
Graphs of edge-intersecting and non-splitting paths ^{*}

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Abstract. The families of Edge Intersection Graphs of Paths in a tree (resp. in a grid) EPT (resp. EPG) are well studied graph classes. Recently we introduced the class of graphs of Edge-Intersecting and Non-Splitting Paths in a Tree (ENPT) [2]. In this model, two vertices are adjacent if they represent two intersecting paths of a tree whose union is also a path. In this study we generalize this graph class by allowing the host graph to be an arbitrary graph. These are the graphs of Edge-Intersecting and Non-Splitting Paths ENP. Although the Edge Intersection Graphs of Paths in an arbitrary graph includes all graphs, we show that this is not the case for ENP. We also show that the class ENP coincides with the family of graphs of Edge-Intersecting and Non-Splitting Paths in a Grid (ENPG). Following similar studies for EPG graph class, we study the implications of restricting the number of bends in the grid, of the individual paths. We show that restricting the bend number also restricts the graph class. Specifically, by restricting the number of bends one gets an infinite sequence of classes such that every class is properly included in the next one.

1 Introduction

1.1 Background

The intersection graph of a family of sets is a graph in which every vertex corresponds to a set in the family, and two vertices of the graph are adjacent if and only if their corresponding set have a non-empty intersection. It is easy to see that every graph is an intersection graph. Therefore, it makes sense to study intersection graphs only when one focuses on specific families of sets. The family of paths on graphs is a commonly studied family of sets. To distinguish the graph on which the paths are defined, from the resulting intersection graph, this graph

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is termed the *host* graph. Given a host graph H and a set \mathcal{P} of paths in H , the Edge Intersection Graph of Paths (EP graph) of \mathcal{P} is denoted by $\text{EP}(\mathcal{P})$. $\text{EP}(\mathcal{P})$ contains a vertex for each path in \mathcal{P} , and it contains an edge between two vertices if the corresponding two paths intersect in at least one edge. A graph G is EP if there exist a graph H and a set \mathcal{P} of paths in H such that $G = \text{EP}(\mathcal{P})$. In this case we say that $\langle H, \mathcal{P} \rangle$ is an EP representation of G . We also denote by EP the family of all graphs G that are EP.

EP graphs have applications in many areas, and in particular in communication networks. Consider a communication network, and routes of messages to be delivered in it. Two paths conflict if they both require the usage of the same link. This conflict model is equivalent to an EP graph. Suppose we try to find a schedule for the messages such that no two messages sharing a link are scheduled at the same time interval. Then a proper vertex coloring of the EP graph corresponds to a feasible schedule on this network.

Often the host graphs are restricted to certain families such as paths, cycles, trees, grids, etc. When H is restricted to paths and cycles we get the well known families of interval graphs [11] and circular arc graphs [15], respectively. When H is restricted to trees, we obtain the family of Edge Intersection Graph of Paths in a tree (EPT) [6], and finally when H is a grid, the corresponding graph is termed an EPG graph [10].

In [2] we defined the graph of edge intersecting and non-splitting paths of a tree (ENPT) of a given representation $\langle T, \mathcal{P} \rangle$ as described above, denoted by $\text{ENPT}(\mathcal{P})$. This graph is a subgraph of $\text{EPT}(\mathcal{P})$: it has a vertex v for each path P_v of \mathcal{P} and two vertices u, v of this graph are adjacent if the paths P_u and P_v edge-intersect and do not split (that is, their union is a path). A graph G is an ENPT graph if there is a tree T and a set of paths \mathcal{P} of T such that $G = \text{ENPT}(\mathcal{P})$. We note that whenever T is a path $\text{EPT}(\mathcal{P}) = \text{ENPT}(\mathcal{P})$ is an Interval Graph. Therefore, the class ENPT includes all Interval Graphs. In this work we extend this definition to the case where the host graph is not necessarily a tree.

The motivation to study edge-intersecting and non-splitting paths arises from all-optical telecommunication networks. In the Wavelength Division Multiplexing (WDM) technology different signals can be multiplexed onto a single optical fiber by using different wavelength ranges of the laser beam [13]. A stream of signals traveling from its source to its destination in optical form is termed a *lightpath*. A lightpath is realized by signals traveling through a series of fibers, on a certain wavelength. Specifically, Wavelength Assignment problems (WLA) are a family of path coloring problems that aim to assign wavelengths (i.e. colors) to lightpaths, so that no two lightpaths with a common edge receive the same wavelength and certain objective function (depending on the problem) is minimized. *Traffic Grooming* is the term used for combination of several low-capacity requests into one lightpath using Time Division Multiplexing (TDM) technology [4]. In this context a set of paths can be combined into one lightpath, thus receiving the same color. One main constraint in traffic grooming is that

the union of the paths receiving the same color should constitute a path or a set of disjoint paths, and this originated the study of the class of ENPT graphs.

1.2 Related Work

EPT graphs have been studied in the literature. Their recognition is NP-complete [5], whereas one can solve in polynomial time the maximum clique [5] and the maximum stable set [14] problems for this class.

Current research on intersection graphs is concentrated on the comparison of various intersection graphs of paths in a tree and their relation to chordal and weakly chordal graphs [7, 8]. The k -edge intersection graphs where two vertices are adjacent if their corresponding paths intersect on at least k edges are studied in [9].

