

NEXT IAS

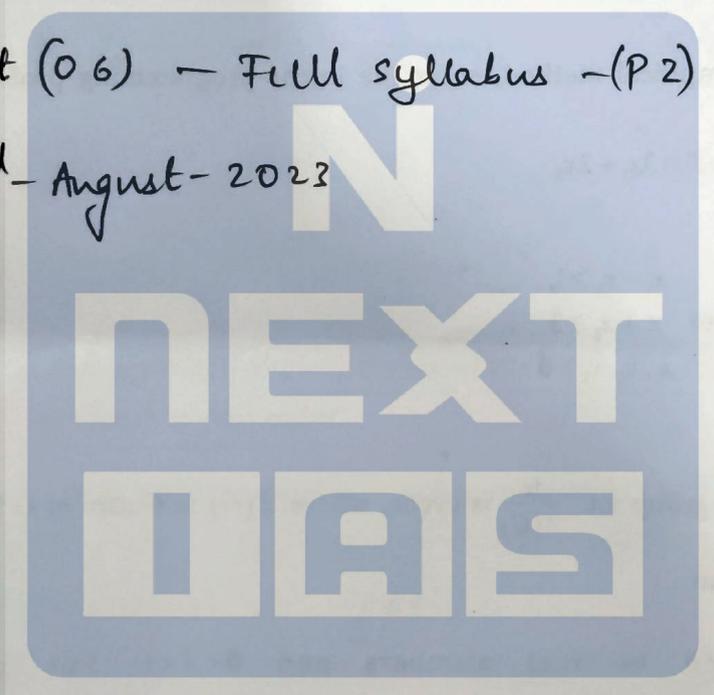
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Test - Test (06) - Full syllabus - (P2)

Date - 23rd - August - 2023



1a) To find units of $\mathbb{Z}[\sqrt{-5}]$

$$\mathbb{Z}[\sqrt{-5}] = \{a + b\sqrt{-5} \mid \text{where } a, b \in \mathbb{Z}\}$$

a unit in an integral domain is that element whose multiplicative inverse exist

if u is unit then $\exists u'$ s.t. $uu' = 1$

To find units of $\mathbb{Z}[\sqrt{-5}]$

if $a + b\sqrt{-5}$ is unit then $\exists c + d\sqrt{-5}$

$$(a + b\sqrt{-5})(c + d\sqrt{-5}) = 1$$

$$\Rightarrow ac - 5bd + \sqrt{-5}(bc + ad) = 1$$

$$\Rightarrow \boxed{ac - 5bd = 1}$$

$$\text{and } \boxed{bc + ad = 0}$$

$$\Rightarrow ac = 1 \text{ \& } bd = 0 \quad \text{where } a, b, c, d \in \mathbb{Z}$$

$\boxed{\text{units are } 1 \text{ and } -1}$

1b) Define winding number.



10) To show every convergent sequence is bounded

let $\{x_n\}$ be cgt

$$\therefore \lim_{n \rightarrow \infty} x_n = l \text{ (finite)}$$

$$\Rightarrow |x_n - l| < \epsilon \text{ for } n \geq m$$

for given $\epsilon > 0$ there exists values of $m \in \mathbb{Z}$ such that $|x_n - l| < \epsilon$

Hence $\{x_n\}$ is a bounded sequence

Conversely,

$$\text{let } y_n = (-1)^n$$

clearly $y_n = \{-1 \text{ or } 1 \text{ depending on } n\}$

$$\therefore |y_n| < 2 \text{ (say)}$$

$$\therefore |y_n| = 1$$

Hence $\{y_n\}$ is bounded

but clearly $\{y_n\}$ is not convergent

as $\lim_{n \rightarrow \infty} (y_n)$ does not exist

1d) To prove converse of Lagrange Theorem is true in cyclic group.

Lagrange Theorem: If H is subgroup of G
then $o(H)$ divides $o(G)$

we show that in cyclic group if
 $o(H) \mid o(G)$ then $H \subseteq G$ and subgroup of G

Since G is cyclic

$$G = \langle a \rangle \text{ where } a^n = e$$

let H be subset of elements of G
such that $o(H) \mid o(G)$

1e)

