

POWER SUPPLIES AND MONITORING EQUIPMENT FOR PULSED MAGNETS

1. Introduction

The general principle of powering and monitoring the pulsed beam transport magnets was described by D. Neet (NPA/Int. 62-9). The greater part of the information contained therein is still valid. However, at that time no operating experience was available. In the meantime modifications and additions were made, that proved to be reliable during the 8 neutrino runs that have been done up to now. These modifications will be described here in detail and a complete and up to date set of circuit diagrams is added. Only these drawings should be used by future users for reference.

The whole setup performed extremely satisfactorily during the neutrino runs. The position of the external beam on target needed readjustment only every few hours. This could easily be made by adjusting the current in the last bending magnet. Over a period of 5 days the current in one of the bending magnets was monitored, giving a difference between highest and lowest recorded value of 2 o/oo. The pulse to pulse accuracy was  $\pm 0.5$  o/oo.

2. Power supplies

The operating principle is that of a feedback control system, in which the difference between a reference input and some function of the controlled variable is used to supply an actuating error signal to the control elements and the controlled system. The amplified error signal is applied in a manner tending to reduce this difference to zero.

The way in which the error signal depends upon the controlled variable determines the behaviour of the system under steady state conditions. The solution of the differential equations of the control system gives the transfer function and its frequency response.

Assuming a sinusoidal input signal, the Laplace transform of the transfer function can then be written as :

$$F = \frac{X_{out}}{X_{in}} = \frac{b_0 + b_1 p + b_2 p^2 + \dots}{a_0 + a_1 p + a_2 p^2 + \dots}$$
 where p is the Laplace operator

The general types of control systems can easily be deduced from this equation

P - element : The output signal is proportional to the input signal

$$F = K = \frac{b_0}{a_0} \text{ (all other terms are zero)}$$

I - element The output signal equals the integral with respect to time of the input signal

$$F = \frac{K_I}{p}, \text{ where } K_I = \frac{b_0}{a_1} \text{ (all other terms are zero)}$$

D - element The output signal equals the derivative with respect to time of the input signal

$$F = K_D \cdot p, \text{ where } K_D = \frac{b_1}{a_0} \text{ (all other terms are zero)}$$

A combination PD would be

$$F = K + K_D \cdot p = K (1 + T_D \cdot p), \text{ where } T_D = \frac{K_D}{K} \text{ is the differentiation time constant}$$

These are only ideal cases, in reality time constants appear that give rise to delays. They present themselves e.g. in the case of a P - element as

$$F = \frac{K}{1 + T_1 \cdot p}, \text{ in which } T_1, \dots \text{ is the time constant for which the inverse transform is } e^{-t/T_1}$$

A PD element as used in our case, then becomes

$$F = K \frac{1 + T_D \cdot p}{1 + T_1 \cdot p}$$

In the Giesenhagen supplies operation is now as follows (see PM 03). A voltage proportional to the instantaneous voltage on the capacitor bank is supplied to one of the inputs of the DC amplifier. In series with this voltage is connected part of the voltage drop in a resistor in the main charging current path, which voltage is therefore proportional to  $C \frac{dV}{dt}$ . A small portion of this voltage is again differentiated by C l. A closer analysis of this circuit will show that the total input voltage can be written as

$$V_X = \frac{b_0 + b_1 p + b_2 p^2}{a_0 + a_1 p} \quad V_{cap} = \frac{K + T_{D1} \cdot p + T_{D2} \cdot p^2}{1 + T_1 p} \cdot V_{cap}$$

where K is the ratio of the voltage divider across the output terminals of the power supply and T are time constants created by  $R_1$ ,  $R_2$ ,  $C_1$ , R and C. The other input of the amplifier is connected to a reference voltage.

As long as  $V_X + V_{ref} > 0$  the D.C. amplifier will show an output voltage that through the power amplifier opens the transducers that control the charging current.

Due to the arrangement of the differentiation of the input signal to the amplifier, the time constants that would otherwise delay this signal with respect to the instantaneous capacitor voltage are now properly counterbalanced, resulting in a system that is completely stable under all load conditions.

The potentiometer that controls the amount of differentiation and therefore the stability should of course be set according to the particular conditions of load and charging current. Diagrams are provided for this (PM 04). It is quite sensitive when a small load and low charging current are used, therefore the charging current should be closely observed in this case, to be certain that no oscillations or small secondary charging peaks occur.

As a rule the current should go down smoothly in about 100 msec at the end of the charging cycle. The shunt signal is available at the terminals on the door.

A second set of diagrams gives the transformer taps to be used for a certain range of output voltage. The bias current of the transducer should be changed simultaneously. To this end a connecting strip inside the supply provides terminals, marked  $X$ ,  $X_4$ ,  $X_3$ ,  $X_2$ ,  $X_1$ , which should be shorted by tags from  $X$  up to the number corresponding to the transformer tapping used.

Although relatively complicated, this principle ensures that the transducer always has the same operating point, thereby providing equal characteristics, for any output voltage.

In practice the output voltage is fixed for a certain application of the power supply, so that transformer tap and bias current are set once and for all.

All diagrams with "number of capacitors" as variable refer of course to the capacitance value with which they were measured i.e. 278  $\mu\text{F}$  each. Whenever other capacitors are used they should of course be redrawn.

### 3. Interlocks

As it became evident that not firing or prefiring of the ignitrons did not result in overloading, but that on the other hand too frequent interruptions of the charging cycle led only to time losses, the interlock was modified so that any ignitron failure did not switch off the power supply but only lights up an indication lamp.

### 4. Timing

In the former setup both kicker magnet and magnetic horn were triggered through delays of about 10 msec from the  $T_0$  pulse. As these delays had an accuracy of about  $1/1000$ , the jitter of the horn pulse with respect to the kicker magnet could amount to 20  $\mu\text{sec}$  on a pulse length of 200  $\mu\text{sec}$ . As this was unacceptable both pulses are now taken from the same point with only an additional 100  $\mu\text{sec}$  delay for the bending magnet.

A simulator was added for testing and running in the absence of P.S. machine pulses.

## 5. Monitoring

A monitoring panel (PM 18) allows display on one oscilloscope of :

- a) Kicker magnet pulse and current in each beam transport magnet
- b) Kicker magnet pulse and current in magnetic horn
- c) Signal induced in the beam current transformer and signal from photo-detector after the horn.

Comparison of these two signals gives a direct check on the efficiency of the horn and the position of the beam on the target.

## 6. Current measuring circuit

The relay that provides the switching action (PM 16) is powered from a higher voltage to minimize the intrinsic delay.

At the input the selector switches both inner conductor and screen of the incoming cable. This prevents closed loops and multiple earthing that give rise to parasites on the current waveform.

## 7. Acknowledgements

R.A. Brown and J.P. Zanasco took care of all the tests and modifications that were found to be necessary.

G. Pluym

/fv

Distribution : (open)

Scientific staff of N.P.A.

PS/4096

1. The first part of the document is a list of names and addresses.

Page 1 of 1

Page 2 of 2

2. The second part of the document is a list of names and addresses.

3. The third part of the document is a list of names and addresses.

4. The fourth part of the document is a list of names and addresses.

5. The fifth part of the document is a list of names and addresses.

6. The sixth part of the document is a list of names and addresses.

7. The seventh part of the document is a list of names and addresses.

8. The eighth part of the document is a list of names and addresses.

Page 3 of 3

9. The ninth part of the document is a list of names and addresses.

10. The tenth part of the document is a list of names and addresses.

11. The eleventh part of the document is a list of names and addresses.

12. The twelfth part of the document is a list of names and addresses.

13. The thirteenth part of the document is a list of names and addresses.

Page 4 of 4

14. The fourteenth part of the document is a list of names and addresses.

15. The fifteenth part of the document is a list of names and addresses.

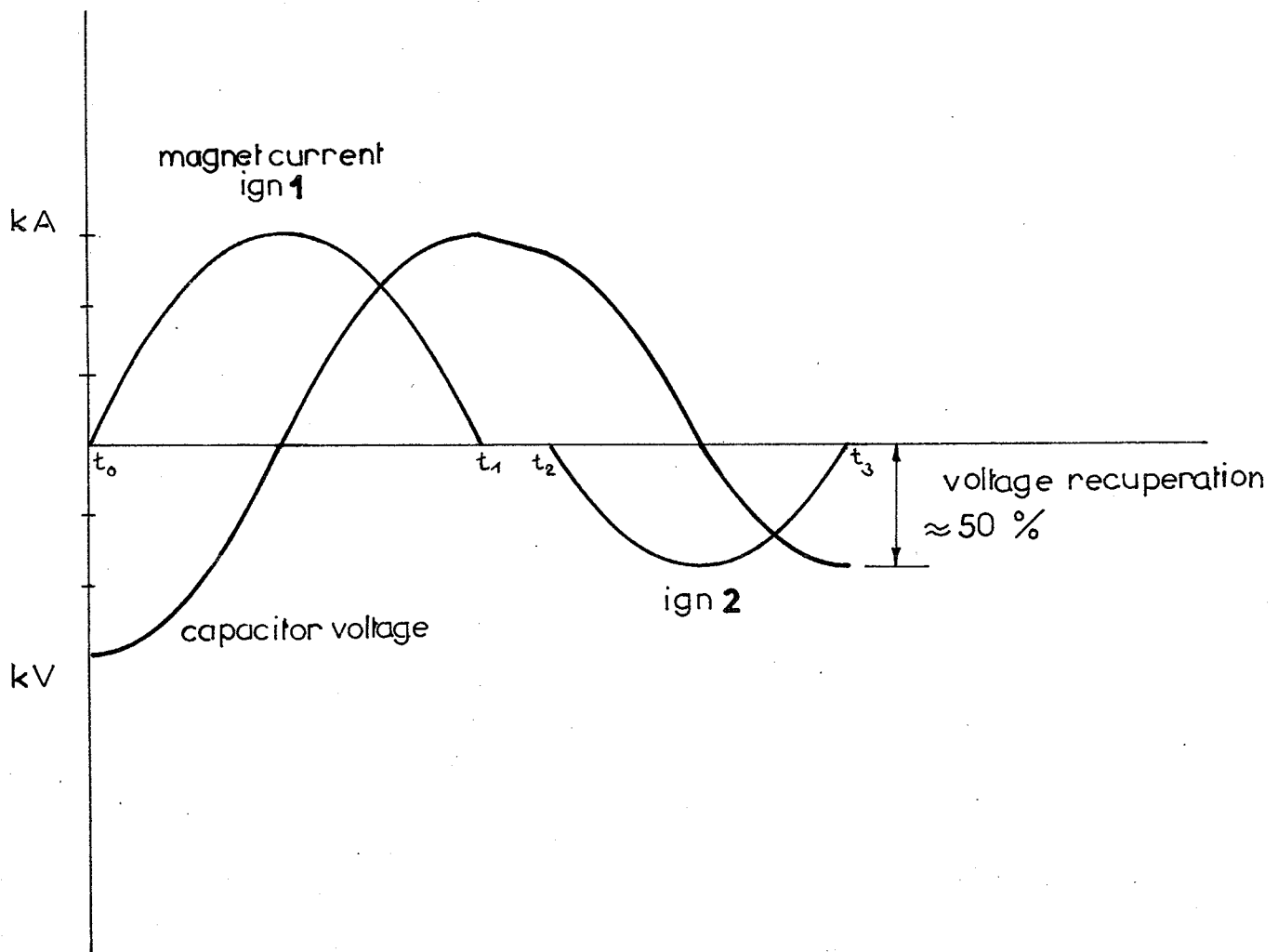
16. The sixteenth part of the document is a list of names and addresses.

17. The seventeenth part of the document is a list of names and addresses.

18. The eighteenth part of the document is a list of names and addresses.

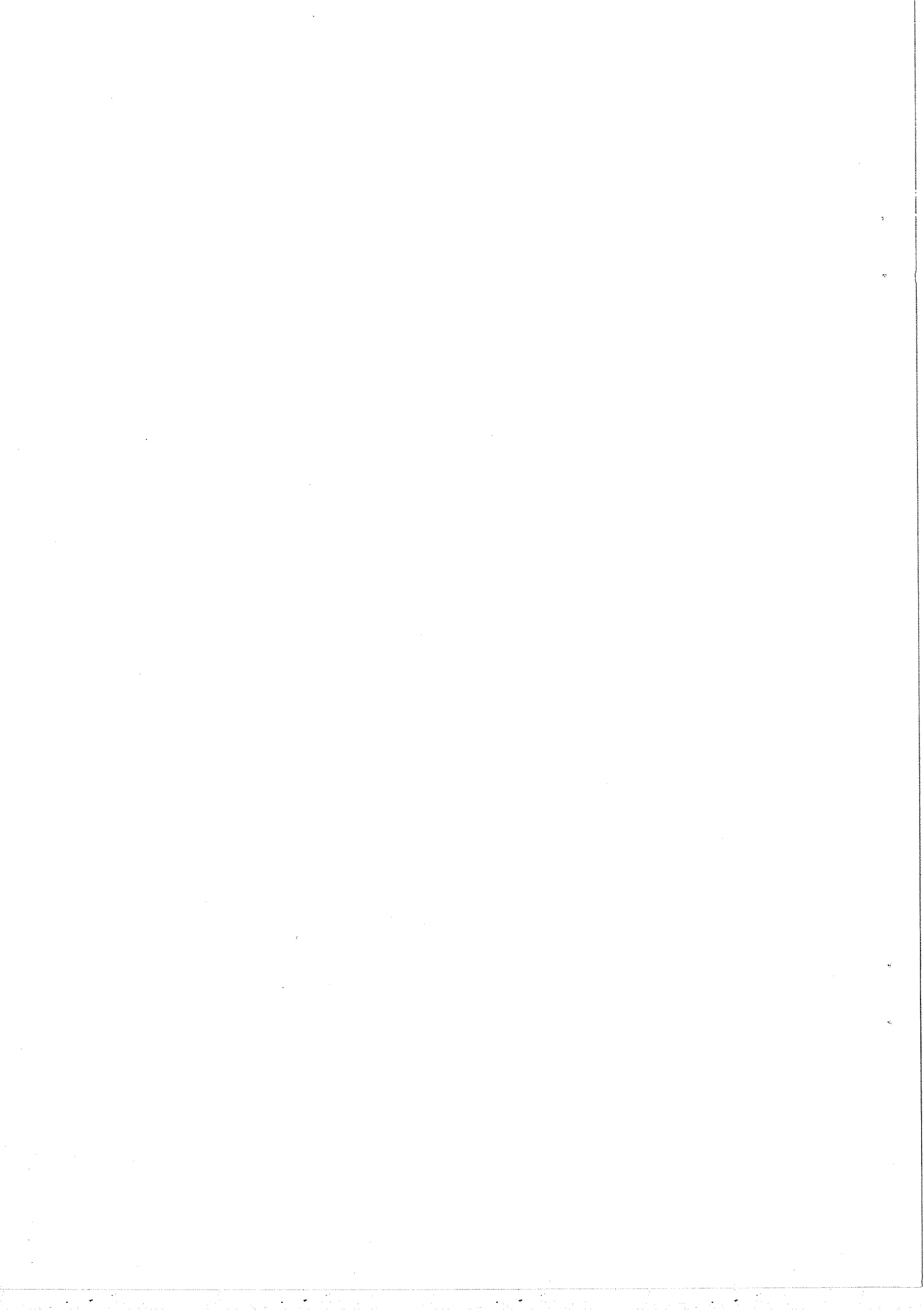
19. The nineteenth part of the document is a list of names and addresses.

20. The twentieth part of the document is a list of names and addresses.

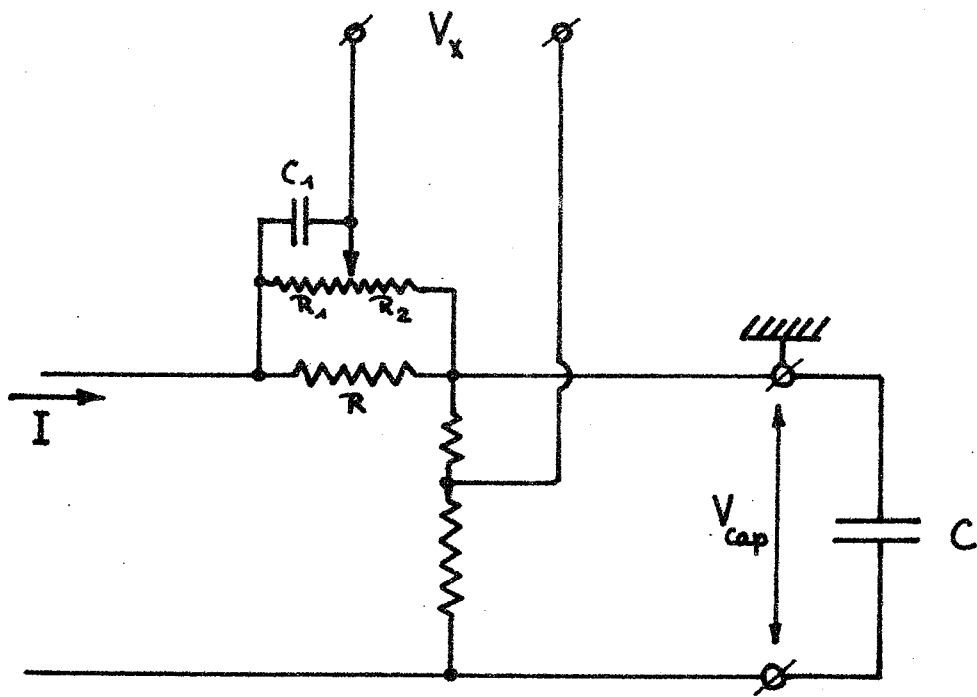


WAVE FORMS

4-10-63  
a.p.

