

NEXT IAS

Name - SHOHAM TEBERIWAL

Roll No - MT23MATL1004

Reg No - NIAS2300018169

Maths Test Series - Test 7 & Test 8
(Optional Next IAS)



Section - A

1a) Given M : maximal ideal of commutative ring with identity

To show: M is prime ideal

Proof:

we know an ideal is prime ideal if for a, b s.t. $ab \in I$ then either $a \in I$ or $b \in I$

Now M is maximal (with unity element)

Suppose $ab \in M$ but $a \notin M$

$\Rightarrow M + (a)$ is another ideal of ring
 $M + (a) \neq M$

$\therefore M$ is maximal

$\Rightarrow M + (a) = R$

$\Rightarrow \exists r$ such that $m + ar = 1$

we show $\frac{R}{M}$ is a field

$$\frac{R}{M} = M + a \quad a \notin M$$

$$(M + a)(M + r) = M + ar = M + 1$$

Hence for every element (non-zero) $\frac{R}{M}$ is a field

$\frac{R}{M}$ is a field $\Rightarrow \frac{R}{M}$ is integral domain

we show if

$\frac{R}{M}$ is I.D then M is prime ideal

$$\frac{R}{M} = M + a \mid a \notin M$$

let $ab \in M$ where $a, b \in R$
 $a \neq 0, b \neq 0$

so; $(M+a)(M+b) = M+ab = M+0$

\Rightarrow for integral domain

either $M+a = M$

or $M+b = M$

$\Rightarrow a \in M$ or $b \in M$

hence M is prime ideal

[M is maximal $\Rightarrow \frac{R}{M}$ is field \Rightarrow integral domain $\Rightarrow M$ is prime]

1B) $f(z)$ is integral function

$$|f(z)| \leq M \text{ for all values of } z$$

$\therefore f(z)$ is analytic for all values of z

$$\Rightarrow f(z) = \sum a_n z^n$$

$$|\sum a_n z^n| \leq M \text{ for all values}$$

if z takes very large value

$$\text{i.e. } z \rightarrow \infty$$

then it will be contradiction

$$\therefore \sum a_n z^n = a_0 + a_1 z + a_2 z^2 + \dots$$

$$\Rightarrow a_1 \dots a_n \text{ all zero}$$

$$\Rightarrow \boxed{f(z) = a_0}$$

$$c) \langle f_n \rangle = \tan^{-1}(nx)$$

To show it's not uniformly convergent on $[0, 1]$

$$\lim_{n \rightarrow \infty} \langle f_n \rangle = \begin{cases} 0 & x=0 \\ \frac{\pi}{2} & x \neq 0 \end{cases}$$

Now, using M_n test

$$M_n = \sup_{x \neq 0} \left(\tan^{-1}(nx) - \frac{\pi}{2} \right) \text{ or } \sup_{x=0} \left| \tan^{-1}(nx) - 0 \right|$$

$$\text{let } f(x) = \tan^{-1}(nx)$$

$$f'(x) = \frac{n}{1+n^2x^2}$$

which is monotonically increasing

$$\text{max. } f(x) = \tan^{-1}(n) \text{ at } x=0$$

$$M_n = \sup \left(\tan^{-1}(n) - 0 \right) = \frac{\pi}{2} \neq 0$$

\therefore by M_n test $\langle f_n \rangle$ is not u.c. on $[0, 1]$

on contrary if $n \in [a, 1]$
 $a > 0$

then $\langle f_n \rangle$ is V.C.

$$M_n = \sup \left| \tan^{-1}(nx) - \frac{\pi}{2} \right| = 0$$

d) If $\sum a_n$ cgs then $\lim a_n = 0$

let $S_n = \sum a_n$

we use Cauchy's sequence theorem
given $\epsilon > 0$ $\exists m \in \mathbb{Z}$ such that
 $|S_{n+p} - S_n| < \epsilon \quad \forall n \geq m$
 $p \in \mathbb{Z}^+$

$$\Rightarrow |S_{n+1} - S_n| < \epsilon \quad \forall n \geq m$$

$$|(a_1 + a_2 + \dots + a_{n+1}) - (a_1 + \dots + a_n)| < \epsilon$$
$$\forall n \geq m$$

$$\Rightarrow |a_{n+1}| < \epsilon \quad \forall n \geq m$$

for any given ϵ $|a_{n+1}| < \epsilon$ (consider $\epsilon \rightarrow 0$)
 $\Rightarrow \exists m$ such that $n \geq m$
 $\Rightarrow \lim_{n \rightarrow \infty} a_{n+1} = 0 \Rightarrow \lim_{n \rightarrow \infty} a_n = 0$

e) Find ring with unity and subring of different unity

$$R = \begin{pmatrix} 1 & 0 & 0 \\ 0 & a & b \\ 0 & c & d \end{pmatrix}$$

$$a, b, c, d \in \mathbb{Z}$$

$\therefore R$ is a ring

$(R, +)$ is abelian group

(R, \times) is quasi-group

$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \in R$ is unity in R

$$R' = \begin{pmatrix} 0 & 0 & 0 \\ 0 & a & b \\ 0 & c & d \end{pmatrix}$$

R' is a subring of R

unity of R' is $\begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

3a) Show $R[x]$ is I.D iff R is I.D.