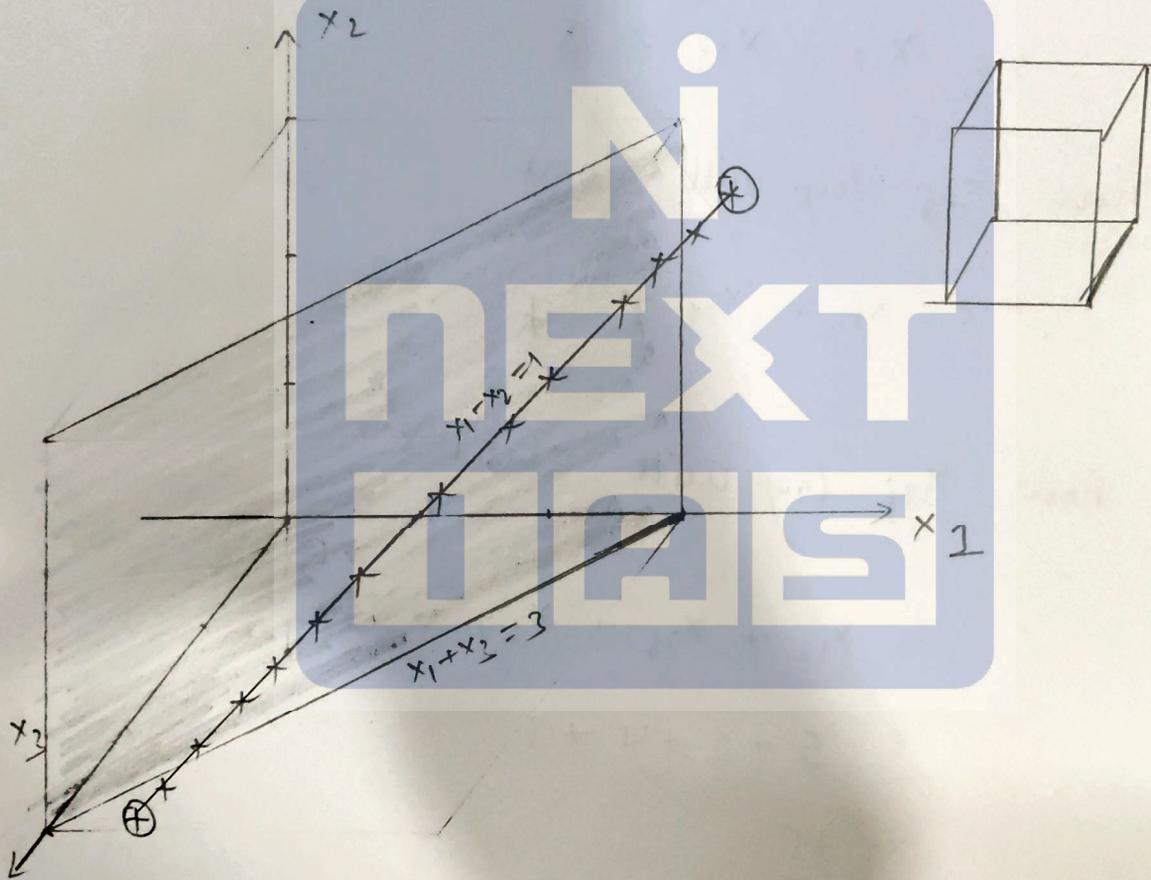
$$\text{Max: } z = 3x_1 + 2x_2$$

subject to

$$x_1 - x_2 \geq 1$$

$$x_1 + x_2 \geq 3$$

$$x_1, x_2, x_3 \geq 0$$



for $x_1 + x_2 \geq 3$
cover all space beyond  frame

& for $x_1 - x_2 \geq 1$ all points to right of line

for maximization, there is no
bounded solution

3a) To show A_4 has no subgroup of order 6

A_4 is group of even permutations on S_4

S_4 is permutations on a, b, c, d

$$o(S_4) = 4! = 24$$

$$\textcircled{b} \quad o(A_4) = 12$$

Elements of S_4 are

even $\left[(a) \right.$

odd $\left[(abcd), \right.$

even $\left[(abc), (acb), (acd), (adc), (abd), (adb) \right.$

$(bcd), (bdc),$

even $\left[(ab)(cd), (ac)(bd), (ad)(bc) \right.$

odd $\left[(ab), (ac), (ad), (bc), (bd), (cd) \right]$

$$\textcircled{c} \quad A_4 = \left\{ (a), (abc), (acb), (acd), (adc), (abd), (adb), (bcd), (bdc), (ab)(cd), (ac)(bd), (ad)(bc) \right\}$$

To show A_3 does not have subgroup of order 6 (b)

If suppose on contrary it has a subgroup of 6
then it will have (a) as identity element
Hence it must have 5 other elements

Suppose

(abc) is one of element — 2nd element

then $(abc)(abc) = (acb)$ — 3rd element

and $(abc)(abc)(abc) = (a)$

let another element be (acd) — 4th element

now $(acd)(acd) = adc$ — 5th element

but $(abc)(acd) = (abd)$ — which does not
belong to set of
above 5 elements

if another element was $(ac)(bd)$
then also it will be a contradiction

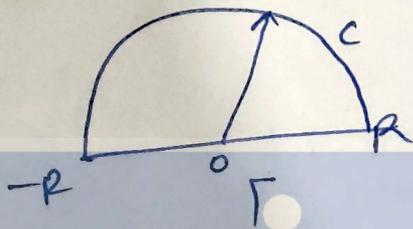
Hence, A_3 cannot have subgroup of order 6

3b)
$$\int_0^{\infty} \frac{dx}{x^4 + a^4}$$

Consider

$$\int_{-\infty}^{\infty} \frac{dz}{z^4 + a^4}$$

and close Γ such that



$$\int_{\Gamma} \frac{dz}{z^4 + a^4} = \int_C \frac{dz}{z^4 + a^4} + \int_{-R}^R \frac{dz}{z^4 + a^4}$$

$$= 2\pi i (\text{sum of residues})$$

for $z^4 + a^4 = 0$
 $\Rightarrow z^4 = -a^4 \Rightarrow z = (-1)^{\frac{1}{4}} a$

$$z = e^{\frac{(2k+1)\pi i}{4}} \cdot a \quad k = 0, 1, 2, 3$$

$$z = e^{i\pi/4} \cdot a, \quad z = e^{i3\pi/4} \cdot a, \quad z = e^{i5\pi/4}, \quad z = e^{i7\pi/4}$$