Several recent papers consider the edge intersection graphs of paths on a grid. Since all graphs are EPG (see [10]), studies focus mostly on the sub-classes of EPG where the paths have a limited number of bends. An EPG graph is B_k -EPG if it admits a representation in which every path has at most k bends. The *bend number* of a graph G is the minimum number k such that G has a B_k -EPG representation. Clearly, a graph is B_0 -EPG if and only if it is an interval graph. B_1 -EPG graphs are studied in [10] in which every tree is shown to be B_1 -EPG, and a characterization of C_4 representations is given. In [1] it is shown that there exists an outer-planar graph that is not a B_1 -EPG. The recognition problem of B_1 -EPG graphs is shown to be NP-complete in [12]. The work [1] investigates the bend number of some special graph classes.

In [2] we define the family of ENPT graphs and study their properties; in particular, we study the representations of induced cycles, that turns out to be much more complex than their counterpart in the EPT graphs (discussed in [6]).

In [3] we focus on graphs with bend number 1. We show that cycles and trees are B_1 -ENPG graphs, that the recognition problem of these graphs is NP-complete in general, and provide a polynomial time recognition algorithm for CO-BIPARTITE graphs.

1.3 Our Contribution

In this work we extend the definition of the family of edge intersecting and non-splitting paths on a tree (ENPT) graphs to the general case in which the host graph is not necessarily a tree. In Section 3 we consider the general case and we show that not every co-bipartite graph is an ENP graph, and that the family of ENP graphs is exactly the family of ENPG graphs. Therefore, it is sufficient to consider ENPG graphs for most of the questions. We thus consider, in Section 4, the effect of restricting the number of bends of the paths, where a bend of a path on a grid is a pair of consecutive edges of the path one of which is vertical and the other is horizontal. We show that restricting the number of bends give rise to an infinite hierarchy of sub-families of ENPG graphs, where every family is properly included in the next family in the hierarchy.

2 Preliminaries

2.1 Graphs, Co-Bipartite Graphs

Given a simple graph (no loops or parallel edges) $G = (V(G), E(G))$ and a vertex v of G , we denote by $\delta_G(v)$ the set of edges of G incident to v , by $N_G(v)$ the set consisting of v and its neighbors in G , and by $d_G(v) = |\delta_G(v)|$ the degree of v in G . Whenever there is no ambiguity we omit the subscript G and write $d(v)$, $\delta(v)$ and $N(v)$. Two adjacent vertices u, v of G are *twins* if $N_G(u) = N_G(v)$. For a graph G , $\bar{V} \subseteq V(G)$ and $\bar{E} \subseteq E(G)$ we denote by $G[\bar{V}]$ and $G[\bar{E}]$ the subgraphs of G induced by \bar{V} and by \bar{E} , respectively. The *union* of two graphs G, G' is the graph $G \cup G' \stackrel{def}{=} (V(G) \cup V(G'), E(G) \cup E(G'))$.

We emphasize that two graphs G and G' are equal if and only if $V(G) = V(G')$ and $E(G) = E(G')$. Therefore, two isomorphic graphs may be distinct, and they are considered as such in the counting arguments in our proofs.

A graph $G = (V, E)$ is *co-bipartite* if V can be partitioned into two cliques. Note that this partition is not necessarily unique. We denote bipartite and co-bipartite graphs as triples (V_1, V_2, E) where

- a) $V_1 \cap V_2 = \emptyset$,
- b) for bipartite graphs V_1 and V_2 are independent sets,
- c) for co-bipartite graphs V_1 and V_2 are cliques,
- d) $E \subseteq V_1 \times V_2$ (in other words E does not contain the cliques' edges).

Unless stated otherwise we assume that G is connected and none of V_1, V_2 is empty.

2.2 Walks, trails, paths, segments, splits

A *walk* in a graph $G = (V(G), E(G))$ is a sequence $P = (e_1, e_2, \dots, e_\ell)$ of edges of $E(G)$ such that there are vertices v_0, v_1, \dots, v_ℓ satisfying $e_i = \{v_{i-1}, v_i\}$ for every $i \in [\ell]$. Clearly, the reverse sequence (e_ℓ, \dots, e_1) is also a walk. The *length* of P is the number ℓ of (not necessarily distinct) edges in the sequence. In this work we do not consider *trivial* (zero length) walks, as such walks do not intersect others. P is *closed* whenever $v_0 = v_\ell$, and *open* otherwise. A *trail* is a walk consisting of distinct edges. A (*simple*) *path* is a walk consisting of distinct vertices except possibly $v_0 = v_\ell$. A contiguous sub-sequence of a walk (resp. trail, path) is termed a sub-walk (resp. sub-trail, sub-path).

Let $P = (e_1, e_2, \dots, e_\ell)$ be a trail with vertices v_0, v_1, \dots, v_ℓ as above. For every $i \in [\ell - 1]$, the triple (e_i, v_i, e_{i+1}) is an *internal point* of P . Whenever P is closed, the triple $(e_\ell, v_\ell = v_0, e_1)$ too, is an internal point of P . We denote the set of internal points of P by $INT(P)$. We say that a vertex v is an internal vertex of P , or equivalently that P crosses v if v is in (i.e. is the second entry of) a triple in $INT(P)$. If P is open $END(P) \stackrel{def}{=} \{v_0, v_\ell\}$ and $TAIL(P) \stackrel{def}{=} \{(e_1, v_0), (e_\ell, v_\ell)\}$ are the sets of *endpoints* of P and *tails* of P , respectively. Given a set \mathcal{P} of trails, we define $TAIL(\mathcal{P}) \stackrel{def}{=} \cup_{P \in \mathcal{P}} TAIL(P)$, $END(\mathcal{P}) \stackrel{def}{=} \cup_{P \in \mathcal{P}} END(P)$ and

$INT(\mathcal{P}) \stackrel{def}{=} \cup_{P \in \mathcal{P}} INT(P)$. For brevity, in the text we often refer to internal points as vertices and to tails as edges. Moreover, when we apply the intersection and union operations on two trails we consider them as sets of internal points and endpoints.

