

#### **BEAM IMPEDANCE**

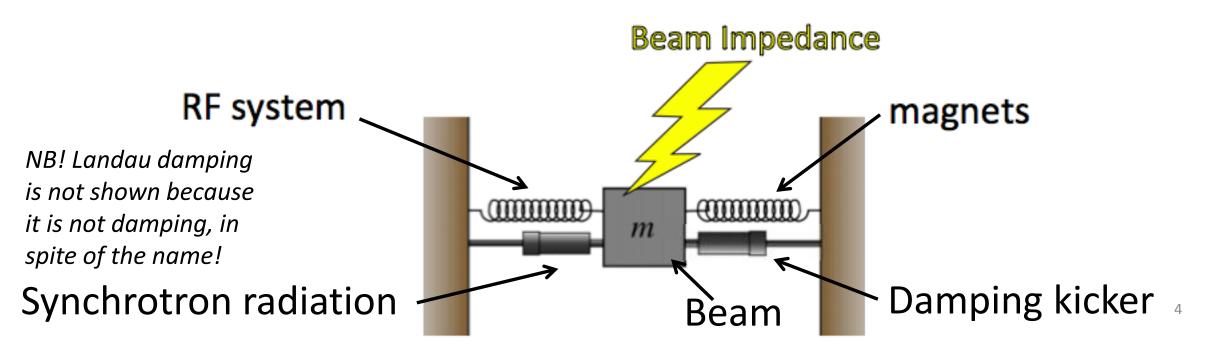
Olav Berrig / CERN

Lanzhou – China May 2018

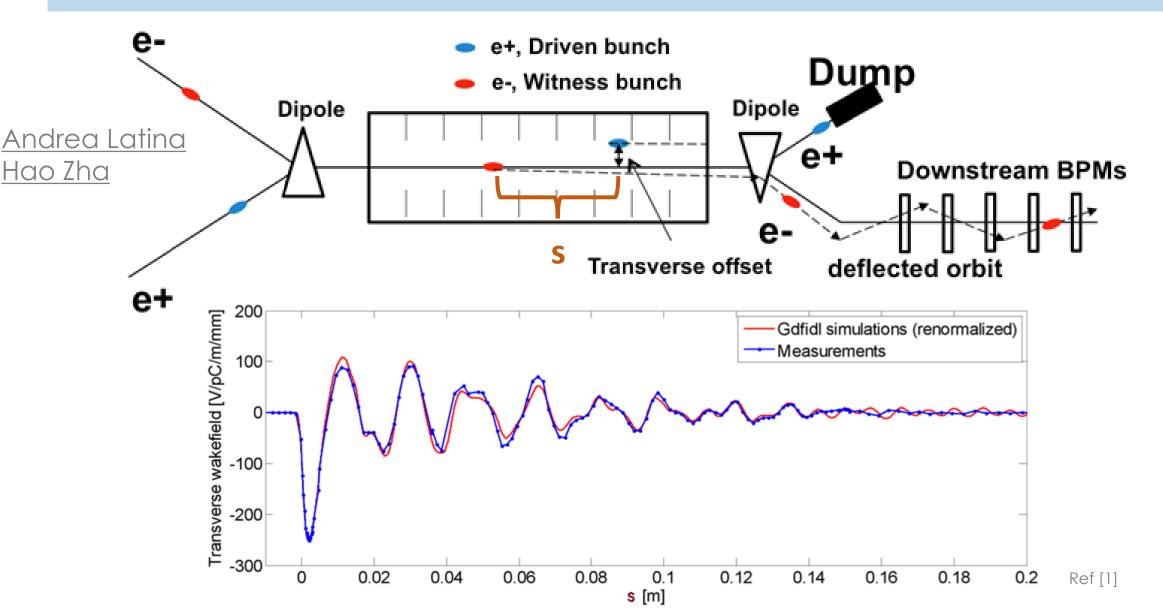
- 1. What is beam impedance?
- 2. Beam impedance is modelled as a lumped impedance
- 3. New formula for longitudinal beam impedance
- 4. Panofsky-Wenzel theorem and transverse impedance
- 5. Lab measurements of beam impedance

- Beam impedance is just a normal impedance.
- However, it is very difficult to understand beam impedance because it is not a lumped impedance but measured over a length.
- In addition it is defined as the difference in impedance between an accelerator equipment and a straight vacuum chamber. The straight vacuum chamber must have constant cross-section; have the same length as the accelerator equipment and have walls that are superconducting (also called perfectly conducting PEC).
- A particle moving in a straight vacuum chamber with constant crosssection and superconducting walls have no beam impedance.

- An accelerator without beam impedance does not have instabilities. Beam impedance is **not** our friend!
- Beam impedance gives the beam a **kick** i.e. a disturbing force acting on the beam. The beam impedance forces will make the beam oscillate, just like a mass suspended between springs:



An example of transverse impedance, that gives the beam a transverse kick! Here measured with the beam

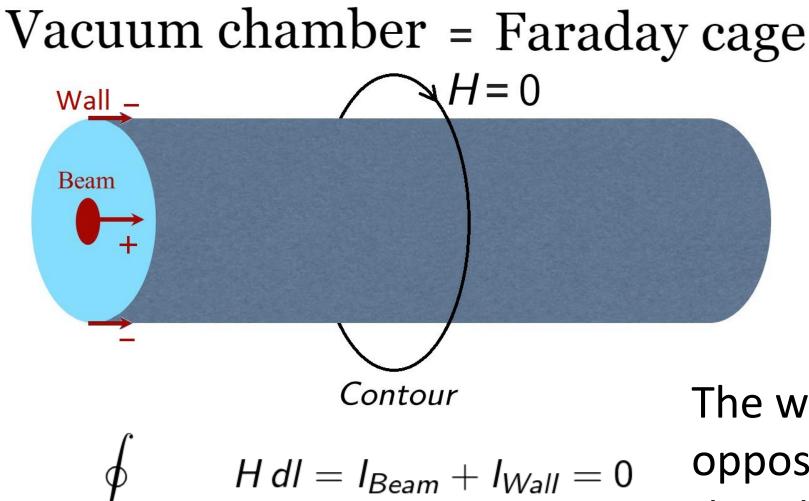


There are many types of beam impedance:

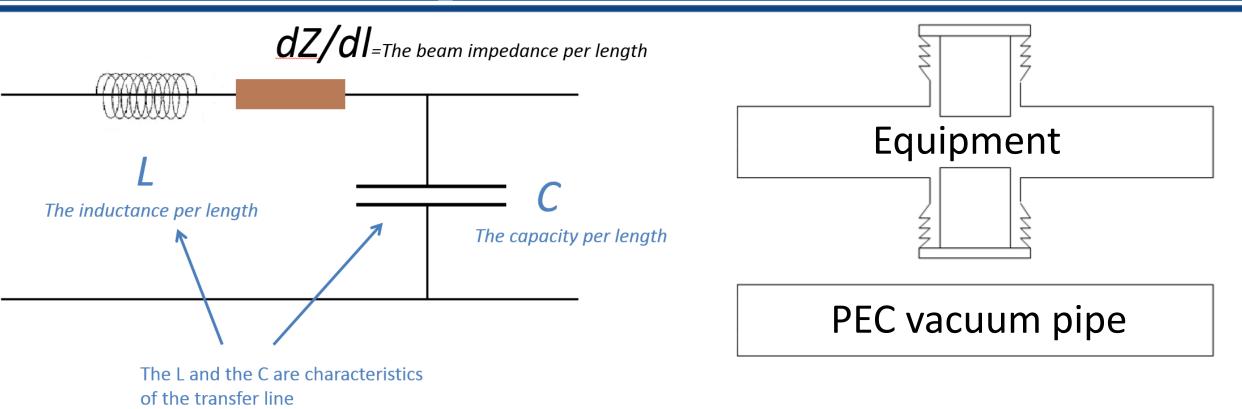
- Beam impedance from the currents in the walls of accelerator equipment (beam coupling impedance):
   1) Resistive wall impedance
   2) Geometric impedance
- Space charge beam impedance
   1) Direct space charge impedance Z<sub>sc</sub>(w)
   2) Indirect space charge impedance \_\_\_\_\_
- Damping kicker impedance, Electron cloud, impedance, ...