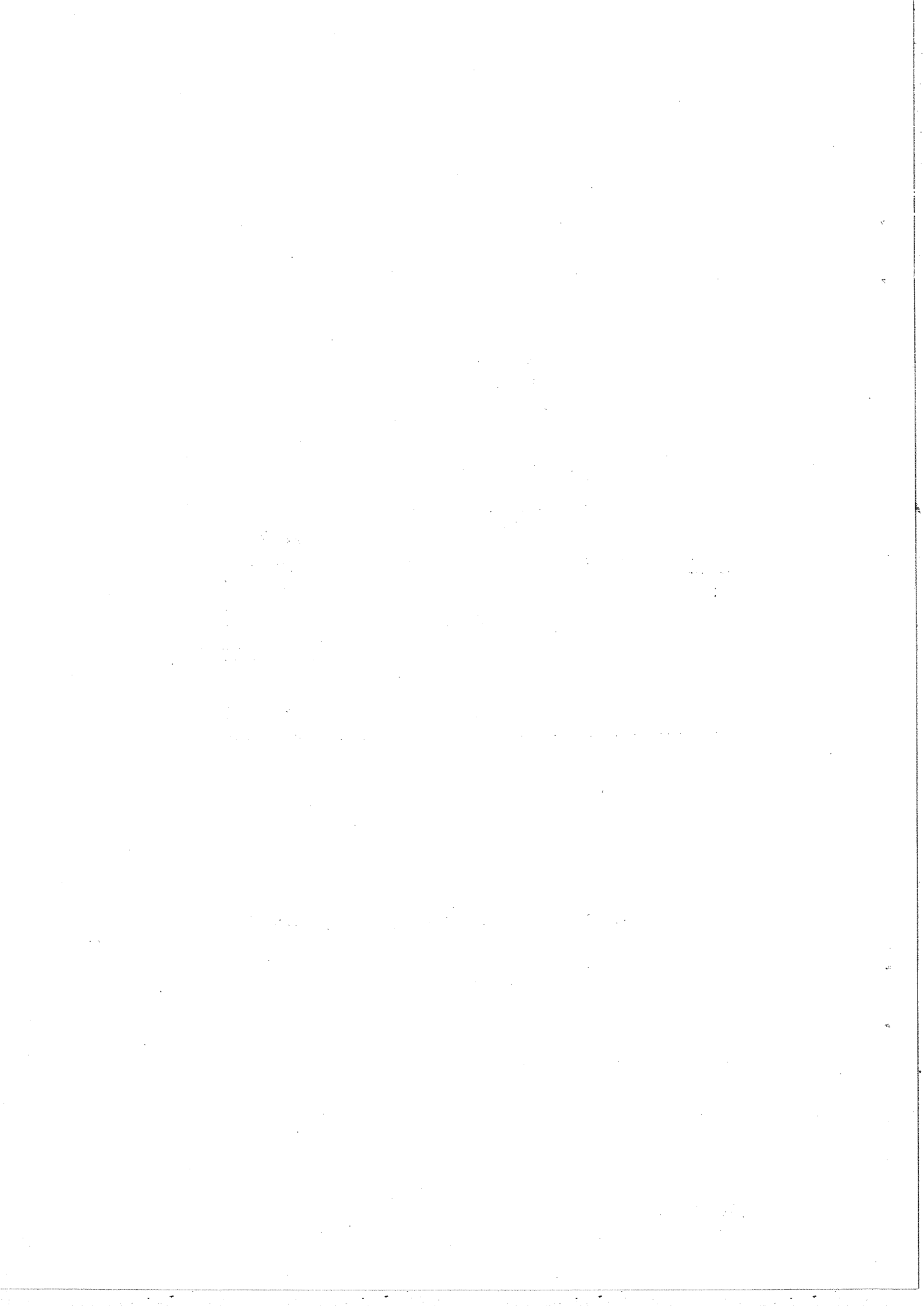


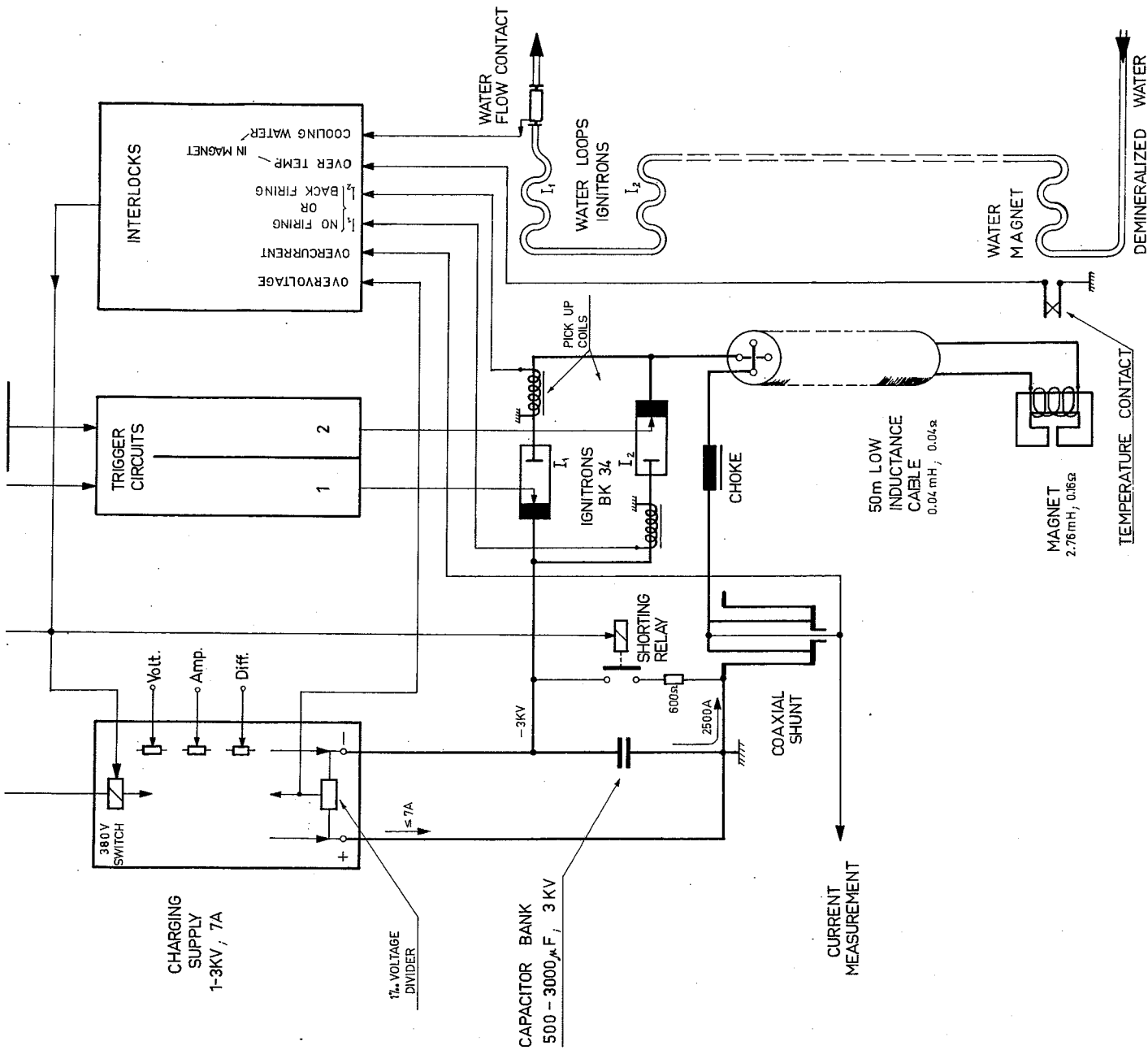


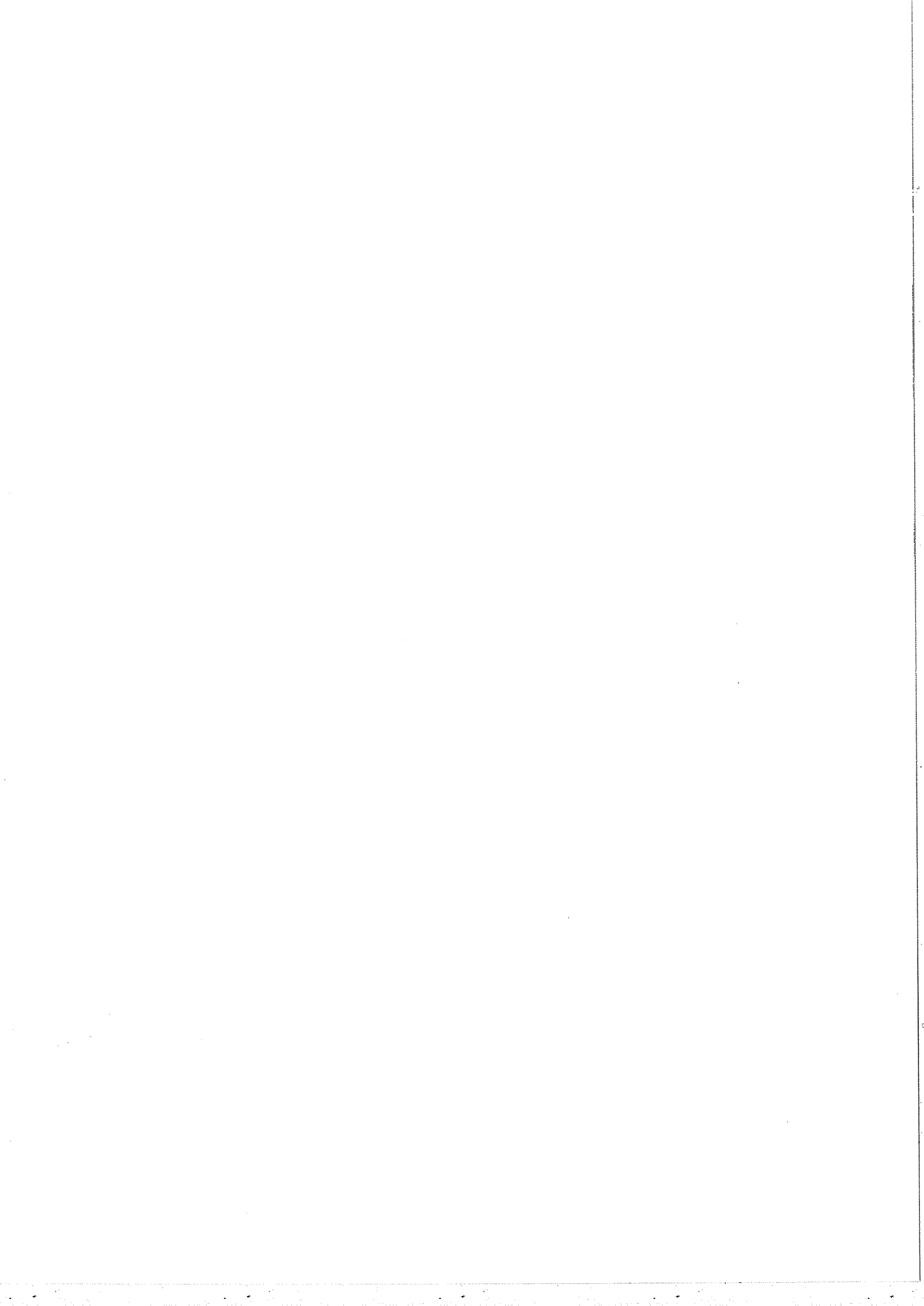


DIFFERENTIATION NETWORK

PS/4096.

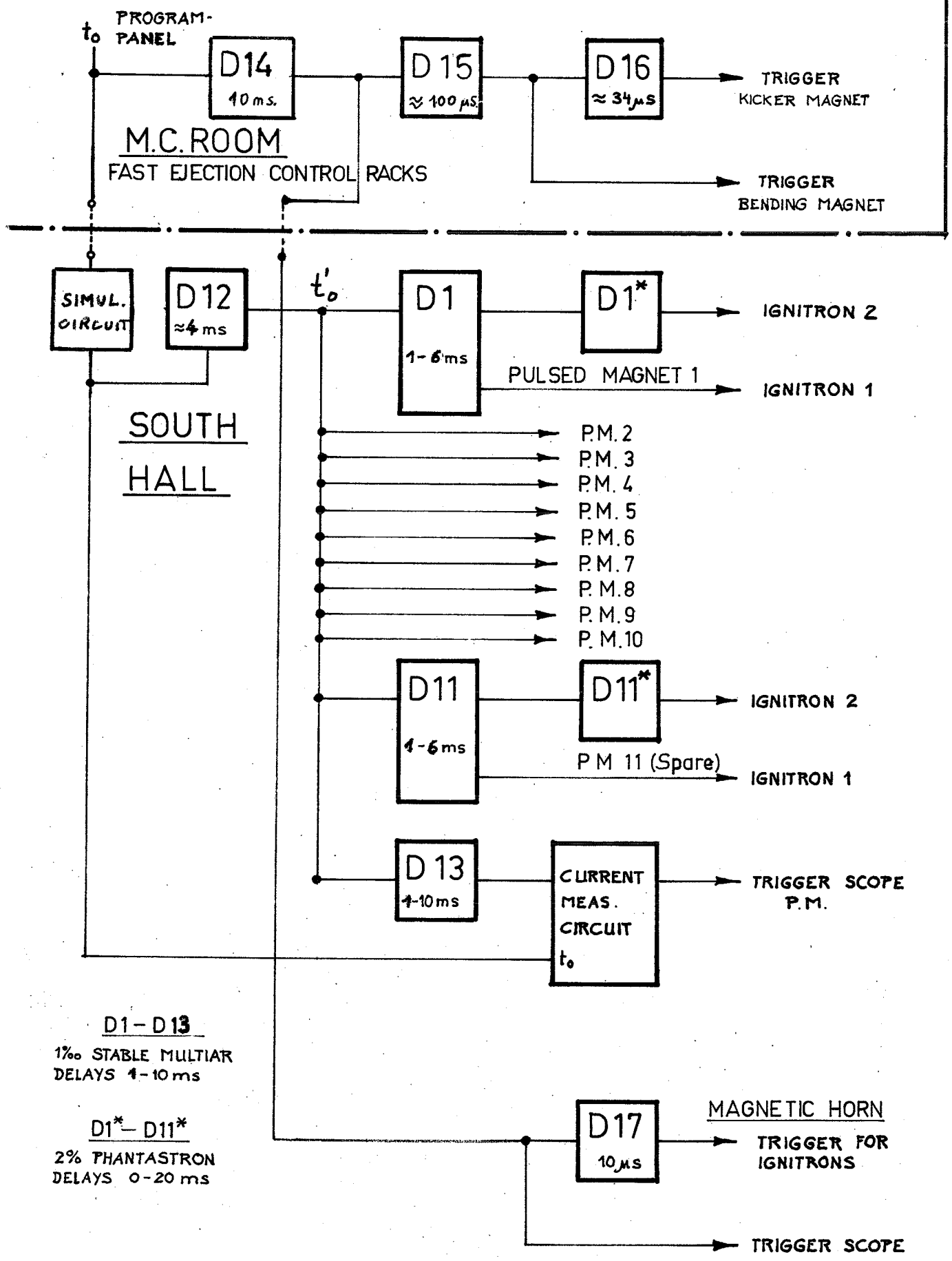


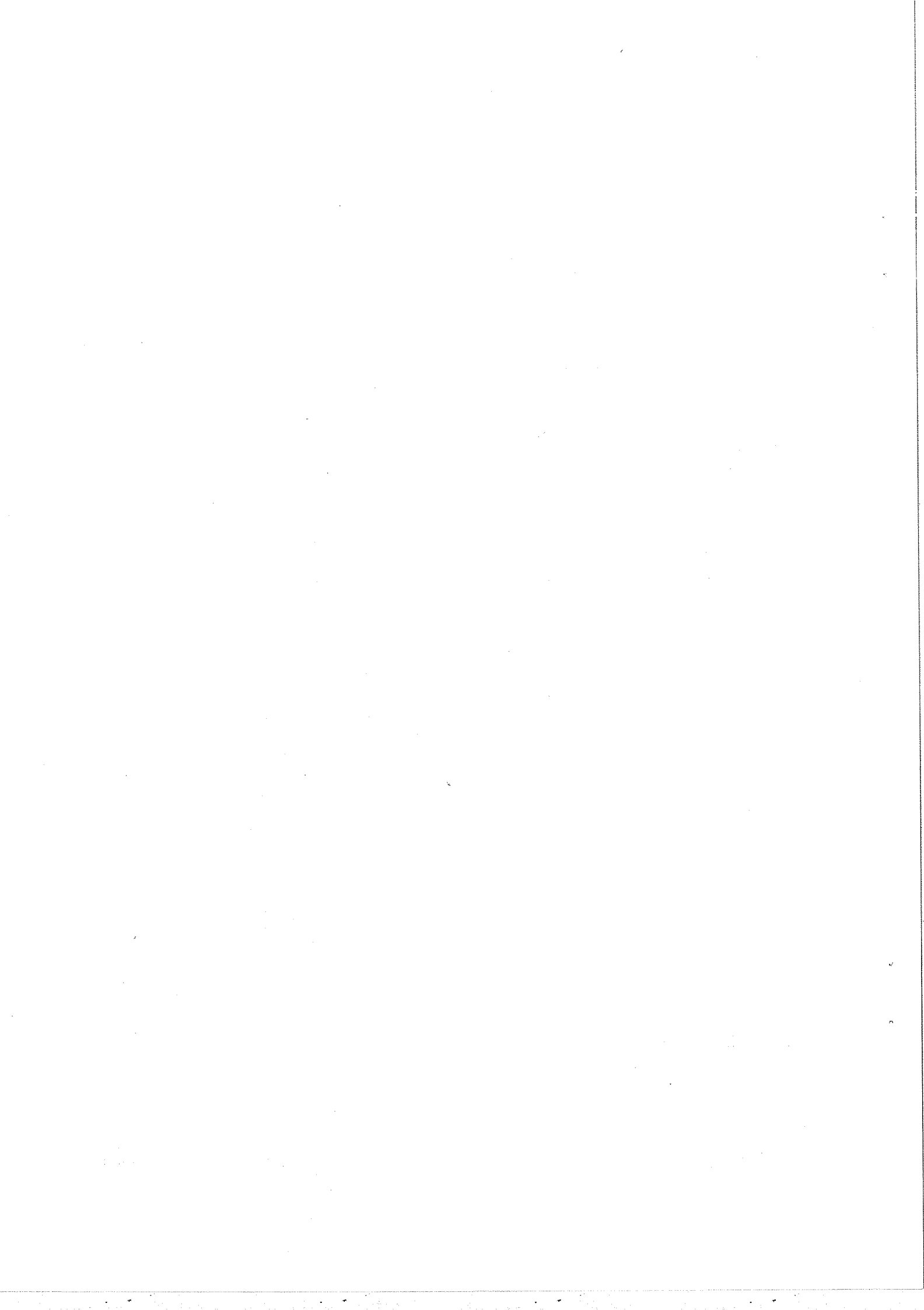


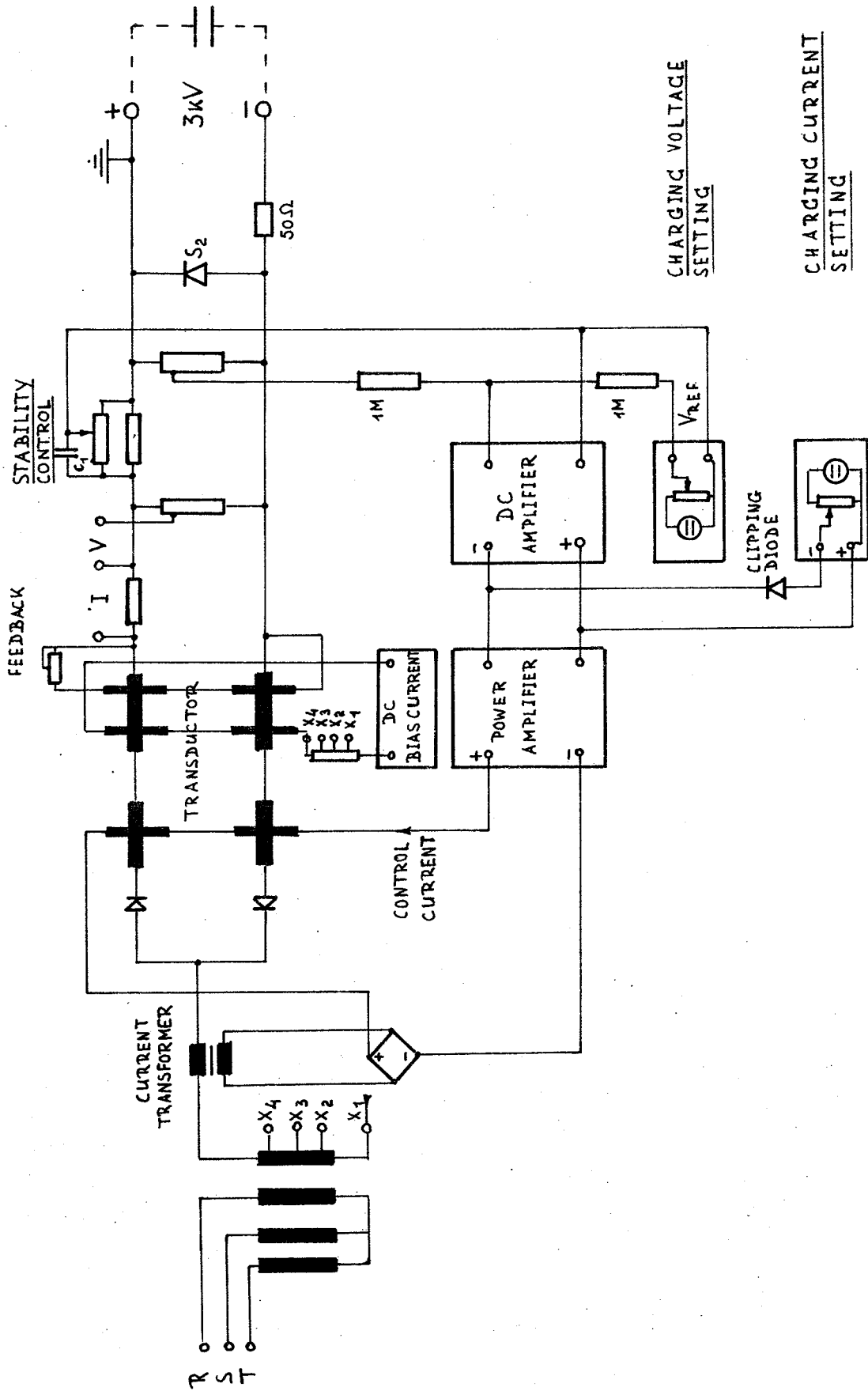


SUBJECT NEUTRINO BEAM  
SUJET TIMING

SIGNATURE *PLUYM.*  
DATE 3/10/63  
REPL. DATE







PM03





kV

3

2

1

TRANSFORMER  
TAPS.