↳ within contour

$$\therefore \text{Res}(z=a) = \lim_{z \rightarrow a} \frac{z-a}{z^4 + a^4} = \frac{1}{4a^3}$$

∴ Sum of residues

$$= \frac{1}{4} \left[z_1^{-3} + z_2^{-3} \right]$$

$$= \frac{1}{4a^3} \left[e^{-\frac{3i\pi}{4}} + e^{-\frac{9i\pi}{4}} \right]$$

$$= \frac{1}{4a^3} \left[\cos \frac{3\pi}{4} - i \sin \frac{3\pi}{4} + \cos \frac{9\pi}{4} - i \sin \frac{9\pi}{4} \right]$$

$$= \frac{1}{4a^3} \left[\frac{-1}{\sqrt{2}} - i \frac{1}{\sqrt{2}} + \frac{1}{\sqrt{2}} - i \frac{1}{\sqrt{2}} \right]$$

$$= \frac{-i}{4a^3} \cdot \sqrt{2}$$

$$\therefore \int_C f(z) dz = 2\pi i \cdot \frac{-i\sqrt{2}}{4a^3} = \frac{2\sqrt{2}}{4a^3}$$

$$\int_C \frac{dz}{z^4+a^4} = \int_0^\pi \frac{Re^{i\theta} d\theta}{R^4 e^{i\theta} + a^4}$$

$$\int_0^\pi \left| \frac{Re^{i\theta} d\theta}{R^4 e^{i\theta} + a^4} \right| \leq \int_0^\pi \frac{R d\theta}{|R^4 - a^4|} = \frac{R\pi}{R^4 - a^4}$$

$$\lim_{R \rightarrow \infty} \frac{R\pi}{R^4 - a^4} = 0$$

$$\therefore \lim_{R \rightarrow \infty} \left| \int_C \frac{dz}{z^4+a^4} \right| \leq 0 \Rightarrow \lim_{R \rightarrow \infty} \int_C \frac{dz}{z^4+a^4} = 0$$

Hence

$$\int_{\Gamma} f(z) dz = \int_C f(z) dz + \int_{-R}^R f(z) dz$$

where $f(z) = \frac{1}{z^4 + a^4}$

taking limit $R \rightarrow \infty$

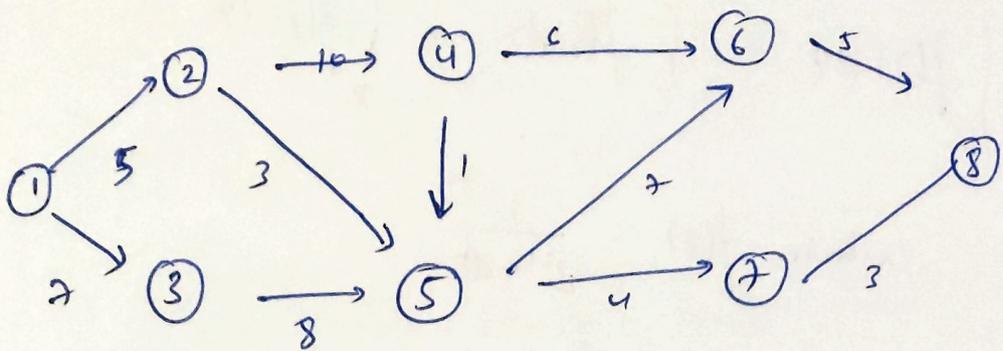
$$\therefore \frac{2\pi i}{4a^3} = 0 + \int_{-\infty}^{\infty} \frac{dz}{z^4 + a^4}$$

$$2 \int_0^{\infty} \frac{dz}{z^4 + a^4} = 2 \frac{\pi i}{4a^3}$$

$$\int_0^{\infty} \frac{dz}{z^4 + a^4} = \frac{\pi i}{4a^3}$$

Answer

3c) To formulate an LPP.



Step I: Read all the nodes as x_i

Step II: Read all costs between nodes as $x_i x_j$ ($i \neq j$)
 [Eg: cost between ① & ② be $x_1 x_2 = 5$]

Step III: For other $x_i x_j$ value not provided consider it to be very large say 1000 & $S = 0$

Step IV: For $i = 1$, run loop till $i = 7$

Step V: For $j = 2$, run loop till $j = 8$

Step VI: ~~For~~ If $i \geq j$, Go to step VIII

Step VII: If $x_i x_j < x_i x_{j+1}$ $S \rightarrow S + x_i x_j$
 Else Go to step VIII