Given two trails $P = (e_1, e_2, \dots, e_\ell)$ and $P' = (e'_1, e'_2, \dots, e'_{\ell'})$, a *segment* of $P \cap P'$ is a maximal trail that constitutes a sub-trail of both P and P' . Since P and P' are trails, $P \cap P'$ is the union of edge disjoint segments. We denote this set by $\mathcal{S}(P, P')$. A tail (resp. endpoint) of a segment is *terminating* if it is in $TAIL(P, P')$ (resp. $END(P, P')$). A *split* of P and P' is a pair of internal points $(e_i, v_i, e_{i+1}), (e'_j, v'_j, e'_{j+1}) \in INT(P) \times INT(P')$ such that $v_i = v'_j$ and $|\{e_i, e_{i+1}\} \cap \{e'_j, e'_{j+1}\}| = 1$. Note that the common edge and the common vertex constitute a non-terminating tail of a segment of $P \cap P'$ and conversely every non-terminating tail of a segment corresponds to a split. We denote by $split(P, P')$ the set of all splits of P and P' , which corresponds to the set of all non-terminating tails of the segments $\mathcal{S}(P, P')$.

$P \parallel P'$ denotes that P and P' are non-intersecting, i.e. *edge-disjoint*. Whenever P and P' intersect and $split(P, P') = \emptyset$ we say that P and P' are *non-splitting* and denote this by $P \sim P'$. Note that in this case all the endpoints of the segments are terminating. As there are at most 4 such endpoints $1 \leq |\mathcal{S}(P, P')| \leq 2$. Moreover, in this case $P \cup P'$ is a trail. When $split(P, P') \neq \emptyset$ we say that P and P' are *splitting* and denote this by $P \approx P'$. Clearly, for any two paths P and P' exactly one of the following holds: $P \parallel P', P \sim P', P \approx P'$. See Figure 1 for an example.

A *bend* of a trail P in a grid H is an internal point of P whose edges have different directions, i.e. one vertical and one horizontal.

2.3 The EP and ENP graph families

Let \mathcal{P} be a set of trails in a graph H . The graphs $EP(\mathcal{P})$ and $ENP(\mathcal{P})$ are such that $V(ENP(\mathcal{P})) = V(EP(\mathcal{P})) = V$ and there is a one to one correspondence between \mathcal{P} and V , i.e. $\mathcal{P} = \{P_v : v \in V\}$. Given two trails $P_u, P_v \in \mathcal{P}$, $\{u, v\}$ is an edge of $EP(\mathcal{P})$ if and only if P_u and P_v have a common edge. Moreover, $\{u, v\}$ is an edge of $ENP(\mathcal{P})$ if and only if $P_u \sim P_v$. Clearly, $E(ENP(\mathcal{P})) \subseteq E(EP(\mathcal{P}))$. A graph G is ENP if there is a graph H and a set of paths \mathcal{P} of H such that $G = ENP(\mathcal{P})$. In this case $\langle H, \mathcal{P} \rangle$ is an ENP *representation* of G . Two representations are *equivalent* if they are representations of the same graph.

Let $\langle H, \mathcal{P} \rangle$ be a representation of an ENP graph G . $\mathcal{P}_e \stackrel{def}{=} \{P \in \mathcal{P} \mid e \in P\}$ denotes the set of trails of \mathcal{P} containing the edge e of H . For a subset $S \subseteq V(G)$ we define $\mathcal{P}_S \stackrel{def}{=} \{P_v \in \mathcal{P} : v \in S\}$. When H is a tree (resp. grid) $EP(\mathcal{P})$ is an EPT (resp. EPG) graph, and $ENP(\mathcal{P})$ is an ENPT (resp. ENPG) graph; these graphs are denoted also as $EPT(\mathcal{P})$, $EPG(\mathcal{P})$, $ENPT(\mathcal{P})$ and $ENPG(\mathcal{P})$. Unless otherwise stated, without loss of generality we assume that H is a complete graph, as any non-edge of H can be substituted with an edge without affecting $ENP(\mathcal{P})$.