#### What is beam impedance? There are many types of beam impedance: Beam impedance from the currents in the walls of accelerator equipment (beam coupling impedance): In the following, I will only talk about beam coupling impedance 1) Resistive wall impedance 2) Geometric impedance **Space charge** beam impedance $Z_{sc}(w)$ 1) Direct space charge impedance 2) Indirect space charge impedance

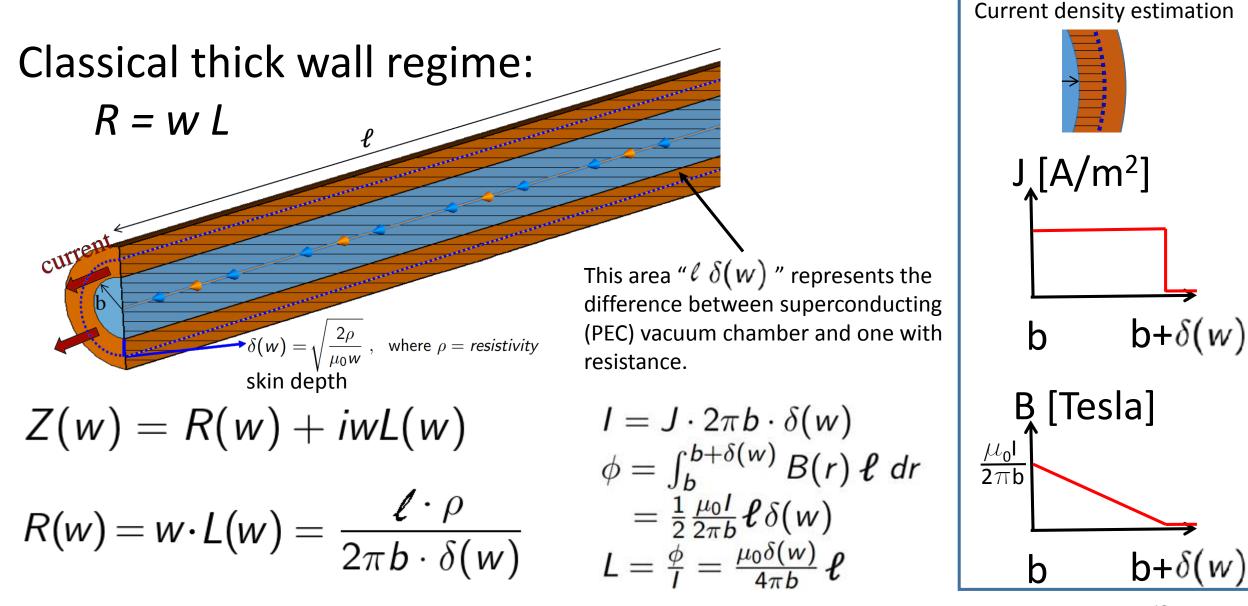
Damping kicker impedance, Electron cloud, impedance, ...



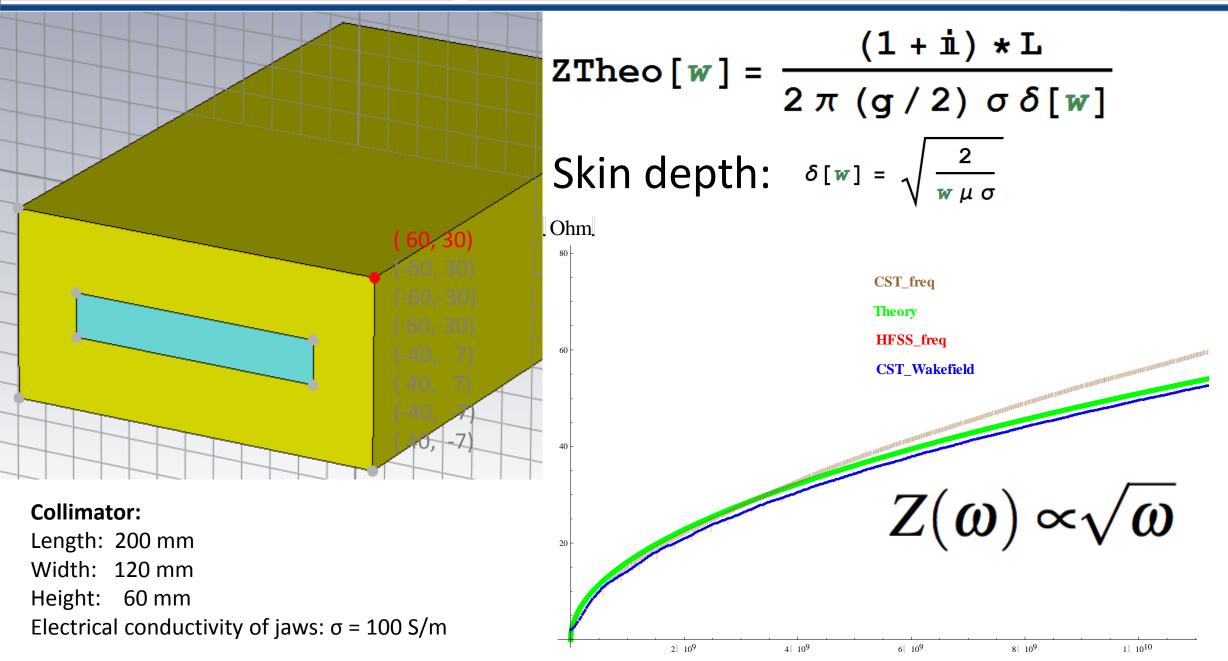
The wall currents must oppose the beam current, so that the fields outside the vacuum chamber are zero



When we calculate the beam impedance for an equipment, we compare the equipment to a perfectly conducting (PEC) vacuum chamber with the same dimensions at start and end.



*Curtesy of M.Migliorati* <sup>10</sup>



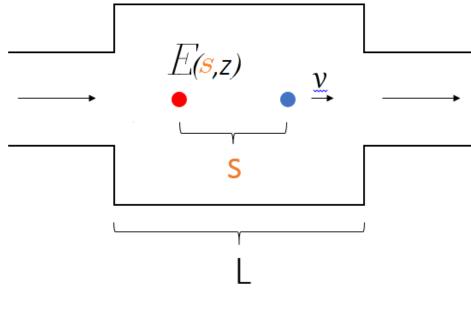
ω

#### R - i w LBeam impedance: R + j w L versus **Circuit definition** "American" Fourier **Chinese and European Fourier** R+jwL R+jwL R-iwL Impedance: $Z(w) = R + j\omega L$ Voltage: $V(t) = V_0 \cdot Cos(w_0 t)$ Add imaginary part: $V(t) = V_0 \cdot (Cos(w_0 t) + j \cdot Sin(w_0 t))$ $= V_0 \cdot e^{jw_0 t}$ Voltage for analysis: $V(\omega) = V_0$ Voltage: $V(t) = V_0 \cdot Cos(w_0 t)$ Voltage: $V(t) = V_0 \cdot Cos(w_0 t)$ Current for analysis: $I(\omega) = I_0 e^{-j\phi}$ Circuit equation: $V(t) = R + L \frac{dI(t)}{dt}$ Circuit equation: $V(t) = R + L \frac{dI(t)}{dt}$ Circuit equation: $V(\omega) = (R + jw_0L) \cdot I(\omega)$ Solution for I: $I(\omega) = \frac{V(\omega)}{R + iw_0 L}$ Fourier Transform: $V(\omega) = R \cdot I(\omega) + j\omega \cdot I(\omega)$ Fourier Transform: $V(\omega) = R \cdot I(\omega) - i\omega \cdot I(\omega)$ $V(\boldsymbol{\omega}) = (R + i\boldsymbol{\omega}L) \cdot I(\boldsymbol{\omega})$ $V(\boldsymbol{\omega}) = (R - i\boldsymbol{\omega}L) \cdot I(\boldsymbol{\omega})$ $=\frac{e^{-J\phi}}{\sqrt{R^2+(w_0L)^2}}\cdot V(\boldsymbol{\omega})$ Solution for I: $I(\omega) = \frac{V(\omega)}{R + i\omega L}$ Solution for I: $I(\omega) = \frac{V(\omega)}{R - i\omega I}$ Convert to time domain: $I(t) = \frac{e^{-j\phi}}{\sqrt{R^2 + (w \cdot I)^2}} \cdot V_0 \cdot e^{jw_0 t}$ Inv.Fourier Transform: $I(t) = \frac{V_0(R \cos(w_0 t) + w_0 L \sin(w_0 t))}{R^2 + w^2 L^2}$ Inv.Fourier Transform: $I(t) = \frac{V_0(R \cos(w_0 t) + w_0 L \sin(w_0 t))}{R^2 + w_0^2 L^2}$ Remove imaginary part: $I(t) = \frac{V_0}{\sqrt{R^2 + (w_0 L)^2}} \cdot Cos(w_0 t - \phi)$ $I(t) = \frac{V_0}{\sqrt{R^2 + (w_0 L)^2}} \cdot Cos(w_0 t - \phi)$ $I(t) = \frac{V_0}{\sqrt{R^2 + (w_0 L)^2}} \cdot Cos(w_0 t - \phi)$ where $\phi = ArcTan(\frac{w_0L}{R})$ where $\phi = ArcTan(\frac{w_0L}{P})$ where $\phi = ArcTan(\frac{w_0L}{P})$

In my experience, accelerator components have only resistive and inductive coupling impedance.