Step VIII: $j \rightarrow j + 1$, Go to step 5

Step IX: $i \rightarrow i + 1$, Go to step 4 ; step X: Print S

Therefore through the linear programming model

x_{12} will be selected

$$\therefore S = x_{12} = 5$$

now x_{2j} loop will start
again x_{25} will be selected

$$\therefore S = x_{12} + x_{25} = 8$$

now x_{5j} loop will start

$$\therefore S = x_{12} + x_{25} + x_{57} = 12$$

now x_{7j} loop will start

$$\therefore S = x_{12} + x_{25} + x_{57} + x_{78}$$

$$= 5 + 3 + 4 + 3$$

$$= 15$$

Answer

Section-B

5 a) $x^p = y^q, \therefore z(x^p + y^q) = 2xy$

To show they are compatible

eq ①: $x^p - y^q = 0$

$\Rightarrow \frac{dx}{x} = \frac{dy}{-y} = \frac{dz}{0}$

$xy = C_1$
 $z = C_2$

eq ②: $z(x^p + y^q) = 2xy$

$\Rightarrow \frac{dx}{xz} = \frac{dy}{yz} = \frac{dz}{2xy}$

$x = C_3 y$

$\frac{dy}{z} = \frac{dz}{2x}$

$\frac{dy}{z} = \frac{dz}{2C_3 y}$

$C_3 y^2 = \frac{z^2}{2} + C_4$

$xy = \frac{z^2}{2} + C_4$

for equations to be compatible

$C_1 = \frac{C_2^2}{2} + C_4$

and

$C_3 y^2 = C_1$

$y^2 = \frac{C_1}{C_3}$

Hence

$z \cdot 2px = 2xy$

② $p = \frac{y}{z}$

$q = \frac{x}{z}$

$$p = \frac{y}{z}, \quad q = \frac{x}{z}$$

$$z \frac{\partial z}{\partial x} = y, \quad z \frac{\partial z}{\partial y} = x$$

$$\frac{\partial^2 z}{\partial x \partial y} = \frac{1}{z}$$

$$D D' z = \frac{1}{z}$$

$$D D' z - \frac{1}{z} = 0$$

$$z^2 = xy + c$$

where c is arbit constant

$$zp = y \quad \left| \quad zq = x \right.$$
$$\frac{dx}{z} = \frac{dz}{y}$$

$$\frac{dx}{z} = \frac{dz}{y}$$
$$\frac{dx}{z} = \frac{dz}{y}$$

$$y dx = \frac{ndy}{z}$$

$$\frac{dn}{n} = \frac{dy}{y}$$

$$x = c'y$$

$$\frac{\partial z}{\partial y} = \frac{c'y}{z}$$

$$z^2 = c'y^2 + c''$$

5b) $f(x) = \sin x$ is extrapolated by polynomial degree 9 with 10 points

To find Error

$$\text{Error} = \left| \frac{\prod_{i=1}^{10} (x-x_i)}{10!} f^{(10)}(\xi) \right|$$

where $f(x) = \sin x$

$$|f^{(10)}(\xi)| = |\sin x| \leq \sin 1 \quad x \in [0, 1]$$

$$\prod_{i=1}^{10} (x-x_i) = (x-x_1)(x-x_2) \dots (x-x_{10})$$

To find max. value of $\prod (x-x_i)$

$$\frac{d}{dx} \prod (x-x_i) = 0$$

\therefore Max. error is $\frac{\prod (x-x_i)}{10!} \cdot \sin 1$
 $x \in [0, 1]$

5c)

$$((p \wedge q) \rightarrow r) \vee (p \wedge q \rightarrow \sim r)$$

if $a \rightarrow b$ then $\sim a \vee b$

So, $(p \wedge q) \rightarrow r$ then $\sim(p \wedge q) \vee r$

$$= \overline{p \wedge q} + r = \overline{p} + \overline{q} + r$$

$$\& (p \wedge q) \rightarrow \sim r = \overline{p \wedge q} + \overline{r} = \overline{p} + \overline{q} + \overline{r}$$

now,

$$(p \wedge q \rightarrow r) \vee (p \wedge q \rightarrow \sim r)$$

$$= \overline{p \wedge q} + r + \overline{p \wedge q} + \overline{r}$$

$$= \overline{p \wedge q} = \sim p \vee \sim q \quad \text{②} \quad \sim(p \wedge q)$$

To write in normal disjunctive format

$$\overline{p} + \overline{q} = \overline{p}(0+0)(r+\overline{r}) + (p+\overline{p})\overline{q}(r+\overline{r})$$

$$= \overline{p}(0r + 0\overline{r} + q\overline{r} + \overline{q}\overline{r}) + (pr + \overline{p}r + p\overline{r} + \overline{p}\overline{r})\overline{q}$$

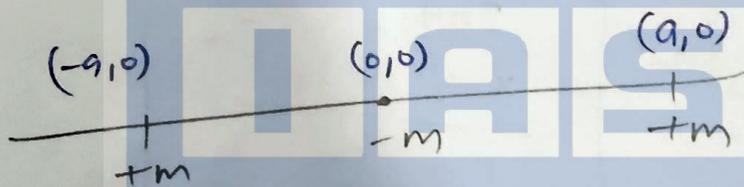
$$= \overline{p}0r + \overline{p}0\overline{r} + \overline{p}q\overline{r} + \overline{p}\overline{q}\overline{r} + p\overline{p}r + p\overline{p}\overline{r}$$