X<sub>1</sub>Y<sub>1</sub>Z<sub>1</sub>

X<sub>2</sub>Y<sub>2</sub>Z<sub>2</sub>

X<sub>3</sub>Y<sub>3</sub>Z<sub>3</sub>

X<sub>4</sub>Y<sub>4</sub>Z<sub>4</sub>

1 2 3 4 5 6 7 8 9 10 11 CAPACITORS

%

80

60

40

20

2 capacitors

6

9

1

2

3

4

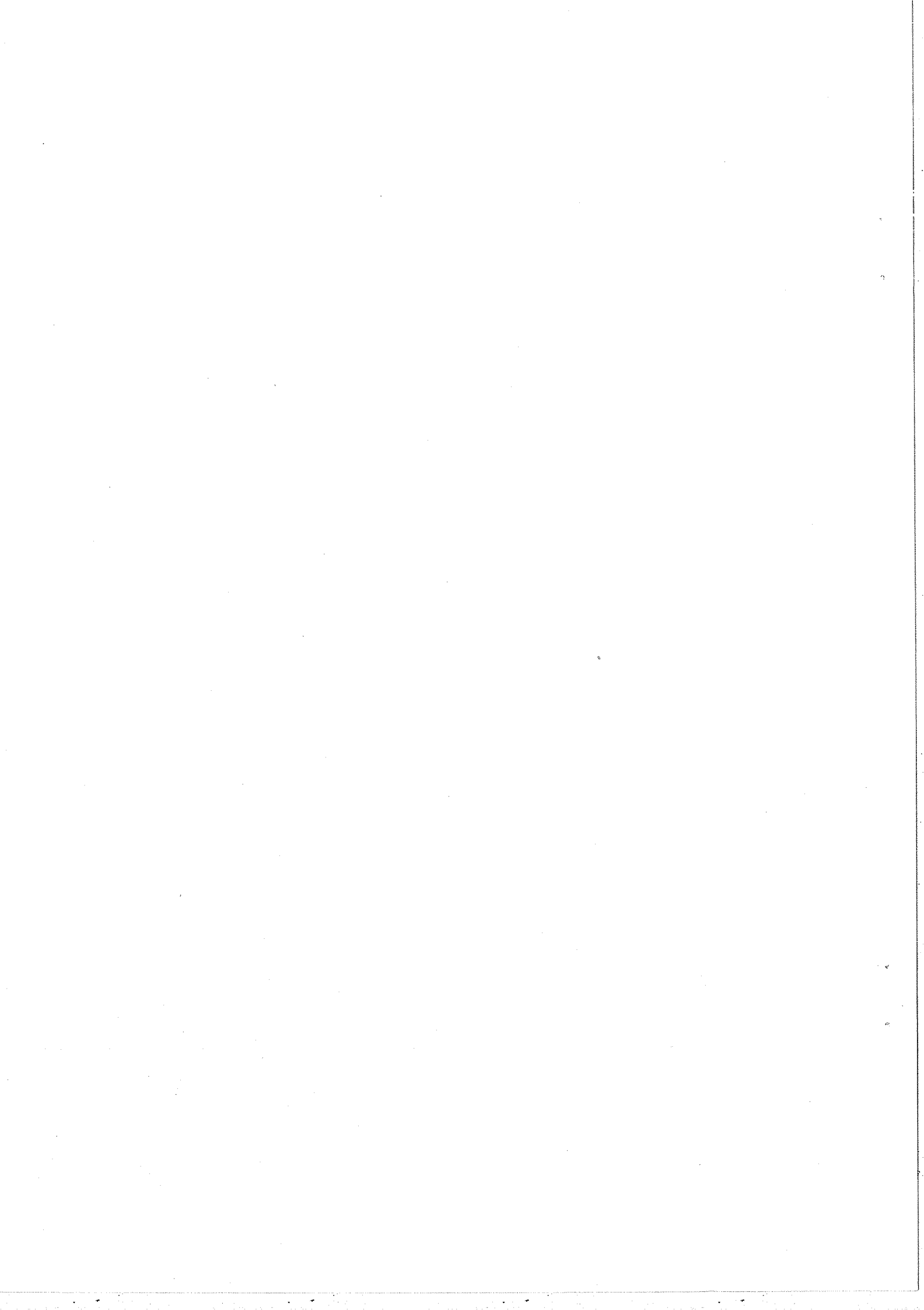
5

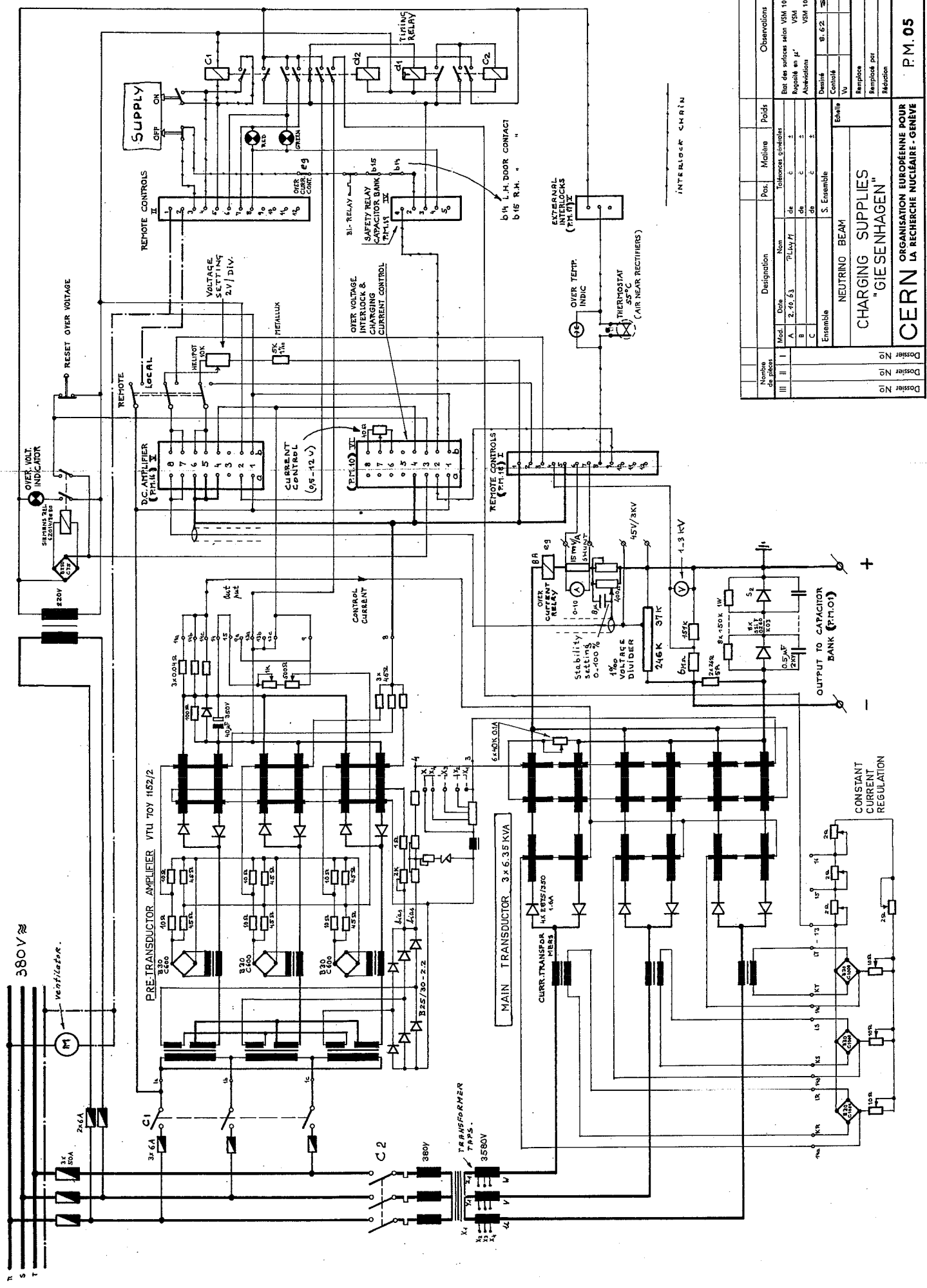
AMPS

PM 04.

4-10-63

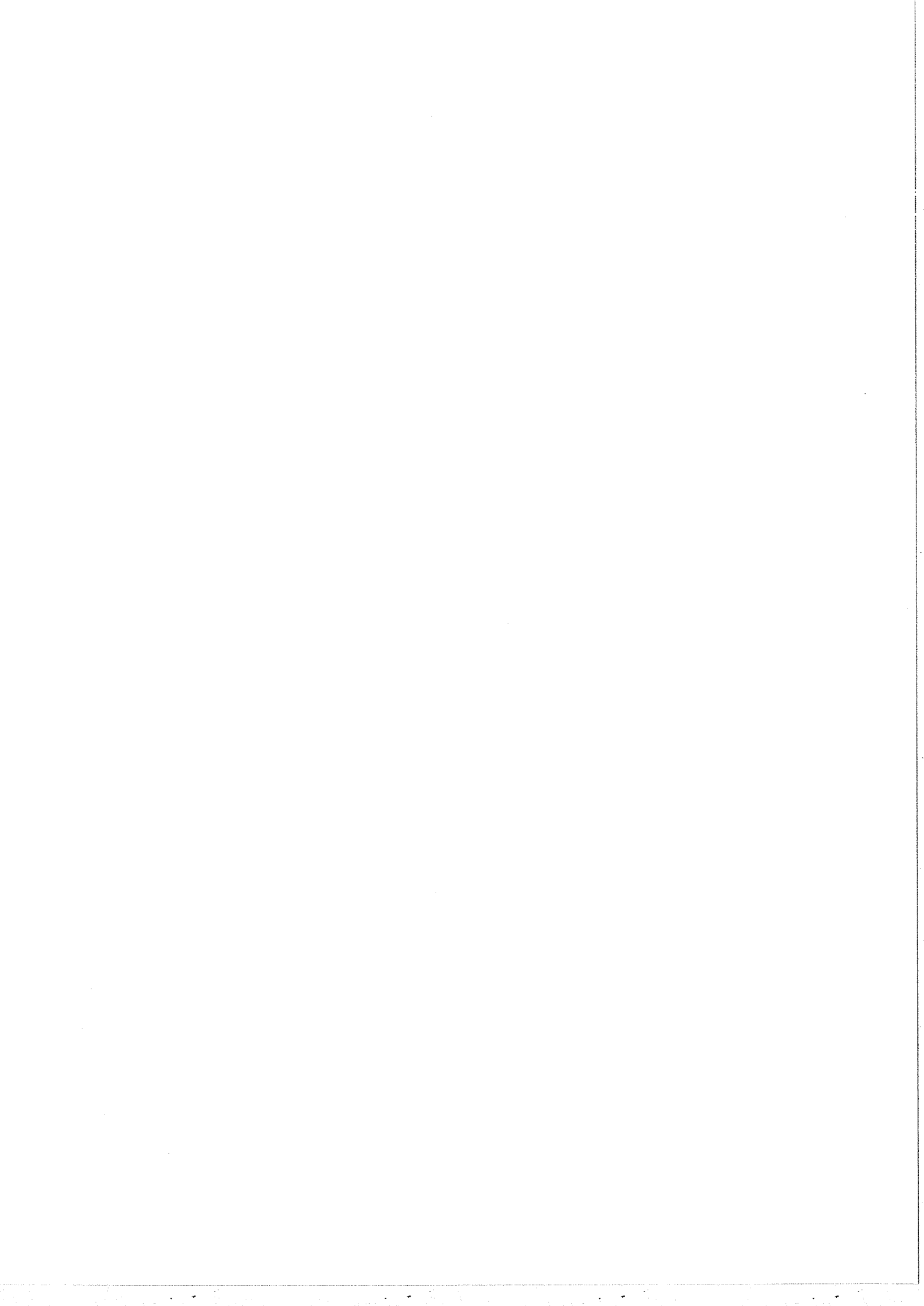
G.D.

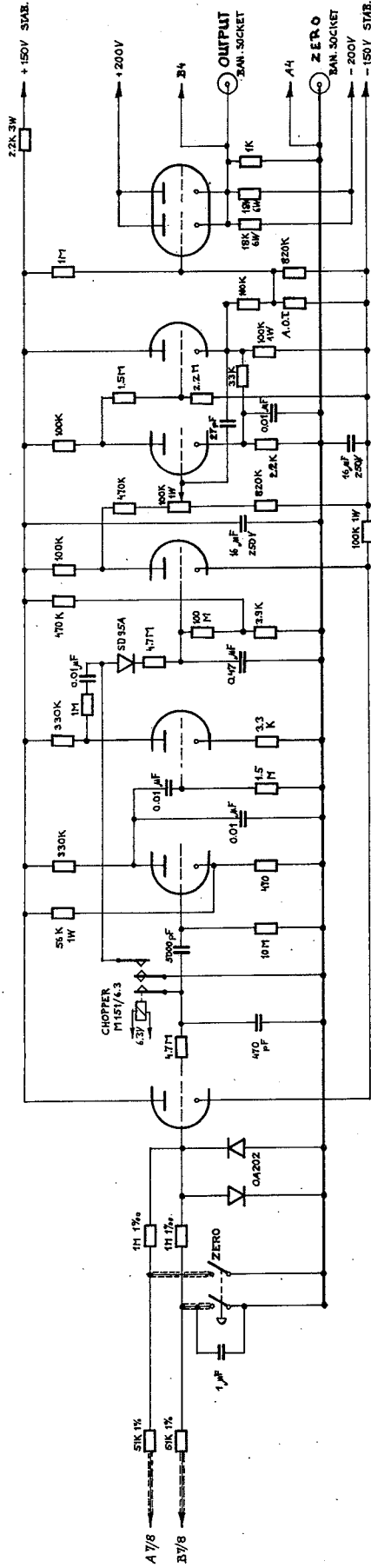




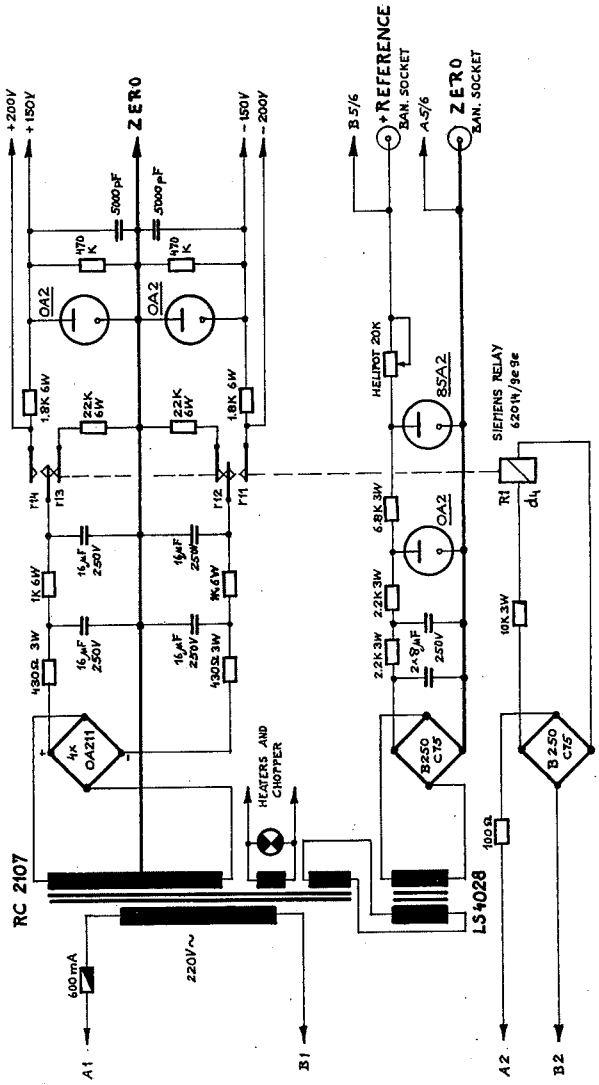
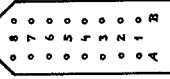
Nombres de pièces		Designation		Pos.		Matiere		Poids		Observations			
III	II	Mod.	Date	de	de	Téléfonc. constructeur							
A			2.10.63	7/L147	7						Etat des surfaces selon VSM 10320		
B				de	de						Rogéité en $\mu^2$ VSM		
C				de	de						VSM 10319		
Ensemble											Dessein	8.62	8.72/8.62
											Controle		
											Etiquette		
											Remplacement par		
											Réduction		
											<b>CHARGING SUPPLIES</b>		
											<b>"GIESENHAGEN"</b>		
											<b>CERN ORGANISATION EUROPEENNE POUR LA RECHERCHE NUCLEAIRE - GENEVE</b>		
											<b>P.M.05</b>		

Dossier No  
Dossier No  
Dossier No

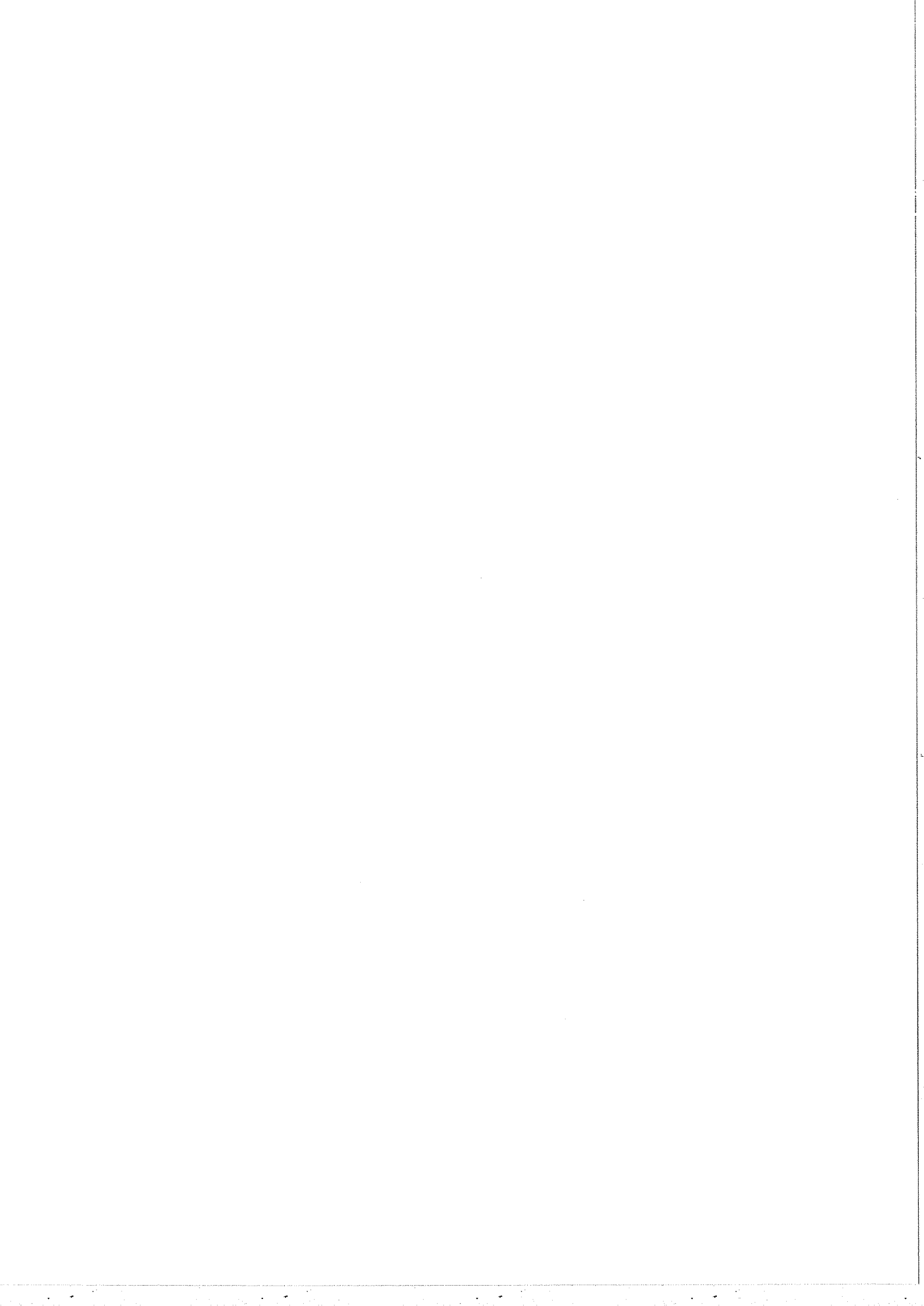




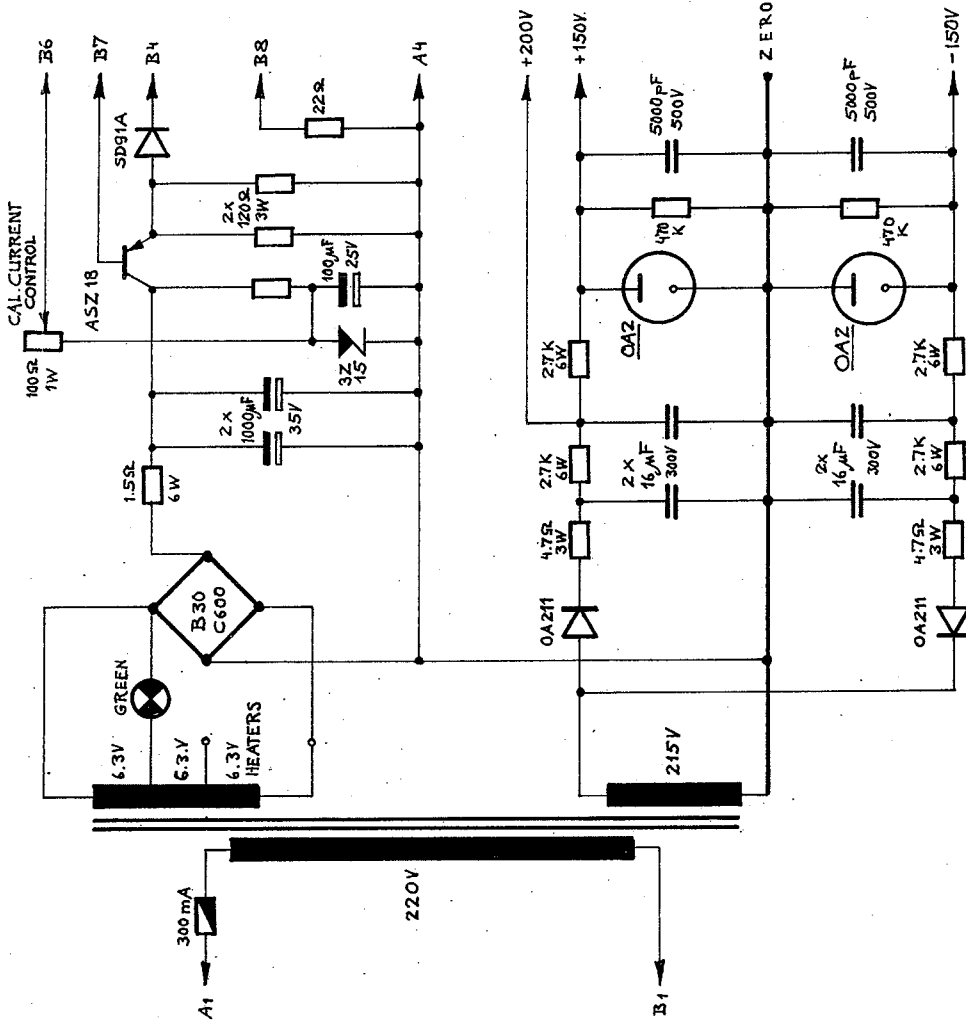
UPPER PLUG  
SEE T.M.13



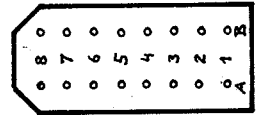
Nombre de pièces		Designation		Matière		Observations	
III	II	Mod	Date	Nom	Tolérance générale	Etat des surfaces selon VSM 10320	
		A	3-70-63	7.4.52/7.1	de	Reçue en µ'	
		B			de	Abréviations	
		C			de	VSM 10319	
Ensemble		S. Ensemble		Echelle		Quantité	7. 8. 62. 5. 304. 2.
		NEUTRINO BEAM		Vn		Remplace	
		D.C. AMPLIFIER FOR		Remplace par		Inclusion	
		P.M. POWER SUPPLY TYPE 3					
		CERN ORGANISATION EUROPEENNE POUR LA RECHERCHE NUCLEAIRE - GENÈVE					P.M.06



