



**ATLAS  
DCS**

# **The ATLAS Detector Control System**

H.J. Burckhart, J. Cook, F. Varela, B. Varnai, CERN, Geneva, Switzerland  
V. Filimonov, V. Khomoutnikov, Y. Ryabov, PNPI, St.Petersburg, Russia

- **Introduction**
- **Organization**
- **Front-End**
- **Back-End**
- **Read-out Chain**
- **Interaction with DAQ**
- **Operations**
- **Conclusions**

**H.J.Burckhart, ICALEPCS 2003, Gyeongju**

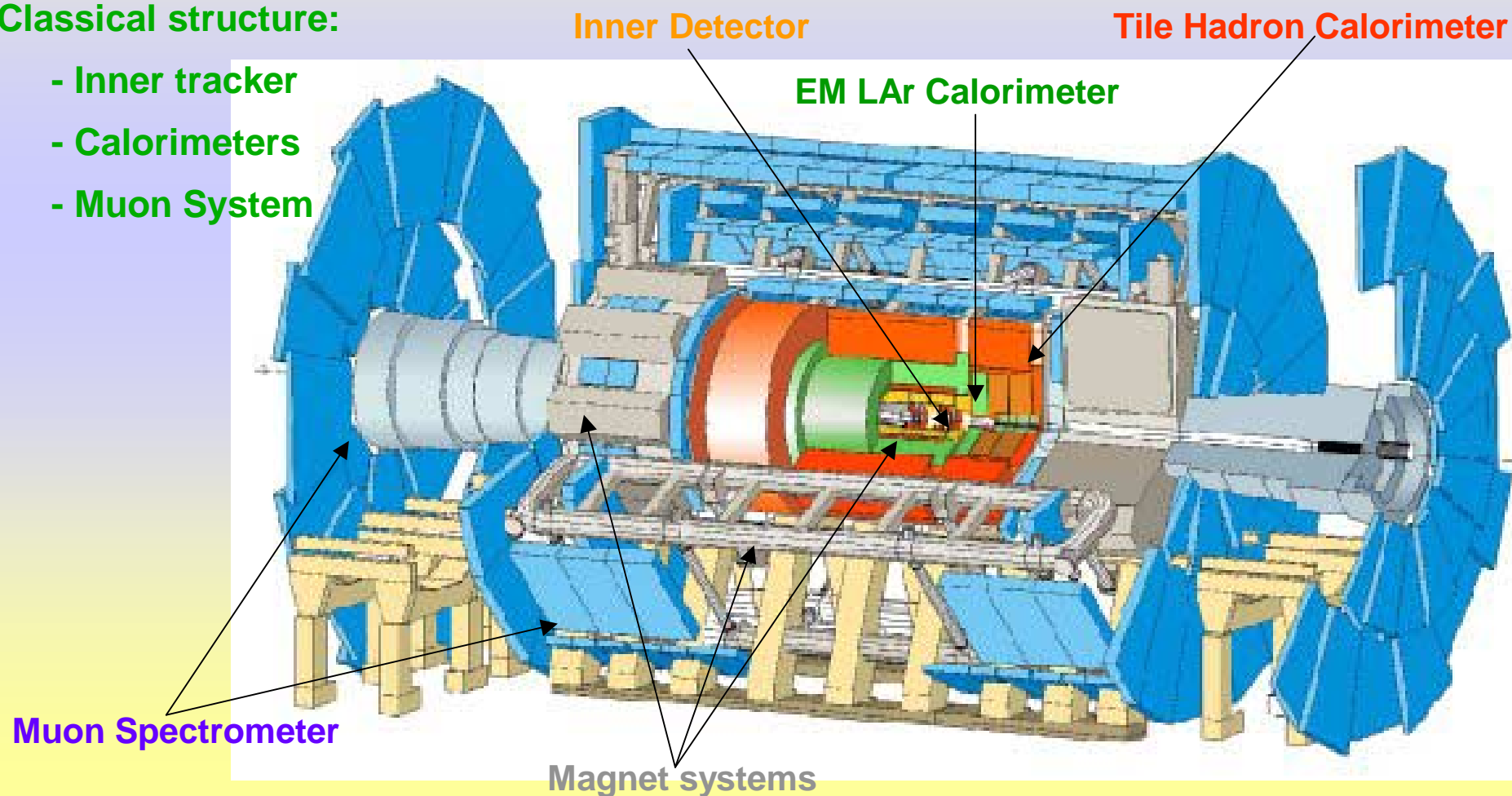


ATLAS  
DCS

# ATLAS (A Toroidal Lhc AparatuS)

- General-purpose particle detector for the p-p collider LHC starting operation in 2007
- 1500 physicist, 150 institutes in 35 countries
- Length 45 m and diameter 25 m.
- Classical structure:

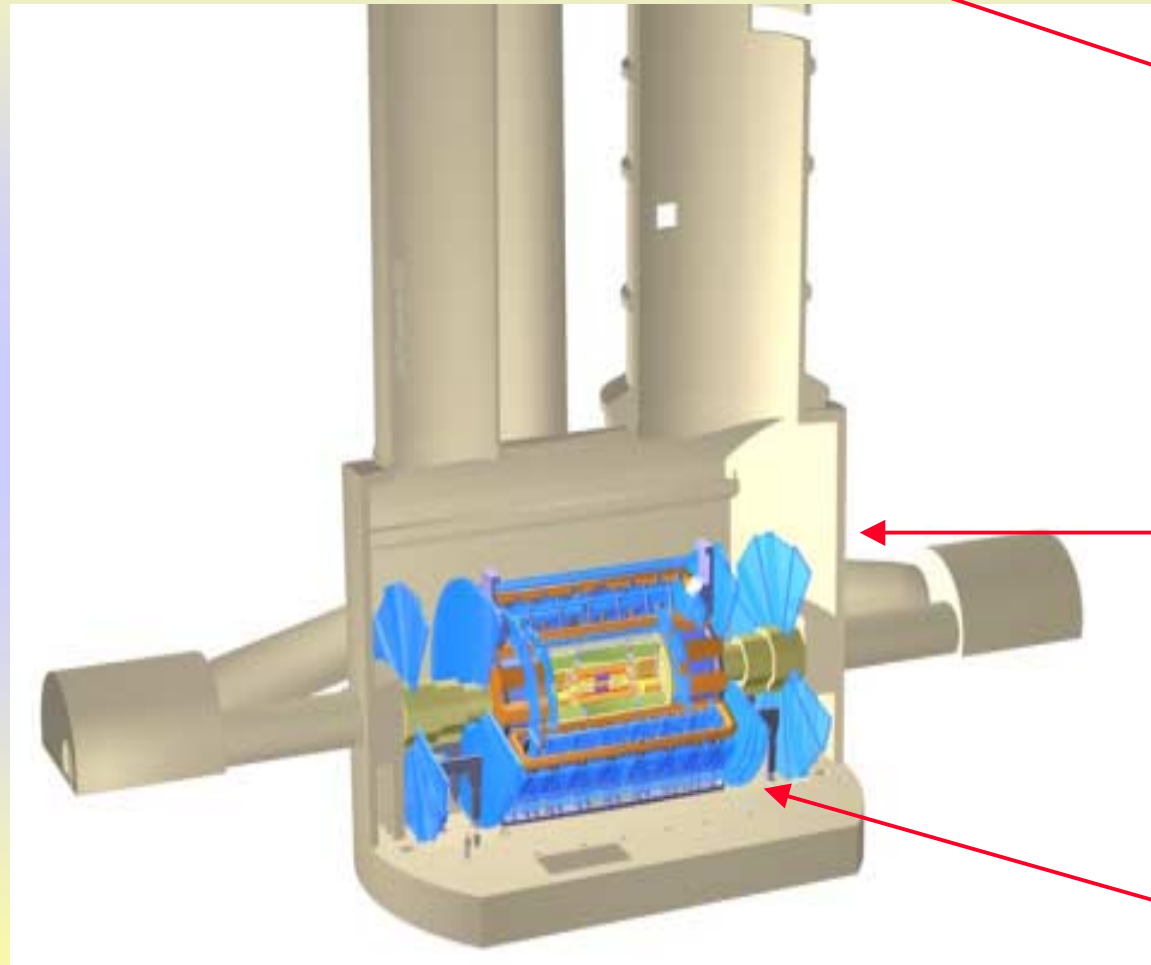
- Inner tracker
- Calorimeters
- Muon System





ATLAS  
DCS

# Experiment Cavern



Control  
room

Electronics  
rooms

Cavern



ATLAS  
DCS

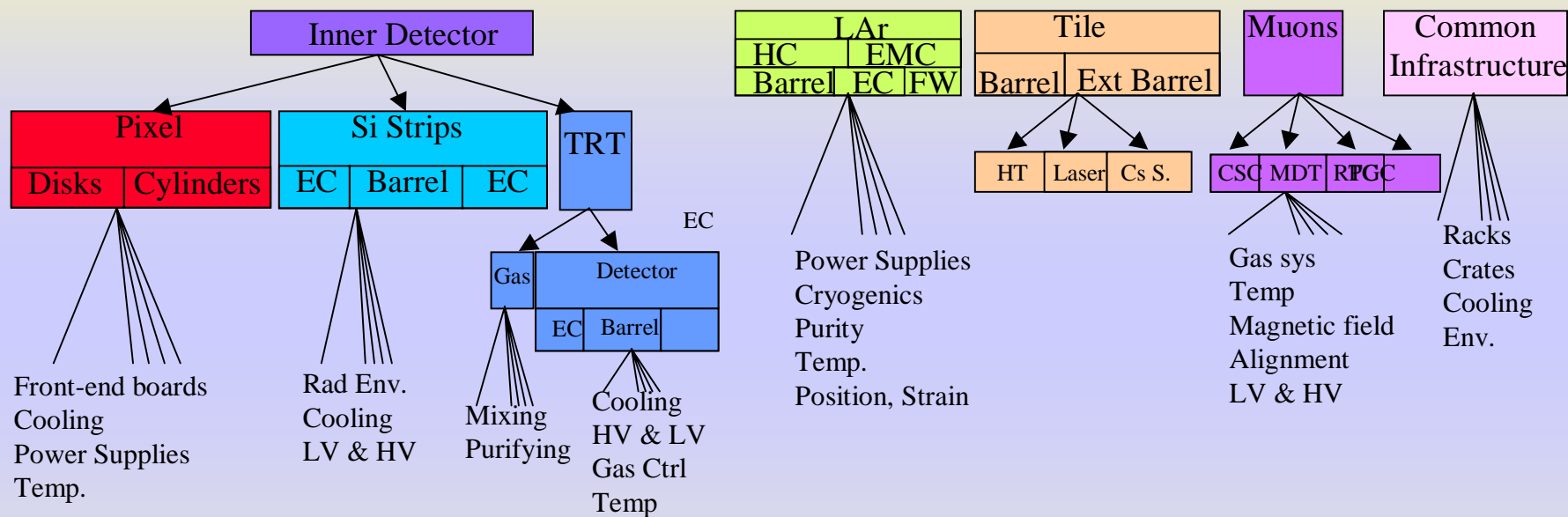
... the „real“ size ...