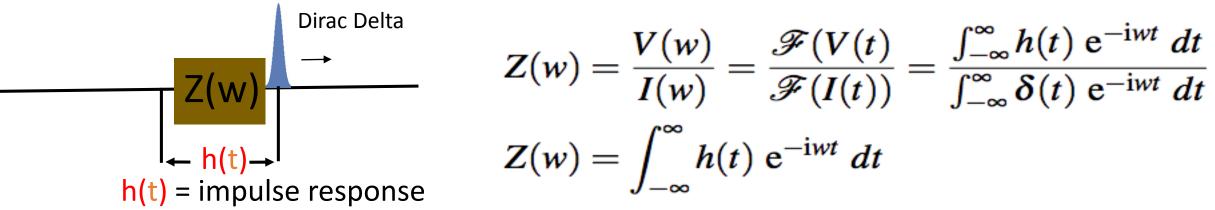
# Beam impedance modelled as lumped impedance

#### **Definition of beam impedance:**

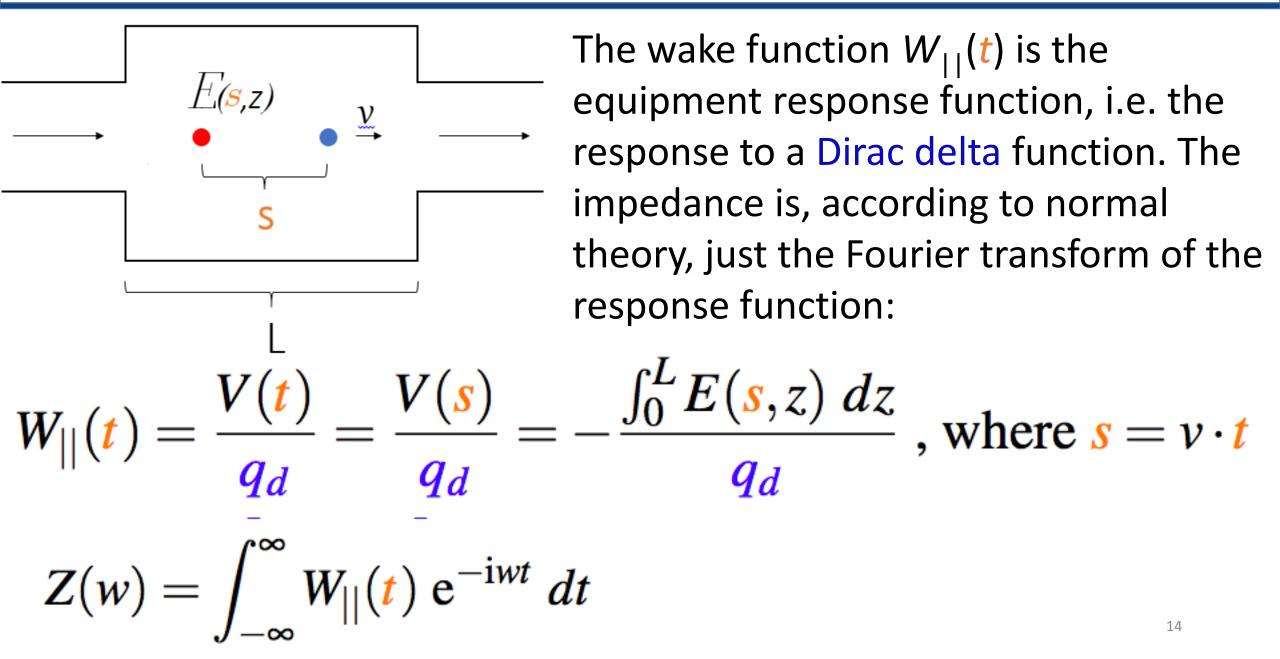


 $V(s) = -\int_{0}^{L} E(s,z) dz$  = Voltage over equipment V(t) = V(s), where  $s = v \cdot t$  $I_d(t) = q_d \cdot \delta(t)$  Drive particle act as a current. (It's a Dirac delta function)  $Z(w) = \frac{V(w)}{I_d(w)} = \frac{\mathscr{F}(V(t))}{\mathscr{F}(I_d(t))} = \frac{\int_{-\infty}^{\infty} V(t) e^{-iwt} dt}{a_d}$  $Z(w) = \int_{-\infty}^{\infty} W_{||}(t) e^{-iwt} dt$ , where  $W_{||}(t) = \frac{V(t)}{2}$ 

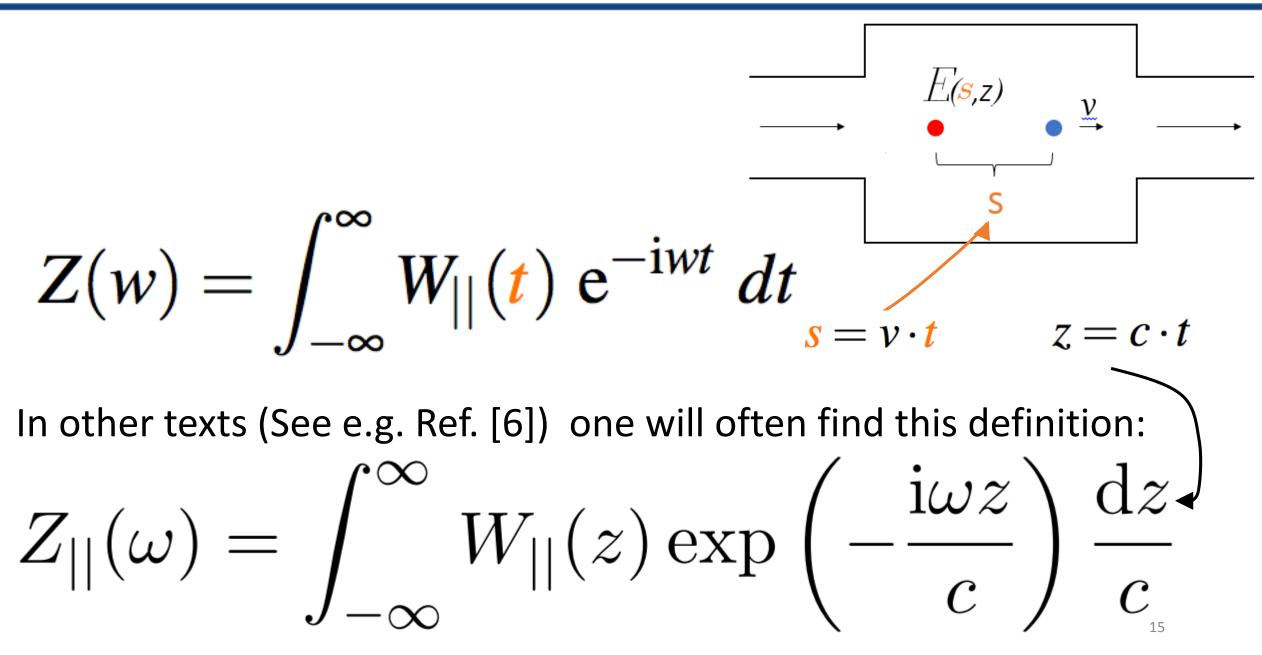
#### **Definition of lumped impedance:**



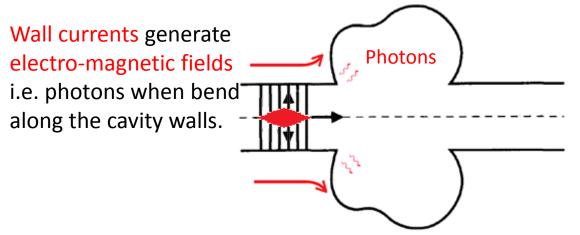
# Beam impedance modelled by lumped impedance



# Beam impedance modelled by lumped impedance

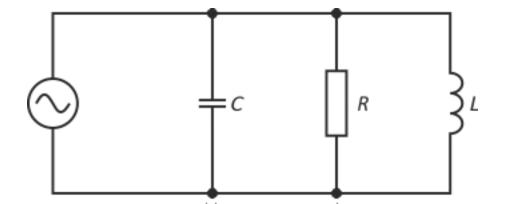


# Beam impedance modelled by lumped impedance



The electro-magnetic fields stays in the cavity and generates a **resonance**, which will disturb i.e. kick the following bunch.

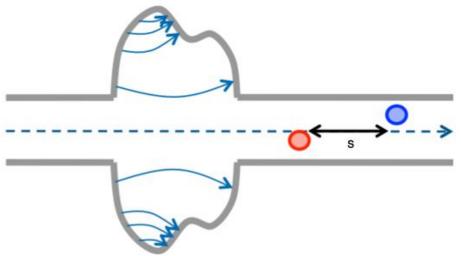
A resonance is modeled as a RLC-circuit:



**RLC-circuit definition** used for resonance ("American" Fourier)  $Z_{\parallel}(W) = \grave{0} W_{\parallel}(t) e^{jWt} dt$  $k_{loss} = \frac{1}{2D} \overset{\forall}{\overset{\circ}{0}} \hat{A} \{ Z_{\parallel}(W) \} \overset{\checkmark}{d} W$  $W_0 = \frac{1}{\sqrt{IC}}; Q = R\sqrt{\frac{C}{I}}$  $Z_{\parallel}(W) = \frac{K}{1 + jQ(W/W_0 - W_0/W)}$  $k_{loss} = \frac{W_0}{4} \frac{R}{Q}$ The energy lost, is equal to the loss factor " $k_{loss}$ " multiplied with the square of the charge of the bunch: The bigger R/Q the bigger the  $E_{loss} = k_{loss} \cdot q_{bunch}^2$ energy loss.

NB! This definition of the loss factor is only valid for a bunch that is a dirac delta function. The more general definition will be given later.