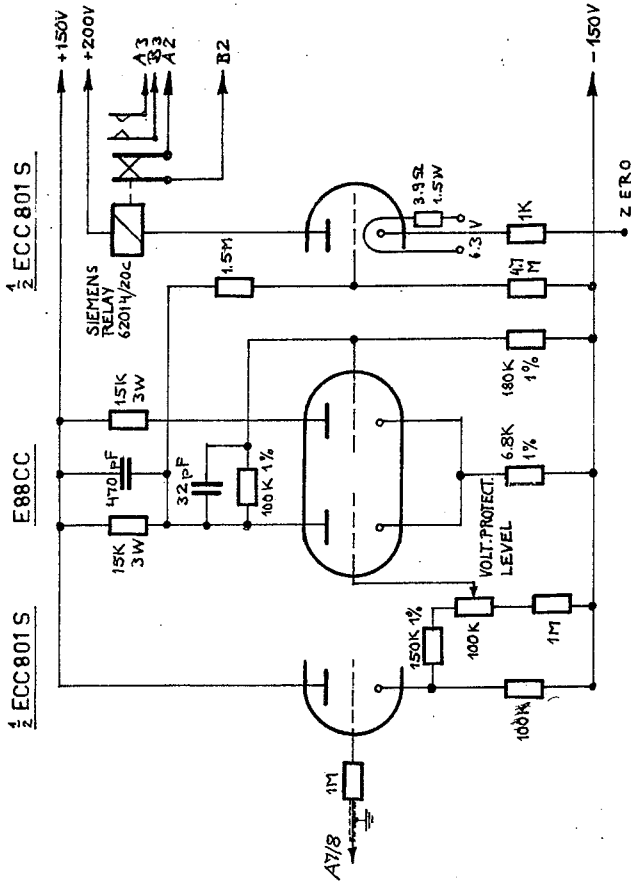
**SUB CHASSIS I**  
POWER SUPPLIES



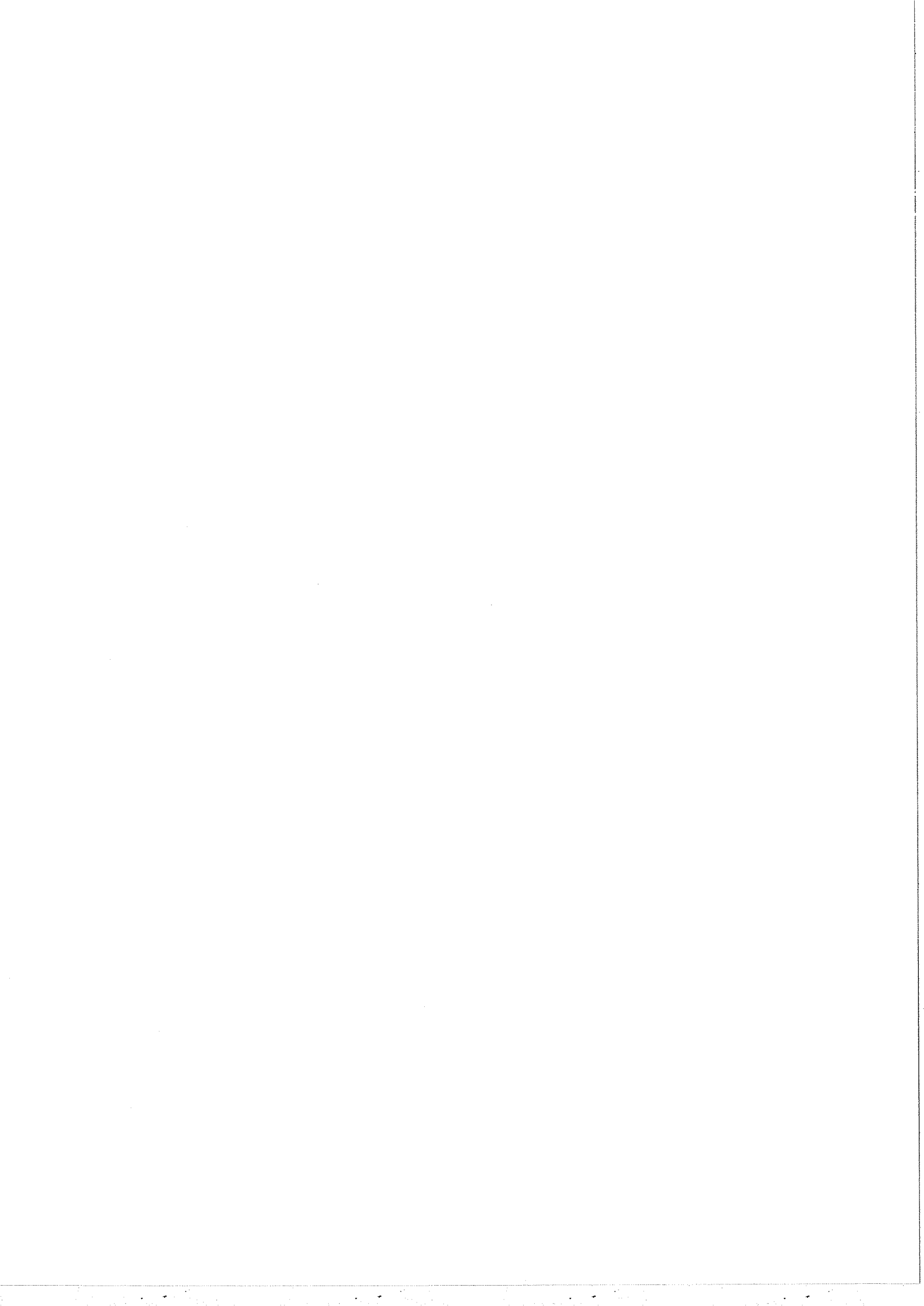
**LOWER PLUG**  
FROM REAR  
SEE P.M. 13



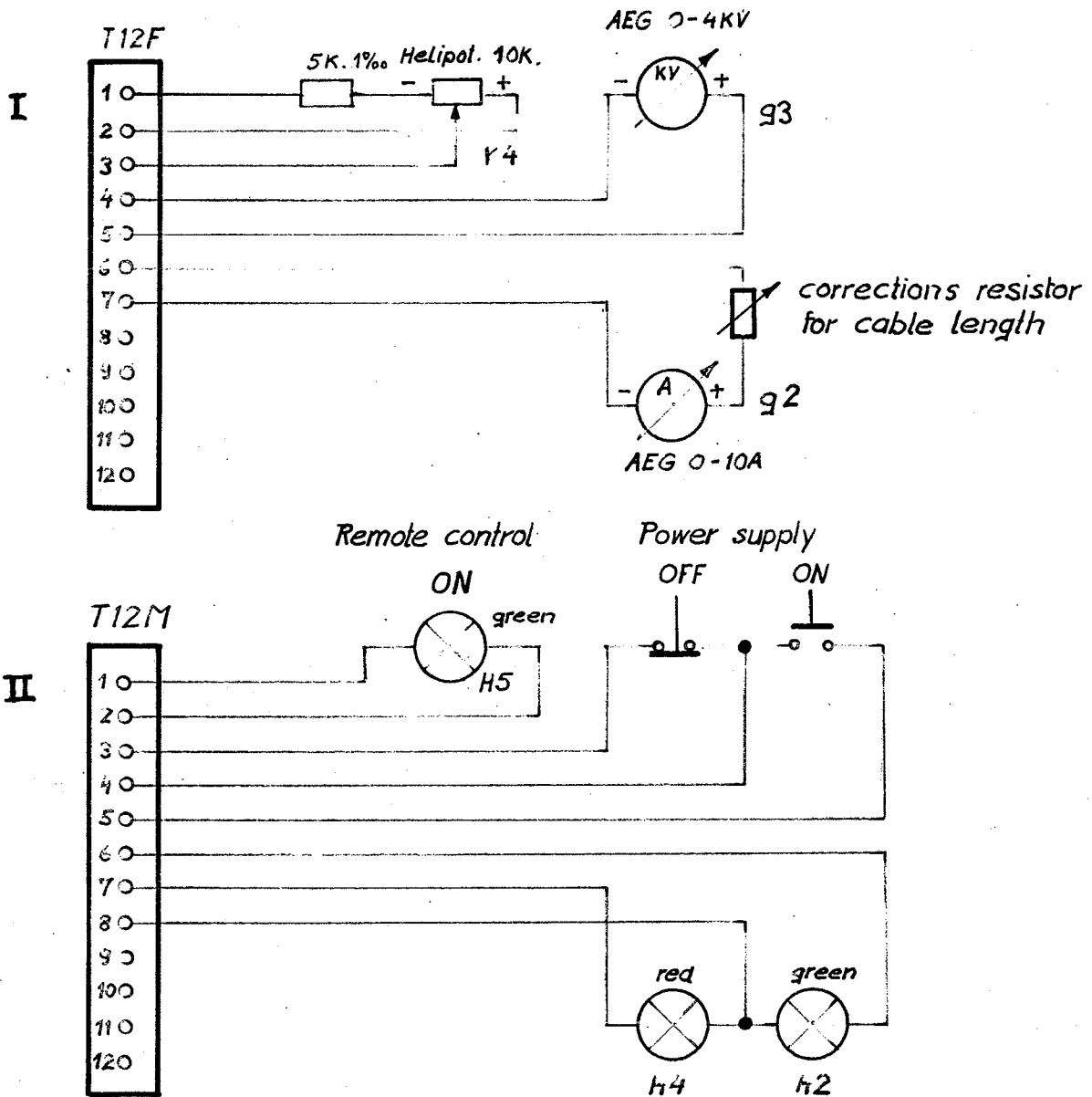
**SUB CHASSIS II**  
OVER VOLTAGE INTERLOCK



Nombre de pièces		Designation		Pos.	Matiere	Poids	Observations
III	I	Mod.	Date	Nom	Tolérances générales		Etat des surfaces selon VSM 10320 Rugosité en µ" VSM Abréviations VSM 10319
		A	4-10-63	PLLYM	à	±	
		B			à	±	
		C			à	±	
Ensemble				S. Ensemble		Echelle	
				NEUTRINO BEAM			
				<b>OVER VOLTAGE INTERLOCK &amp; CHARGING CURRENT CONTROL</b>			
				<b>CERN ORGANISATION EUROPÉENNE POUR LA RECHERCHE NUCLÉAIRE - GENÈVE</b>			
Dossier No		Dossier No		Dossier No		Dessiné 9.8.62 S. Z. B.	
						Contrôle	
						Vu	
						Remplace	
						Remplacé par	
						Réduction	
							<b>P.M. 07</b>

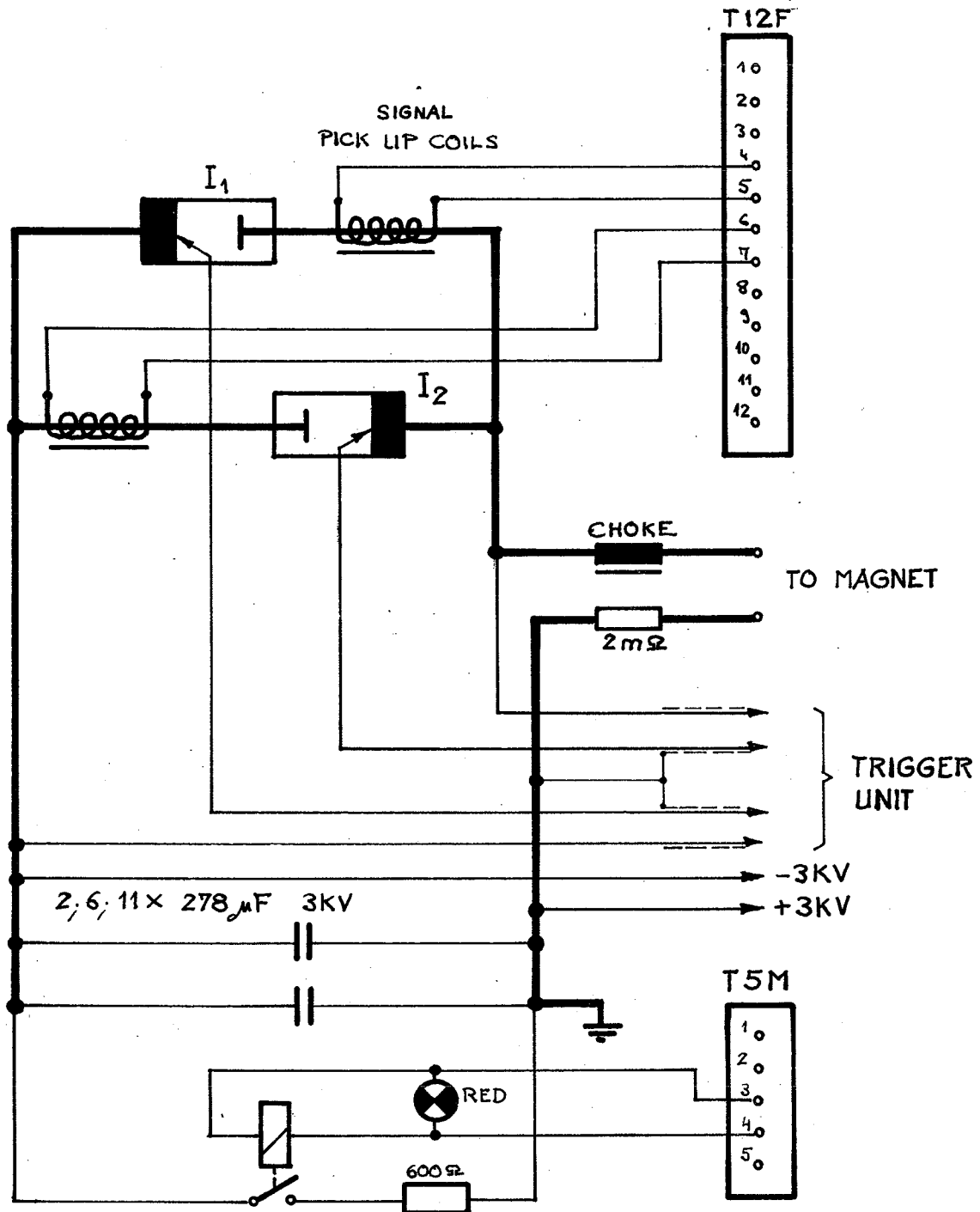




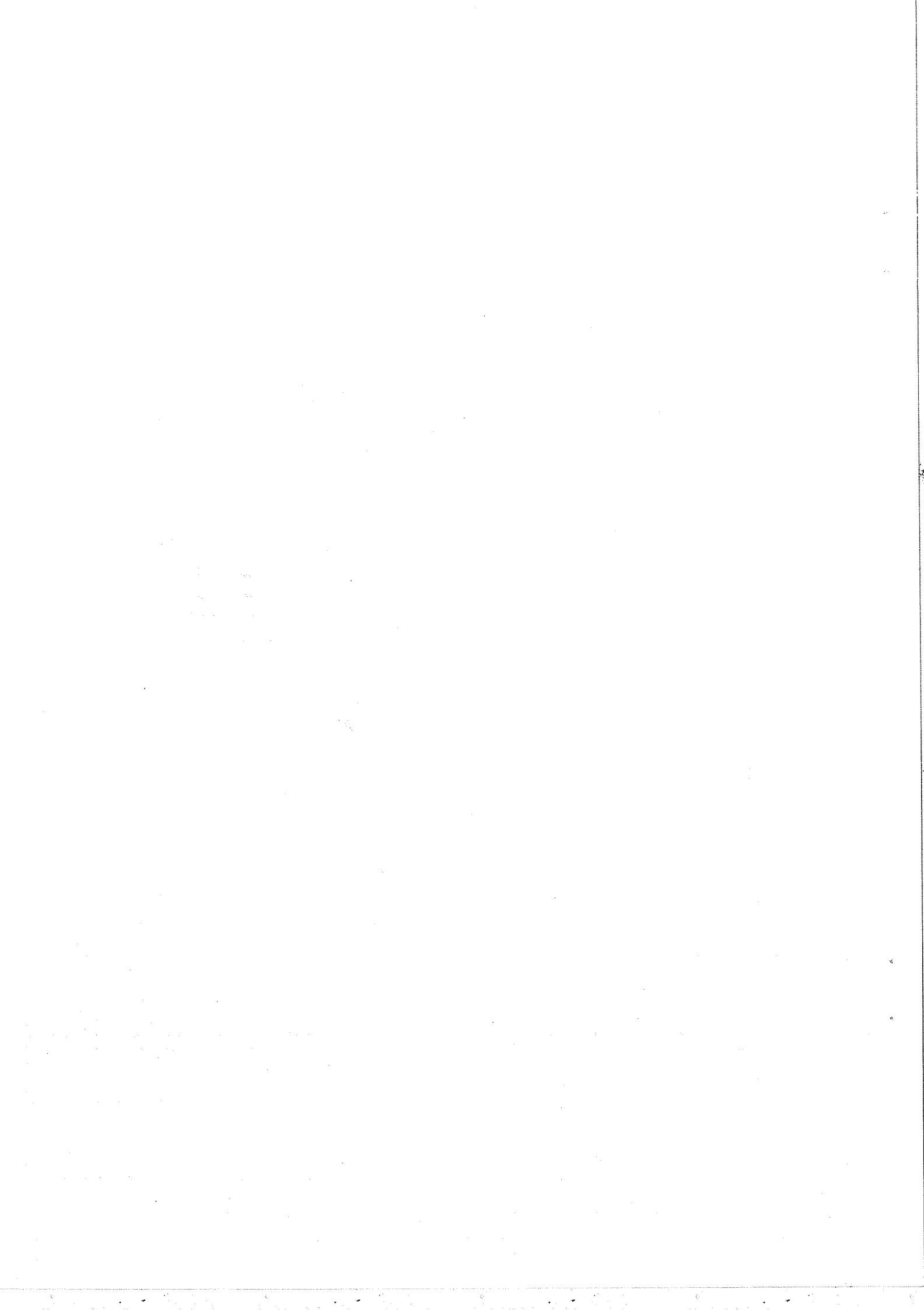


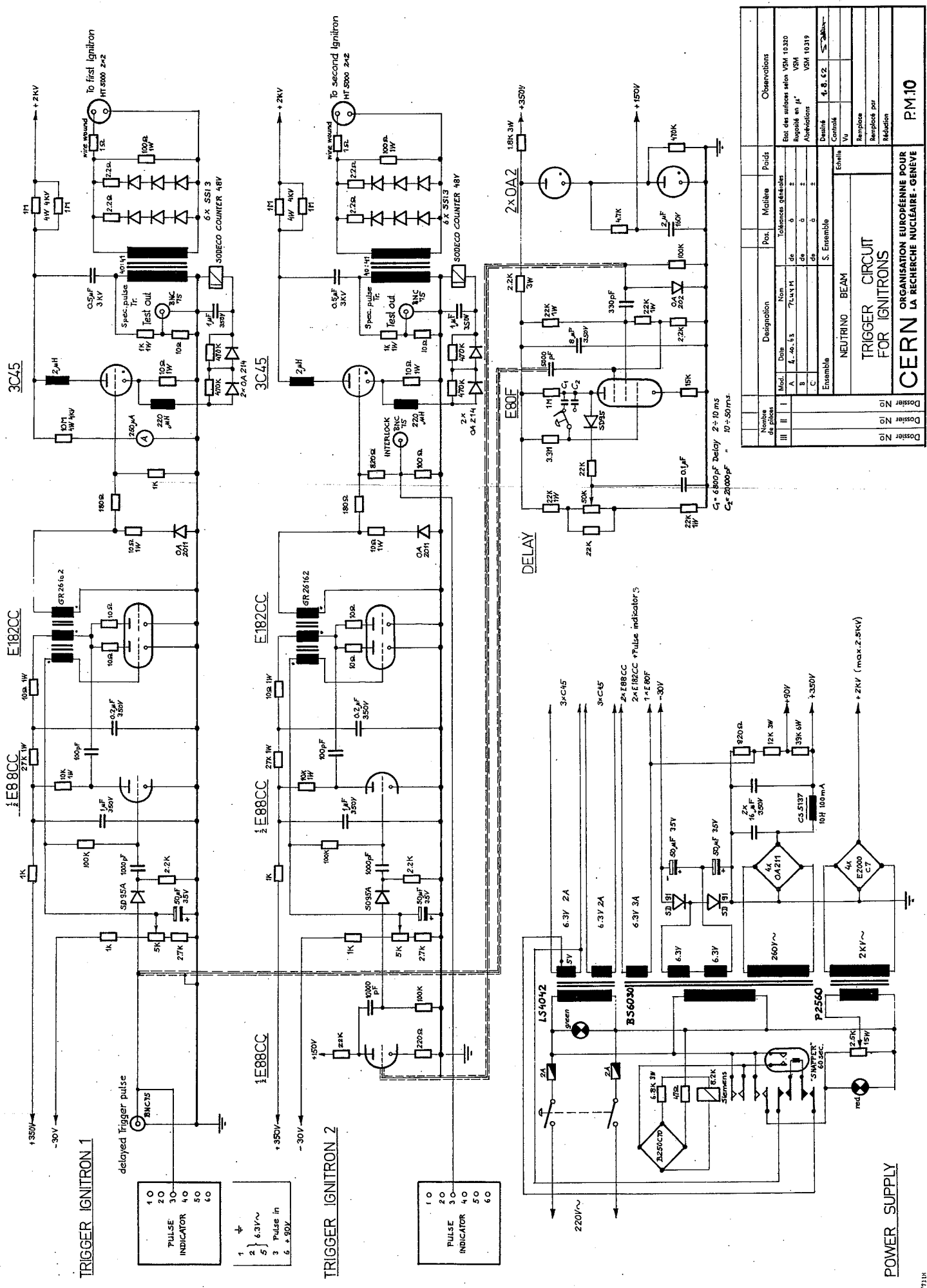
Nombre de pièces			Designation			Pos.	Matière	Poids	Observations	
III	II	I	Mod.	Date	Nom	Tolérances générales			Etat des surfaces selon VSM 10320	
			A	4-10-63	PLUYM	de	à	±	Rugosité en $\mu$ " VSM	
			B			de	à	±	Abréviations VSM 10319	
			C			de	à	±		
Ensemble			S. Ensemble						Dessiné	23-6-62. 67
			NEUTRINO BEAM						Contrôlé	
			REMOTE CONTROL UNIT						Vu	
			FOR P.M. POWER SUPPLY						Remplace	
									Remplacé par	
									Réduction	
Dossier N°			Dossier N°			Dossier N°			CERN ORGANISATION EUROPÉENNE POUR LA RECHERCHE NUCLÉAIRE - GENÈVE	
									P.M.08	



