P_4$ is a basis.

In [26] it was shown that Vámos-like matroids violate the Ingleton inequalities. Mayhew and Royle show that among the matroids on eight elements [24], there are 44 non-representable matroids and 39 of them are Vámos-like. The remaining 5 matroids are four relaxations of P_8 and a relaxation of L_8 . Our tests concluded that out of these 44 matroids, which are not representable over any field, only the Vámos matroid itself has the half-plane property. Furthermore, the minor-minimal matroids from Theorem 5.2 all satisfy Ingleton's inequalities.

For finding further instances of matroids with the half-plane property that are not weakly determinantal, we use the following criterion.

Theorem 5.12 (Cor. 4.3 in [22]). If a homogeneous, multiaffine polynomial is weakly-determinantal, then it is SOS-Rayleigh.

Indeed, we found 14 matroids, including the Vámos matroid \mathcal{M}_{502} , for which some Rayleigh differences are a sum of squares but not all. This shows that these have the half-plane property but are not weakly determinantal.

Theorem 5.13. The matroids \mathcal{M}_k for k in

 $\{409, 413, 414, 415, 417, 418, 419, 438, 440, 445, 498, 500, 501, 502\}$

have the half-plane property but are not SOS-Rayleigh. In particular, these matroids are not weakly determinantal.

For each of the matroids M in the list, we produce symbolic certificates for the existence of a pair i, j such that $\Delta_{i,j}h_M$ is not an sum of squares by using the following argument, and Lemma 5.14. Code for producing the certificates can be found in the ancillary files M2Code.m2 and Appendix.pdf.

A homogeneous polynomial $h \in \mathbb{R}[x_1, \ldots, x_n]$ of degree 2d-2 is a sum of squares if there exists a symmetric positive semidefinite matrix $G \in \mathbb{R}^{\binom{n}{d-1} \times \binom{n}{d-1}}$ (Gram matrix) such that $h = m^t Gm$, where $m \in \mathbb{R}^{\binom{n}{d-1}}$ is the vector of all multiaffine monomials of degree d-1. Therefore, in order to prove that h is not a sum of squares, one needs to show that, the Gram spectrahedron

$$S_G := \left\{ \lambda \in \mathbb{R}^k : G_0 + \lambda_1 G_1 + \dots \lambda_k G_k \succeq 0 \right\}$$

is empty.

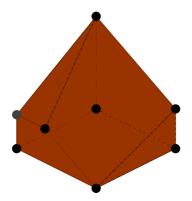


FIGURE 3. The dependent sets of size 4 of the matroid \mathcal{M}_{417} are the five quadrilateral facets of the depicted heptahedron.

Lemma 5.14. Let $h \in \mathbb{R}[x_1, \ldots, x_n]$ be a non-zero homogeneous polynomial of degree 2d - 2, and S_G be its Gram spectrahedron defined by the pencil

$$G_0 + \lambda_1 G_1 + \dots \lambda_k G_k \succeq 0$$

for some real symmetric matrices $G_1, \ldots, G_k \in \mathbb{R}^{\binom{n}{d-1} \times \binom{n}{d-1}}$. If there exists a positive definite matrix $A \in \mathbb{R}^{\binom{n}{d-1}}$ such that $\operatorname{tr}(AG_i) = 0$ for all $i = 0, \ldots, k$, then S_G is empty.

Proof. Assume that $S_G \neq \emptyset$. Then there exists $\lambda \in \mathbb{R}^k$ such that

$$G = G_0 + \lambda_1 G_1 + \dots + \lambda_k G_k$$

is positive semidefinite with $\operatorname{tr}(AG) = 0$. Since A is positive definite, there exist an invertible matrix $B \in \mathbb{R}^{\binom{n}{d-1} \times \binom{n}{d-1}}$ such that $BB^t = A$. Since G is positive semidefinite and non-zero,

$$0 = \operatorname{tr}(AG) = \operatorname{tr}(BB^tG) = \operatorname{tr}(B^tGB) > 0$$

gives a contradiction.

Example 5.15. The circuit hyperplanes of the sparse paving matroid \mathcal{M}_{417} are given by the quadrilateral faces of the heptahedron depicted in Figure 3.

Remark 5.16. For the matroids \mathcal{M}_k where k is in

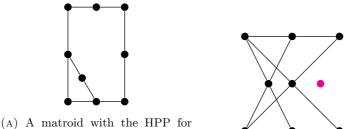
 $\{393, 395, 397, 399, 400, 401, 403, 404, 405, 410, 411, 412, 421, 423, 433, 664, 717\}$

there are some indices i, j such that the SDP solver cannot find positive semidefinite rational Gram matrices during the SOS test on $\Delta_{i,j}$ but only positive semidefinite Gram matrices having floating points as entries (i.e, they are approximate). These numerical results indicate that these matroids might be SOS-Rayleigh but we do not have a symbolic certificate for that. However, there is always another pair of indices for which we can find a rational positive semidefinite Gram matrix, so this issue does not affect the proof of the half-plane property.