The Longitudinal beam impedance is a function of the transverse position of the drive and test particles i.e. 4 variables. It can therefore be decomposed into 15 parameters (Z0,  $Z1_{xd}$ ,  $Z1_{xt}$ , etc..) that represent all combinations of the 4 variables:



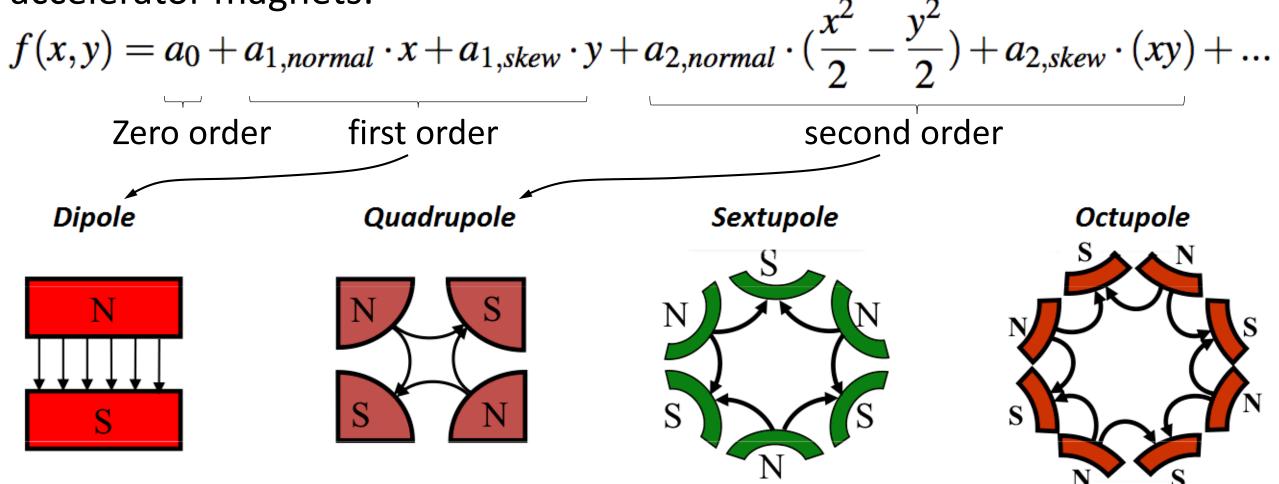
Z[xd, xt, yd, yt] = Z0  $+Z1_{xd} \cdot xd + Z1_{xt} \cdot xt + Z1_{yd} \cdot yd + Z1_{yt} \cdot yt$   $+Z2_{xdxd} \cdot xdxd + Z2_{xtxt} \cdot xtxt + Z2_{ydyd} \cdot ydyd + Z2_{ytyt} \cdot ytyt$   $+Z2_{xdxt} \cdot xdxt + Z2_{xdyd} \cdot xdyd + Z2_{xdyt} \cdot xdyt$   $+Z2_{xtyd} \cdot xtyd + Z2_{xtyt} \cdot xtyt + Z2_{ydyt} \cdot ydyt$ 

#### Holomorphic decomposition:

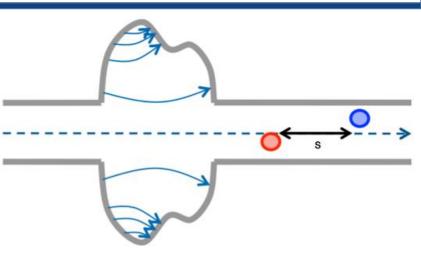
Any two dimensional field, and very importantly a field that can really exist (so not an artificially constructed field), can be decomposed into multipolar components. This is the same idea used in Fourier transforms. The holomorphic decomposition expands the field into normal and skew multipolar functions:

$$f(x,y) = a_0 + a_{1,normal} \cdot x + a_{1,skew} \cdot y + a_{2,normal} \cdot (\frac{x}{2} - \frac{y}{2}) + a_{2,skew} \cdot (xy) + \dots$$
Zero order first order second order
NB! Notice that the coefficients for x squared and y
squared are same numerical value but opposite signs

The normal and skew multipolar functions are well known from accelerator magnets:



Using the holomorphic decomposition for both the drive and test particles, knowing that the coefficients for the squared values of xd & yd and xt & yt must be of opposite sign, the formula can be reduced to 13 terms:



$$Z[xd, xt, yd, yt] = Z0$$
  
+  $Z1_{xd} \cdot xd + Z1_{xt} \cdot xt + Z1_{yd} \cdot yd + Z1_{yt} \cdot yt$   
+  $Z2_{drive} \cdot (xdxd - ydyd) + Z2_{test} \cdot (xtxt - ytyt)$   
+  $Z2_{xdxt} \cdot xdxt + Z2_{xdyd} \cdot xdyd + Z2_{xdyt} \cdot xdyt$   
+  $Z2_{xtyd} \cdot xtyd + Z2_{xtyt} \cdot xtyt + Z2_{ydyt} \cdot ydyt$ 

Using a property, called the Lorentz reciprocity principle, which says that if we exchange the positions of the drive and test particles. the beam impedance stays unchanged, i.e. Z[xd, xt, yd, yt] = Z[xt, xd, yt, yd]. This leads to 5 equalities:

 $Z1_{xd} = Z1_{xt}, \ Z1_{yd} = Z1_{yt}, \ Z2_{drive} = Z2_{test}, \ Z2_{xdyd} = Z2_{xtyt}, \ Z2_{xdyt} = Z2_{xtyd}$ The new formula for longitudinal beam impedance finally has only 8 terms:

Z[xd, xt, yd, yt] = Z0 $+Z1_x \cdot (xd + xt) + Z1_y \cdot (yd + yt)$  $+Z2_A \cdot (xdxd - ydyd + xtxt - ytyt)$  $+Z2_B \cdot (xdyd + xtyt) + Z2_C \cdot (xdyt + xtyd)$  $+Z2_D \cdot xdxt + Z2_E \cdot ydyt$ 

Using a property, called the Lorentz reciprocity principle, which says that if we exchange the positions of the drive and test particles. the beam impedance stays unchanged, i.e. Z[xd, xt, yd, yt] = Z[xt, xd, yt, yd]. This leads to 5 equalities:

 $Z1_{xd} = Z1_{xt}, \ Z1_{yd} = Z1_{yt}, \ Z2_{drive} = Z2_{test}, \ Z2_{xdyd} = Z2_{xtyt}, \ Z2_{xdyt} = Z2_{xtyd}$ The new formula for longitudinal beam impedance finally has only 8 terms:

Z[xd, xt, yd, yt] = Z0+  $Z1_x \cdot (xd + xt) + Z1_y \cdot (yd + yt)$ Quadrupolar term  $\rightarrow + Z2_A \cdot (xdxd - ydyd + xtxt - ytyt)$ 

 $+Z2_B\cdot(xdyd+xtyt)+Z2_C\cdot(xdyt+xtyd)$ 

 $+Z2_D \cdot xdxt + Z2_E \cdot ydyt$ 

Using a property, called the Lorentz reciprocity principle, which says that if we exchange the positions of the drive and test particles. the beam impedance stays unchanged, i.e. Z[xd, xt, yd, yt] = Z[xt, xd, yt, yd]. This leads to 5 equalities:

 $Z1_{xd} = Z1_{xt}, \ Z1_{yd} = Z1_{yt}, \ Z2_{drive} = Z2_{test}, \ Z2_{xdyd} = Z2_{xtyt}, \ Z2_{xdyt} = Z2_{xtyd}$ The new formula for longitudinal beam impedance finally has only 8 terms:

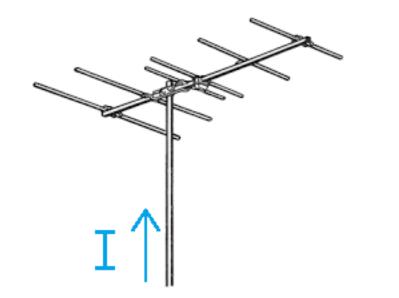
Z[xd, xt, yd, yt] = Z0+  $Z1_x \cdot (xd + xt) + Z1_y \cdot (yd + yt)$ Quadrupolar term  $\rightarrow + Z2_A \cdot (xdxd - ydyd + xtxt - ytyt)$ 

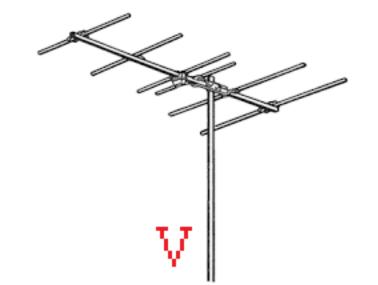
 $+Z2_B \cdot (xdyd + xtyt) + Z2_C \cdot (xdyt + xtyd)$ 