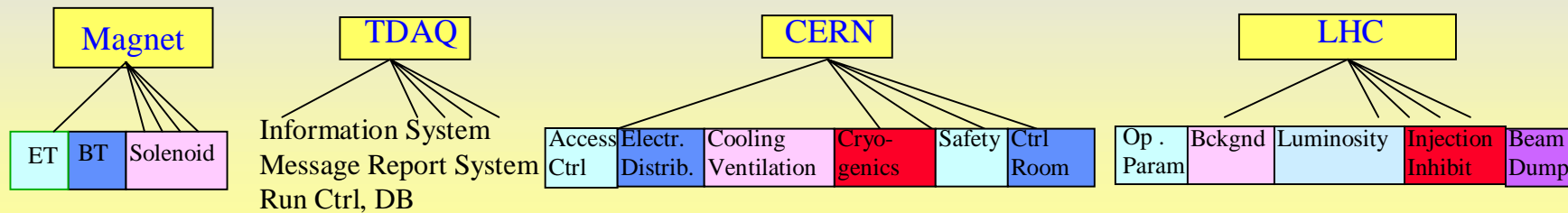


# Logical Structure

## Detector



## External Systems

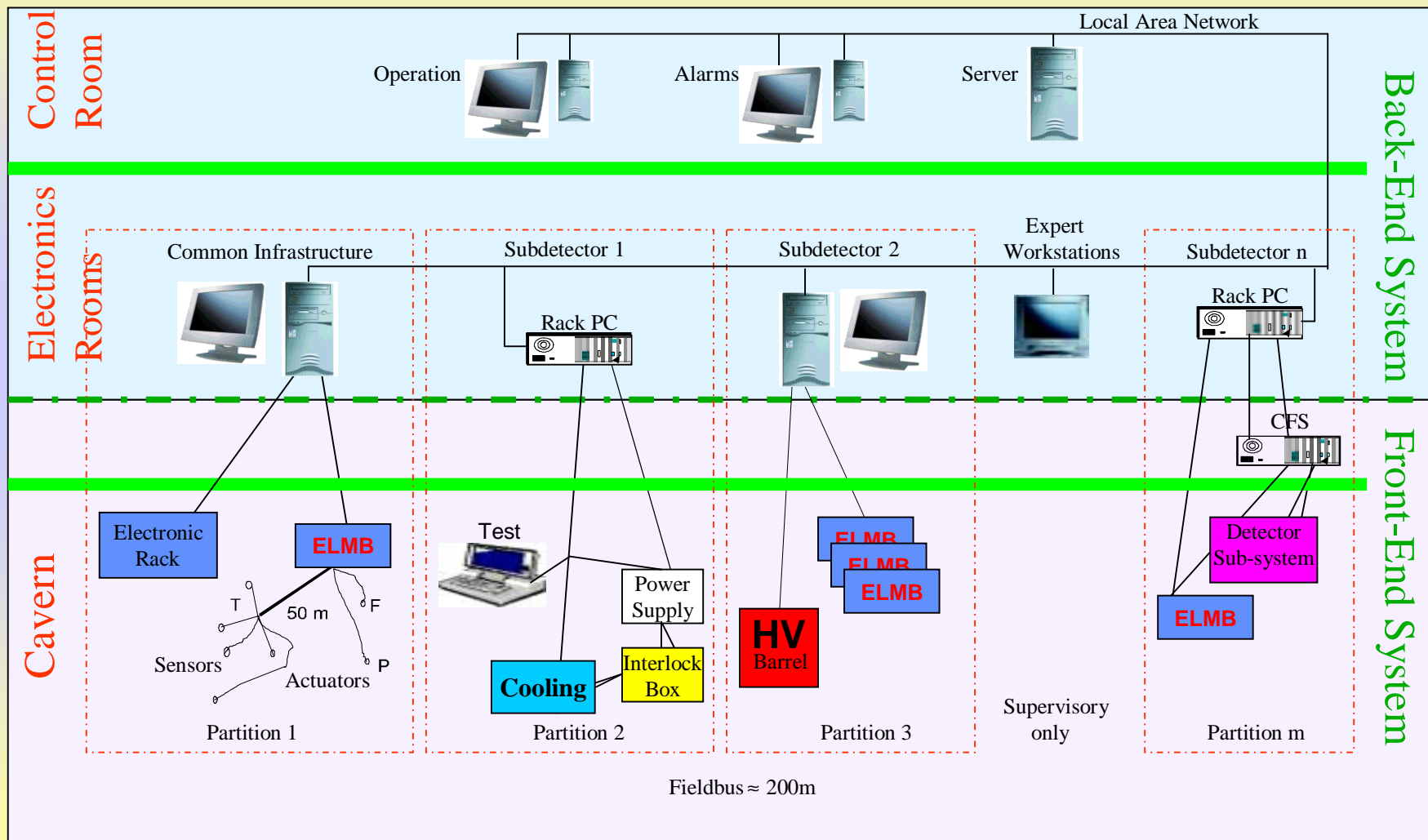




ATLAS  
DCS

# Physical Deployment

Implemented by SCADA PVSS-II (selected by the Joint Controls Project)