Lemma 1. *Let K be a clique of an ENP graph. Then one of the following holds:*

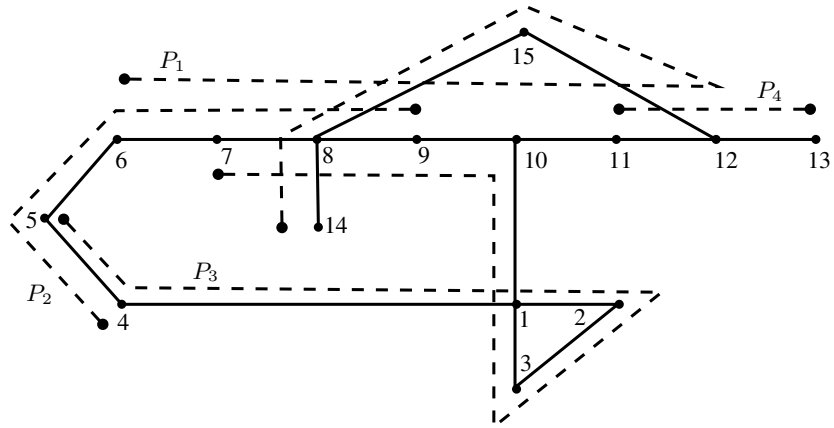


Fig. 1: The pairs of paths (P_2, P_4) and (P_3, P_4) do not share a common edge, therefore $P_2 \parallel P_4$ and $P_3 \parallel P_4$. P_1 and P_4 have a common edge $\{11, 12\}$, and 12 is a common internal vertex constituting a split of P_1 and P_4 , therefore $P_1 \approx P_4$. Similarly P_1 and P_3 have three common edges and 10 is a split vertex of P_1 and P_3 , therefore $P_1 \approx P_3$. P_1 and P_2 have three common edges but no splits, then $P_1 \sim P_2$. The same holds for the pair (P_2, P_3) . However, we note that in the latter case the common edges are separated into two segments. The vertex 8 is not a split point of P_1 and P_2 because the only internal points of P_1 involving this vertex are $(e_{7,8}, 8, e_{7,9}), (e_{14,8}, 8, e_{8,15})$, and the only internal point of P_2 involving it is $(e_{7,8}, 8, e_{7,9})$. Moreover, $|\{e_{7,8}, e_{7,9}\} \cap \{e_{7,8}, e_{7,9}\}| = 2 \neq 1$ and $|\{e_{7,8}, e_{7,9}\} \cap \{e_{14,8}, e_{7,15}\}| = 0 \neq 1$.

- i) $\cup \mathcal{P}_K$ is an open trail and $\cap \mathcal{P}_K \neq \emptyset$.
- ii) $\cup \mathcal{P}_K$ is a closed trail, and for every edge e of $\cup \mathcal{P}_K$ there exists an edge e' of $\cup \mathcal{P}_K$ such that $P \cap \{e, e'\} \neq \emptyset$ for every path $P \in \mathcal{P}_K$.

Proof. If $\cup \mathcal{P}_K$ contains two internal points (e_1, v, e_2) and (e'_1, v, e'_2) such that $|\{e_1, e_2\} \cap \{e'_1, e'_2\}| = 1$. Then there are two paths $P, P' \in \mathcal{P}_K$ such that $(e_1, v, e_2) \in INT(P)$ and $(e'_1, v, e'_2) \in INT(P')$. Therefore $split(P, P') \neq \emptyset$ and $P \approx P'$ contradicting the fact that K is a clique. Therefore $\cup \mathcal{P}_K$ is a disjoint union of trails. However, if $\cup \mathcal{P}_K$ contains two disjoint trails, then $P \parallel P'$ for any two paths P, P' from two distinct trails of $\cup \mathcal{P}_K$, contradicting the fact that K is a clique. Therefore $\cup \mathcal{P}_K$ is one trail.

- i) If $\cup \mathcal{P}_K$ is an open trail, then we can embed it on the real line, so that the individual paths of \mathcal{P}_K are intervals on the real line. Then, the result follows from the Helly property of intervals.
- ii) If $\cup \mathcal{P}_K$ is a closed trail, let e be any edge of this trail. Let \mathcal{P}_e be the set of trails in \mathcal{P}_K containing the edge e . Then $\cup(\mathcal{P}_K \setminus \mathcal{P}_e)$ is an open trail. By the previous result there is an edge e' of this trail that is contained of all these paths. Therefore, all the paths of \mathcal{P}_K contain either e or e' .

□

Based on this lemma we say that K is an *open* (resp. *closed*) clique if $\cup \mathcal{P}_K$ is an open (resp. closed) trail. It will be convenient to use the following corollary of Lemma 1 in order to unify the two cases into one.

Corollary 1. *Let K be a clique of an ENP graph, with a representation $\langle H, \mathcal{P} \rangle$. Then $\cup \mathcal{P}_K$ is a sub-trail of a closed trail in which for every edge e there exists an edge e' such that $P \cap \{e, e'\} \neq \emptyset$ for every $P \in \mathcal{P}_K$.*

We denote a closed trail whose existence is guaranteed by Corollary 1 as $\mathcal{P}^{(K)}$. Note that $\mathcal{P}^{(K)}$ consists of at most one edge more than $\cup \mathcal{P}_K$

3 ENP

In this section we show that a) the family of ENP graphs does not include all co-bipartite graphs (Theorem 1), and b) the family of ENP graphs coincides with the family of ENPG graphs (Theorem 2).

We proceed with definitions regarding the relationship between the representations of two cliques. Given two vertex disjoint cliques K, K' of an ENP graph G with a representation $\langle H, \mathcal{P} \rangle$, we denote $\mathcal{S}(K, K') \stackrel{def}{=} \mathcal{S}(\mathcal{P}^{(K)}, \mathcal{P}^{(K')})$. A segment $S \in \mathcal{S}(K, K')$ is *quiet in K* if does not contain tails of paths of \mathcal{P}_K , and *busy in K* , otherwise. The importance of segments stems from the following observation:

Observation 31 *Consider a pair of trails $(P, P') \in \mathcal{P}_K \times \mathcal{P}_{K'}$. Then,*

- i) $P \cap P' \subseteq \cup \mathcal{S}(K, K')$, and

ii) $split(P, P')$ corresponds to the set of all non-terminating segment endpoints crossed by both P and P' .

$\mathcal{C}_{n,n}$ is the set of all co-bipartite graphs $G(K, K', E)$ where $K = [n]$ and $K' = \{i' : i \in [n]\}$. The following lemma bounds the number of graphs of this form as a function of the number of segments.

Lemma 2. *For any $s \geq 0$, the number of graphs $G = (K, K', E) \in \mathcal{C}_{n,n}$ with a representation $\langle H, \mathcal{P} \rangle$ such that $|\mathcal{S}(K, K')| \leq s$ is at most $(4n)!((2n + 2s)!)^2$.*

Theorem 1. CO-BIPARTITE $\not\in$ ENP.