So normal disjunctive form is

$$(\sim p \wedge q \wedge r) \cup (\sim p \wedge q \wedge \sim r) \cup (\sim p \wedge \sim q \wedge r) \cup (\sim p \wedge \sim q \wedge \sim r) \\ \cup (p \wedge \sim q \wedge r) \cup (p \wedge \sim q \wedge \sim r)$$

which is neither tautology nor contradiction

5d) To find stream function of two equal sources and an equal sink midway



let them be placed along x-axis
 & sink at origin & distance between
 two sources be $2a$

$$\therefore W = -m \log(z+a) - m \log(z-a) + m \log z$$

Complex
 potential

$$W = -m \log(z^2 - a^2) + m \log z$$

$$W = -m \log\left(\frac{z^2 - a^2}{z}\right)$$

$$W = \phi + i\psi$$

$$\therefore \psi = -m \tan^{-1} \frac{y}{x-a} - m \tan^{-1} \left(\frac{y}{x+a} \right) + m \tan^{-1} \left(\frac{y}{x} \right)$$

$$= -m \left[\tan^{-1} \left(\frac{y}{x-a} \right) + \tan^{-1} \left(\frac{y}{x+a} \right) - \tan^{-1} \left(\frac{y}{x} \right) \right]$$

$$= -m \left[\tan^{-1} \left(\frac{\frac{y}{x-a} + \frac{y}{x+a}}{1 - \frac{y^2}{x^2-a^2}} \right) - \tan^{-1} \left(\frac{y}{x} \right) \right]$$

$$= -m \left[\tan^{-1} \left(\frac{2xy}{x^2-a^2-y^2} \right) - \tan^{-1} \left(\frac{y}{x} \right) \right]$$

$$= -m \tan^{-1} \left[\frac{\frac{2xy}{x^2-y^2-a^2} - \frac{y}{x}}{1 + \frac{2xy}{x^2-y^2-a^2} \cdot \frac{y}{x}} \right]$$

$$= -m \tan^{-1} \left[\frac{2x^2y - y^2x + y^3 + a^2y}{x^3 + xy^2 - a^2x} \right]$$

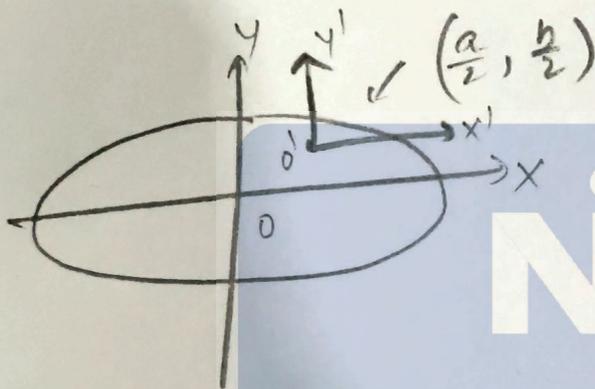
$$\psi = -m \tan^{-1} \left[\frac{x^2y + y^3 + a^2y}{x(x^2 + y^2 - a^2)} \right]$$

$$= -m \tan^{-1} \left(\frac{y}{x} \cdot \frac{(x^2 + y^2 + a^2)}{(x^2 + y^2 - a^2)} \right)$$

c) To show at center of quadrant, principal axes are inclined at $\frac{1}{2} \tan^{-1} \left(\frac{4ab}{a^2 - b^2} \right)$

We know angle of inclination is given by

$$2\theta = \tan^{-1} \left(\frac{2F}{B-A} \right)$$



$$I_{O'X'} = I_{Ox} + M \left(\frac{b}{2} \right)^2 = \frac{Mb^2}{4} + \frac{Mb^2}{4} = \frac{Mb^2}{2}$$

$$I_{O'Y'} = I_{Oy} + M \left(\frac{a}{2} \right)^2 = \frac{Ma^2}{4} + \frac{Ma^2}{4} = \frac{Ma^2}{2}$$

$$I_{X'Y'} = ?$$

$$I_{X'Y'} = \int dm \left[x - \frac{a}{2} \right] \left[y - \frac{b}{2} \right]$$

$$\sigma = \frac{M}{\pi ab}$$

$$= \int \int \sigma \left(x - \frac{a}{2} \right) \left(y - \frac{b}{2} \right) dx dy$$

$$= \sigma \int_{-a}^a \int_{-b\sqrt{1-\frac{x^2}{a^2}}}^{b\sqrt{1-\frac{x^2}{a^2}}} \left(x - \frac{a}{2} \right) \left(y - \frac{b}{2} \right) dy dx$$

$$I_{xy} = \int_{-a}^a (x - \frac{a}{2}) \left(\frac{y^2}{2} - \frac{by}{2} \right) \sqrt{1 - \frac{x^2}{a^2}} dx$$

$$= \int_{-a}^a (x - \frac{a}{2}) (-b^2) \sqrt{1 - \frac{x^2}{a^2}} dx$$

$$= 2 \int_0^a \left(\frac{a}{2} - b^2 \right) \frac{\sqrt{a^2 - x^2}}{a} dx$$

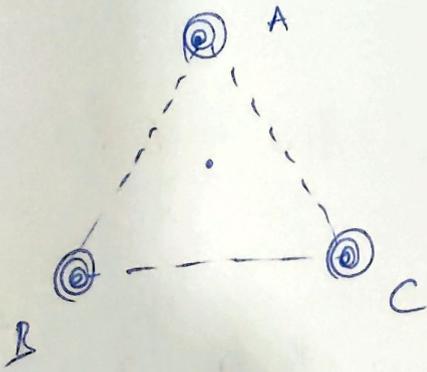
$$= 2b^2 \int_0^a \sqrt{a^2 - x^2} dx$$

$$= 2b^2 \left[\frac{x}{2} \sqrt{a^2 - x^2} + \frac{a^2}{2} \sin^{-1} \left(\frac{x}{a} \right) \right]_0^a$$