From sensors/actuator up to complex computer-based systems e.g. VME, PLC

Specific and general purpose fieldbus I/O modules e.g. Embedded Local Monitor Board



ATLAS  
DCS

# Special Requirements

- u **Development at different places**
- u **Large variety of equipment**
  - n Homogeneity
  - n Flexibility
- u **Types of operation**
  - n Stand-alone for prototype development
  - n Stand-alone sub-detector, sub-system
  - n Integrated operation as detector
  - n Data taking
- u **Adaptability to operational procedures (which are still only partly known to date) Requirements!!!**

**Strategy: Use commercial HW and SW components and JCOP tools to build the control system**



ATLAS  
DCS

# Front-End Systems

## Positioning of Front-End electronics:

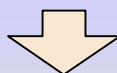
### Difficulties in cavern:

- Ionizing radiation
- Magnetic field up to 1.5 T
- No access during operation
- Limited space available

### Difficulties outside cavern:

Cabling

## Standardization



- **Industrial devices: outside cavern**
  - Define read-out protocol to Back-End (OPC)
- **Purpose-built equipment: in cavern**
  - Use Embedded Local Monitor Board (ELMB) for controls
  - Connect to Back-End via CAN field bus





**ATLAS  
DCS**

## **ELMB**

### Applications:

- u **Monitoring of environment**
  - n Temperature (Pixel, SCT, TRT)
- u **Control of power supplies**
  - n High Voltage (SCT, TRT)
  - n Low Voltage (LAr)
- u **Supervision of cooling**
  - n Pixel, SCT, Tile, TRT
- u **Control of detector elements**
  - n MDT (custom firmware)
  - n TGC (custom firmware)
- u **Control of infrastructure**
  - n Racks (all LHC exp.)
  - n Gas (all LHC exp.)



### Features:

- u 64 channels 16-bit ADC
- u 24 digital I/O ports
- u add-ons via SPI
- u Radiation tolerant HW and SW
- u Read-out conform to CANopen protocol

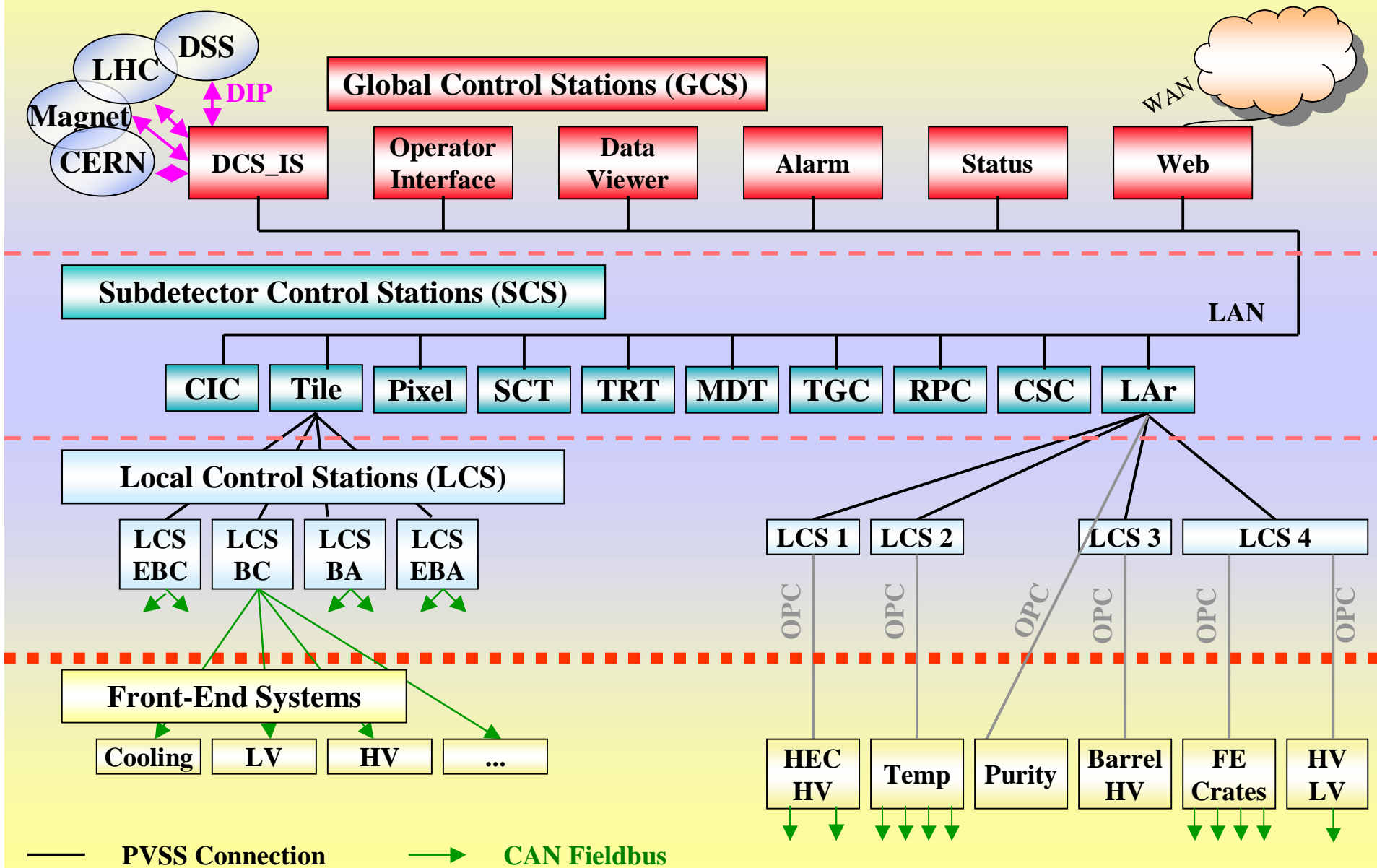
**5000 ELMBs used in ATLAS = 400.000 channels**