Proof. $|\mathcal{C}_{n,n}| = 2^{n^2}$ because there are n^2 pairs of vertices $(v, v') \in K \times K'$, and for every such pair, either $(v, v') \in E$ or $(v, v') \notin E$. In the rest of the proof we show that every $G \in \mathcal{C}_{n,n}$ has a representation $\langle H', \mathcal{P}' \rangle$ for which $s = |\mathcal{S}(K, K')| \leq 12n$. By Lemma 2, the number of such representations and therefore $|\mathcal{C}_{n,n} \cap \text{ENP}|$ is at most $(4n)!((2n + 2s)!)^2 \leq (4n)!((2n + 24n)!)^2 = (4n)!(26n)!(26n)!$. Therefore, $\log |\mathcal{C}_{n,n} \cap \text{ENP}| = O(n \log n)$, whereas $\log |\mathcal{C}_{n,n}| = n^2$ concluding the proof. It remains to show that G has a representation with $s \leq 12n$ segments.

The number of busy segments of $\mathcal{S}(K, K')$ is at most $4n$, because $|END(\mathcal{P}_K)| = 2n$ and an endpoint can be in at most 2 segments. We now bound the number of quiet segments of $\mathcal{S}(K, K')$. Consider two endpoints from $END(\mathcal{P}_K)$ that are consecutive on $\mathcal{P}^{(K)}$ and let P be the sub-trail of $\mathcal{P}^{(K)}$ between these two endpoints. By this choice, every trail of \mathcal{P}_K intersecting P includes P . Let $\bar{\mathcal{S}}$ be the set of segments S that are sub-trails of P (thus $V(S) \subseteq INT(P)$). Suppose that $|\bar{\mathcal{S}}| > 4$. Consider the two edges $e_{a'}$ and $e_{b'}$ of $\mathcal{P}^{(K')}$ whose existence are guaranteed by Corollary 1. These two edges divide $\mathcal{P}^{(K')}$ into at most two open trails. One of these open trails contains (at least) 3 segments $S_1, S_2, S_3 \in \bar{\mathcal{S}}$ where the indices are in the order they appear on this open trail from $e_{a'}$ to $e_{b'}$ (see Figure 2). Let also v_{i1}, v_{i2} be the endpoints of S_i in the same order. We claim that the representation obtained by adding to H a new vertex x and two edges $\{v_{21}, x\}, \{x, v_{22}\}$ and finally modifying all the trails intersecting P (that therefore include S_2) so that the segment S_2 is replaced by the trail $(\{v_{21}, x\}, \{x, v_{22}\})$ is an equivalent representation. Clearly, any trail that does not intersect S_2 is not affected by this modification. Consider two trails P_v and $P_{v'}$ such that $(v, v') \in K \times K'$ and both intersect S_2 . P_v includes P and therefore includes all the vertices of S_2 , in particular crosses v_{21} and v_{22} . On the other hand, by Corollary 1, $P_{v'}$ contains at least one of $e_{a'}$ and $e_{b'}$. Without loss of generality let $e_{b'} \in P_{v'}$. Then, v_{22} is an internal vertex of $P_{v'}$. We conclude that $v_{22} \in split(P_v, P_{v'})$, i.e. $(v, v') \notin E(G)$. After the modification, we have $v_{31} \in split(P_v, P_{v'})$, thus (v, v') is not an edge of the resulting graph. Therefore, the new representation is equivalent to $\langle H, \mathcal{P} \rangle$. After this modification, S is not a segment of $\mathcal{S}(K, K')$ and the new representation has one segment less. We can apply this transformation until we get an equivalent representation $\langle H', \mathcal{P}' \rangle$ having at most 4 quiet segments between every two consecutive vertices of $END(\mathcal{P}_K)$. In other words, $\langle H', \mathcal{P}' \rangle$ has at most $8n$ quiet

segments of $\mathcal{S}(K, K')$. Adding the at most $4n$ busy segments, we conclude that $s \leq 12n$. \square

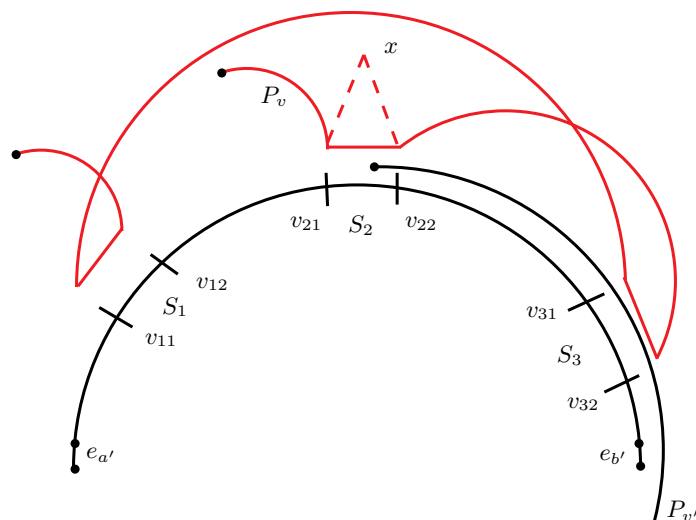


Fig. 2: Getting a representation with at most $8n$ quiet segments in the proof of Theorem 1. Whenever there are 3 segments on one side of the closed trail, the middle one can be bypassed.