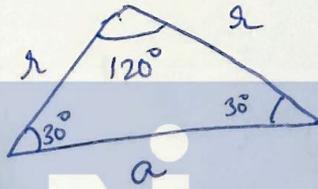
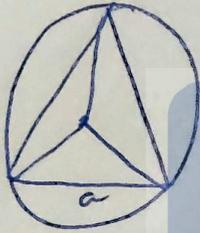
$$= \frac{2a^2 b^2}{2} \cdot \frac{\pi}{2} = \frac{Mab}{4}$$

$$2 \tan \theta = \frac{2 \left(\frac{Mab}{4} \right)}{\frac{Ma^2}{2} - \frac{Mb^2}{2}} = \frac{ab}{a^2 - b^2}$$

6a)



for Δ , orthocenter/circumcenter will be O



$$\cos 120^\circ = \frac{2r^2 - a^2}{2r^2} \Rightarrow -\frac{1}{2} = \frac{2r^2 - a^2}{2r^2}$$

$$\Rightarrow -r^2 = 2r^2 - a^2$$

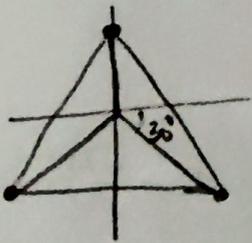
$$a^2 = 3r^2$$

$$r = \frac{a}{\sqrt{3}}$$

complex potential will be given by

$$W = \frac{ik}{2\pi} \log(z - re^{i\pi/2}) + \frac{ik}{2\pi} \log(z - re^{i\pi+\pi/2})$$

$$+ \frac{ik}{2\pi} \log(z - re^{-i\pi/2})$$



to find velocity at A
 we take complex potential due to B & C

$$w' = \frac{ik}{2\pi} \log(z - re^{i\pi/6}) + \frac{ik}{2\pi} \log(z - re^{-i\pi/6})$$

$$\frac{dw'}{dz} = \frac{ik/2\pi}{z - re^{i\pi/6}} + \frac{ik/2\pi}{z - re^{-i\pi/6}}$$

at $z = re^{i\pi/2}$

$$q = \frac{ik/2\pi}{r(e^{i\pi/2} - e^{i\pi/6})} + \frac{ik/2\pi}{r(e^{i\pi/2} - e^{-i\pi/6})}$$

$$e^{i\pi/2} = i$$

$$e^{i\pi/6} = \cos \frac{\pi}{6} + i \sin \frac{\pi}{6} = \frac{\sqrt{3}}{2} + \frac{i}{2}$$

$$e^{-i\pi/6} = \frac{\sqrt{3}}{2} - \frac{i}{2}$$

$$q = \frac{ik/2\pi}{r\left(\frac{i}{2} + \frac{\sqrt{3}}{2} + \frac{3i}{2}\right)} + \frac{ik/2\pi}{r\left(\frac{i}{2} + \frac{\sqrt{3}}{2} - \frac{3i}{2}\right)} = \frac{ik}{2\pi r} \left[\frac{\sqrt{3}}{6} \frac{i}{2} + \frac{-\sqrt{3}}{6} \frac{-i}{2} \right]$$

$$= \frac{ik}{2\pi r} \cdot i = \frac{k}{2\pi r}$$

$$T = \frac{2\pi r}{q} = \frac{2\pi r}{k/2\pi r} = \frac{4\pi^2 r^2}{k} = \frac{4\pi^2 a^2}{3k}$$

put $r = \frac{a}{\sqrt{3}}$

6b)

$$x(y^2+z) - y(x^2+z) = (x^2-y^2)z$$

its auxiliary Lagrange equation is

$$\frac{dx}{x(y^2+z)} = \frac{dy}{-y(x^2+z)} = \frac{dz}{x^2-y^2}$$

$$\frac{\frac{dx}{x} + \frac{dy}{y} + \frac{dz}{z}}{y^2+z-x^2-z+x^2-y^2} = \frac{\frac{dx}{x} + \frac{dy}{y} + \frac{dz}{z}}{0}$$

$$\Rightarrow \frac{dx}{x} + \frac{dy}{y} + \frac{dz}{z} = 0$$

$$\Rightarrow \boxed{xyz = C_1}$$

$$= \frac{x dx + y dy - z dz}{x^2 y^2 + x^2 z - x^2 y^2 - y^2 z + x^2 z + y^2 z}$$

$$\Rightarrow \boxed{x^2 + y^2 = z^2 + C_2}$$

$$\phi(xyz, x^2 + y^2 - z^2) = 0$$

For particular solution

along $x+y=0$ & $z=1$

$$x = -y \quad \& \quad z = 1$$

$$\Rightarrow -x^2 = 4 \quad \therefore \quad xyz = 4$$

$$\& \quad 2x^2 = 1 + c_2$$

$$\Rightarrow \boxed{+24 + 1 + c_2 = 0}$$

$$\Rightarrow \boxed{2xyz + 1 + x^2 + y^2 - z^2 = 0}$$

(or)

$$f(x, y, z) = x^2 + y^2 - z^2 + 2xyz + 1 = 0$$

↳ integral surface

6c)

x	y	Δy_0	$\Delta^2 y_0$	$\Delta^3 y_0$	$\Delta^4 y_0$
0	-3	6	2	6	0
1	3	8	8	6	0
2	11	16	14	6	0
3	27	30	20	6	0
4	57	50			
5	107				