(i) we show that $R[x]$ is I.D when R is I.D

if R is I.D

$$\Rightarrow a \neq 0, b \neq 0 \in R$$

$$ab \neq 0 \in R$$

⊙ $ab = 0$ then $a = 0$ or $b = 0$

$$R[x] = \{a_0 + a_1x + \dots + a_nx^n \mid a_0, a_1, \dots \in R\}$$

suppose $g_1(x) \cdot g_2(x) = 0$

$$\Rightarrow (a_0 + a_1x + \dots + a_nx^n)(b_0 + b_1x + \dots + b_nx^n) = 0$$

$$\Rightarrow a_0b_0 + (a_1b_0 + a_0b_1)x + \dots = 0$$

$$\Rightarrow a_0b_0 = 0 \Rightarrow a_0 = 0 \text{ or } b_0 = 0$$

$$\therefore a_0, b_0 \in R$$

$$\Rightarrow a_1b_0 + a_0b_1 = 0$$

$$\text{if } a_0 = 0 \Rightarrow a_1b_0 = 0 \Rightarrow a_1 = 0$$

$$\& b_0 \neq 0$$

hence $a_0, a_1, \dots, a_n = 0$

$$\text{i.e. } g_1(x) = 0$$

hence $R[x]$ is I.D.

(ii) conversely if $R[x]$ is I.D., we show
 R is I.D.

$$\text{if } p_1(x) \cdot p_2(x) = 0 \\ \Rightarrow p_1(x) = 0 \quad \text{or} \quad p_2(x) = 0$$

i.e. $a_0 b_0 = 0$

$$a_1 b_0 + a_0 b_1 = 0$$

⋮

⋮

(Coefficient) n^{th} term $= 0$

$$a_0 = 0$$

$$a_1 = 0$$

⋮

⋮

$$a_n = 0$$

$$\therefore p_1(x) = 0$$

similarly if

$$a_0 b_0 = 0$$

$$a_0 \in R \quad b_0 \in R$$

then $a_0 = 0$ from above

$$\text{or } a_1 b_0 = 0 \Rightarrow a_1 = 0$$

$$\Rightarrow R \text{ is I.D.}$$

— Q.E.D.

3b) To maximize profits

operations	time			Total time
	x	y	z	
I	1	2	2	200
II	2	1	1	220
III	3	1	2	180

min sales

Profit

let # products of x $\rightarrow x$
 # (no. of products) of y $\rightarrow y$
 # (" " ") of z = z

Profit : $10x + 15y + 8z$

$$\left. \begin{array}{l} x \geq 10 \\ y \geq 20 \\ z \geq 30 \end{array} \right\} \text{min. sales}$$

time constraints :

$$\begin{array}{l} \text{operation I : } x + 2y + 2z \leq 200 \\ \text{operation II : } 2x + y + z \leq 220 \\ \text{operation III : } 3x + y + 2z \leq 180 \end{array}$$

$$\therefore x \geq 10 \Rightarrow \text{ ~~} x \geq 10 \text{ }~~$$

$$\text{let } x = 10 + a, \quad y = 20 + b, \quad z = 30 + c$$

$$\Rightarrow \text{Profit} : 10(10+a) + 15(20+b) + 8(30+c)$$

$$\text{Profit } \gamma = 10a + 15b + 8c + 640$$

time constraints:

$$\textcircled{I} : 10 + a + 2(20 + b) + 2(30 + c) \leq 200$$

$$a + 2b + 2c \leq 90$$

$$\textcircled{II} : 2(10 + a) + 20 + b + 30 + c \leq 220$$

$$2a + b + c \leq 150$$

$$\textcircled{III} : 3(10 + a) + 20 + b + 2(30 + c) \leq 180$$

$$3a + b + 2c \leq 70$$

LPP: $\gamma : 10a + 15b + 8c$

$$a + 2b + 2c \leq 90$$

$$2a + b + c \leq 150$$

$$3a + b + 2c \leq 70$$

$$a, b, c \geq 0$$

		10	15	8	0	0	0	
		a	b	c	s_1	s_2	s_3	b
15	b	0	1	$\frac{4}{5}$	$\frac{3}{5}$	0	$\frac{-1}{5}$	40
0	s_2	0	0	$\frac{-3}{5}$	$\frac{-1}{5}$	1	$\frac{-3}{5}$	90
10	a	1	0	$\frac{2}{5}$	$\frac{-1}{5}$	0	$\frac{2}{5}$	10
Z_j		10	15	16	7	0	1	
Δ		0	0	-8	-7	0	-1	

optimality is achieved

$$\boxed{a = 10} \quad \boxed{b = 40}$$

$$\therefore x = 10 + a = 20$$

$$y = 20 + b = 60$$

$$z = 30 + c = 30$$

$$\begin{aligned} \text{Profit} &= 10x + 15y + 8z \\ &= 1340 \end{aligned}$$

introduce surplus/slack variables

$$\left. \begin{aligned} a + 2b + 2c + s_1 &= 90 \\ 2a + b + c + s_2 &= 150 \\ 3a + b + 2c + s_3 &= 70 \end{aligned} \right\} a, b, c, s_1, s_2, s_3 \geq 0$$

	10	15	8	0	0	0		
	a	b	c	s_1	s_2	s_3	b	θ
$0 s_1$	1	2	2	1	0	0	90	45 \rightarrow outgoing
$0 s_2$	2	1	1	0	1	0	150	150
$0 s_3$	3	1	2	0	0	1	70	70
$Z_j =$	0	0	0	0	0	0		
$\Delta =$	10	15	8	0	0	0		

Incoming

	a	b	c	s_1	s_2	s_3	b	θ
15 b	$\frac{1}{2}$	1	1	$\frac{1}{2}$	0	0	45	90
$0 s_2$	$\frac{3}{2}$	0	0	$-\frac{1}{2}$	1	0	105	70
$0 s_3$	$\frac{5}{2}$	0	1	$-\frac{1}{2}$	0	1	25	10 \rightarrow outgoing
Z_j	$\frac{15}{2}$	15	15	$\frac{15}{2}$	0	0		
Δ	$\frac{15}{2}$	0	-ve	-ve	0	0		