Theorem 2. ENP=ENPG

Proof. Clearly, ENPG \subseteq ENP. To prove the other direction, consider an ENP graph G with a representation $\langle H, \mathcal{P} \rangle$. We transform this representation into an equivalent ENPG representation, in three steps. In the first step, we obtain an equivalent representation $\langle H', \mathcal{P}' \rangle$ where H' is planar. In the second step, we transform $\langle H', \mathcal{P}' \rangle$ to an equivalent representation $\langle H'', \mathcal{P}'' \rangle$ where H'' is planar and $\Delta(H'') \leq 4$. Finally, we transform $\langle H'', \mathcal{P}'' \rangle$ to an ENPG representation.

The host graph H can be embedded in a plane such that the vertices are mapped to a set of points in general position on the plane and the edges are drawn as straight line segments. Specifically, no three points are co-linear and no three segments intersect at one point. Note that the mapping of the edges might intersect, however as the points are in general position, we can assume that no three edges intersect at the same point. For every intersection point of two edges e, e' , we can add a vertex v to H and subdivide the edges e and e' (and consequently the paths in \mathcal{P} containing e and e') such that the resulting 4 edges are incident to v . Every pair of paths P, P' that include e and e' respectively now intersect at v . However as we are not concerned with vertex intersections, the resulting representation is a representation of G . We continue in this way until

all intersection points are replaced by a vertex. The graph H' of the resulting representation $\langle H', \mathcal{P}' \rangle$ is clearly planar.

We now transform the representation $\langle H', \mathcal{P}' \rangle$ to a representation $\langle H'', \mathcal{P}'' \rangle$ where H'' is planar with maximum degree at most 4. We start with $\langle H'', \mathcal{P}'' \rangle = \langle H', \mathcal{P}' \rangle$, and as long as there is a vertex v with $d_{H''}(v) > 4$, we eliminate such a vertex without introducing new vertices of degree more than 4 using the following procedure described in Figure 3: we number the edges incident to v as e_1, e_2, \dots, e_{d_v} in counterclockwise order according to the planar embedding of H' . Then e_1 and e_{d_v} are in the same face F of H'' . We replace the vertex v with a path of d_v vertices v_1, v_2, \dots, v_{d_v} such that each edges e_i is incident to v_i . Clearly, the constructed path is part of F . We now construct the gadget in Figure 3 within the face F , where every path crossing v from an edge e_i to another edge e_j with $i < j$ is modified as described in the figure. Clearly, we do not lose intersections in this process. On the other hand, every pair of paths that intersect within the gadget have at least one edge incident to v in common before the transformation. Moreover, two paths have a split vertex within the gadget if and only if they split at v before the transformation.

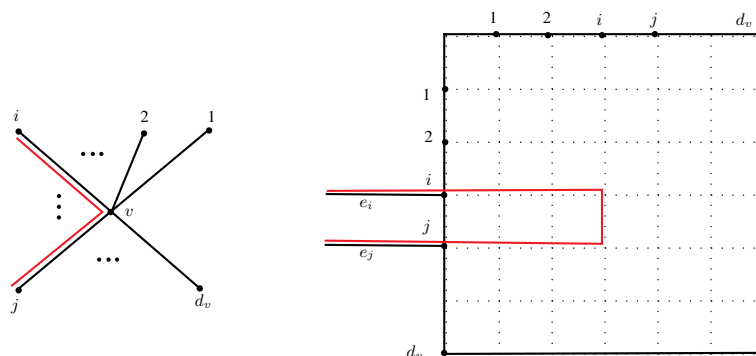


Fig. 3: The gadget used in the second transformation in the proof of Theorem 2

The last step is implied by the following theorem.

Theorem 2.3 [16]: A planar graph H'' with maximum degree at most 4 can be embedded in a grid graph H''' of polynomial size: the vertices u'' of H'' are mapped to vertices u''' of H''' ; each edge $e'' = \{u'', v''\}$ of H'' is mapped to a path e''' between u''' and v''' in H''' ; the intermediate vertices of e''' belong to exactly one such path. Given an embedding of H'' guaranteed by the theorem, we embed every trail $P'' \in \mathcal{P}''$ to a trail P''' of H''' by embedding every edge e'' of it to the corresponding path e''' of H''' . P''' is clearly a walk. P''' a trail, because otherwise there is an edge of H''' that is contained in the embedding of two distinct edges of H'' , contradicting the last guarantee of the theorem. Clearly two trails P''_1, P''_2 of \mathcal{P}'' intersect if and only if the corresponding paths P'''_1, P'''_2 in

\mathcal{P}''' intersect. Moreover a split $(e''_{11}, v'', e''_{12}), (e''_{21}, v'', e''_{22})$ of two paths P''_1, P''_2 is mapped to a split $(e'''_{11}, v''', e'''_{12}), (e'''_{21}, v''', e'''_{22})$ of the corresponding paths P'''_1, P'''_2 and this mapping is one to one. \square

4 B_k -ENPG

In this section we investigate the effect of restricting the number of bends of the paths on the family of ENPG graphs. An ENPG graph is B_k -ENPG if it has an ENPG representation $\langle H, \mathcal{P} \rangle$, in which every path $P \in \mathcal{P}$ has at most k bends. The graph $PM_n \in \mathcal{C}_{n,n}$ is the co-bipartite graph (V, V', E) with $|V| = |V'| = n$ and E constitutes a perfect matching. In what follows we present upper and lower bounds for the bend number of this graph depending on n (lemmata 3 and 6). Using these bounds we show in Theorem 3 that for some infinite and increasing sequence of numbers k_1, k_2, \dots there is a graph in $B_{k_{i+1}}$ -ENPG that is not B_{k_i} -ENPG, thus proving the existence of an infinite hierarchy within the family of ENPG graphs. The following upper bound whose proof can be found in the appendix is implied by the representation in Figure 4.