Dipolar terms H & V  $\rightarrow + Z2_D \cdot xdxt + Z2_E \cdot ydyt$ 

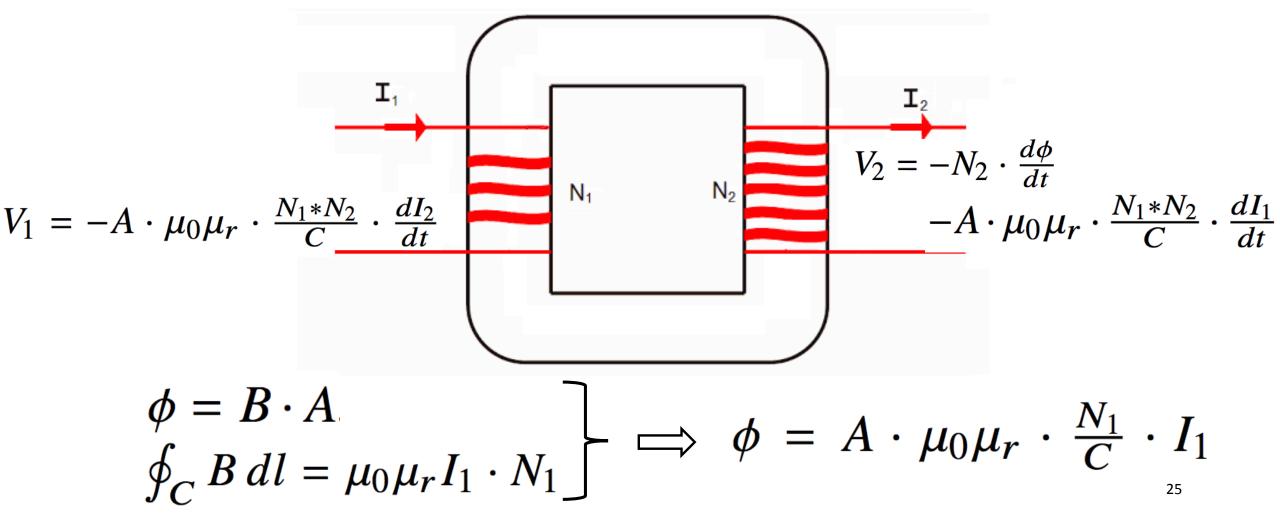
Interchanging the drive and test particles, will give the same beam impedance.

It is caused by the **Lorentz reciprocity theorem** (well known to RF people as the identity S21≡S12):

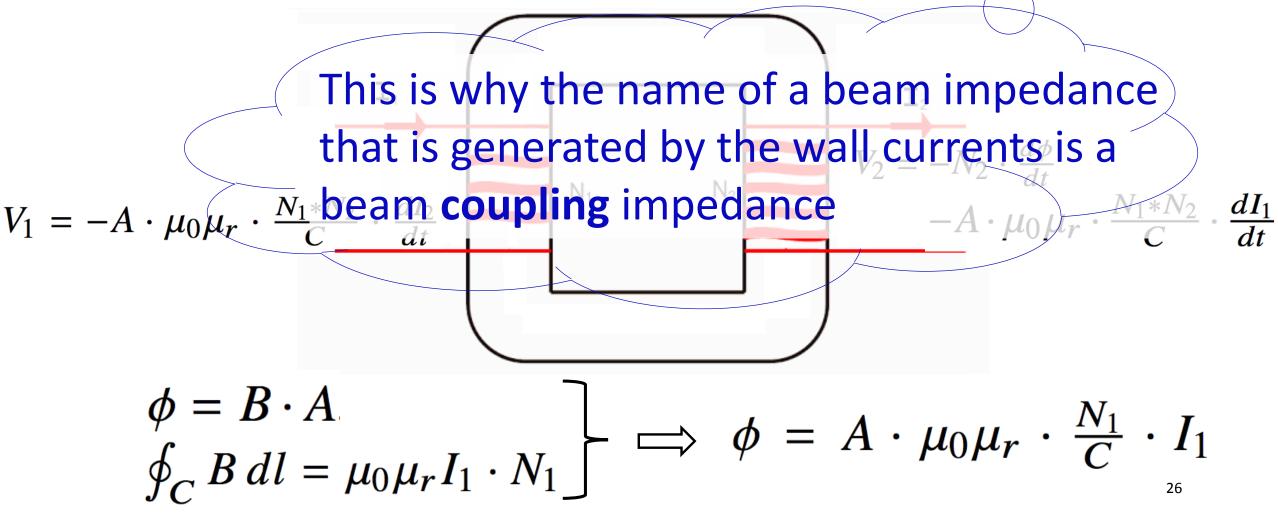


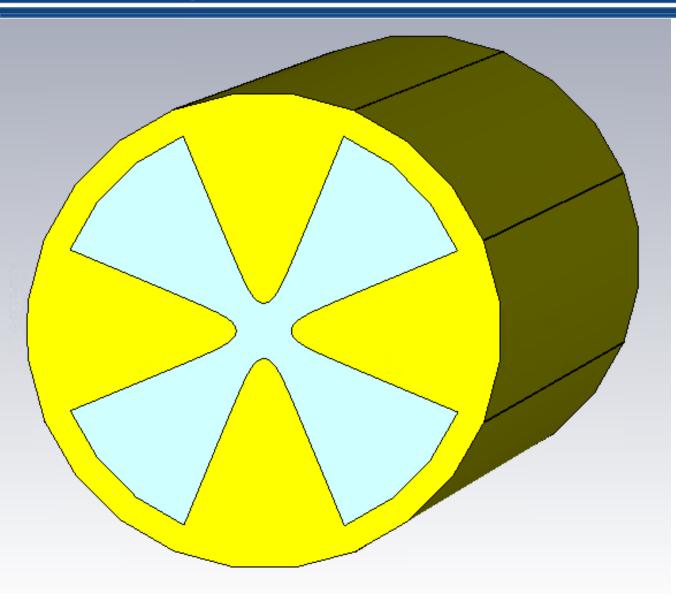


The Lorentz reciprocity theorem is responsible for coupling primary and secondary windings in a transformer:



The Lorentz reciprocity theorem is responsible for coupling primary and secondary windings in a transformer:  $\bigcirc$ 





The new formula shows that 90 degree symmetrical structures only have dipolar impedance and that this impedance is the same in all directions

- This new formula is not valid for resonances nor for non-relativistic beams  $\beta < 1$ , because both are spread out in 3D.
- The formula is practically valid for beams with  $\beta \approx 1$ , even though theoretically there will always be other terms, but these terms are proportional to  $\frac{1}{\gamma^2}$ , so will not be important in practice:

$$Z[xd, xt, yd, yt] = Z0$$
  
+ Z1<sub>x</sub> · (xd + xt) + Z1<sub>y</sub> · (yd + yt)  
+ Z2<sub>A</sub> · (xdxd - ydyd + xtxt - ytyt)  
+ Z2<sub>B</sub> · (xdyd + xtyt) + Z2<sub>C</sub> · (xdyt + xtyd)  
+ Z2<sub>D</sub> · xdxt + Z2<sub>E</sub> · ydyt

The rigid bunch approximation states that the beam motion is little affected during the passage through the structure. So the beam shape is rigid and it always moves Wakefield unchanged with the bunch.  $v = \beta c e_z$  The force acting on the test particle:  $F(x, y, z, t) = q(E(x, y, z, t) + v \times B(x, y, z, t))$  $\nabla \times F = \nabla \times q(E + v \times B)$ 

> Using Maxwell's equations:  $\nabla \times E(x, y, z, t) = -\frac{\partial B(x, y, z, t)}{\partial t}$

$$\mathbf{v}\cdot \mathbf{B}(x,y,z,t)=0$$

$$\nabla \times \boldsymbol{F} = q \left[ -\frac{\partial \boldsymbol{B}}{\partial t} - \beta c \frac{\partial \boldsymbol{B}}{\partial z} \right]$$

Very important: The force acting on the test particle: Because the wakefield is only  $\nabla \times \mathbf{F} = q \left[ -\frac{\partial \mathbf{B}}{\partial t} - \beta c \frac{\partial \mathbf{B}}{\partial z} \right]$ a function of "s" then: B(s) This leads to  $\nabla \times \boldsymbol{F} = \begin{vmatrix} \boldsymbol{x} & \boldsymbol{y} & \boldsymbol{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F & F & F \end{vmatrix} = \left( \frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \right) \hat{\boldsymbol{x}} + \left( \frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x} \right) \hat{\boldsymbol{y}} + \left( \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \right) \hat{\boldsymbol{z}}$ Position of drive particle:  $v \cdot t$  $\nabla_{\perp}F_{z} = \frac{\partial F_{\perp}}{\partial z} - q \left[ -\frac{\partial B_{y}}{\partial t} \widehat{y} - \beta c \frac{\partial B_{y}}{\partial z} \widehat{y} + \frac{\partial B_{x}}{\partial t} \widehat{x} + \beta c \frac{\partial B_{x}}{\partial z} \widehat{x} \right]$ Position of the test particle: z $z = vt - s \implies -\begin{cases} \frac{\partial s}{\partial t} = v \\ \frac{\partial s}{\partial z} = -1 \end{cases}$  $\nabla_{\perp}F_{z}(x,y,z,\tau) = -\frac{\partial F_{\perp}(x,y,z,\tau)}{\partial z}$ When inserting the partial differentials on the right, the terms in the bracket cancels out and gives zero.