Incoming

c) To find analytic function

$$f(z) = u(r, \theta) + i v(r, \theta)$$

$$\frac{\partial u}{\partial r} = \frac{\partial v}{\partial \theta}$$

$$\& \frac{\partial u}{\partial \theta} = -\frac{\partial v}{\partial r}$$

$$v(r, \theta) = r^2 \cos 2\theta - r \cos \theta + 2$$

$$\therefore \frac{\partial v}{\partial r} = 2r \cos 2\theta - \cos \theta \quad \text{--- (1)}$$

$$\frac{\partial v}{\partial \theta} = \frac{1}{r} \left[-2 \sin 2\theta r^2 + r \sin \theta \right] \quad \text{--- (2)}$$

$$= -2r \sin 2\theta + \sin \theta$$

☺ $\frac{\partial u}{\partial r} = -2r \sin 2\theta + \sin \theta$ from (2)

$$u(r, \theta) = -r^2 \sin 2\theta + \frac{r}{2} \sin \theta + f(\theta)$$

$$= -r^2 \sin 2\theta + r \sin \theta + f(\theta) \quad \text{--- (3)}$$

$$\frac{\partial u}{\partial \theta} = -2r \cos 2\theta + \cos \theta \quad \text{from (1)}$$

$$u_\theta = -2r^2 \cos 2\theta + r \cos \theta \Rightarrow u = -r^2 \sin 2\theta + r \sin \theta + f_2(r) \quad \text{--- (4)}$$

from (3) & (4)

$$u(r, \theta) = -r^2 \sin 2\theta + 2 \sin \theta + C$$

$$\therefore f(z) = -r^2 \sin 2\theta + 2 \sin \theta + C + i \left(r^2 \cos 2\theta - \frac{r \cos \theta}{+2} \right)$$

$$f(z) = r^2 (-\sin 2\theta + i \cos 2\theta) + 2(\sin \theta - i \cos \theta) + 2i + C$$

$$\cos(2\theta + \pi) = -\sin 2\theta \quad \left. \begin{array}{l} \cos(\theta + \pi/2) = \sin \theta \\ \sin(\theta + \pi/2) = -\cos \theta \end{array} \right\} -i(\cos \theta + i \sin \theta)$$

$$f(z) = r^2 e^{i(\pi/2 + 2\theta)} + r e^{i(\theta - \pi/2)} + C'$$

where C' is constant

Section - B

$$5a) \quad (z - xp - yq)(p + q) = 1$$

$$\Rightarrow z - xp - yq = \frac{1}{p+q}$$

$$\boxed{z = xp + yq + \frac{1}{p+q}} \quad \text{--- (1)}$$

by Clairaut's form

$$\boxed{\frac{dp}{f_x + pf_z} = \frac{dq}{f_y + qf_z} = \frac{-dx}{f_p} = \frac{-dy}{f_q} = \frac{-dz}{p f_p + q f_q}}$$

$$f: z - xp - yq - \frac{1}{p+q}$$
$$f_x = -p \quad \& \quad f_z = 1 \quad \& \quad f_y = -q$$

$$\Rightarrow \frac{dp}{0} = \frac{dq}{0} \Rightarrow p = a, \quad q = b$$

put in (1)

$$\boxed{z = ax + by + \frac{1}{a+b}}$$

where a, b are arbitrary constants

5b) Write algo to solve $xe^x - 1 = 0$ by bisection correct to 4 decimal places

Here correct to four decimal places means
max. error = $0.00005 = e$ (say)
allowed

Algorithm is: —

1. Input $y = f(x)$ // $f(x) = xe^x - 1$

2. Input x_0, x_1

3. Find $y_0 = f(x_0)$ and $y_1 = f(x_1)$

4. If $y_0 y_1 > 0$, go to step 2
Else proceed, go to step 5

5. If $|x_0 - x_1| < e$, go to step 9
Else go to step 6

6. $x_2 = \frac{x_0 + x_1}{2}$, find $y_2 = f(x_2)$

7. If $y_0 y_2 > 0$, then $y_0 = y_2$ and $x_1 = x_2$
Else $y_1 = y_2$ and $x_0 = x_2$

8. Go to 5

9. Print x_1

10. End at step

c) To find boolean expression

(i) Y is 1 only A is 1 and B is 1
 or if A is 0 and B is 0

A	B	Y
0	0	1
0	1	
1	1	1
1	0	

$$\therefore Y = \bar{A}\bar{B} + AB$$

(ii)

A	B	C	Y
0	0	0	0
0	1	1	1
0	1	0	0
0	0	1	0
1	0	0	0
1	1	1	1
1	1	0	1
1	0	1	1

$$Y = \bar{A}BC + ABC + \bar{A}\bar{B}C + A\bar{B}\bar{C}$$

it can be simplified further
 (P.T.O)

only A = 0

all 1

only C = 0

only B = 0

$$Y = \bar{A}BC + AB\bar{C} + A\bar{B}C + AB\bar{C}$$

$$= B(C + A\bar{B}C) + AB\bar{C}$$

$$= C(B + \bar{B}A) + AB\bar{C}$$

$$= C(B + A) + AB\bar{C}$$

$$= AC + BC + AB\bar{C}$$

$$= A(C + B\bar{C}) + BC$$

$$= A(B + C) + BC$$

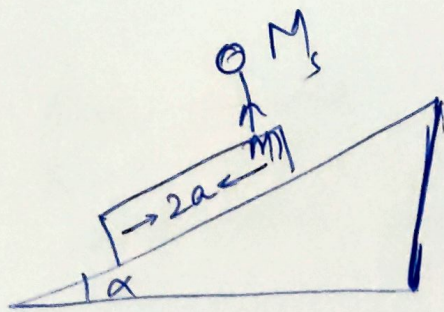
$$= AB + AC + BC$$

$$Y = AB + BC + AC$$

$$\text{😊 } A + \bar{A} = 1$$

$$\text{😊 } X + \bar{X}Y = X + Y$$

d)