Clearly $\Delta^4 y_0 = 0$
 \Rightarrow polynomial will be of degree 3

$$f(x) = y_0 + u \Delta y_0 + \frac{u(u-1)}{2!} \Delta^2 y_0 + \frac{u(u-1)(u-2)}{3!} \Delta^3 y_0$$

$$u = \frac{x-x_0}{h} = \frac{x-0}{1} = x$$

$$\begin{aligned} \therefore f(x) &= -3 + x(6) + \frac{x(x-1)}{2} \cdot 2 + \frac{x(x-1)(x-2)}{6} \cdot 6 \\ &= -3 + 6x + x^2 - x + x(x^2 - 3x + 2) \\ &= x^3 + 5x - 3 + x^3 - 3x^2 + 2x \end{aligned}$$

$$\boxed{f(x) = x^3 - 2x^2 + 7x - 3} \quad \text{Answer}$$

8a) To simplify $F(x, y, z)$

using sum of product form (conjunctive form)
use of $\Sigma 1$'s

$$f(x, y, z) = xy z + xy \bar{z} + x \bar{y} z + \bar{x} y z$$

$$= x(yz + y\bar{z} + \bar{y}z) + \bar{x}yz$$

$$= x(y(z + \bar{z}) + \bar{y}z) + \bar{x}yz$$

$$= x(y + \bar{y}z) + \bar{x}yz$$

$$= x(y + z) + \bar{x}yz$$

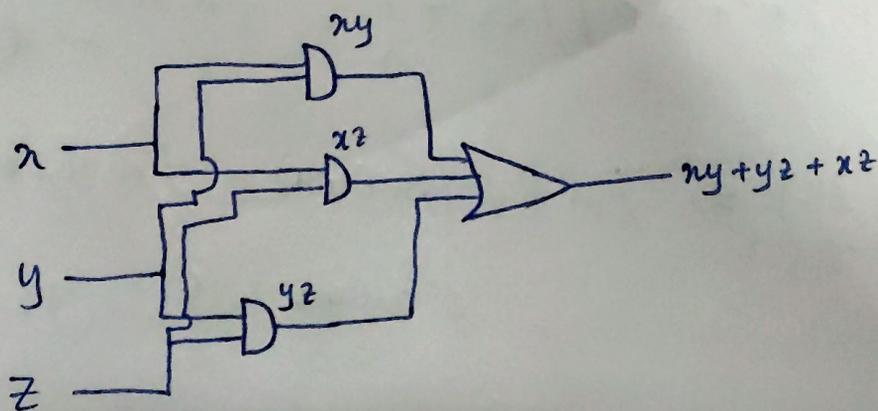
$$= xy + xz + \bar{x}yz$$

$$= y(x + \bar{x}z) + xz$$

$$= y(x + z) + xz$$

$$= xy + yz + xz$$

$$\therefore \boxed{A + \bar{A} = 1}$$
$$\& \boxed{A + \bar{A}B = A + B}$$



8b) Given $F = -\frac{k}{r^2}$

$$V = \int F dr = \int -\frac{k}{r^2} dr = \frac{k}{r} + C$$

$$K.E = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2 + \dot{z}^2)$$

$$K.E = \frac{1}{2} m (\dot{r}^2 + r^2 \sin^2 \theta \dot{\phi}^2 + \dot{\theta}^2)$$

$$L = K.E. - V \quad (\text{or } T - V)$$

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2 + r^2 \sin^2 \theta \dot{\phi}^2) - \frac{k}{r} - C$$

which is Lagrangian in spherical coordinates

Now, $\frac{\partial L}{\partial x} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right)$

$$\therefore \frac{\partial L}{\partial r} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right)$$

$$\Rightarrow \frac{1}{2} m (\dot{\theta}^2 + \sin^2 \theta \dot{\phi}^2) 2r + \frac{k}{r^2} = \frac{1}{2} m \dot{r} \cdot 2 \quad \text{--- (1)}$$

$$\frac{\partial L}{\partial \theta} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) \Rightarrow \frac{1}{2} m r^2 \dot{\phi}^2 (2 \sin \theta \cos \theta) = \frac{1}{2} m r^2 2 \dot{\theta}$$

$$\dot{\phi}^2 \sin \theta \cos \theta = \dot{\theta} \quad \text{--- (2)}$$

and $\frac{\partial L}{\partial \dot{\phi}} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\phi}} \right) \Rightarrow 0 = \frac{1}{2} m \dot{r}^2 \sin^2 \theta \cdot 2 \ddot{\phi}$

$\Rightarrow \boxed{\dot{r}^2 \sin^2 \theta \ddot{\phi} = 0}$ (3)

$\therefore \ddot{\phi} = 0 \Rightarrow \boxed{\ddot{\phi} = c}$

in eq (2)