The force acting on the test particle: Very important: Because the wakefield is only  $\nabla \times \mathbf{F} = q \left[ -\frac{\partial \mathbf{B}}{\partial t} - \beta c \frac{\partial \mathbf{B}}{\partial z} \right]$ a function of "s" then: B(s) This leads to  $\nabla \times \boldsymbol{F} = \begin{vmatrix} \boldsymbol{x} & \boldsymbol{y} & \boldsymbol{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \boldsymbol{F} & \boldsymbol{F} & \boldsymbol{F} \end{vmatrix} = \left( \frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \right) \hat{\boldsymbol{x}} + \left( \frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x} \right) \hat{\boldsymbol{y}} + \left( \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \right) \hat{\boldsymbol{z}}$ Position of drive particle:  $v \cdot t$  $\nabla_{\perp}F_{z} = \frac{\partial F_{\perp}}{\partial z} - q \left[ -\frac{\partial B_{y}}{\partial t} \widehat{y} - \beta c \frac{\partial B_{y}}{\partial z} \widehat{y} + \frac{\partial B_{x}}{\partial t} \widehat{x} + \beta c \frac{\partial B_{x}}{\partial z} \widehat{x} \right]$ Position of the test particle: z $z = vt - s \implies -\begin{cases} \frac{\partial s}{\partial t} = v \\ \frac{\partial s}{\partial z} = -1 \end{cases}$  $\nabla_{\perp}F_{z}(x,y,z,\tau) = -\frac{\partial F_{\perp}(x,y,z,\tau)}{\partial z}$ When inserting the partial differentials on the right, the terms in the bracket cancels Panofsky Wenzel theorem out and gives zero. 31

$$\nabla_{\perp}F_{z}(x,y,z,\tau) = -\frac{\partial F_{\perp}(x,y,z,\tau)}{\partial s}$$

To obtain the theorem in terms of impedance, one can simply start from the wake function form:

$$\nabla_{\perp} w_{||}(x, y, z, \tau) = \frac{\partial w_{\perp}}{\partial s}(x, y, z, \tau)$$

Then change the s derivative with the time derivative. Use  $\partial s = v \partial \tau = \beta c \ \partial \tau$ :

$$\nabla_{\perp} w_{||}(x, y, z, \tau) = \frac{1}{\beta c} \frac{\partial w_{\perp}}{\partial \tau}(x, y, z, \tau)$$

Finally take the Fourier transform on both sides:

$$\nabla_{\perp} \int_{-\infty}^{+\infty} e^{-i\omega\tau} w_{z}(x, y, z, \tau) d\tau = \frac{1}{\beta c} \int_{-\infty}^{+\infty} e^{-i\omega\tau} \frac{\partial w_{\perp}(x, y, z, \tau)}{\partial \tau} d\tau$$
$$\nabla_{\perp} Z_{\parallel}(x, y, z, \omega) = \frac{\omega}{\beta c} Z_{\perp}(x, y, z, \omega)$$
Panofsky Wenzel theorem  $Z_{\perp}$ 

NB! The transverse impedance is defined with a complex *i* factor:  $_{+\infty}^{+\infty} e^{-i\omega\tau} w_{\perp}(x, y, z, \tau) d\tau$ 

$$\nabla_{\perp} Z_{\parallel}(x, y, z, \omega) = \frac{\omega}{\beta c} \mathbf{Z}_{\perp}(x, y, z, \omega)$$

Using the following definitions:

(
$$\boldsymbol{\omega}$$
)  
 $\nabla_{\perp} Z_{\parallel} = \frac{\partial Z_{\parallel}}{\partial xt} \hat{\boldsymbol{x}} + \frac{\partial Z_{\parallel}}{\partial yt} \hat{\boldsymbol{y}}$  and  $\boldsymbol{Z}_{\perp} = Z_x \hat{\boldsymbol{x}} + Z_y \hat{\boldsymbol{y}}$ 

 $Z_{\perp,x} = \frac{\beta c}{w} \cdot \frac{\partial Z_{\parallel}}{\partial xt}$  $Z_{\perp,y} = \frac{\beta c}{w} \cdot \frac{\partial Z_{\parallel}}{\partial yt}$ 

 $Z_{\perp,x}(\boldsymbol{\omega}) = Z\mathbf{1}_x + 2Z\mathbf{2}_A \cdot xt + Z\mathbf{2}_B \cdot yt + Z\mathbf{2}_C \cdot yd + Z\mathbf{2}_D \cdot xd$  $Z_{\perp,y}(\boldsymbol{\omega}) = Z\mathbf{1}_y - 2Z\mathbf{2}_A \cdot yt + Z\mathbf{2}_B \cdot xt + Z\mathbf{2}_C \cdot xd + Z\mathbf{2}_E \cdot yd$ 

$$Z[xd, xt, yd, yt] = Z0$$
  
+ Z1<sub>x</sub> · (xd + xt) + Z1<sub>y</sub> · (yd + yt)  
+ Z2<sub>A</sub> · (xdxd - ydyd + xtxt - ytyt)  
+ Z2<sub>B</sub> · (xdyd + xtyt) + Z2<sub>C</sub> · (xdyt + xtyd)  
+ Z2<sub>D</sub> · xdxt + Z2<sub>E</sub> · ydyt

$$\nabla_{\perp} Z_{\parallel}(x, y, z, \omega) = \frac{\omega}{\beta c} \mathbf{Z}_{\perp}(x, y, z, \omega)$$

Using the following definitions:

$$Z_{||} = Z_{z}$$

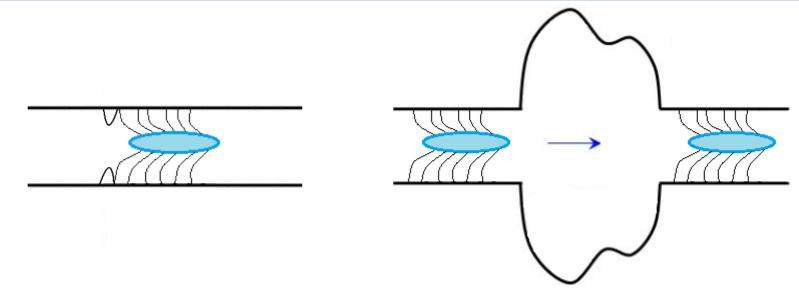
$$\nabla_{\perp} Z_{||} = \frac{\partial Z_{||}}{\partial xt} \hat{x} + \frac{\partial Z_{||}}{\partial yt} \hat{y} \quad \text{and} \quad Z_{\perp} = Z_{x} \hat{x} + Z_{y} \hat{y}$$

$$Z_{\perp,x} = \frac{\beta c}{w} \cdot \frac{\partial Z_{||}}{\partial xt}$$
$$Z_{\perp,y} = \frac{\beta c}{w} \cdot \frac{\partial Z_{||}}{\partial yt}$$
Panofsky Wenzel theorem

Panofsky Wenzel theorem In differential form

$$Z_{\perp,x}(\boldsymbol{\omega}) = Z\mathbf{1}_x + 2Z\mathbf{2}_A \cdot xt + Z\mathbf{2}_B \cdot yt + Z\mathbf{2}_C \cdot yd + Z\mathbf{2}_D \cdot xd$$
$$Z_{\perp,y}(\boldsymbol{\omega}) = Z\mathbf{1}_y - 2Z\mathbf{2}_A \cdot yt + Z\mathbf{2}_B \cdot xt + Z\mathbf{2}_C \cdot xd + Z\mathbf{2}_E \cdot yd$$

$$Z[xd, xt, yd, yt] = Z0$$
  
+  $Z1_x \cdot (xd + xt) + Z1_y \cdot (yd + yt)$   
+  $Z2_A \cdot (xdxd - ydyd + xtxt - ytyt)$   
+  $Z2_B \cdot (xdyd + xtyt) + Z2_C \cdot (xdyt + xtyd)$   
+  $Z2_D \cdot xdxt + Z2_E \cdot ydyt$ 



- Because of the rigid bunch approximation, which states that the beam motion is little affected during the passage through a structure, the wake field is the same before and after the passage of an equipment.
- Therefore, it is as if B is only a function of "s". <u>A criterion for the Panofsky-Wenzel</u> theorem is therefore that the vacuum chamber has to have the same cross-section before and after the equipment – otherwise the B-field is not the same.