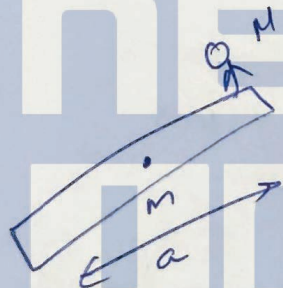


To show he will reach other end in 't'

$$t = \sqrt{\frac{4Ma}{(m+M)g \sin \alpha}}$$

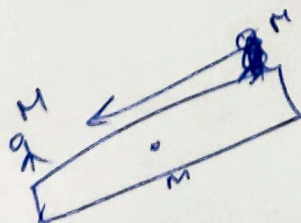
we solve using combined center of mass of both bodies

initially:



$$(y_{cm})_i = \frac{\left(\frac{2a}{2}\right)m + (2a)M}{m+M} = \frac{2aM + am}{M+m}$$

finally



$$(y_{cm})_f = \frac{M(0) + \left(\frac{2a}{2}\right)m}{M+m} = \frac{am}{M+m}$$

$$\therefore \Delta y_{\text{cm}} = \frac{2aM}{m+M}$$

$$y = ut + \frac{1}{2} a_y t^2$$

$$a_y = +g \sin \alpha, \quad u = 0$$

$$\Delta y_{\text{cm}} = +\frac{1}{2} g \sin \alpha t^2$$

$$\frac{2aM}{m+M} = \frac{1}{2} g \sin \alpha t^2$$

$$t = \sqrt{\frac{4Ma}{(M+m)g \sin \alpha}}$$

— Home proved

e (i) flow where stream function exist
but velocity function doesn't exist

$\Rightarrow \psi(x, y)$ exist \Rightarrow eqⁿ of continuity satisfied
 $\nabla \phi(x, y)$ doesn't exist \Rightarrow irrotational flow

$$\Rightarrow \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \quad \text{but} \quad \frac{\partial v}{\partial x} \neq \frac{\partial u}{\partial y}$$

$$u(x, y) = -xy$$

$$v(x, y) = \frac{y^2}{2}$$

$$\vec{q} = -xy \hat{i} + \frac{y^2}{2} \hat{j}$$

Note: there can
be infinitely such
cases

$$(ii) \quad W = \frac{k}{\pi} \tan^{-1}\left(\frac{z}{c}\right)$$

$$w = \phi + i\psi = \frac{k}{\pi} \tan^{-1}\left(\frac{z}{c}\right)$$

$$\psi(x, y) = \frac{W(z) - \overline{W(\bar{z})}}{2i}$$

$$= \frac{k}{2\pi i} \left[\tan^{-1}\left(\frac{x+iy}{c}\right) - \tan^{-1}\left(\frac{x-iy}{c}\right) \right]$$

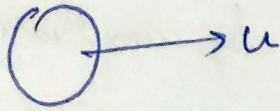
$$\psi(x,y) = \frac{k}{2i\pi} \left[\tan^{-1} \left(\frac{\frac{x+iy}{c} - \frac{x-iy}{c}}{1 + \frac{x^2+y^2}{c^2}} \right) \right]$$

$$\psi(x,y) = \frac{k}{2\pi} \tan^{-1} \left(\frac{2iy}{x^2+y^2+c^2} \right)$$

or $\frac{y}{x^2+y^2+c^2} = k$



6a) Describe flow for circular cylinder of radius a moving with velocity u along x -axis



Clearly it's symmetric flow

(i) $\nabla^2 \phi = 0$: eqⁿ of continuity

(ii) boundary condⁿ: $(q_r)_{r=a} = +V \cos \theta$

$(q_r)_{r=\infty} = 0$

$\nabla^2 \phi = 0$

$\Rightarrow \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} = 0$

$\left(\frac{\partial^2 \phi}{\partial z^2} = 0 \right)$

$\phi(r, \theta) = R(r), \theta(\theta)$

$\Rightarrow \frac{\partial \phi}{r \partial r} + \frac{\partial^2 \phi}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} = 0$

$\frac{R' \theta}{r} + \frac{R'' \theta}{1} + \frac{R \theta''}{r^2} = 0$

$\frac{r R' + r^2 R''}{R} = -\frac{\theta''}{\theta} = \text{constant}$

for symmetrical flow
constant = n^2

$$\Rightarrow \boxed{r^2 R'' + r R' - n^2 R = 0}$$

and

$$\boxed{\theta'' + n^2 \theta = 0}$$

by Cauchy's method

$$[D(D+1) + D - n^2] R = 0$$

$$[D^2 - n^2] R = 0$$

$$R(r) = C_1 r^n + C_2 r^{-n} \quad \text{--- (1)}$$

by auxiliary eqⁿ

$$m^2 + n^2 = 0$$

$$\theta(\theta) = C_3 \cos n\theta + C_4 \sin n\theta$$

--- (2)

put $n=1$ for symmetry (2)

$$\phi = R(r) \cdot \theta(\theta) = \sum_{\text{from (1), (2)}} (C_1 r^n + C_2 r^{-n}) (C_3 \cos n\theta + C_4 \sin n\theta)$$

$$\text{if } r=a, \quad -\frac{\partial \phi}{\partial r} = U \cos \theta$$

\Rightarrow clearly $n=1$ and $C_4=0$

$$\Rightarrow \boxed{\phi(r, \theta) = \left(a_0 r + \frac{b_0}{r}\right) \cos \theta}$$

$$-\frac{\partial \phi}{\partial r} = q_r = -\frac{\partial}{\partial r} \left(a_0 r + \frac{b_0}{r} \right) \cos \theta$$

$$= - \left(a_0 - \frac{b_0}{r^2} \right) \cos \theta = \left(-a_0 + \frac{b_0}{r^2} \right) \cos \theta$$

at $r = R$, $q_r = U \cos \theta$

$$\Rightarrow -a_0 + \frac{b_0}{R^2} = U \quad \text{--- (3)}$$

at $r = \infty$, $q_r = 0$

$$\Rightarrow -a_0 = 0 \quad \text{--- (4)}$$

\Rightarrow from (3) & (4)