Lemma 3. $PM_n \in B_{(2(n-1))}$ -ENPG.

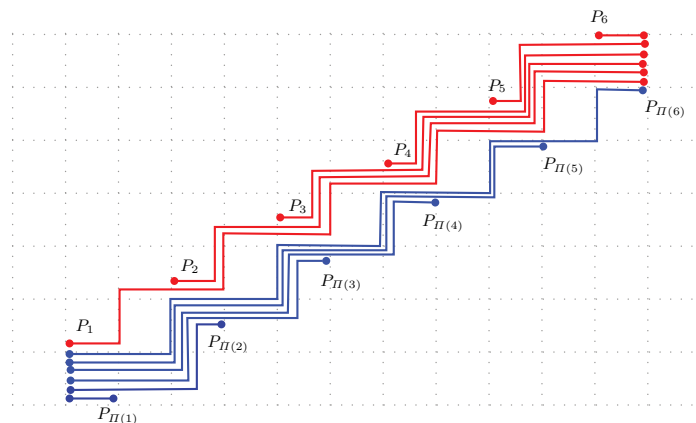


Fig. 4: The ENPG representation of the graph PM_n with $2(n-1)$ bends (proof of Lemma 3)

To prove the lower bound, we consider a given number k of bends and we upper bound the number n such that $PM_n \in B_k$ -ENPG. We first show that a bound on the number of bends implies a bound on the total number of bends in the representation of a clique (Lemma 4). Then we show that this implies an upper bound on the number of segments (Lemma 5), and finally using this bound we bound n from above (Lemma 6).

Lemma 4. *Let K be a complete graph with B_k -ENPG representation $\langle H, \mathcal{P} \rangle$. Then $\cup \mathcal{P}_K$ contains at most $2 \lfloor \frac{(3-\delta_K)k}{2} \rfloor$ bends, where $\delta_K = 1$ when K is an open clique and 0 otherwise.*

Proof. If K is an open clique ($\delta_K = 1$), then there exists an edge e contained in every $P \in \mathcal{P}_K$. e divides $\cup \mathcal{P}_K$ into two trails each of which contains at most k bends. Therefore, $\cup \mathcal{P}_K$ contains at most $2k = 2 \lfloor \frac{(3-\delta_K)k}{2} \rfloor$ bends. If K is a closed clique ($\delta_K = 0$), consider a trail $P = (e_1, \dots, e_\ell)$ of \mathcal{P}_K . Let P_1 (resp. P_ℓ) be a trail containing e_1 (resp. e_ℓ) with the maximum number of edges from $\cup \mathcal{P}_K \setminus P$. $P \cup P_1 \cup P_\ell = \cup \mathcal{P}_K$, because otherwise there is an edge $e \in \cup \mathcal{P}_K \setminus \{P, P_1, P_\ell\}$ that is included in some trail P' that does not contain neither e_1 nor e_ℓ , i.e. does not intersect P , contradicting the fact that K is a clique. We conclude that the number of bends of $\cup \mathcal{P}_K$ is at most $3k$. Moreover, this number is even because $\cup \mathcal{P}_K$ is a closed trail. Therefore the number of bends of $\cup \mathcal{P}_K$ is at most $2 \lfloor \frac{3k}{2} \rfloor = 2 \lfloor \frac{(3-\delta_K)k}{2} \rfloor$. \square

Corollary 2. *A clique K of a B_1 -ENPG graph is an open clique and $\cup \mathcal{P}_K$ has at most 2 bends.*

In the appendix we prove the following lemma

Lemma 5. *Let $G = (K, K', E) \in \mathcal{C}_{n,n}$ with a B_k -ENPG representation $\langle H, \mathcal{P} \rangle$. Then*

- i) $|\mathcal{S}(K, K')| \leq 3k$.*
- ii) Moreover, this upper bound is asymptotically tight: there exist infinitely many pairs k, n with a graph $G \in \mathcal{C}_{n,n} \cap B_k$ -ENPG such that $|\mathcal{S}(K, K')| = 3k - 6$.*

Lemma 6. *If $n > 36k^2 + 6k$, then $\text{PM}_n \notin B_k$ -ENPG.*

Sketch of Proof: Let $\text{PM}_n = (K, K', E)$ and assume by contradiction that PM_n is a B_k -ENPG graph with a corresponding ENPG representation $\langle H, \mathcal{P} \rangle$. Let $\mathcal{S} = \mathcal{S}(K, K')$. By Lemma 5, $|\mathcal{S}| \leq 3k$. Therefore, $|\mathcal{S}|(4 \cdot |\mathcal{S}| + 2) \leq 36k^2 + 6k < n$, i.e. $\frac{n}{|\mathcal{S}|} > 4 \cdot |\mathcal{S}| + 2$.

For an edge $e = (v, v') \in E$ we say that e is *realized* in segment $S \in \mathcal{S}$ if $P_v \cap P_{v'} \cap S \neq \emptyset$. Every edge $e = (v, v')$ is realized in at least one segment, because otherwise $P_v \cap P_{v'} = \emptyset$, contradicting the fact that $(v, v') \in E$. As $|E| = n$, there is at least one segment S in which $\ell \geq n/|\mathcal{S}| > 4 \cdot |\mathcal{S}| + 2$ edges are realized. As E is a perfect matching, these ℓ edges $E_S \subseteq E$ constitute a perfect matching of the subgraph $G_S = (K_S, K'_S, E_S) = \text{PM}_\ell$ induced by all the endpoints of E_S .