(10.000 pieces presently being produced)



ATLAS  
DCS

# Organization Back-End





# Functions GCS

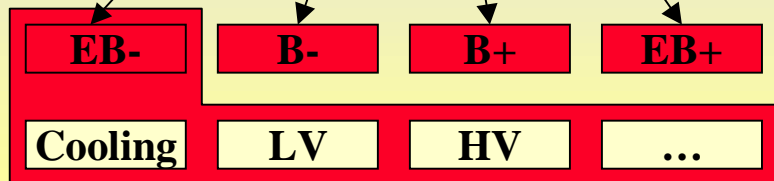
## Global Operation



## Subdetector



## Subsystem



## 1) Operator interactions (Main Control Room)

- § Send commands
- § Logging (Cmds, Incidents, system errors)
- § Browse log files
- § High level monitoring of:
  - § subdetectors
  - § external systems
- § Display (permanently) critical data
- § Alarms (display and acknowledge)
- § Plot any data on request
- § Change parameters (settings)
- § Dis/enabling and masking of any channel
- § Connection to DAQ
- § Export and import data

## 2) Services

- § Interface to Data Bases
- § Logging
- § Web service
- § Interface to GSM
- § Communication to external systems
  - § LHC
  - § CERN services
  - § Magnet
- § Alarms
- § Name server



ATLAS  
DCS

Global Operation

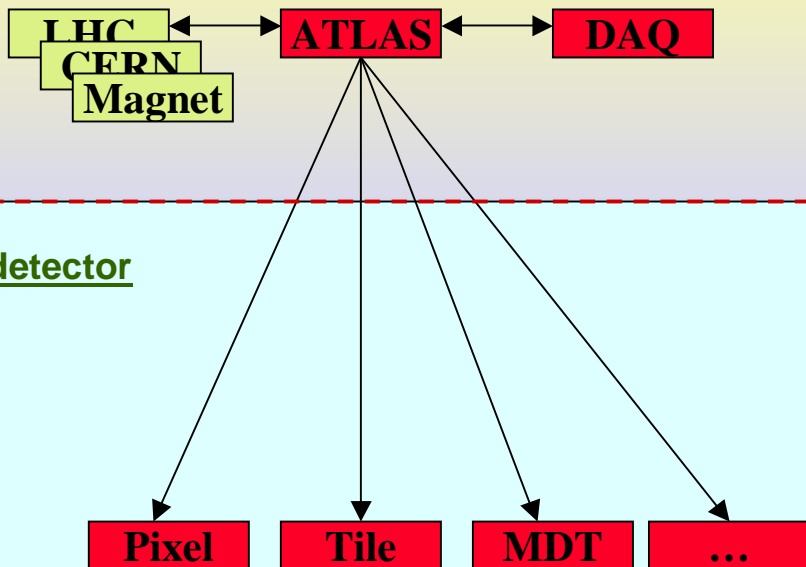
# Functions SCS

## Subdetector Operation (electr. room or surface)

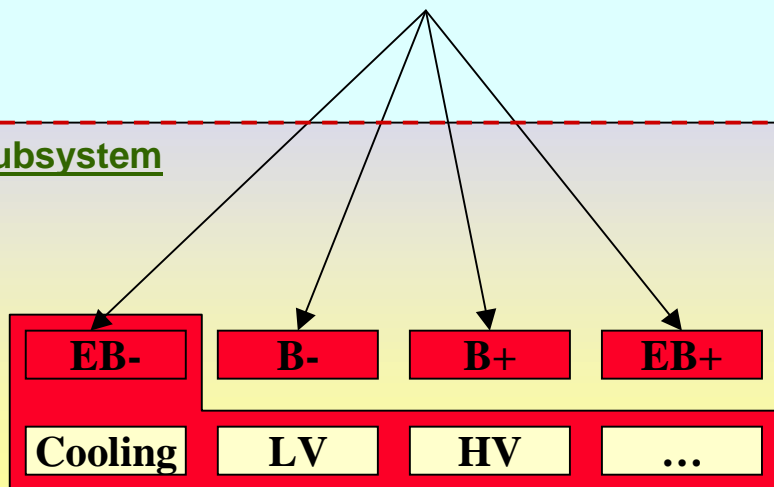
All actions for this subdetector, which are possible from the Global Control Stations, must also be possible from the SCS