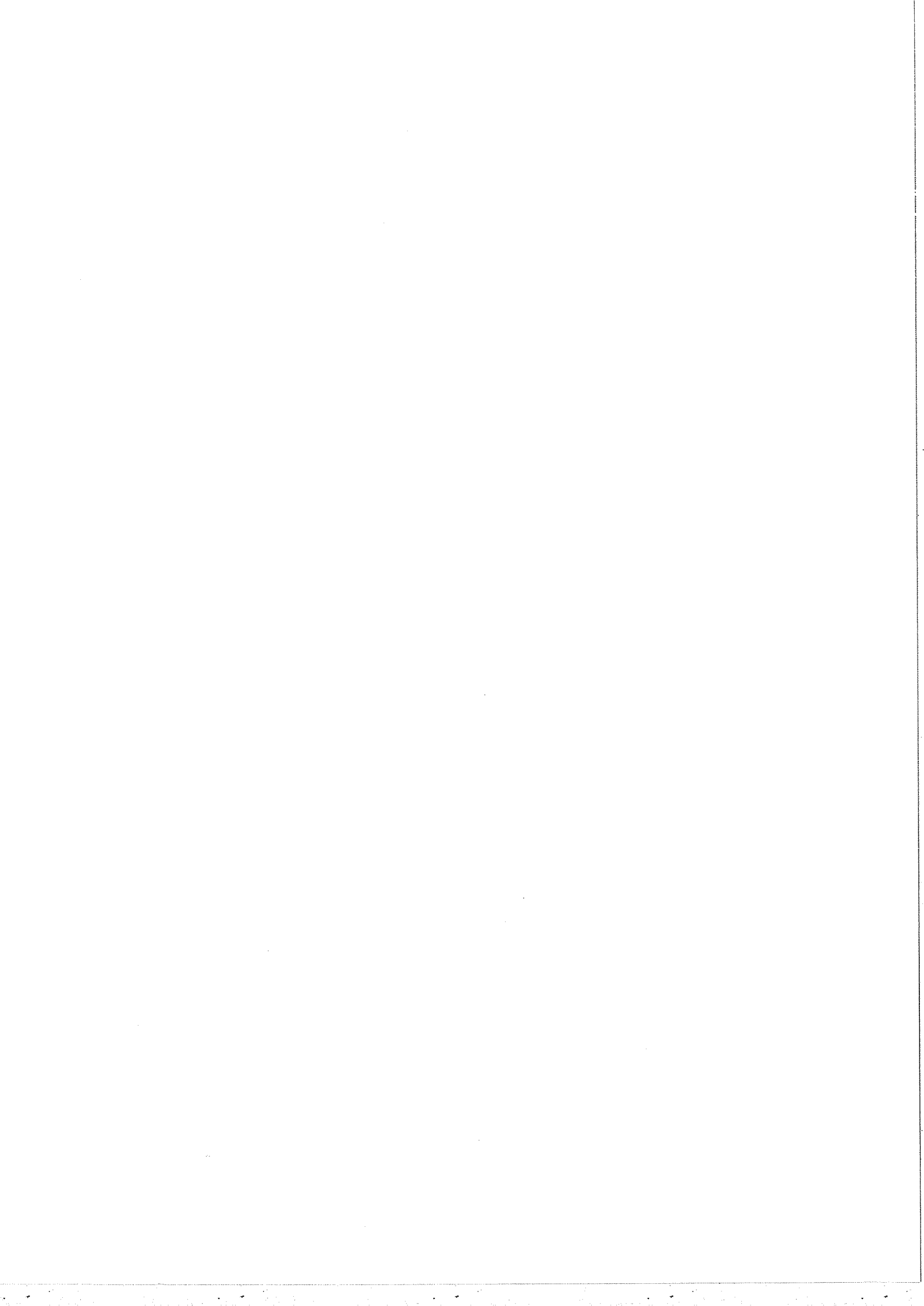


Nombre de pièces			Designation		Pos.	Matière	Poids	Observations			
III	II	I	Mod.	Date	Nom	Tolérances générales			Etat des surfaces selon VSM 10320 Rugosité en $\mu''$ VSM Abréviations VSM 10319		
			A	4-10-63	PLUYM	de	à	±			
			B			de	à	±			
			C			de	à	±			
			Ensemble		S. Ensemble			Dessiné	27.8.62	S. <i>[Signature]</i>	
			NEUTRINO BEAM				Echelle		Contrôlé		
			CONNECTIONS TO CAPACITOR BANK						Vu		
									Remplace		
									Remplacé par		
									Réduction		
Dossier No			CERN ORGANISATION EUROPÉENNE POUR LA RECHERCHE NUCLÉAIRE - GENÈVE				P.M.09				





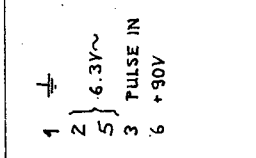
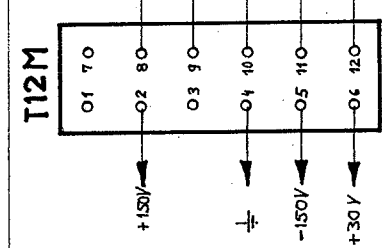
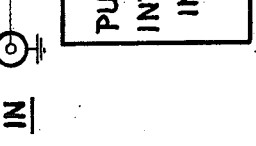
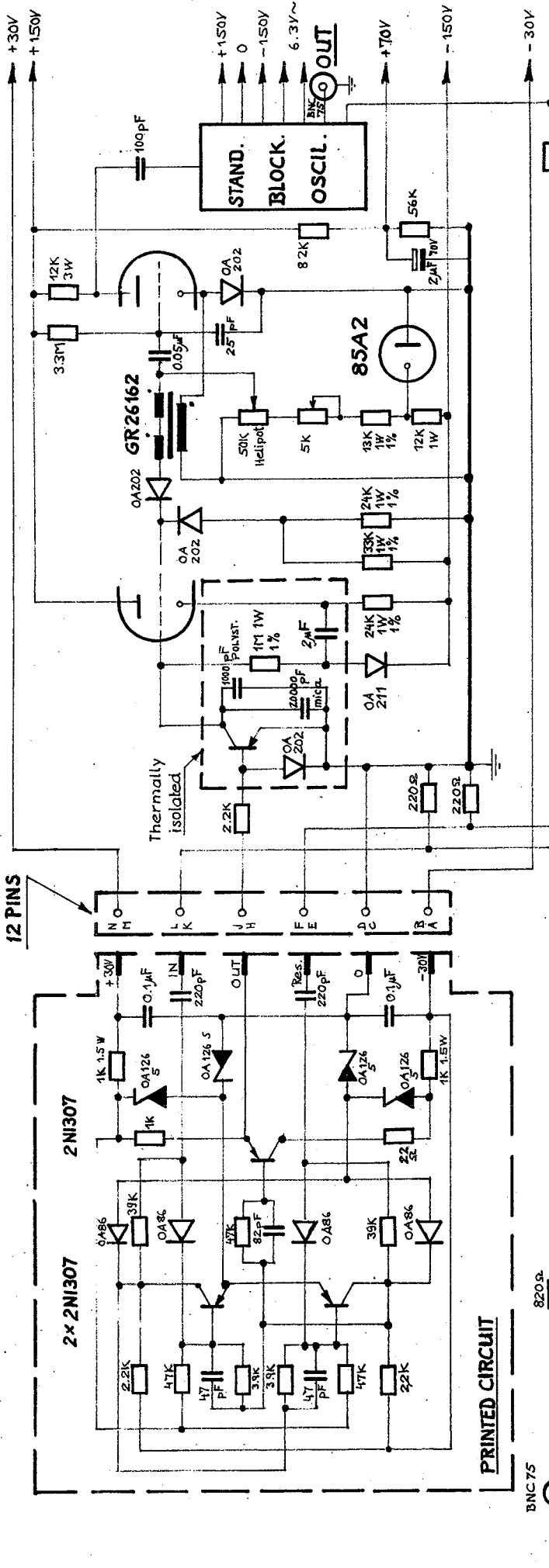
Nomenclature de pièces		Designation		Pos.		Matière		Observations	
III	II	Mod.	Date	Non	Tolérances générales				
		A	4.10.63	7.1.1.1.1.4	da	0	+		Etat des surfaces selon VSM 10320
		B			da	0	+		Regulate en µ"
		C			da	0	+		Abrevoir
					da	0	+		VSM 10319
Ensemble		S. Ensemble						Destiné à: B. 6.2	
		NEUTRINO BEAM		Echelle				Contrat	
		TRIGGER CIRCUIT						Remplace	
		FOR IGNITRONS						Remplace par	
		CERN ORGANISATION EUROPEENNE POUR LA RECHERCHE NUCLEAIRE - GENEVE						Modèle	
								PM10	



PRINTED CIRCUIT SOCKET

OC450K

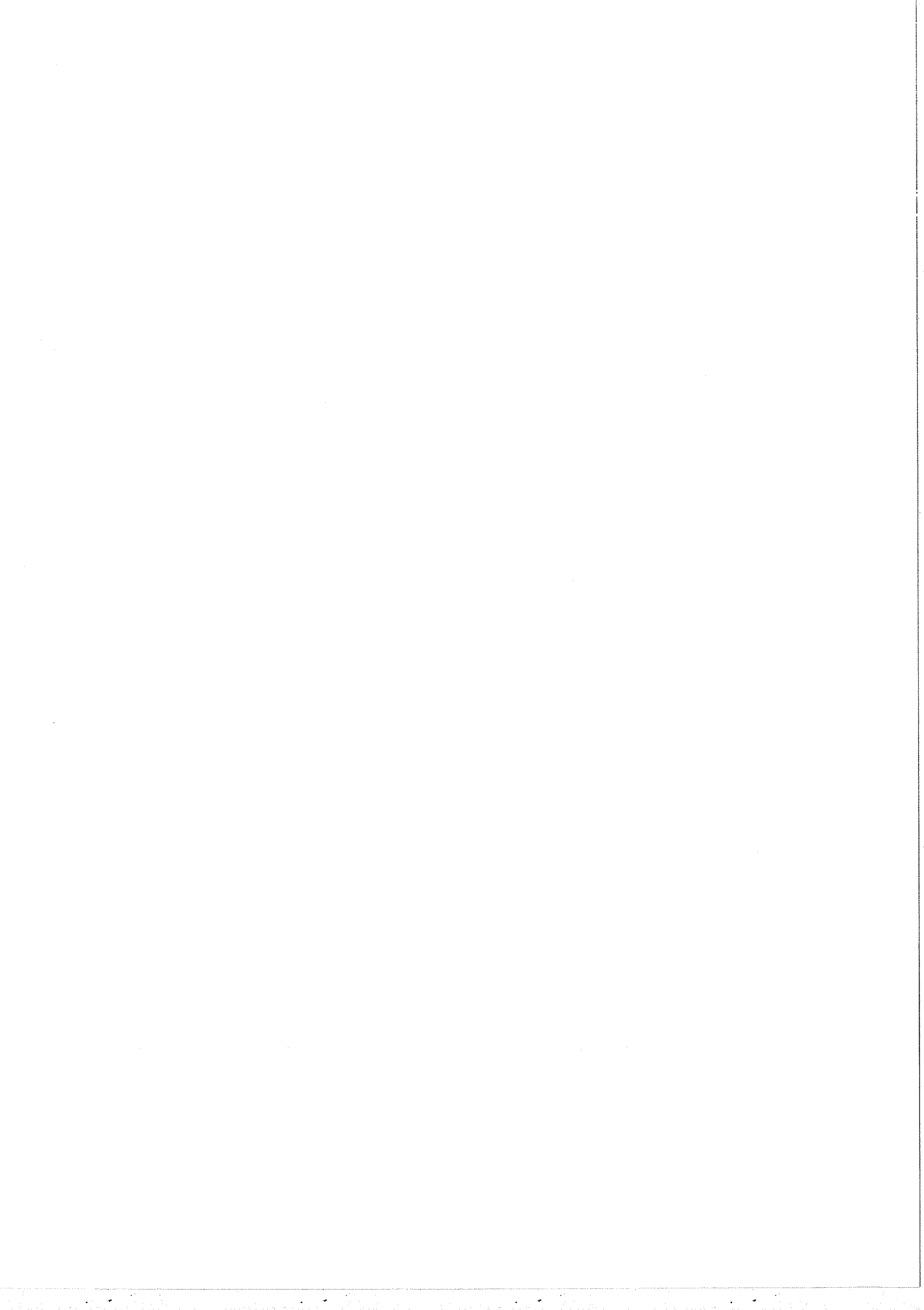
E88CC



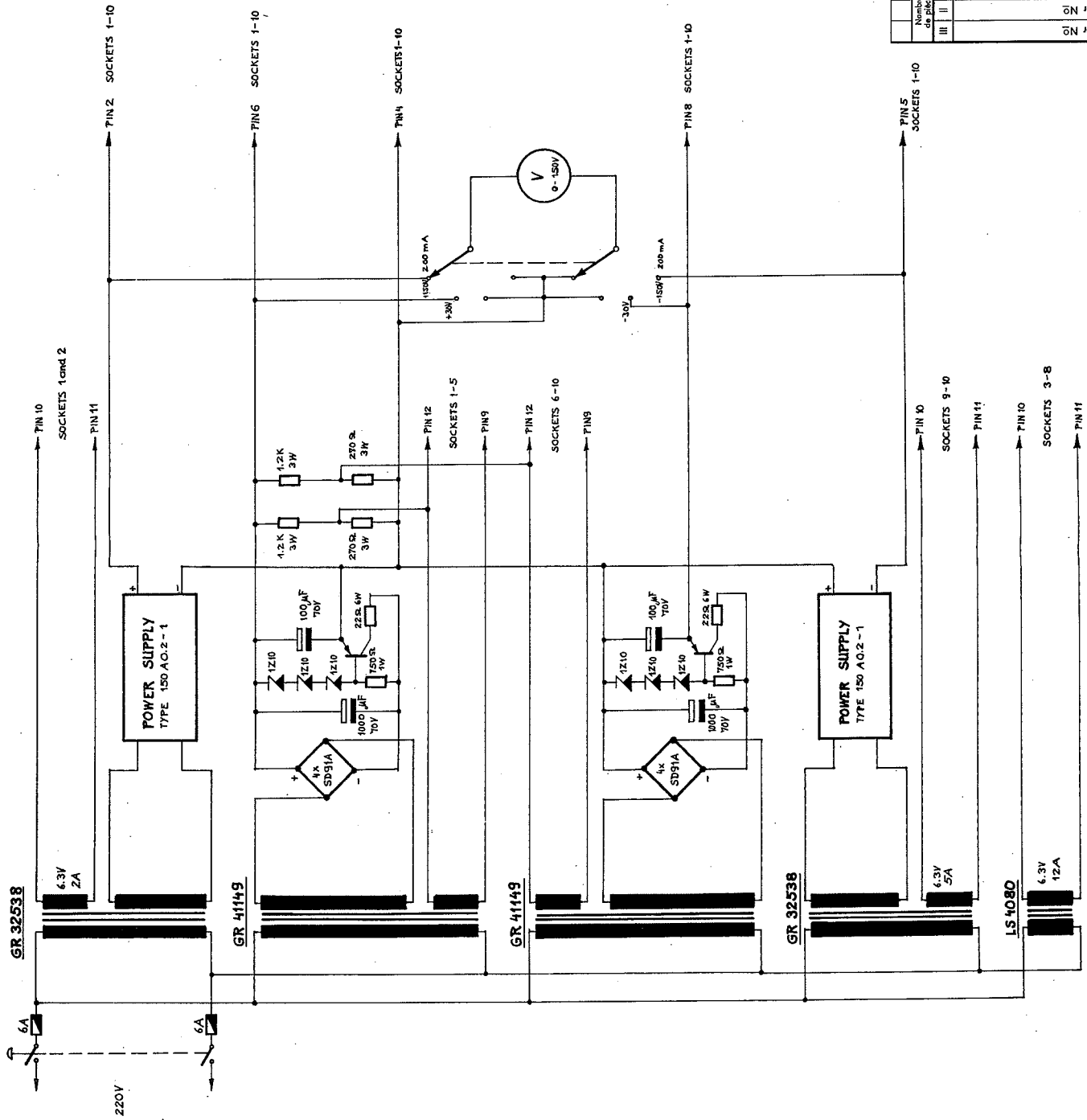
PULSE INDICATORS: 1  
2 } 6.3V~  
3 PULSE IN  
6 +90V

2 VARIABLE DELAY CIRCUITS IN ONE "3UNITS" STANDARD RACK

Nombre de pièces		Designation		Pos.		Matière		Poids		Observations	
III	I	Mod.	Date	Tolérances générales						Etat des surfaces selon VSM 10320	
	A	A	4-10-63	de		à ±				Rugosité en µ"	
	B	B		de		à ±				Abréviations	
	C	C		de		à ±				VSM 10319	
Ensemble				S. Ensemble				Dessiné		2.8.62 S. Dubois	
NEUTRINO BEAM				Echelle				Remplace			
VARIABLE DELAY 1 ÷ 10ms				Remplacé par							
				Réduction							
CERN ORGANISATION EUROPÉENNE POUR LA RECHERCHE NUCLÉAIRE - GENÈVE										PM11	