$$\phi(r, \theta) = \frac{R^2 U \cos \theta}{r} \quad \text{if } R = a$$

$$a_0 = 0$$

$$b_0 = R^2 U$$

then $\boxed{\phi(r, \theta) = \frac{U a^2 \cos \theta}{r}}$ Answer

To find streamlines

$$\frac{dr}{-\frac{\partial \phi}{\partial r}} = \frac{r d\theta}{-\frac{\partial \phi}{\partial \theta}} \Rightarrow \frac{dr}{-U a^2 \cos \theta / r^2} = \frac{r d\theta}{-U a^2 \sin \theta / r}$$

$$\Rightarrow \frac{r^2 dr}{\cos \theta} = \frac{r^2 d\theta}{\sin \theta} \Rightarrow \frac{dr}{r} = \frac{\cos \theta}{\sin \theta} d\theta$$

$$\ln r = \ln \sin \theta + \ln c \Rightarrow \boxed{r = c \sin \theta}$$
 Answer
 where c is arbit constant

6b) To find orthogonal surface to

$$\frac{z(x+y)}{3z+1} = C$$

$$\text{let } f = \frac{z(x+y)}{3z+1}$$

$$\frac{\partial f}{\partial x} = \frac{z}{3z+1}$$

$$\frac{\partial f}{\partial y} = \frac{z}{3z+1}$$

$$\frac{\partial f}{\partial z} = (x+y) \frac{(3z+1) - 3z}{(3z+1)^2} = \frac{x+y}{(3z+1)^2}$$

$$df = f_x dx + f_y dy + f_z dz$$

orthogonal surface is

$$\frac{dx}{f_x} = \frac{dy}{f_y} = \frac{dz}{f_z}$$

$$\frac{dx}{z/3z+1} = \frac{dy}{z/3z+1} = \frac{dz}{(x+y)/(3z+1)^2}$$

$$\Rightarrow dx = dy = \frac{z(3z+1) dz}{(x+y)}$$

$$\Rightarrow dx = dy \Rightarrow \boxed{x = y + c} \quad (1)$$

$$\& \frac{x dx}{x} = \frac{y dy}{y} = \frac{z(3z+1) dz}{x+y}$$

by Lagrange multipliers $(x, y \& -1)$

$$\Rightarrow \frac{x dx + y dy - z(3z+1) dz}{(x+y) - (x+y)}$$

$$\Rightarrow x dx + y dy - (3z^2 + z) dz = 0$$

$$\boxed{\frac{x^2}{2} + \frac{y^2}{2} - z^3 - \frac{z^2}{2} = c_2} \quad (2)$$

orthogonal surface is

$$\phi(x, y, \frac{x^2+y^2-z^2-z^3}{2}) = 0 \quad \text{Answer}$$

if it passes through $z=1$ & $x^2+y^2=1$

then put in (2)

$$\frac{1}{2} - \frac{3}{2} = c_2 \Rightarrow \boxed{c_2 = -1}$$

$$\boxed{\frac{x^2+y^2}{2} = 2z^3 + z^2 - 2}$$

Answer

$$\& x = y + c \Rightarrow \begin{cases} x^2 + y^2 - 2xy = c^2 \\ 1 - 2xy = c^2 \\ 1 - 2y(y+c) = c^2 \end{cases}$$

$$c^2 + 2yc + 2y^2 - 1$$

$$c \text{ discriminant} = 0 \Rightarrow B^2 = 4AC \Rightarrow (2y)^2 = 4(2y^2 - 1) \Rightarrow \boxed{y = \pm 1}$$

c) y_x is polynomial in 3rd degree

→ it takes 4 values of x

x_0	y_0	Δy_0	$\Delta^2 y_0$	$\Delta^3 y_0$	$\Delta^4 y_0$
x_0	y_0	$y_1 - y_0$	$y_2 - 2y_1 + y_0$	$\Delta^2 y_1 - \Delta^2 y_0$	—
x_1	y_1	$y_2 - y_1$	$y_3 - 2y_2 + y_1$		
x_2	y_2	$y_3 - y_2$			
x_3	y_3				

by newton's forward interpolation

$$y_x = y_0 + u \Delta y_0 + \frac{u(u-1)}{2} \Delta^2 y_0 + \frac{u(u-1)(u-2)}{6} \Delta^3 y_0$$

where $u = \frac{x - x_0}{h}$

where $x_0 = 0$, $x_1 = 1$, $x_2 = 2$, $x_3 = 3$

$h = 1$

$\therefore \boxed{u = x}$

$$y_x = y_0 + x \Delta y_0 + \frac{x(x-1)}{2} \Delta^2 y_0 + \frac{x(x-1)(x-2)}{6} \Delta^3 y_0$$

$$\int_0^2 y_x dx = \int_0^2 y_0 + n \Delta y_0 + \frac{x(x-1)}{2!} \Delta^2 y_0 + \frac{x(x-1)(x-2)}{3!} \Delta^3 y_0 dx$$

$$x(x-1)(x-2) = x^3 - 3x^2 + 2x$$

$$= 2y_0 + \frac{2^2}{2} \Delta y_0 + \frac{\Delta^2 y_0}{2!} \left[\frac{x^3}{3} - \frac{x^2}{2} \right]_0^2 + \frac{1}{6} \Delta^3 y_0 \left[\frac{x^4}{4} - x^3 + x^2 \right]_0^2$$

$$= 2y_0 + 2\Delta y_0 + \frac{1}{3} \Delta^2 y_0 + 0$$

$$= 2y_0 + 2(y_1 - y_0) + \frac{1}{3}(y_2 - 2y_1 + y_0)$$

$$= 2y_1 + \frac{y_2}{3} - \frac{2y_1}{3} + \frac{y_0}{3}$$

$$\int_0^2 y_x dx = \frac{y_0}{3} + \frac{4}{3} y_1 + \frac{y_2}{3}$$

Now

$$\int_1^2 y_x dx = y_0 x \Big|_1^2 + \Delta y_0 \frac{x^2}{2} \Big|_1^2 + \frac{\Delta^2 y_0}{2!} \left[\frac{x^3}{3} - \frac{x^2}{2} \right]_1^2 + \frac{1}{6} \Delta^3 y_0 \left[\frac{x^4}{4} - x^3 + x^2 \right]_1^2$$