- Summary status of this sub-detector
- Archiving of summary information
- Full operation of this sub-detector
- Coordination and synchronization of services or sections of the detector
- Verification of commands
- Logging of commands
- Execution of automatic procedures or actions
- Receive commands from DAQ
- Export data to DAQ
- Send messages to DAQ
- Connect to services in the layer above

## Subdetector



## Subsystem





ATLAS  
DCS

Global Operation

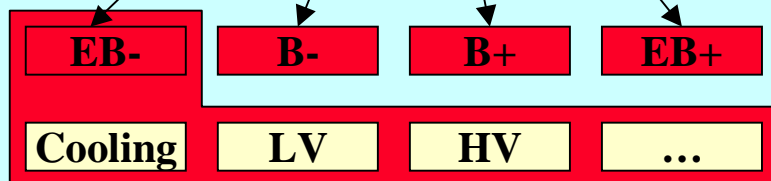
# Functions LCS



Subdetector



Subsystem



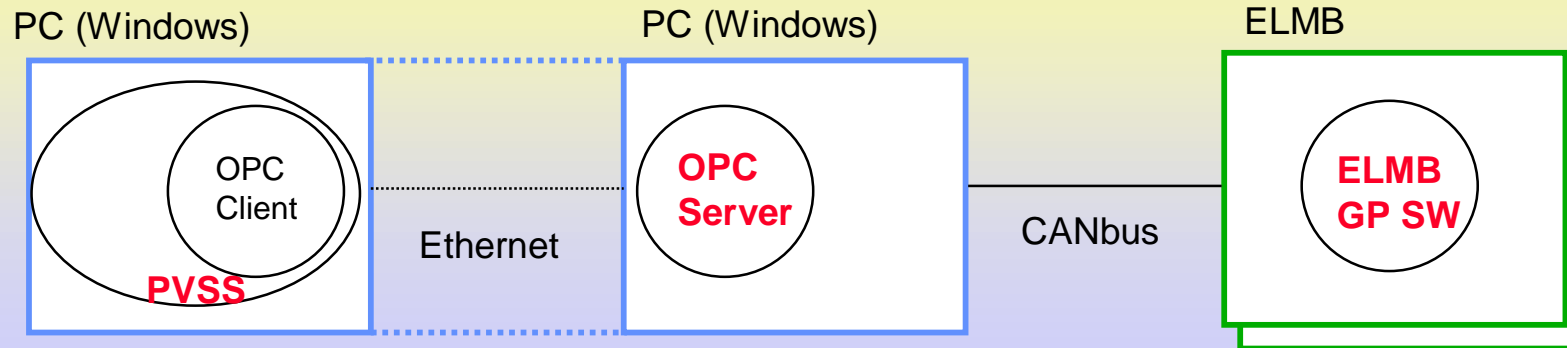
Sub-system Operation (electronics room)

- Hardware monitoring and control
- Readout/Write data from/to the front-end
- Calculations (calibration, conversions, etc.)
- Triggering of automatic actions (inc. feedback)
- Archiving of raw data into the PVSS DB



ATLAS  
DCS

# Read-out Chain



## u PVSS

- n Fine calibration
- n Calculations
- n Detects threshold crossing
  - 1 Warnings, alarms
  - 1 Automatic actions
- n Archiving
- n Data visualization
- n Data exchange with DAQ