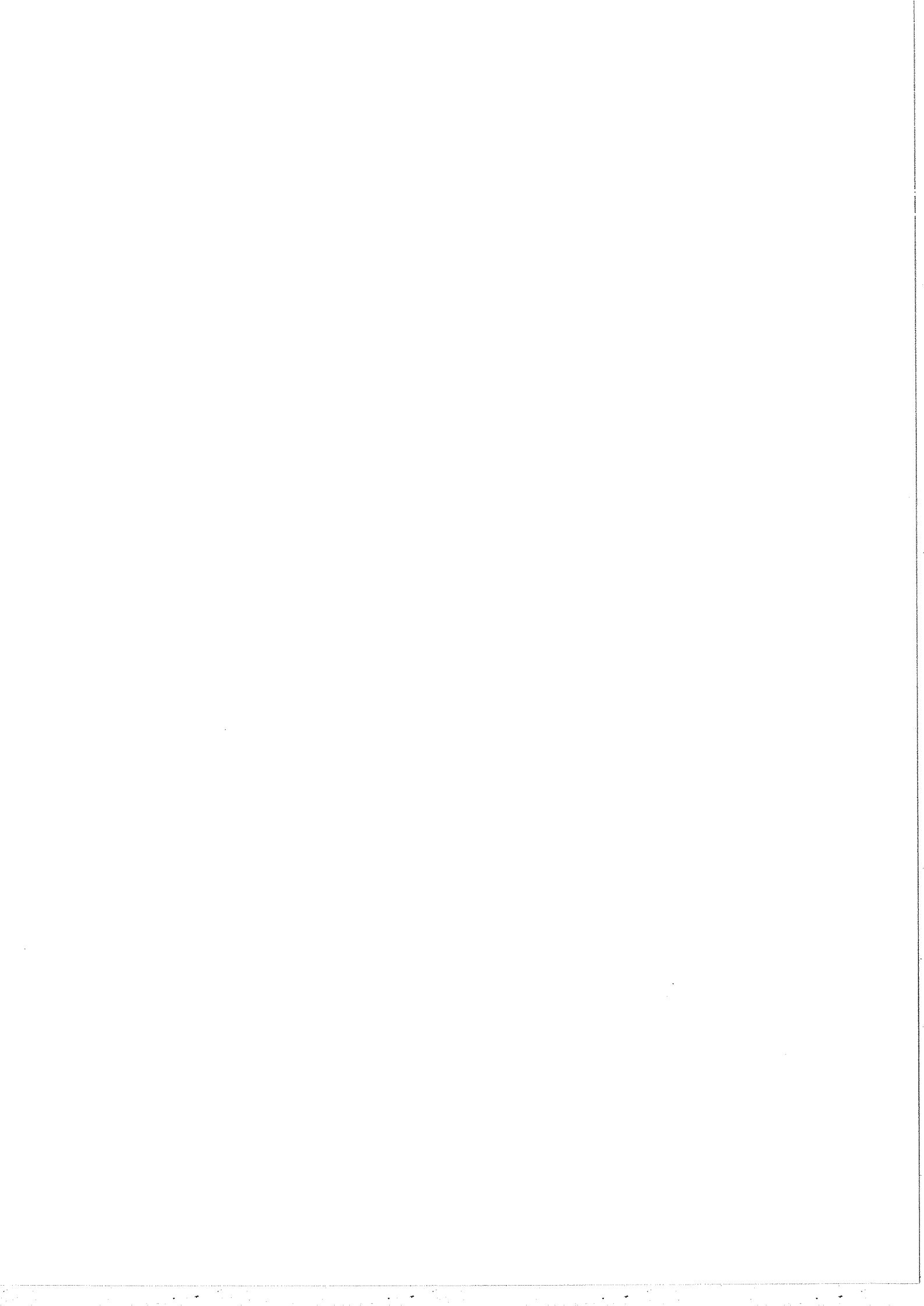


OUTPUT CONNECTIONS:  
10 x T12F CONNECTED AS INDICATED IN DRAWING

T12F

01
02
03
04
05
06
07
08
09
09
09

Nombre de pièces		Designation		Pos. Matière		Poids		Observations	
III	II	I	Mod.	Date	Nom	Tolérances générales			
			A	4.10.63	7LLYM	de 0	2		Etat des surfaces selon VSM 10.320
			B			de 0	2		Supporte en µ'
			C			de 0	2		Attributions VSM 10.319
Ensemble		S. Ensemble		Destiné		Contrôle		Vo	
		NEUTRINO BEAM		Échelle					
		POWER SUPPLY FOR DELAY CIRCUIT 1: 10ms		Remplacement					
		CERN ORGANISATION EUROPÉENNE POUR LA RECHERCHE NUCLÉAIRE - GENÈVE		Réduction					
Dossier N°								P.M.12	



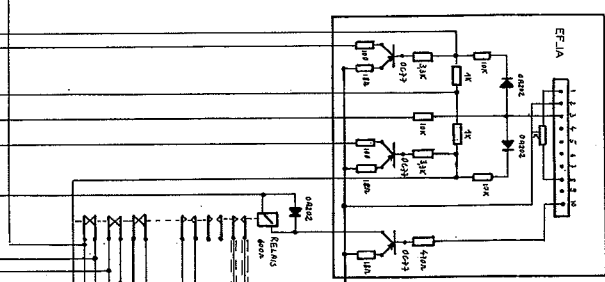
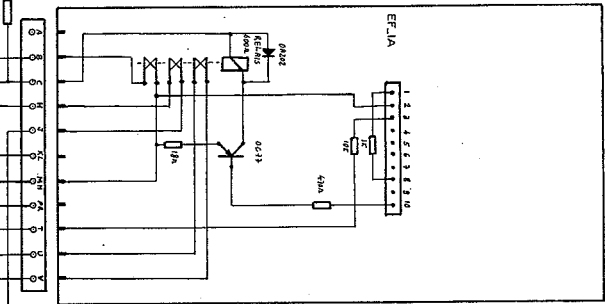
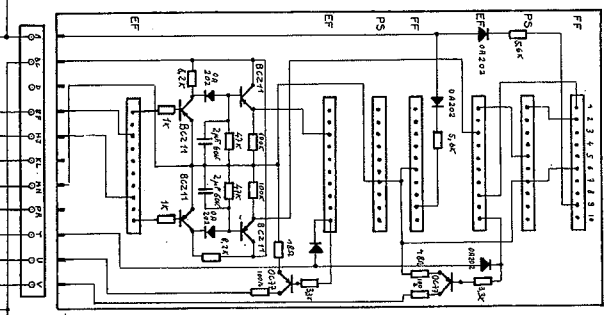
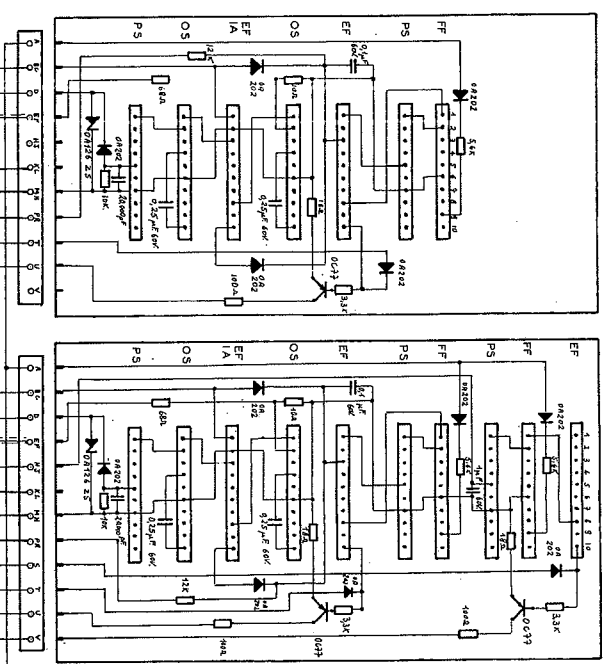
NO FIRING I1

NO FIRING2 & OVERCURRENT

BACK FIRING 11.12

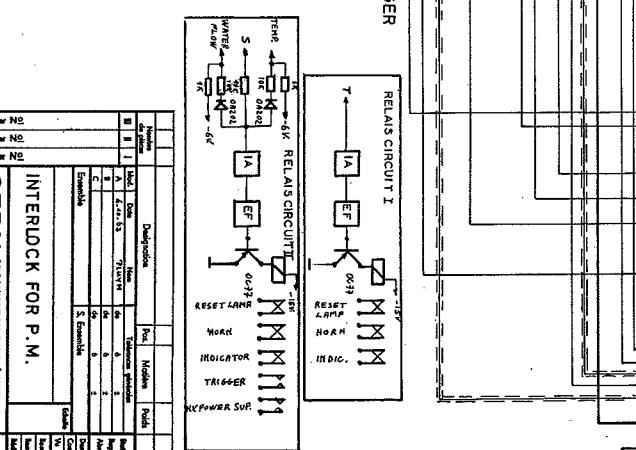
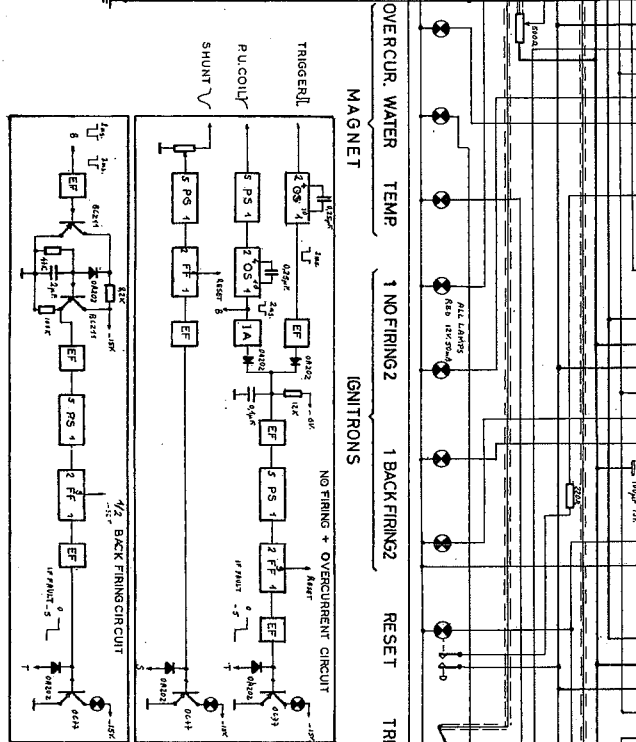
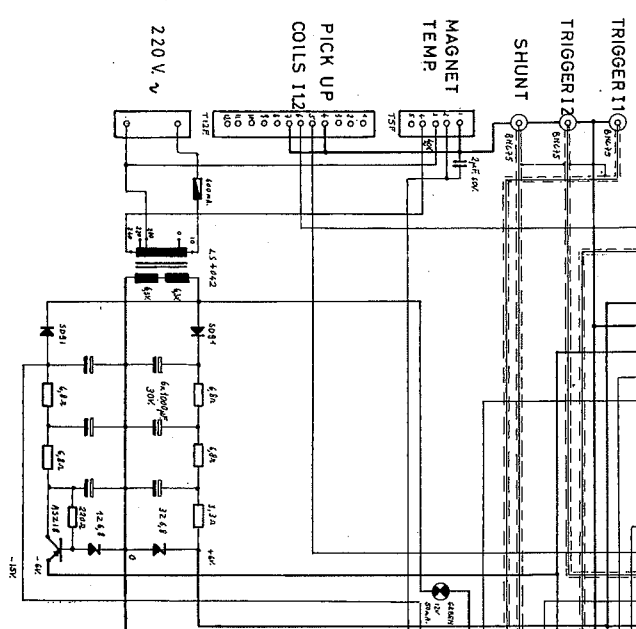
RELAYS CIRCUIT I

RELAYS CIRCUIT II



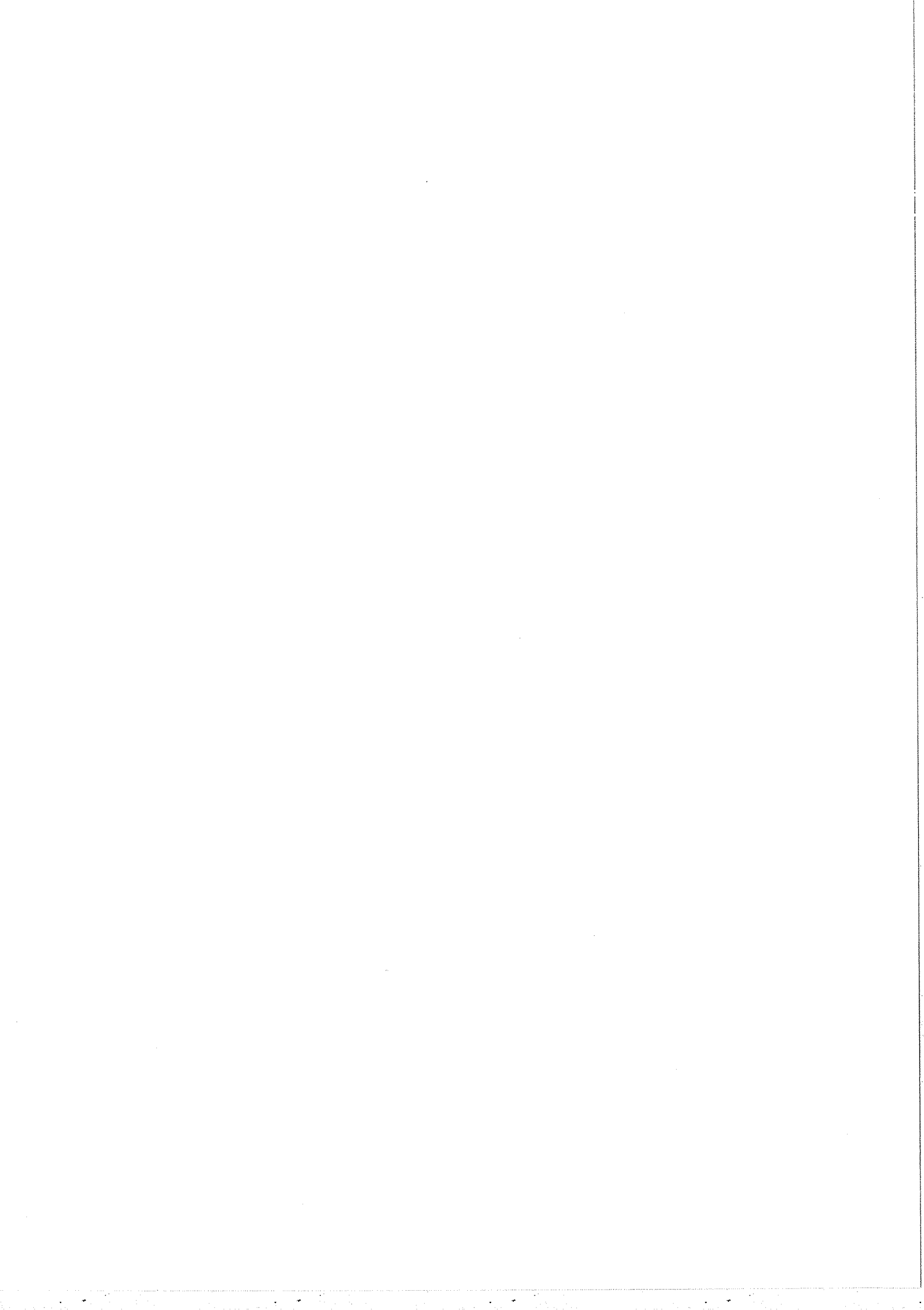
FOR SIMPLIFICATION THE RELAYS-DC LINES HAVE NOT BEEN DRAWN IN THE FRONT OF THIS DRAWING.

HORN INDICATORS  
HV POWER SUPPLY  
IGNITRONS TRIGGER  
WATER FLOW

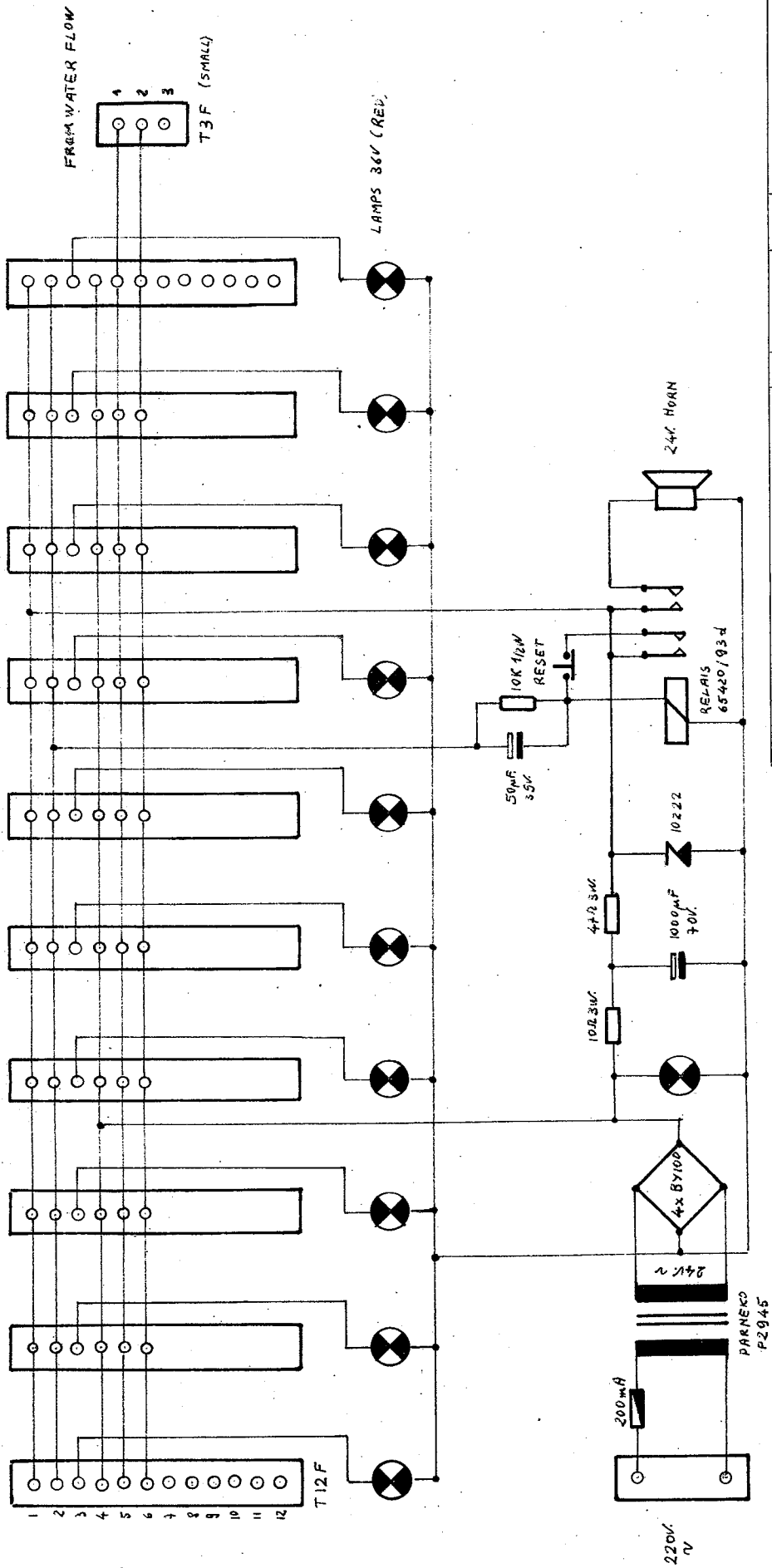


Order No.	Part No.	Description	Qty.	Notes	Remarks
1	6A2	6A2	1		
2	6X5	6X5	1		
3	6AV6	6AV6	1		

INTERLOCK FOR P.M. CERN ORGANISATION EUROPEAN ORGANISATION FOR RESEARCH NUCLEAR ENERGY P.M.13

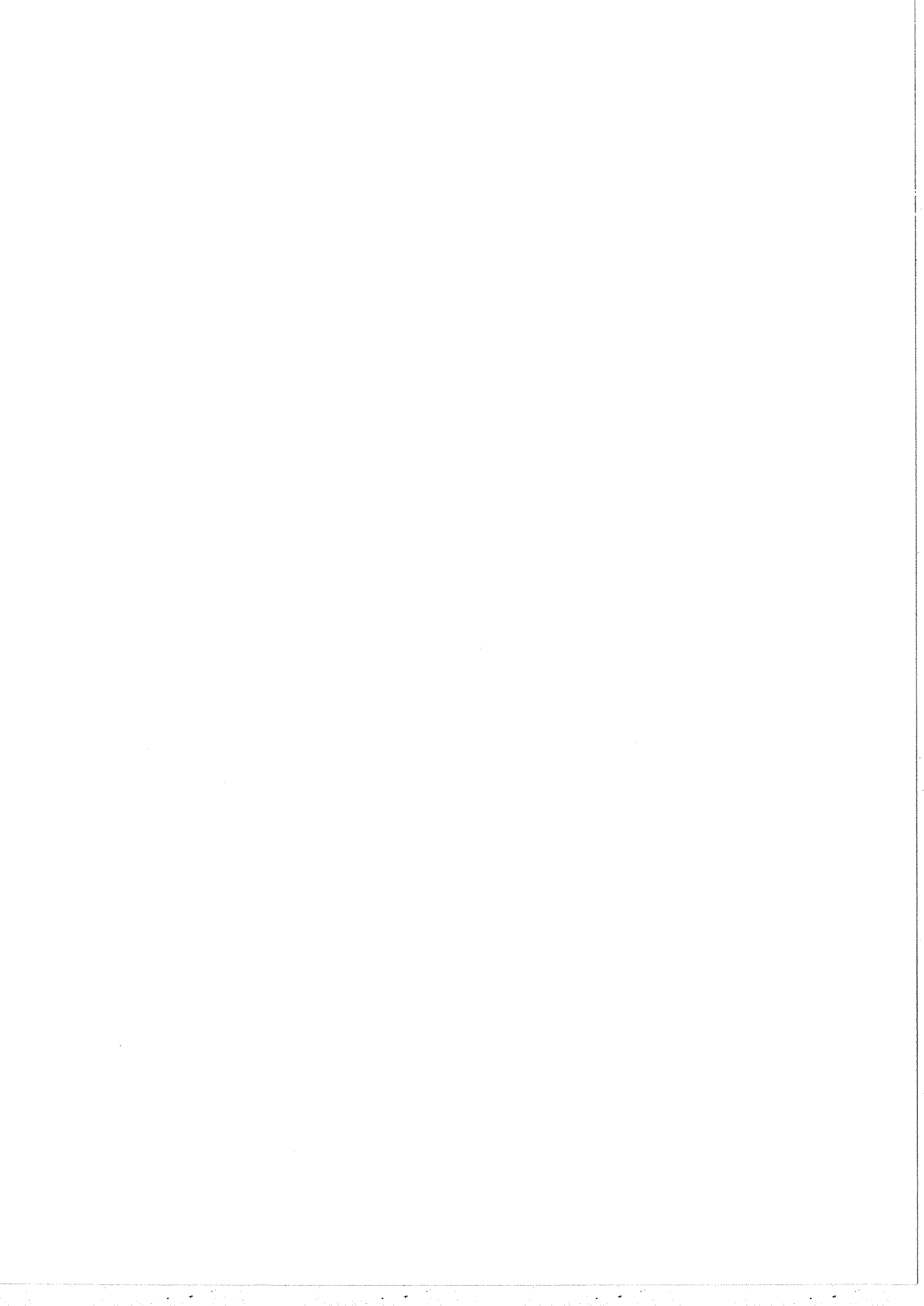


FROM P.M. INTERLOCKS

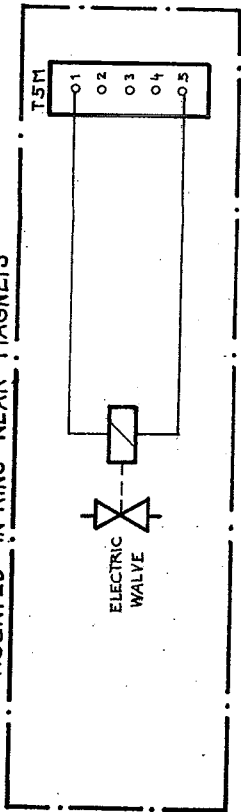


Nombre de pièces		Designation		Pos.	Matière	Poids	Observations
III	II	I	Mod.	Date	Nom	Tolérances générales	
			A	4-10-63	PLUYM	de à ±	
			B			de à ±	Dessiné 4-10-63 G.2. Contrôlé Vu Remplace Remplacé par Réduction
			C			de à ±	
		Ensemble		S. Ensemble		Echelle	
<b>INTERLOCK INDICATORS</b>							
<b>CERN ORGANISATION EUROPÉENNE POUR LA RECHERCHE NUCLÉAIRE - GENEVE</b>							