$$= \int_0^2 y_x dx - \int_0^1 y_x dx$$

$$= \left[\int_0^1 y_x dx - \left[y_0 + \frac{\Delta y_0}{2} + \frac{\Delta^2 y_0}{2!} \left(\frac{1}{2} \right) + \frac{1}{6} \Delta^3 y_0 \left(\frac{1}{4} \right) \right] \right]$$

$$\int_0^1 y_x dx = y_0 + \frac{\Delta y_0}{2} - \frac{\Delta^2 y_0}{12} + \frac{\Delta^3 y_0}{24}$$

$$= y_0 + \frac{y_1 - y_0}{2} - \frac{(y_2 - 2y_1 + y_0)}{12} + \frac{1}{24} \begin{pmatrix} y_3 - 2y_2 + y_1 \\ -y_2 + 2y_1 - y_0 \end{pmatrix}$$

$$= y_0 \left(1 - \frac{1}{2} + \frac{1}{12} - \frac{1}{24} \right) + y_1 \left(\frac{1}{2} + \frac{1}{6} + \frac{3}{24} \right)$$

$$+ y_2 \left(-\frac{1}{12} - \frac{3}{24} \right) + \frac{y_3}{24}$$

$$= \frac{3}{8} y_0 + \frac{19}{24} y_1 - \frac{5y_2}{24} + \frac{y_3}{24}$$

$$\therefore \int_1^2 y_x dx = \int_0^2 y_x dx - \int_0^1 y_x dx$$

$$= \left[\frac{y_0}{3} + \frac{4}{5} y_1 + \frac{y_2}{3} \right] - \left[\frac{3}{8} y_0 + \frac{19}{24} y_1 - \frac{5y_2}{24} + \frac{y_3}{24} \right]$$

$$= \frac{-y_0}{24} + \frac{13y_1}{24} + \frac{13y_2}{24} - \frac{y_3}{24}$$

———— QED

8a) To reduce to canonical form

$$y u_{xx} + (x+y) u_{xy} + x u_{yy} = 0$$

i.e. $Rr + Ss + Tt = 0$

$\hookrightarrow \lambda^2 + S\lambda + T = 0$ } characteristic auxiliary eqn

$$y\lambda^2 + (x+y)\lambda + x = 0$$

$$\lambda(\lambda+x) + 1(y\lambda+x) = 0$$

$$(\lambda+1)(y\lambda+x) = 0$$

$$\Rightarrow \lambda = -1 \text{ and } \lambda = -\frac{x}{y}$$

characteristic is $\frac{dy}{dx} + \lambda = 0$

$$\frac{dy}{dx} - 1 = 0 \quad \& \quad \frac{dy}{dx} - \frac{x}{y} = 0$$

$$\Rightarrow y - x = c_1 \quad \& \quad \frac{y^2 - x^2}{2} = c_2$$

let $u(x,y) = x - y$
 $v(x,y) = \frac{x^2 - y^2}{2}$ } they are L.P.

$$\frac{\partial u}{\partial x} = 1$$

$$\frac{\partial v}{\partial x} = x$$

$$P = \frac{\partial^2 z}{\partial x^2} = \frac{\partial^2 z}{\partial u^2} \frac{\partial u}{\partial x} + \frac{\partial^2 z}{\partial v^2} \frac{\partial v}{\partial x} = \frac{\partial^2 z}{\partial u^2} + \frac{\partial^2 z}{\partial v^2} \cdot x$$

$$Q = \frac{\partial^2 z}{\partial x \partial y} = \frac{\partial^2 z}{\partial u^2} \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + \frac{\partial^2 z}{\partial v^2} \frac{\partial v}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial^2 z}{\partial u \partial v} \left(\frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} \right)$$

P Q R S T

$$z = R + xS + Q + x(S + xT)$$

$$q = \frac{\partial z}{\partial y} = \frac{\partial^2 z}{\partial x \partial y} \frac{\partial x}{\partial y} + \frac{\partial^2 z}{\partial y^2} \cdot \frac{\partial y}{\partial y}$$

$$= -\frac{\partial z}{\partial x} - y \frac{\partial z}{\partial x}$$

$$t = \frac{\partial}{\partial y} \left(-\frac{\partial z}{\partial x} - y \frac{\partial z}{\partial x} \right)$$

$$= -\frac{\partial z}{\partial x^2} \cdot \frac{\partial x}{\partial y} - \frac{\partial z}{\partial x \partial y} \cdot \left(\frac{\partial x}{\partial y} \right) - \frac{\partial z}{\partial x} - y \left[\frac{\partial^2 z}{\partial x \partial y} \frac{\partial x}{\partial y} + \frac{\partial^2 z}{\partial y^2} \cdot \frac{\partial y}{\partial y} \right]$$

$$= R + yS - Q + yS + y^2 T$$

$$s = \frac{\partial^2 z}{\partial x \partial y} = \frac{\partial}{\partial y} \left(\frac{\partial z}{\partial x} + x \frac{\partial z}{\partial x} \right)$$

$$= \frac{\partial^2 z}{\partial x^2} \cdot \frac{\partial x}{\partial y} + \frac{\partial^2 z}{\partial x \partial y} \cdot \frac{\partial x}{\partial y} + x \left[\frac{\partial^2 z}{\partial x \partial y} \frac{\partial x}{\partial y} + \frac{\partial^2 z}{\partial y^2} \cdot \frac{\partial y}{\partial y} \right]$$