We first show that there is at most one path of \mathcal{P}_{K_S} crossing both endpoints of S . Assume by contradiction that there are two paths $P_u, P_v \in \mathcal{P}_{K_S}$ crossing both endpoints of S . Let u' be the unique neighbor of u in K'_S . Then $P_{u'} \subseteq S$ because otherwise $P_{u'}$ splits from P_u . Therefore, $P_v \supseteq S \supseteq P_{u'}$, i.e. $P_v \sim P_{u'}$ and $(v, u') \in E_S$, contradicting the fact that $G_S = \text{PM}_\ell$. Similarly, there is at most one path from $\mathcal{P}_{K'_S}$ crossing both endpoints of S . We conclude that G_S

contains a subgraph $\bar{G}_S = (\bar{K}_S, \bar{K}'_S, \bar{E}_S) = \text{PM}_{\bar{\ell}}$ where $\bar{\ell} \geq \ell - 2 > 4 \cdot |S|$ with a representation in which every path crosses at most one endpoint of S .

Consider an edge $e = (v, v')$ of \bar{G}_S . P_v and $P_{v'}$ do not cross the same endpoint of S , as otherwise they would split. Let w, w' be the endpoints of S . There is a set \bar{E}_S of $\bar{\ell} \geq \bar{\ell}/2 > 2 \cdot |S|$ edges such that their endpoints induce a graph $\bar{G}_S = (\bar{K}_S, \bar{K}'_S, \bar{E}_S) = \text{PM}_{\bar{\ell}}$, where no path $P_v \in \mathcal{P}_{\bar{K}_S}$ crosses w' and no path $P_{v'} \in \mathcal{P}_{\bar{K}'_S}$ crosses w . All the paths of $\mathcal{P}_{\bar{K}_S}$ (resp. $\mathcal{P}_{\bar{K}'_S}$) have one endpoint in $\text{INT}(S)$. The other endpoint of such a path can be in one of the $|S|$ segments, or between two of them. We classify the paths of $\mathcal{P}_{\bar{K}_S}$ by the location of the other endpoint. As $\bar{\ell} > 2 \cdot |S|$, there are at least two paths P_{v_1} and P_{v_2} in the same category, i.e. crossing exactly the same segment endpoints. For $i \in \{1, 2\}$ let $P_{v'_i}$ be the unique neighbour of v_i in \bar{K}'_S . $C = (v_1, v_2, v'_2, v'_1)$ is a cycle of $G = \text{ENPG}(\mathcal{P})$, therefore it is also a cycle of $\text{EPG}(\mathcal{P})$. We note that every pair of intersecting paths among these 4 paths intersect also in S . Then C is also a cycle of the interval graph obtained by restricting all the trails of $\langle H, \mathcal{P} \rangle$ to S . As an interval graph cannot contain an induced C_4 , it must contain one chord. Assume without loss of generality that (v_1, v'_2) is such a chord. By definition, this chord is not in PM_n . We conclude that $P_{v_1} \approx P_{v'_2}$, implying $\text{split}(P_{v_1}, P_{v'_2}) \neq \emptyset$. As P_{v_1} and P_{v_2} cross exactly the same segment endpoints, we have $\text{split}(P_{v_2}, P_{v'_2}) = \text{split}(P_{v_1}, P_{v'_2}) \neq \emptyset$, contradicting the fact that (v_2, v'_2) is an edge of G . \square

We are now ready to prove the main result of this section.

Theorem 3. *There is an infinite increasing sequence of integers $\{k_i : i = 1, 2, \dots\}$ such that $\text{B}_{k_i}\text{-ENPG} \subsetneq \text{B}_{k_{i+1}}\text{-ENPG}$ for $i \in \{1, 2, \dots\}$.*

Proof. Consider the family of $\text{B}_k\text{-ENPG}$ graphs for some integer $k \geq 1$, and let $G = \text{PM}_{36k^2+6k+1}$. $G \notin \text{B}_k\text{-ENPG}$ by Lemma 6. On the other hand, by Lemma 3, $G \in \text{B}_{72k^2+12k}\text{-ENPG}$. Therefore $\text{B}_k\text{-ENPG} \subsetneq \text{B}_{72k^2+12k}\text{-ENPG}$. We conclude that the infinite sequence defined as $k_{i+1} = 72k_i^2 + 12k_i$ for any $i > 1$ satisfies the claim where $k_1 \geq 0$ is chosen arbitrarily. \square

5 Summary and Future Work

In this work we generalized the family of ENPT graphs to ENP graphs in which the host graphs can be any graph. We showed that without loss of generalization, we can restrict the host graphs to grids. Moreover, this family ENPG does not contain all graphs, as opposed to the family of EPG graphs that contains all graphs. We showed that by restricting the number of bends in the paths, we can define an infinite hierarchy of subfamilies of ENPG.

Although most of the results in this work are proved for cobipartite graphs, the counting arguments used in the proofs of Theorem 1 and Lemma 6 can be extended to the more general case of graphs with a large clique number. This extension is work in progress. Another open question is to find the sequence of the smallest numbers k_i such that $\text{B}_{k_i}\text{-ENPG} \subsetneq \text{B}_{k_{i+1}}\text{-ENPG}$ for every i . In particular, is $\text{B}_1\text{-ENPG} \subsetneq \text{B}_2\text{-ENPG} \subsetneq \dots$? In [2] we studied recognition

problems in given graph pairs, i.e. a pair $((\text{EPT}(\mathcal{P}), \text{ENPT}(\mathcal{P}))$ of graphs that are defined on the same set of vertices. A similar study on EP, ENP graph pairs is another interesting research direction.

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