#### Lab measurements of beam impedance. Wire #1

We can measure the beam impedance with wire measurements

This is based on the assumption that a bunch interacts with an equipment in exactly the same way as a coaxial cable (i.e. a wire inside the equipment):

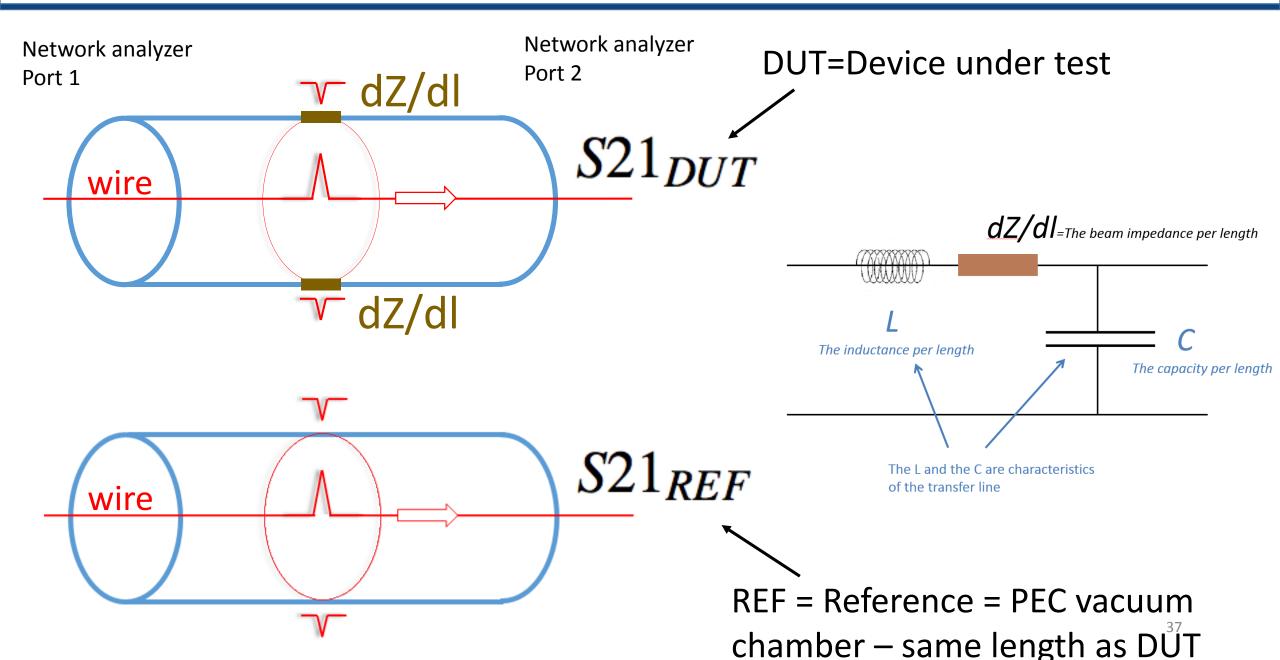
Ultra-relativistic beam field

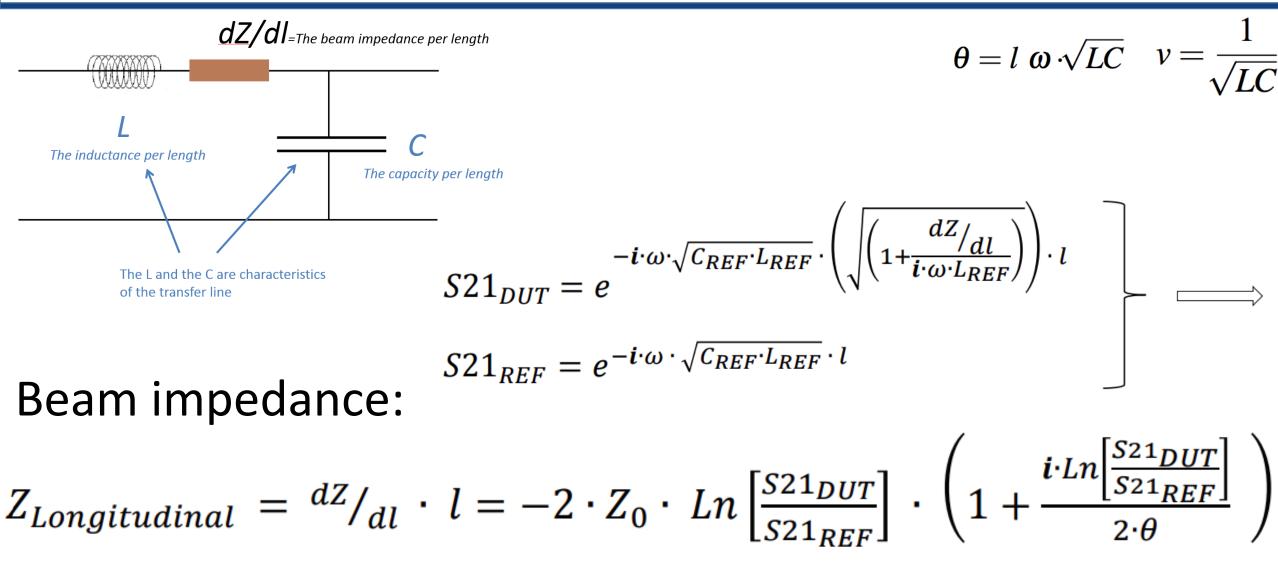
$$E_r(r,\omega) = Z_0 H_{\varphi}(r,\omega) = \frac{Z_0 q}{2\pi r} \exp\left(-j\frac{\omega}{c}z\right)$$

TEM mode coax waveguide

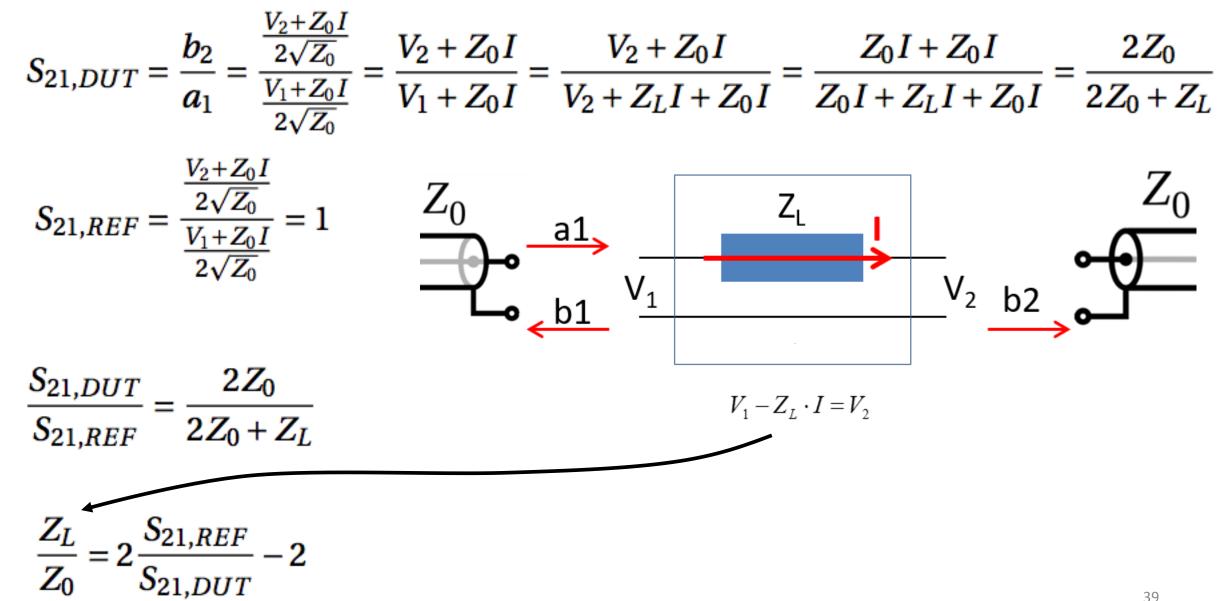
$$E_r(r,\omega) = Z_0 H_{\varphi}(r,\omega) = Z_0 \frac{\text{const}}{r} \exp\left(-j\frac{\omega}{c}z\right)$$

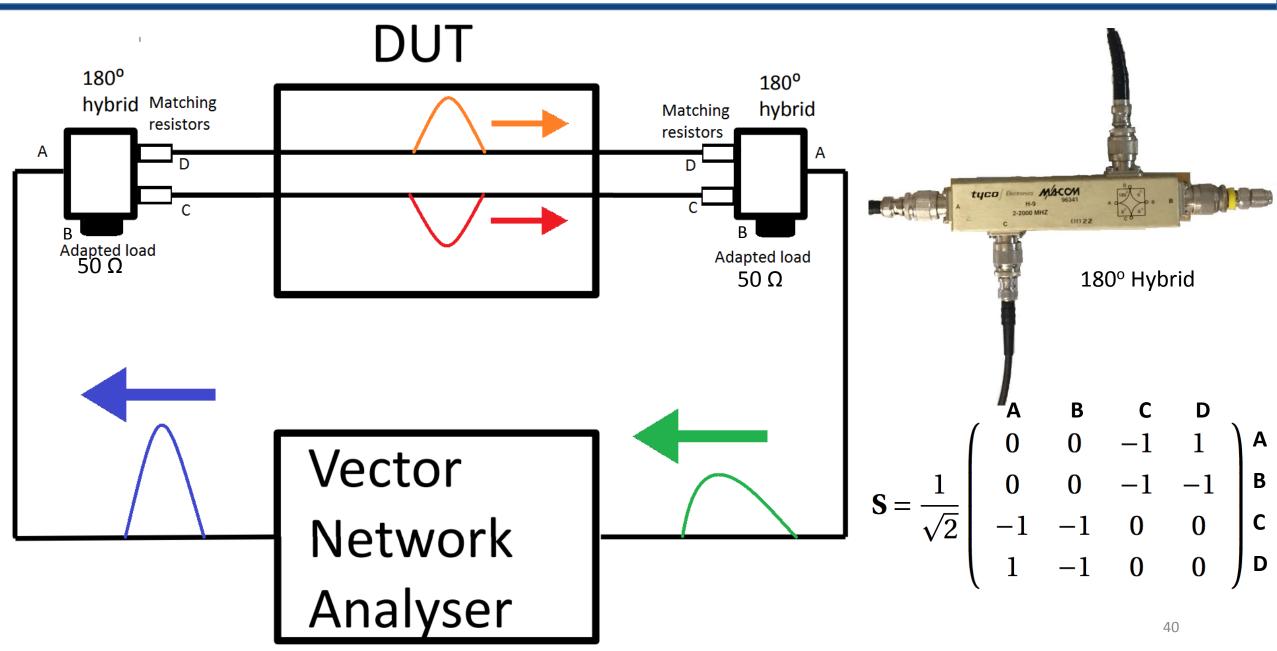
See A.Mostacci: <u>http://pcaen1.ing2.uniroma1.it/mostacci/wire\_method/care\_impedance.ppt</u>