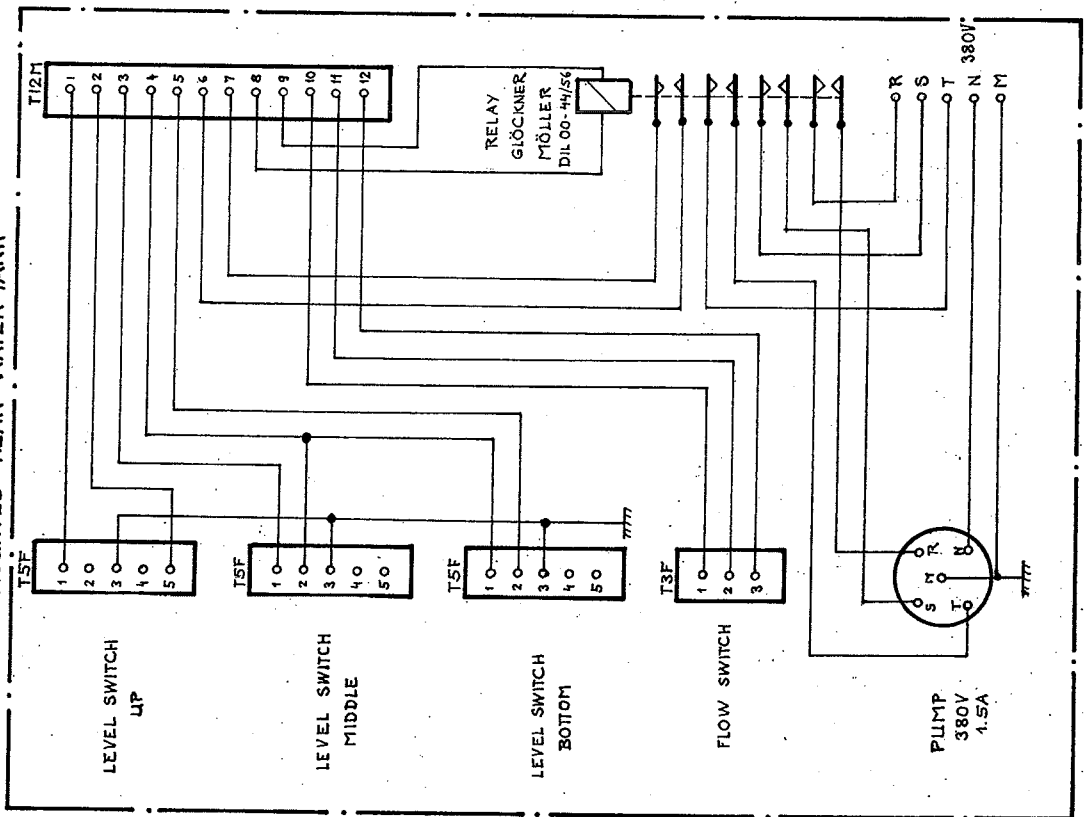
P. M. 14



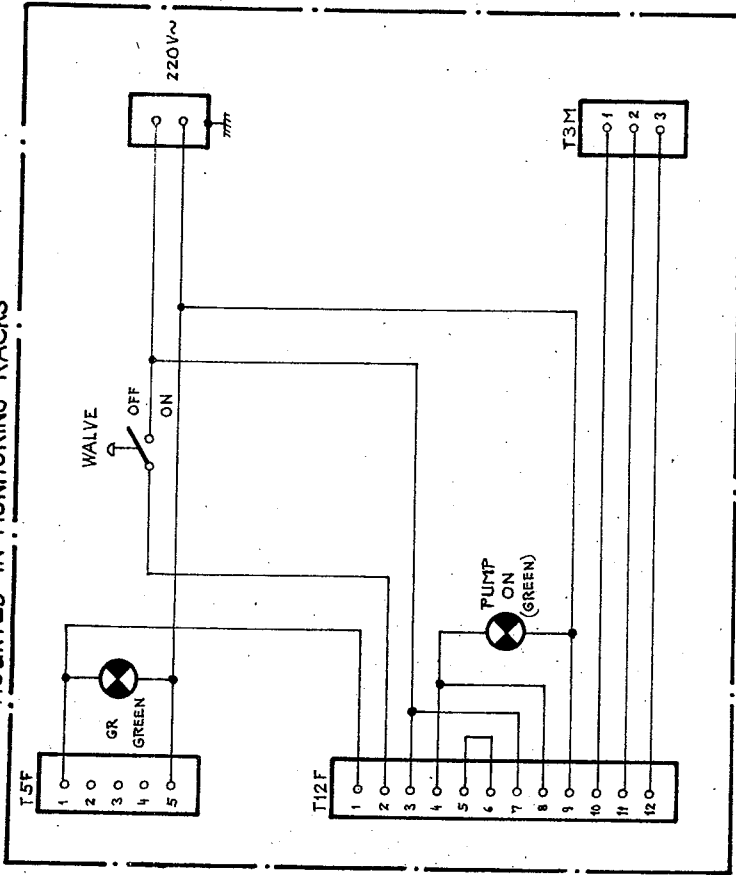
MOUNTED IN RING NEAR MAGNETS



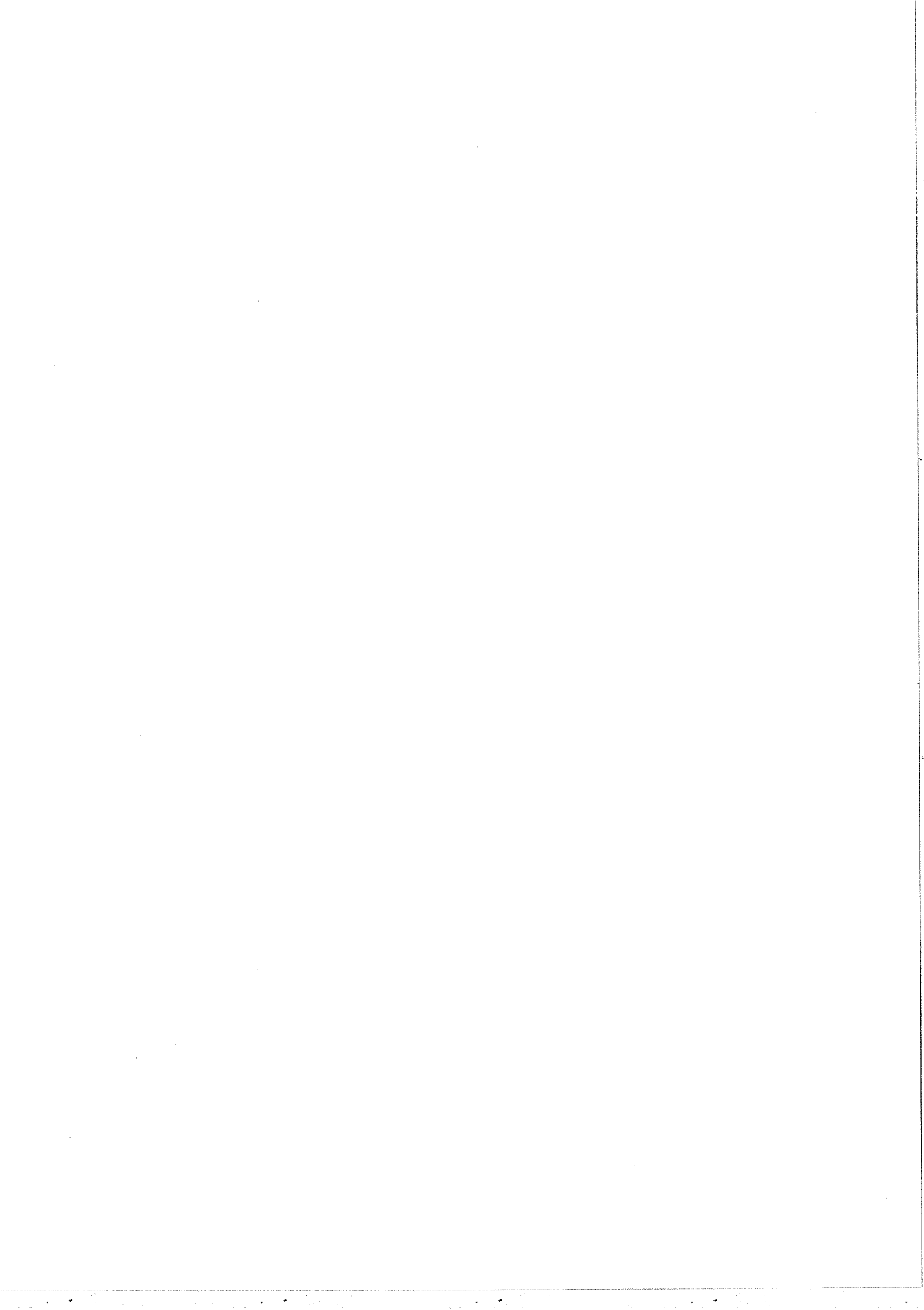
MOUNTED NEAR WATER TANK



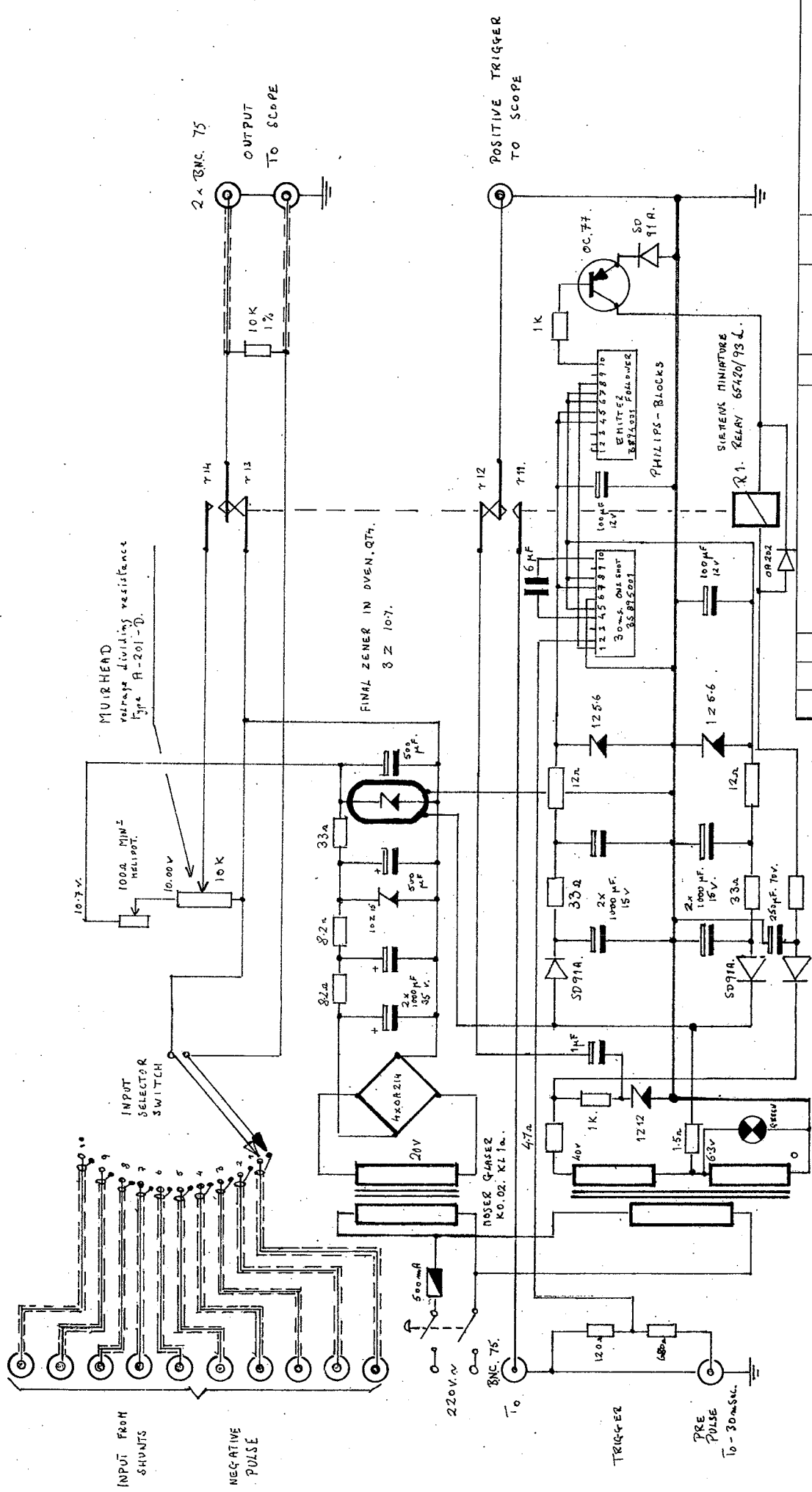
MOUNTED IN MONITORING RACKS



Nombre de pièces		Designation		Pos.	Matiere	Poids	Observations	
III	II	I	Mod.	Date	Nom	Tolérances générales	Etat des surfaces selon VSM 10320 Rugosité en $\mu$ VSM Abréviations VSM 10319	
			A	4-10-63	PLUM M	de		
			B			de		
			C			de		
		Ensemble		S. Ensemble		Designé 6. 9. 62		
		NEUTRINO BEAM		Echelle		Contrôlé Vu		
		WATER CIRCUIT		Remplace		Remplacé par		
		FOR PULSED MAGNETS AND IGNITRONS		Réduction		Réduction		
		CERN ORGANISATION EUROPÉENNE POUR LA RECHERCHE NUCLÉAIRE - GENÈVE				P. M.15		



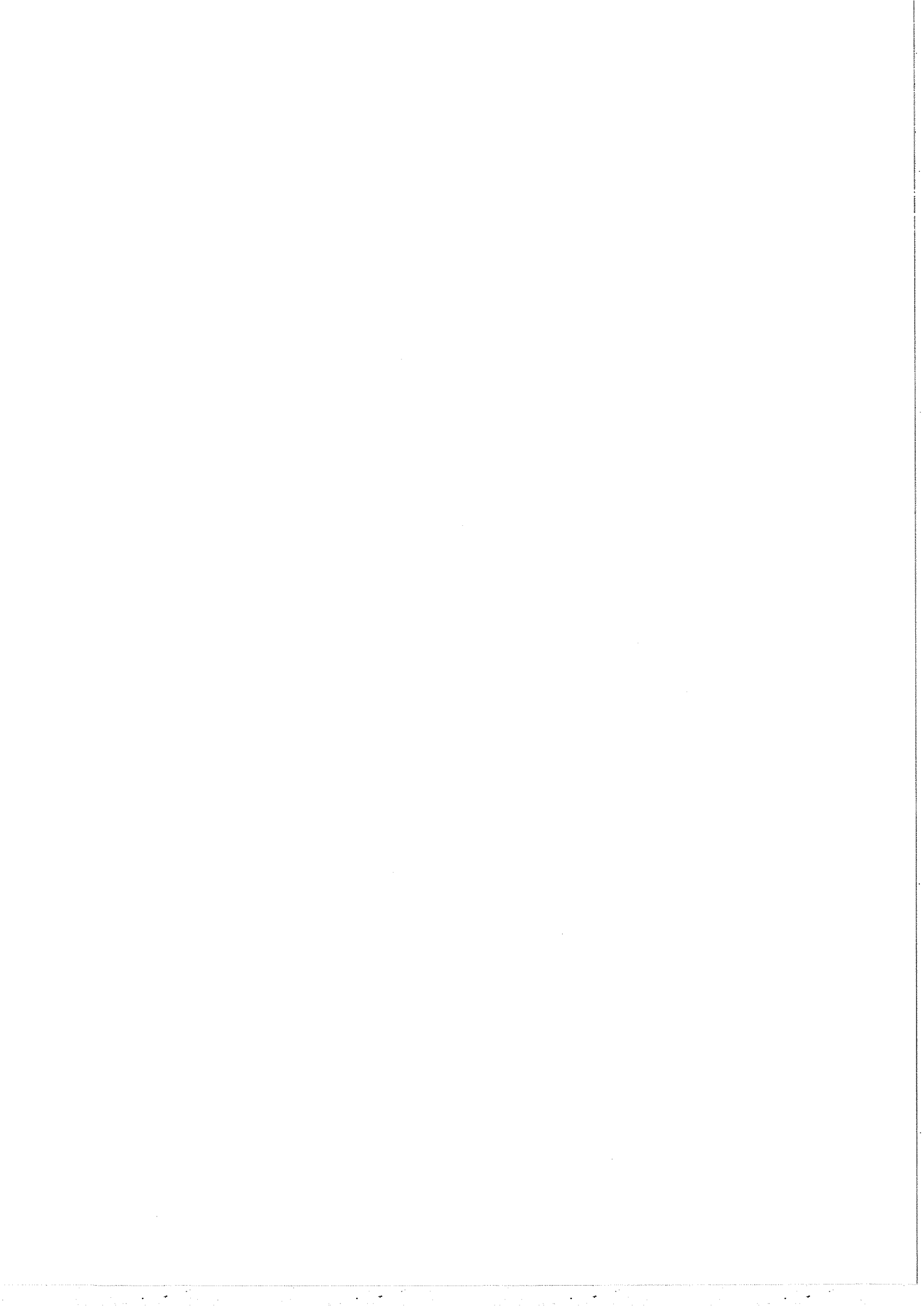


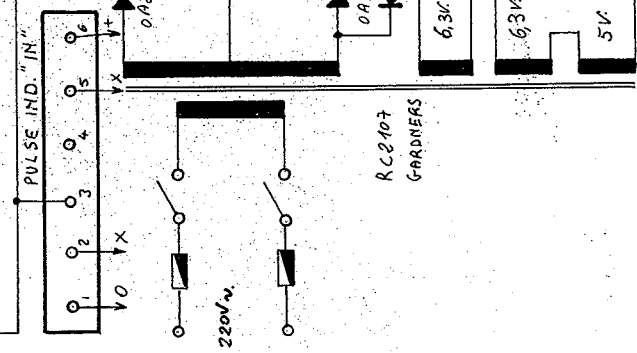
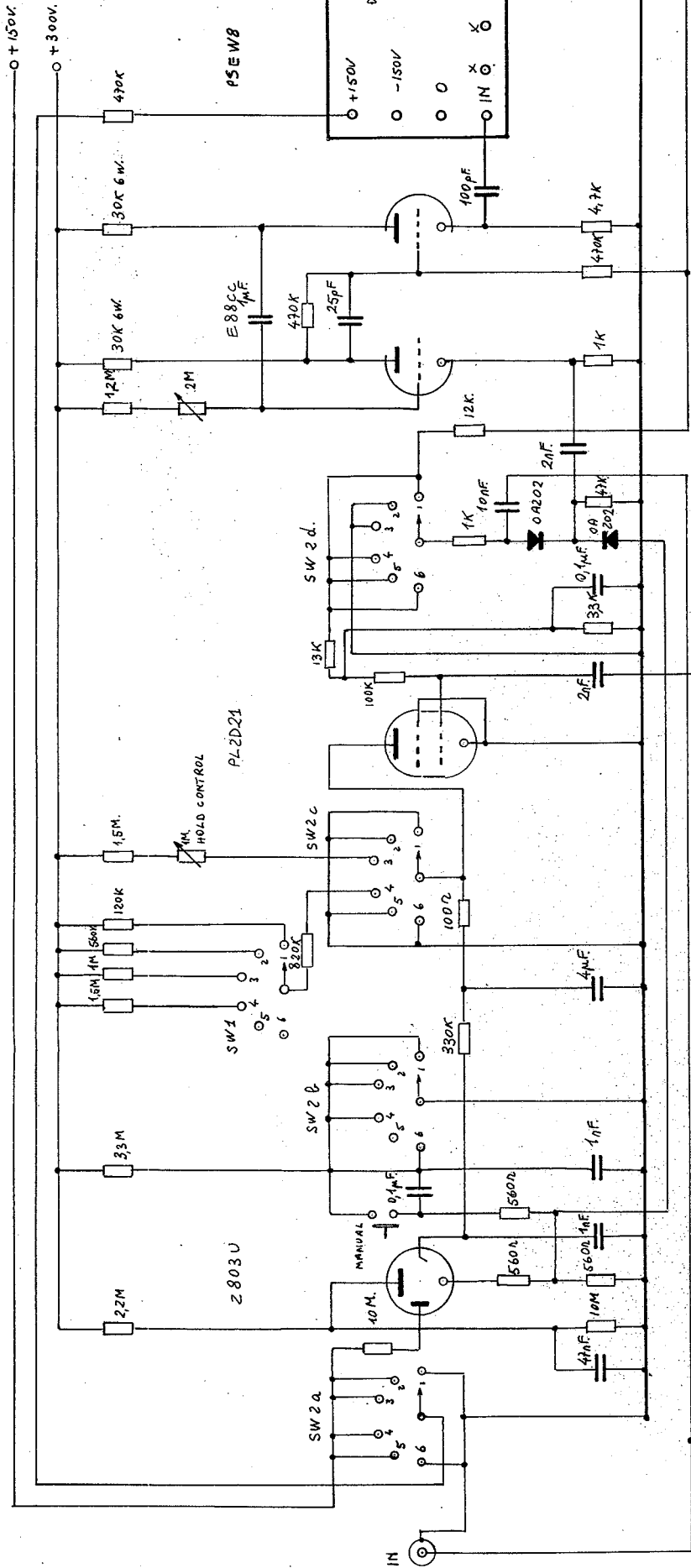