## u OPC

- n Conversion to physical units
- n Data filtering

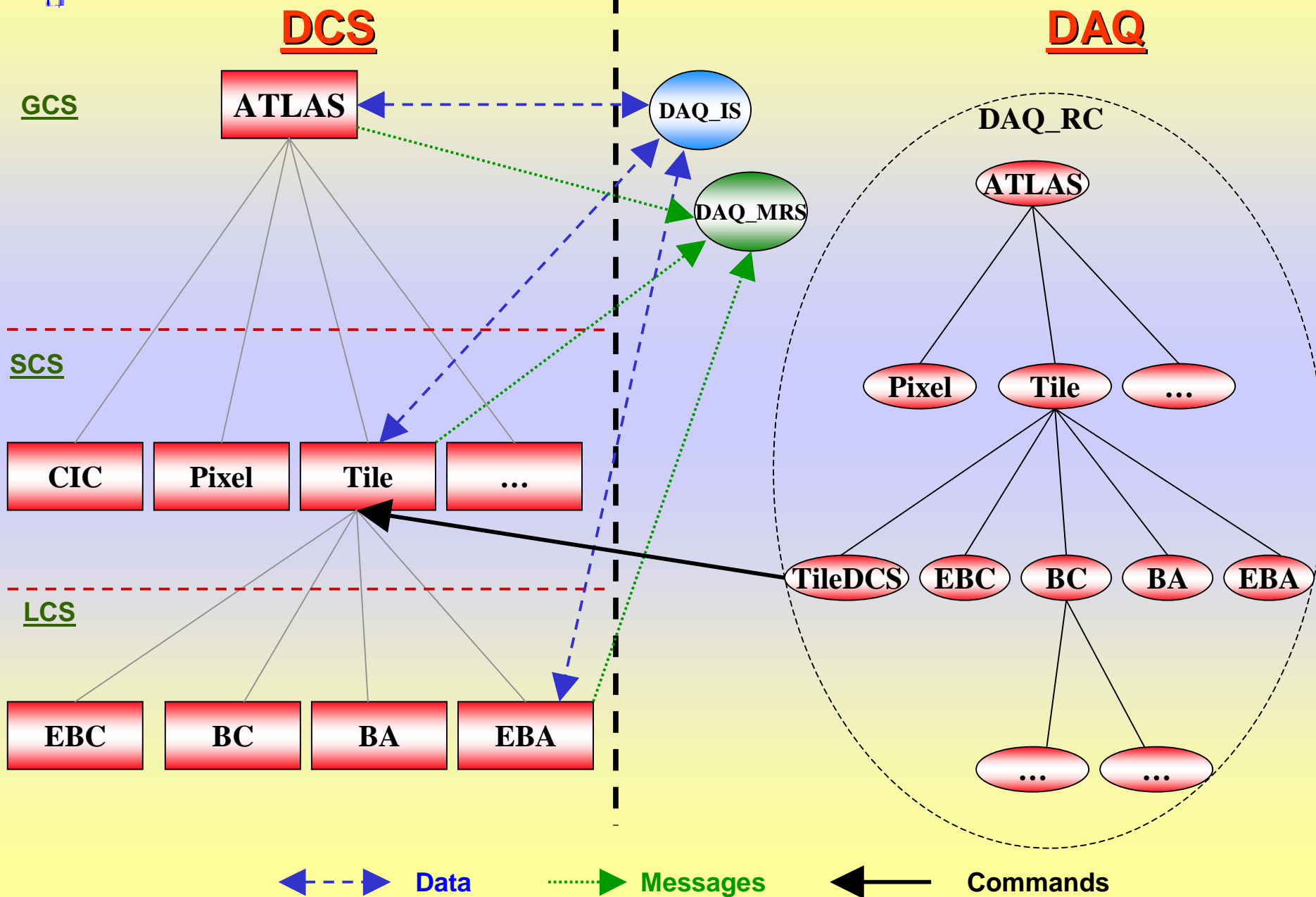
## u ELMB

- n Parameter setting
- n Calibration (<1%)
- n Read-out modes
  - 1 Polling
  - 1 Periodic
  - 1 On change