$\ddot{\theta} = c^2 \sin \theta \cos \theta$

$\frac{d^2 \theta}{dt^2} = c^2 \sin \theta \cos \theta$

$\frac{1}{2} \left(\frac{d\theta}{dt} \right)^2 = c^2 \frac{\sin^2 \theta}{2}$

$\boxed{\ddot{\theta}^2 = c^2 \sin^2 \theta + c'}$ (4)

in eq (1)

$\frac{1}{2} m \left(c^2 \sin^2 \theta + c' + \sin^2 \theta \cdot c^2 \right) \ddot{r} + \frac{k}{r^2} = \frac{1}{2} m \ddot{r}$

$\boxed{\frac{m \ddot{r}^2}{2} = \frac{-k}{r} + m \left(2c^2 \sin^2 \theta + c' \right) \frac{\dot{r}^2}{2} + c''}$ (5)

at t

eq (4) & (5) are required eqⁿ of motion

8c) string in eq^m position @ $x=0, x=l$

Initially in eq^m position

& Initial velocity is $\lambda n(l-n)$

∴ Boundary conditions:

$$x=0, u(x,t) = 0$$

$$x=l, u(x,t) = 0$$

Initial conditions:

$$u_x(x,0) = \lambda n(l-n)$$

wave eqⁿ is given by

$$c^2 \frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial t^2}$$

let $u(x,t) = X(x) T(t)$ — variable separable method

$$\Rightarrow c^2 X'' T = X T''$$

$$\textcircled{a} \frac{X''}{X} = \frac{T''}{c^2 T} = \text{constant}$$

Case I constant = 0

$$\Rightarrow X'' = 0$$

$$\Rightarrow X(x) = c_1 x + c_2$$

but boundary conditions not satisfied

Case II

constant = +ve = k^2 (say)

$$\frac{x''}{x} = k^2$$

$$\Rightarrow x(x) = C_1 e^{kx} + C_2 e^{-kx}$$

BCs are @ $x=0 \Rightarrow 0 = C_1 + C_2$

@ $x=l \Rightarrow 0 = C_1 e^{kl} + C_2 e^{-kl}$

$\Rightarrow C_1 = C_2 = 0$ Rejected

Case III

constant = -ve = $-k^2$ (say)

$$\frac{x''}{x} = -k^2$$

$$x(x) = C_1 \sin kx + C_2 \cos kx$$

@ $x=0 \Rightarrow C_1(0) + C_2 = 0 \Rightarrow C_2 = 0$

@ $x=l \Rightarrow C_1 \sin kl = 0 \Rightarrow kl = n\pi$ or $k = \frac{n\pi}{l}$

$\therefore \frac{T''}{CT} = -k^2$ (or) $\frac{T''}{T} = -C^2 k^2$

$$T(t) = C_3 \sin ckt + C_4 \cos ckt$$

$$u(x,t) = \sum_{n=0}^{\infty} \sin \frac{n\pi x}{l} \left(A_n \sin \frac{cn\pi}{l} t + B_n \cos \frac{cn\pi}{l} t \right)$$

at $t=0, u(x,t)=0 \Rightarrow A_n(0) + B_n = 0 \Rightarrow B_n = 0$

$$u_t = \sum \sin \frac{n\pi x}{l} \left[A_n \cdot \frac{cn\pi}{l} \cdot \cos \frac{cn\pi}{l} t \right]$$

$$u_n(l-x) = \sum \left(A_n \cdot \frac{n\pi}{l} \right) \frac{\sin n\pi x}{l} \quad \text{at } t = 0$$

$$\Rightarrow A_n \left(\frac{n\pi}{l} \right) = \frac{2}{l} \int_0^l u_n(l-x) \frac{\sin n\pi x}{l} dx$$

$$= \frac{2}{l} \left[\frac{-\cos n\pi x}{\frac{n\pi}{l}} u_n(l-x) \right]_0^l + \int_0^l \frac{\cos n\pi x}{\left(\frac{n\pi}{l} \right)^2} \cdot d[l-2x] dx$$

$$= \frac{2}{l} \left[\frac{1}{\left(\frac{n\pi}{l} \right)^2} \frac{\sin n\pi x}{l} d(l-2x) \right]_0^l - \frac{1}{\left(\frac{n\pi}{l} \right)^2} \int_0^l \sin n\pi x (-2) dx$$

$$= \frac{2}{l} \frac{2l}{\left(\frac{n\pi}{l} \right)^2} \int_0^l \frac{\sin n\pi x}{l} dx$$

$$= \frac{4l}{l \cdot \left(\frac{n\pi}{l} \right)^3} - \frac{\cos n\pi x}{l} \Big|_0^l$$

$$= \frac{+4l^2}{n^3 \pi^3} [1 - \cos n\pi]$$

$$A_n \left(\frac{2k+1}{l} \pi \right) = \frac{8l^2}{(2k+1)^3 \pi^3} \quad \text{if } n \text{ is odd, } \cos n\pi = -1$$

$$A_n = \frac{8dl^3}{(2k+1)^4 \pi^3}$$

Therefore

$$u(x, t) = \sum_{k=0}^{\infty} \frac{8dl^3}{(2k+1)^4 \pi^3} \sin \frac{(2k+1)\pi x}{l} \sin \frac{c(2k+1)\pi t}{l}$$

~~Ni~~ which is required eqⁿ

NEXT

OAS