PARMEKO  
P2946, 9000/57

Nombre de pièces		Designation		Pos.		Matière		Poids		Observations	
III	II	I	Mod.	Date	Nom	de	a	±			
			A			de	a	±		Etat des surfaces selon VSM 10320	
			B			de	a	±		Rugosité en μ" VSM	
			C			de	a	±		Abréviations VSM 10319	
Ensemble		S. Ensemble								Dessiné	8.10.63
										Contrôlé	
										Vu	
										Remplace	
										Remplacé par	
										Réduction	
										Etelle	
										NEUTRINO BEAM	
										CURRENT MEASURING CIRCUIT	
										CERN ORGANISATION EUROPEENNE POUR LA RECHERCHE NUCLEAIRE - GENEVE	
										PM 16	

Dossier No  
Dossier No  
Dossier No





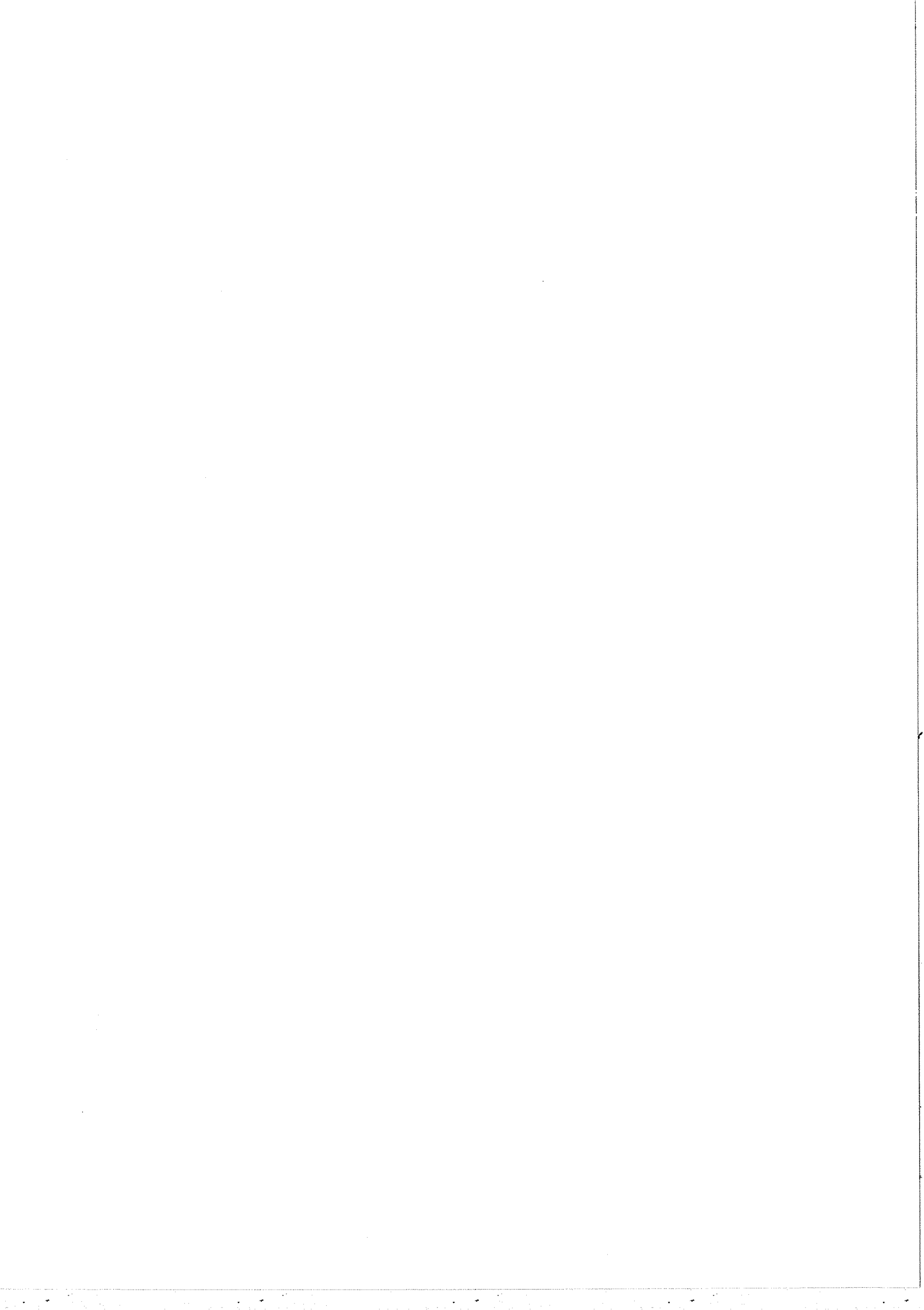
**SW1 (REPETITION RATE)**  
 1 = 2 sec.  
 2 = 3 sec.  
 3 = 4 sec.  
 4 = 5 sec.

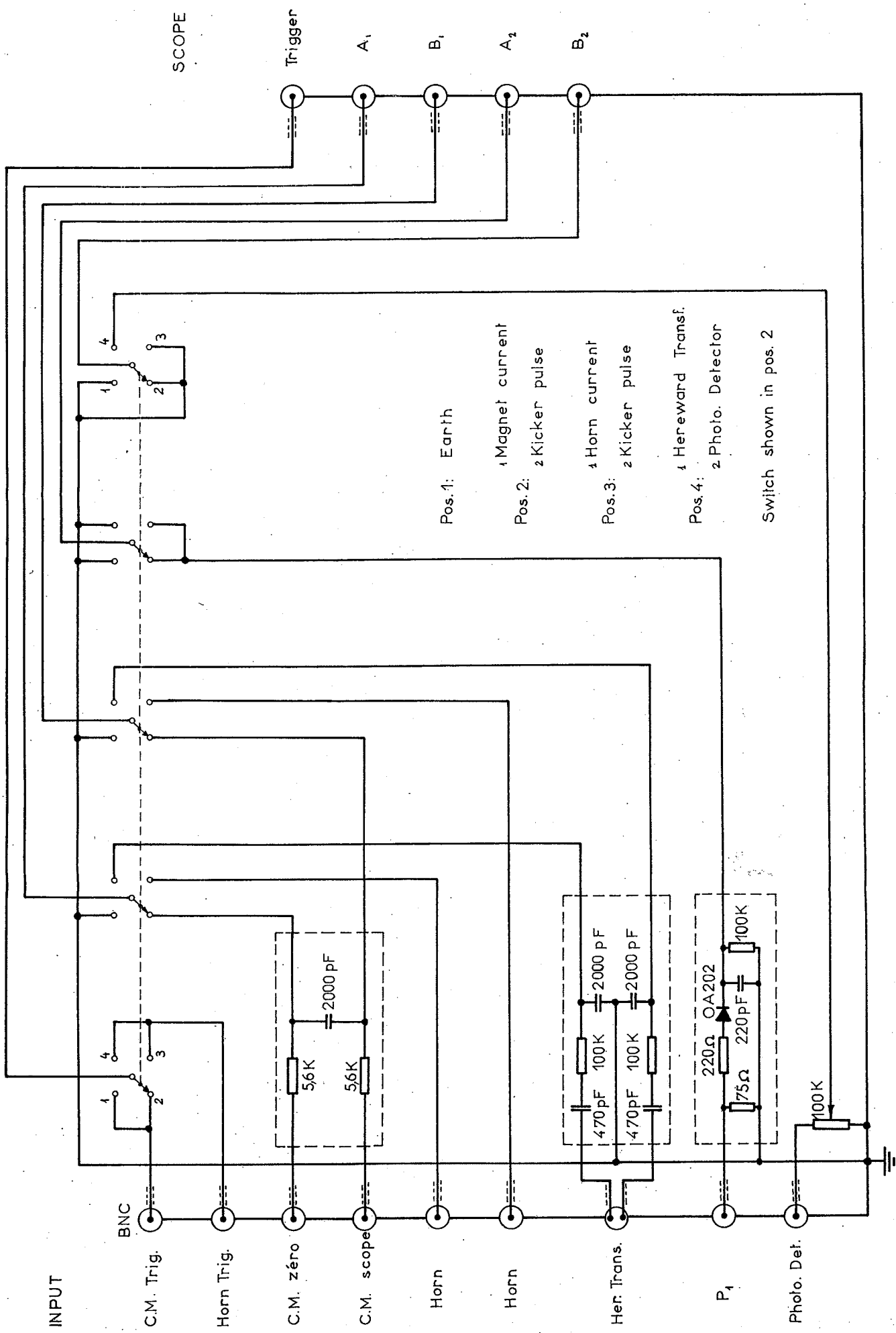
**SW2 (MODE OF OPERATION)**  
 1 = STOP  
 2 = EXTERNAL  
 3 = AUTOMATIC  
 4 = SIMULATOR  
 5 = MANUAL  
 6 = STOP

Nombre de pièces		Designation		Pos.		Matiere		Poids		Observations	
I	II	Mod.	Date	de	à	de	à	Tolérances générales			
III		A								Etat des surfaces selon VSM 10320	
		B								Rugosité en µ"	
		C								Abréviations VSM 10319	
Ensemble										S. Ensemble	
Echelle										Dessiné 62	
										Contrôlé Vu	
										Remplace	
										Remplacé par	
										Réduction	
										PM 17	

# SIMULATOR

CERN ORGANISATION EUROPEENNE POUR LA RECHERCHE NUCLEAIRE - GENÈVE





INPUT

SCOPE

BNC

C.M. Trig.

Horn Trig.

C.M. zéro

C.M. scope

Horn

Horn

Her. Trans.

P<sub>1</sub>

Photo. Det.

Pos. 1: Earth

1 Magnet current

Pos. 2: 2 Kicker pulse

Pos. 3: 1 Horn current

2 Kicker pulse

Pos. 4: 1 Hereward Transf.

2 Photo. Detector

Switch shown in pos. 2

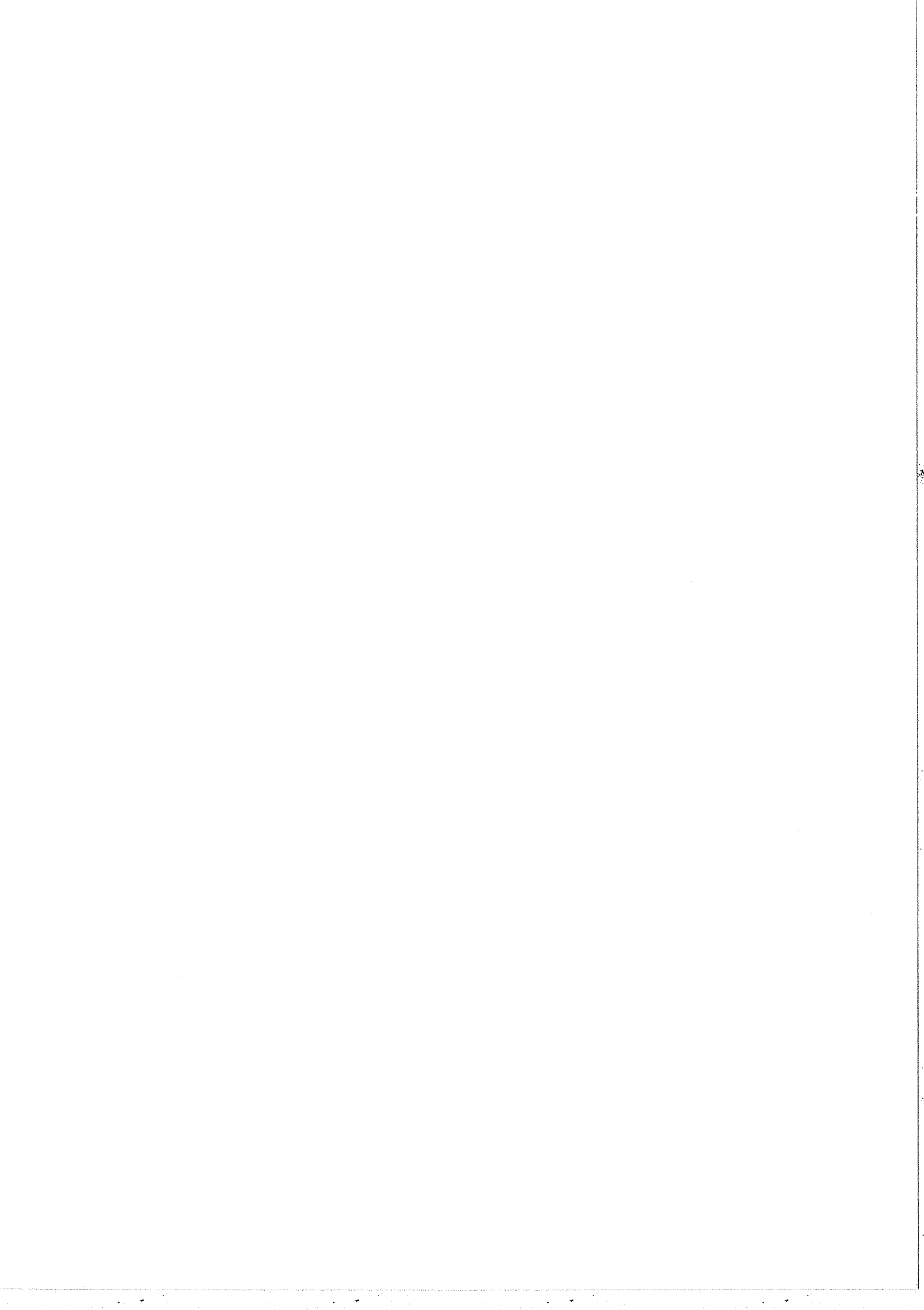
Trigger

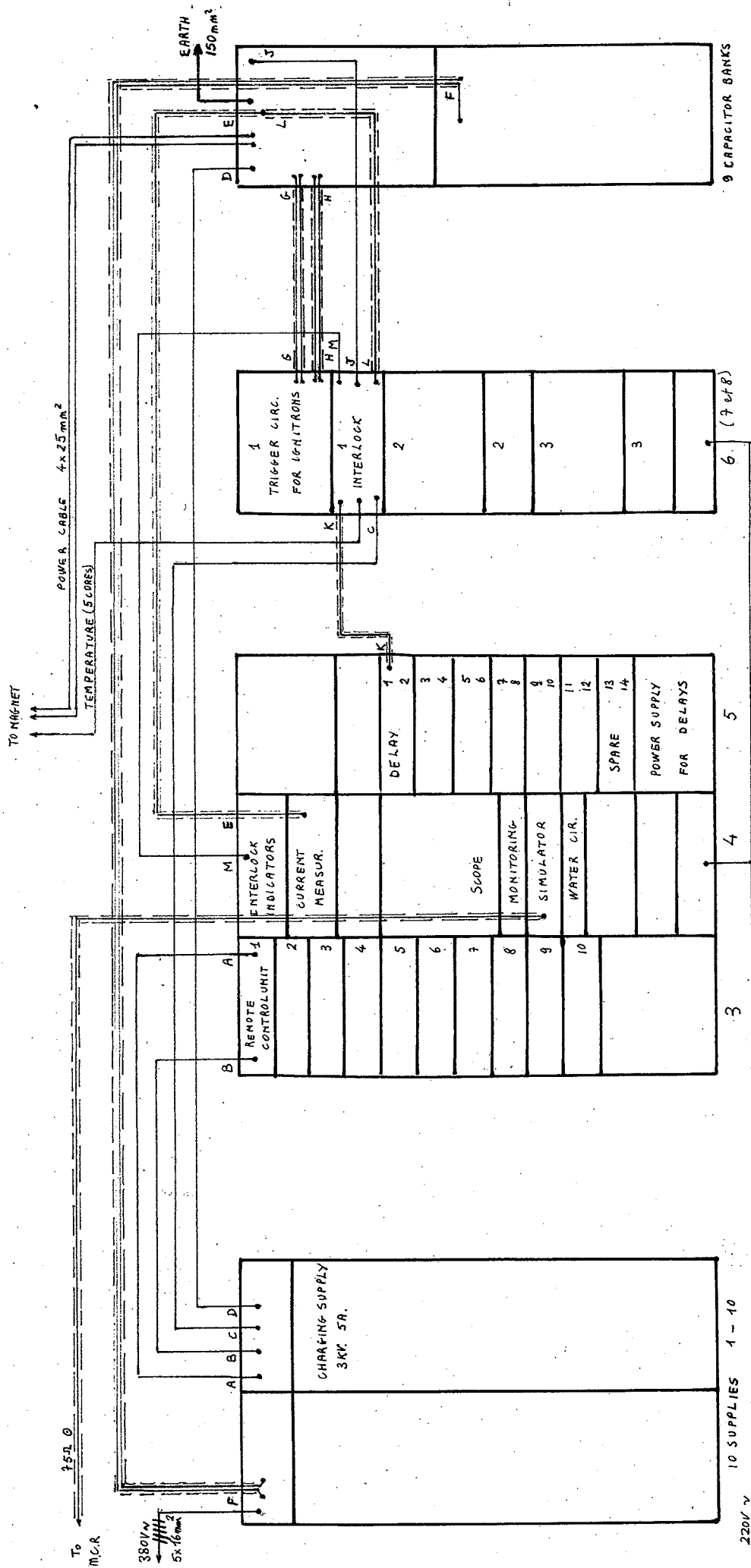
A<sub>1</sub>

B<sub>1</sub>

A<sub>2</sub>

B<sub>2</sub>





- A & B REMOTE CONTROL 12 CORES
- C POWER SUPPLY INTERL. 3 CORES
- D CAPAC. BANK INTERL. 5 CORES
- E SHUNT SIGNAL 75Ω 0
- F H.V. CABLE Special
- G & H TRIGGER IGNITRONS 400Ω
- J P.U. COILS 12 CORES
- K TIMING SIGNAL 75Ω 0
- L OVERCURRENT SIGNAL 75Ω 0
- M INTERLOCK INDICATORS 12 CORES

Nombre de pièces		Designation		Pos.		Matière		Poids		Observations	
III	II	I	Mod.	Date	Nom	de	à	de	à	de	à
			A			±					Etat des surfaces selon VSM 10320
			B			±					Rugosité en μ" VSM
			C			±					Abréviations VSM 10319
		Ensemble		S. Ensemble						Dessiné 4.10.63 G.Z.	
										Contrôle Vu	
										Remplace	
										Remplacé par	
										Réduction	
										Echelle	
										<h1 style="margin: 0;">CABLE PLAN</h1>	
										<h2 style="margin: 0;">CERN ORGANISATION EUROPEENNE POUR LA RECHERCHE NUCLEAIRE - GENEVE</h2>	
										<h3 style="margin: 0;">P.M. 19</h3>	