ATLAS  
DCS

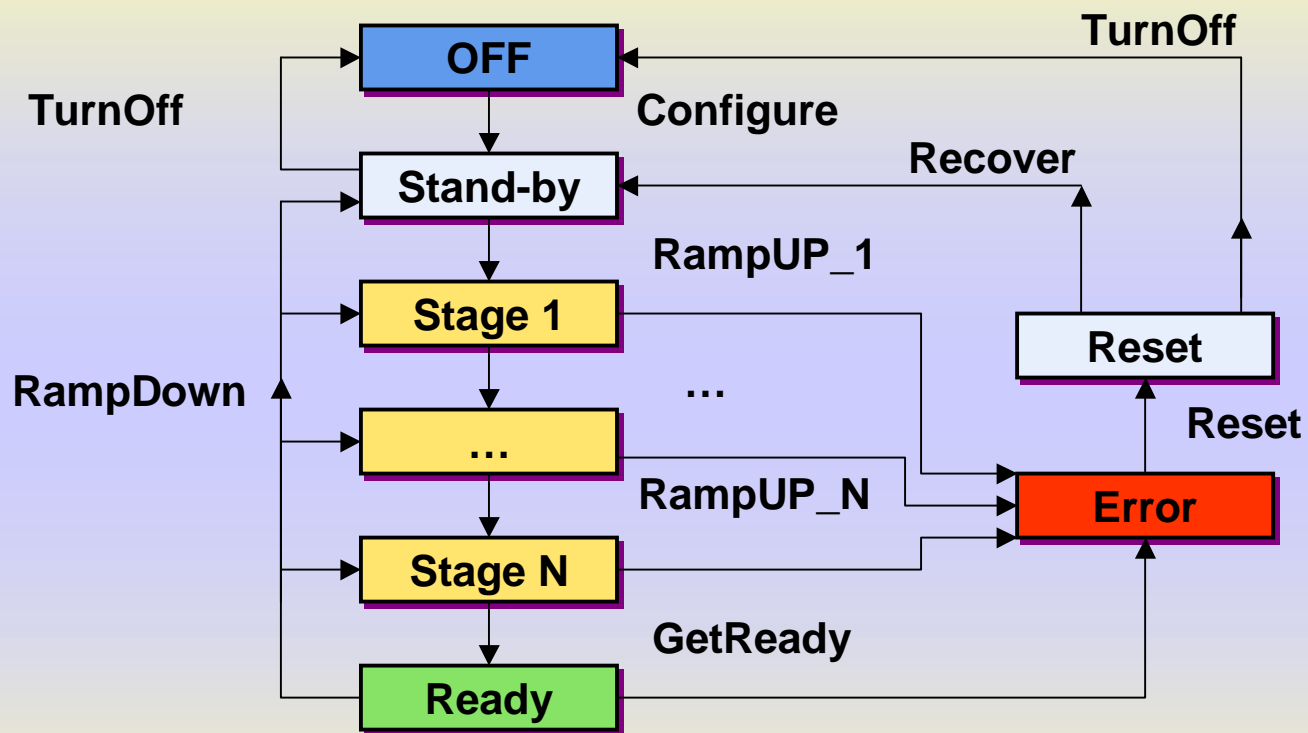
# DCS-DAQ-Connection





ATLAS  
DCS

# FSM of Sub-Detector

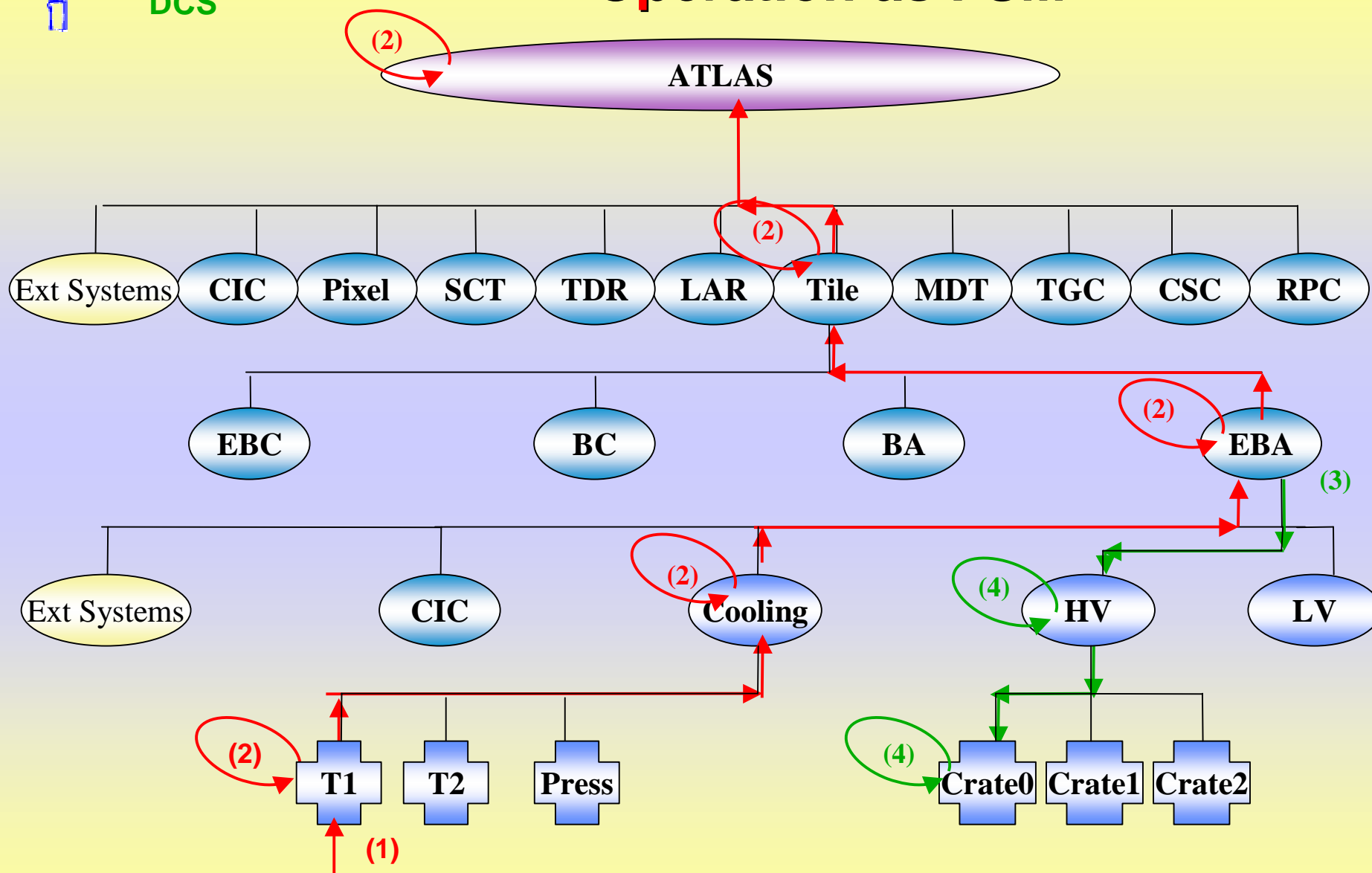






ATLAS  
DCS

# Operation as FSM



(1) Detector overheating

(2) State transition (READY -> Error)

(3) Automatic action on the HV system

(4) State transition (ON -> OFF)



ATLAS  
DCS

# Conclusions

- u **DCS models the hierarchical organization of the ATLAS detector**
- u **The control of the Front-End is standardized**
  - n Protocol for industrial devices
  - n ELMB for purpose-built equipment
- u **The Back-End is implemented with PVSS-II**
  - n Provides interconnection between stations
  - n JCOP adds tools and devices
- u **DCS and DAQ independent systems, but seamless interconnection**
- u **FSM approach very useful**
  - n Allows to model the hierarchy
  - n Flexible rules for operation