$$= -R - yS - xS - xyT$$

now, $yx + (x+y)s + xt = 0$

$$\Rightarrow y \left[\cancel{x} + 2xy + Q + \cancel{x^2} \right] - (x+y) \left[\cancel{x} + \cancel{(x+y)} + \cancel{xy} \right] + x \left[\cancel{x} + 2xy + \cancel{y^2} - Q \right] = 0$$

$$\Rightarrow S(2xy - (x+y)^2 + 2xy) = Q(x-y)$$

$$(x+y)^2 = x^2 + y^2 + 2xy$$

$$S(2xy - x^2 - y^2) = Q(x-y)$$

$$-S(x-y)^2 = Q(x-y)$$

$$S(x-y) = -Q$$

canonical form is

$$\boxed{\frac{\partial^2 z}{\partial u \partial v} u = -\frac{\partial z}{\partial v}}; \quad \boxed{z_{uv} + \frac{z_v}{u} = 0}$$

$$\textcircled{a} \quad u \frac{\partial^2 z}{\partial u \partial v} + \frac{\partial z}{\partial v} = 0$$

$$\textcircled{a} \quad uv \frac{\partial^2 z}{\partial u \partial v} + v \frac{\partial z}{\partial v} = 0$$

$$\ln u = V \Rightarrow u = e^{+u}$$

$$\ln v = V \Rightarrow v = e^v$$

$$\Rightarrow (D D' + D') z = 0$$

$$D'(D+1)z = 0$$

$$z = e^{-v} \phi_1(u) + \phi_2(u) \Rightarrow z = u \phi_1(\ln u) + \phi_2(\ln u)$$

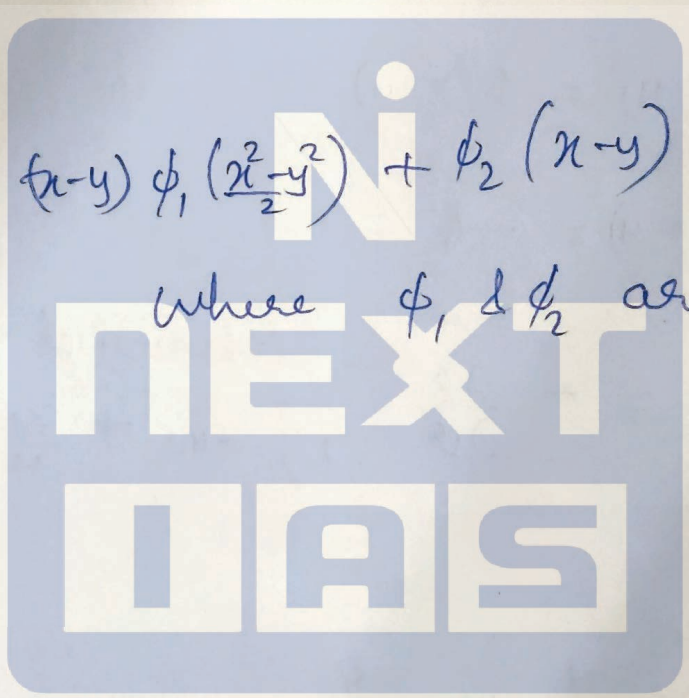
$$z = u \phi_1 + \phi_2$$

$$z = (x-y) \phi_1 \left(\frac{x+y}{2} \right) + \phi_2(x-y)$$

$$\text{or } z = (x-y) \phi_1 \left(\frac{x+y}{2} \right) + \phi_2(x-y)$$

$$z = (x-y) \phi_1 \left(\frac{x^2-y^2}{2} \right) + \phi_2(x-y)$$

where ϕ_1 & ϕ_2 are arbit functions



$$8b) \quad v_r = u \left(1 - \frac{a^2}{r^2} \right) \cos \theta$$

$$v_\theta = -u \left(1 + \frac{a^2}{r^2} \right) \sin \theta$$

For stream lines

$$\frac{dr}{v_r} = \frac{r d\theta}{v_\theta}$$

$$\Rightarrow v_\theta dr - v_r r d\theta = 0$$

$$-u \left(1 + \frac{a^2}{r^2} \right) \sin \theta dr - u \left(1 - \frac{a^2}{r^2} \right) \cos \theta r d\theta = 0$$

$$u \left(1 + \frac{a^2}{r^2} \right) \sin \theta dr + u \left(1 - \frac{a^2}{r^2} \right) \cos \theta r d\theta = 0$$

$$M dr + N d\theta = 0$$

$$\left. \begin{aligned} \frac{\partial M}{\partial \theta} &= u \left(1 + \frac{a^2}{r^2} \right) \cos \theta \\ \frac{\partial N}{\partial r} &= u \left(1 + \frac{a^2}{r^2} \right) \cos \theta \end{aligned} \right\} \text{it's exact}$$

$$U \int \left(+ \frac{a^2}{r^2} \right) dr + \int u \left(r - \frac{a^2}{r} \right) \cos \theta d\theta = C$$