We provide the list of simple matroids on 8 elements of rank 3 and 4 that are HPP, that are not HPP, some matroids that are not SOS-Rayleigh, and matroids for which we could not detect whether they are SOS-Rayleigh at https://zenodo.org/record/6108027

Properties	Count
Half-plane property	287
Certified SOS-Rayleigh	256
Half-plane property but not SOS-Rayleigh	14
Not having the HPP	22

TABLE 3. Summary of the classification of simple connected matroids on 8 elements and rank 3 or 4 all of whose proper minors have the half-plane property.



which it is unknown whether it is SOS-Rayleigh



(B) (Non-Pappus9) +e

FIGURE 4

6. Experiments on Matroids on Nine Elements

In this section, we implement the methods used in the previous section on simple and connected matroids on 9 elements of rank 3 and 4. We use the list of all simple matroids on 9 elements provided by Matsumoto, Moriyama, Imai and Bremner in [23]. In this case the number of matroids is very high and we provide our results at https://zenodo.org/record/6108027.

After excluding forbidden minors, we conduct an SOS test on the Rayleigh differences of simple connected matroids on 9 elements of rank 3. Our tests show that the only minimal forbidden minors for the half-plane property on 9 elements of rank 3 are the Pappus, non-Pappus and (non-Pappus)+e matroids. The remaining 116 matroids have the half-plane property. For ten of these matroids there are some indices (i, j) such that for $\Delta_{i,j}$ the SDP solver can only find positive semidefinite Gram matrices with floating point entries (i.e., they are approximate). On the other hand, we could not certify that they are not SOS-Rayleigh. The numerical data from the SDP outputs suggests that such $\Delta_{i,j}$ are sums of squares with non-rational coefficients only.

Example 6.1. The matroid M shown in Figure 4a on ground set E = [9] with nonbases $\{1, 2, 3\}, \{1, 4, 5\}, \{2, 4, 6\}, \{3, 7, 8\}$ and $\{5, 7, 9\}$ is one of the ten matroids of rank 3 with the HPP for which our algorithm cannot prove or disprove that they are SOS-Rayleigh.

There are 185982 simple matroids on 9 elements of rank 4. We first extend the list of excluded minors (by adding those of rank 3 on 9 elements, and of rank 4 on 8 elements), and eliminate matroids having one of the 35 forbidden minors as a minor. By applying a sums of squares test on the Rayleigh differences of the remaining connected matroids, we found that 4125 matroids have the half-plane property. For each of them, there is a pair (i, j) such that the SDP solver could find positive semidefinite rational Gram matrices during the SOS test on $\Delta_{i,j}$. In addition, there are 819 matroids for which the SDP solvers could only find positive

MARIO KUMMER AND BÜŞRA SERT

Properties	Count
Half-plane property	116
Undetected SOS-Rayleigh	10
Not having the HPP	3

TABLE 4. Summary of the classification of simple connected matroids on 9 elements and rank 3 all of whose proper minors have the half-plane property.

Properties	Count
Half-plane property	4125
Candidates for having the HPP	819
Not having the HPP	1218
Undetected	556

TABLE 5. Summary of the test results on simple connected matroids on 9 elements of rank 4 all of whose proper minors have the half-plane property.

semidefinite Gram matrices with floating point entries (i.e., they are approximate). The numerical results suggest they might have the half-plane property, but our computations do not provide a proof. We list those matroids under the category "Candidates for having the half-plane property".

We found 1218 matroids that do not have the half-plane property all of whose proper minors have the half-plane property. By using the Julia package "Homotopy Continuation", for each such M, we were able to find indices (i, j) and $x \in \mathbb{R}^7$ such that $\Delta_{i,j}(h_M)(x) < 0$.

Note that our experiments do not provide a complete classification with respect to the half plane property for matroids on 9 elements with rank 4. There are 556 matroids that neither pass the SOS test, nor the test for finding negative points. We suspect that the Rayleigh differences of those matroids are non-negative, but not sums of squares. However, our computations do not provide a proof. These are listed under the name "Undetected". Due to computational time constraints, we did not perform tests for the SOS-Rayleigh property on matroids on 9 elements of rank 4: Once we found a sums of squares representation for one pair of indices, we did not continue to check the remaining ones.

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