θ -constant
 no $\frac{1}{r}$ term

$$U \sin \theta \left(r - \frac{a^2}{r} \right) = C$$

streamlines

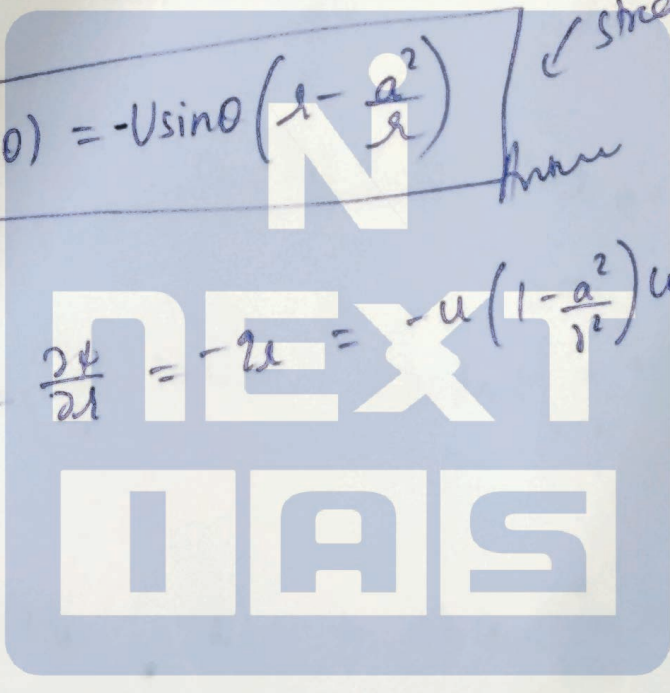
Answer

$$\psi(r, \theta) = -U \sin \theta \left(r - \frac{a^2}{r} \right)$$

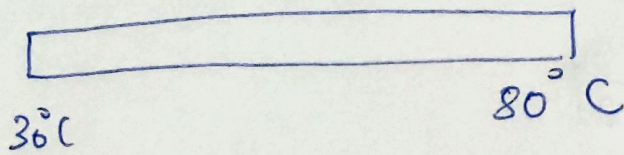
stream function

check:

$$\frac{\partial \psi}{\partial \theta} = -U \cos \theta = -u \left(1 - \frac{a^2}{r^2} \right) \cos \theta$$



x)



for steady state

$$\frac{\partial^2 u}{\partial x^2} = 0$$

$$u = ax + b$$

$$\text{at } x=0 \Rightarrow b = 30$$

$$\text{at } x=l \Rightarrow al + 30 = 80 \Rightarrow a = \frac{50}{l}$$

$$u(x) = \frac{50}{20}x + 30 = \frac{5x}{2} + 30$$

$$\therefore \text{at } t=0 \Rightarrow u(x,0) = \frac{5x}{2} + 30 \quad \text{--- (1)}$$

and later conditions

$$u(0,t) = 40^\circ\text{C}$$

$$u(l,t) = 60^\circ\text{C}$$

$$u(x,t) = x + 40$$

$$\text{@ } x=0, T=40$$

$$\text{@ } x=20, T=60$$

BC' Conditions

$$\underline{\text{Let}} \quad y(x,t) = u(x,t) - (x+40) \quad \text{--- (2)}$$

$$\therefore y(0,t) = 0 \quad \& \quad y(20,t) = 0$$

Now heat eqⁿ is

$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial y}{\partial t}$$

by variable separable $y = X(x), T(t)$

$$\frac{X''}{X} = \frac{T'}{c^2 T} = \text{Constant}$$

(Applying boundary conditions)

if constant = 0

$$X(x) = 0$$

$$ax + b = X(x)$$

$$@ n=0$$

$$y(x) = 0$$

$$@ x=l$$

$$y(x) = 0$$

$$a = b = 0$$

Rejected

if constant = +ve
constant = n^2

$$X'' = n^2 X$$

$$X(x) = C_1 e^{nx} + C_2 e^{-nx}$$

$$@ n=0, C_1 + C_2 = 0$$

$$@ x=l, C_1 e^{nl} + C_2 e^{-nl} = 0$$

$$C_1 = C_2 = 0$$

Rejected

if constant = -ve

$$\text{Constant} = -n^2$$

$$X'' + n^2 X = 0$$

$$X(x) = C_1 \cos nx + C_2 \sin nx$$

$$@ x=0$$

$$C_1 = 0$$

$$@ x=l$$

$$\sin nl = 0$$

$$nl = n'l$$

$$n = \frac{n'l}{l} \quad n' \in \mathbb{Z}$$

$$\therefore y(x,t) = \sum C_n \sin \frac{n\pi x}{l} e^{-\frac{c^2 n^2 \pi^2}{l^2} t}$$

Now applying initial conditions

$$\begin{aligned} y(x, 0) &= u(x, 0) - (x + 40) && \text{from (1)} \\ &= \left(\frac{5x}{2} + 30\right) - (x + 40) \\ &= \frac{3x}{2} - 10 \end{aligned}$$

$$\Rightarrow \frac{3x}{2} - 10 = \sum a_n \sin \frac{n\pi x}{l}$$

$$a_n = \frac{2}{l} \int_0^l \left(\frac{3x}{2} - 10\right) \sin \frac{n\pi x}{l} dx$$

put $l=20$

$$a_n = \frac{1}{10} \int_0^{20} \left(\frac{3x}{2} - 10\right) \sin \frac{n\pi}{20} x dx$$

$$a_n = \frac{1}{10} \left[\frac{\left(\frac{3x}{2} - 10\right) \cos \frac{n\pi x}{20}}{-\frac{n\pi}{20}} \Big|_0^{20} + \int_0^{20} \frac{3}{2} \frac{\cos \frac{n\pi x}{20}}{\frac{n\pi}{20}} dx \right]$$

$$= \frac{1}{10} \left[\frac{20 \cos n\pi + 10}{-\frac{n\pi}{20}} + \frac{3}{2} \cdot \frac{1}{\left(\frac{n\pi}{20}\right)^2} \sin \frac{n\pi x}{20} \Big|_0^{20} \right]$$

$$a_n = \frac{-20}{n\pi} (1 + 2 \cos n\pi)$$

$$\therefore y(x, t) = \sum \frac{-20}{n\pi} (1 + \cos 2n\pi) \sin \frac{n\pi x}{20} e^{-\frac{c^2 n^2 \pi^2}{400} t}$$

$$u(x, t) = y(x, t) + (x + u_0) \text{ from (2)}$$

$$u(x, t) = (x + u_0) + \sum \frac{-20}{n\pi} (1 + \cos 2n\pi) \sin \frac{n\pi x}{20} e^{-\frac{c^2 n^2 \pi^2}{400} t}$$