This is the improved log formula, which is used for wire measurements





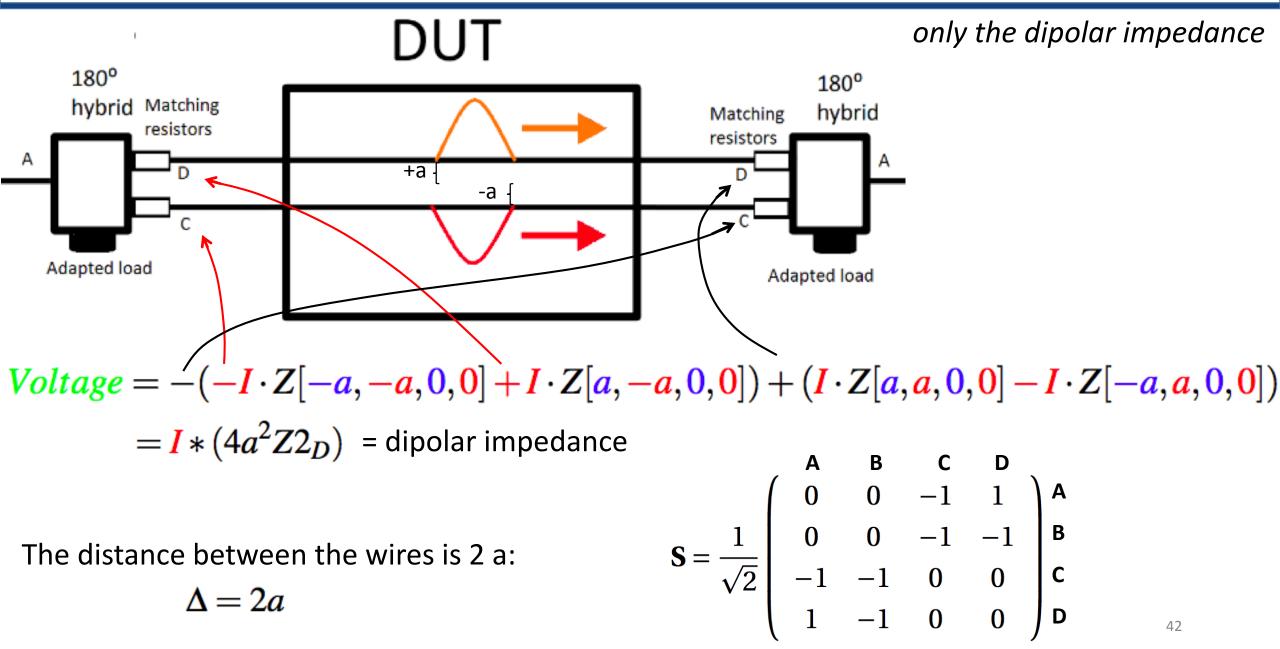
 $\begin{bmatrix} \sum_{i=1}^{Network} \\ \sum_{i=1}^{Network} \end{bmatrix} \begin{bmatrix} z_{\perp} = \frac{\beta c}{\omega \Delta^2} \\ Z_0 \\ Ln \begin{bmatrix} S21_{REF} \\ S21_{DUT} \end{bmatrix} \end{bmatrix} \begin{bmatrix} 1 + \frac{Ln[S21_{DUT}]}{Ln[S21_{REF}]} \end{bmatrix}$ Characteristic impedance  $Z_0$  of two wires, each with diameter "d" and with distance between them " $\Delta$ " is (See <u>https://en.wikipedia.org/wiki/Twin-lead</u>):

$$Z_0 \approx \frac{120}{\sqrt{\varepsilon_r}} Ln \left[ 2\frac{\Delta}{d} \right]$$

DUT

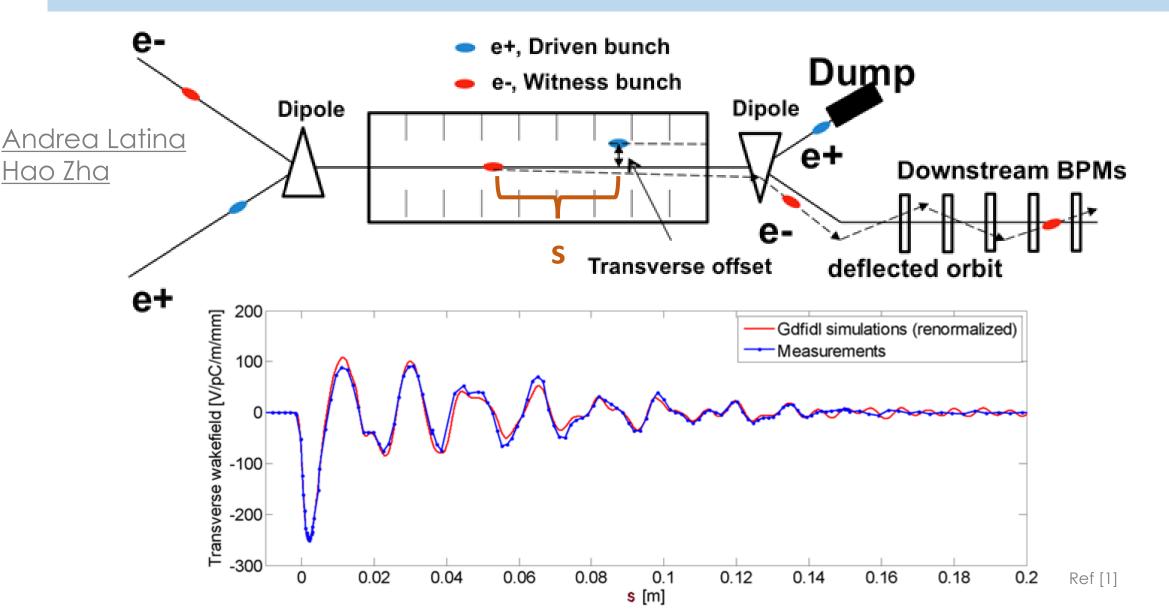
Two wire measurement give only the dipolar impedance

Example:  $\Delta = 10.0 \text{ mm}$   $Z = 120/1 \cdot \ln(40) \approx 450 \text{ Ohm}$  d = 0.5 mm i.e. 225 Ohm per wire Subtract 50 Ohm, as usual, this gives 175 Ohm per wire. So it is always 175 Ohm per wire – independent of the chamber diameter! <sup>41</sup>

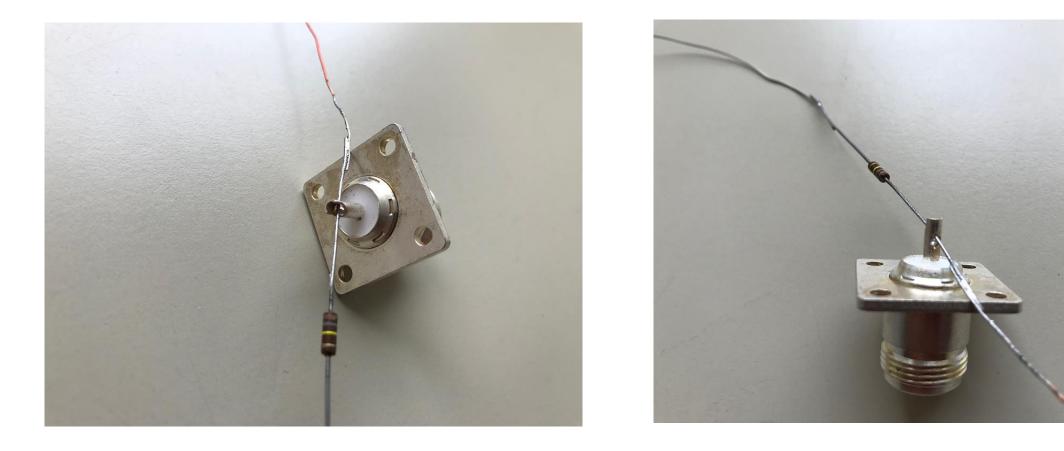


#### Another measure of transverse beam impedance!

An example of transverse impedance, that gives the beam a transverse kick! Here measured with the beam



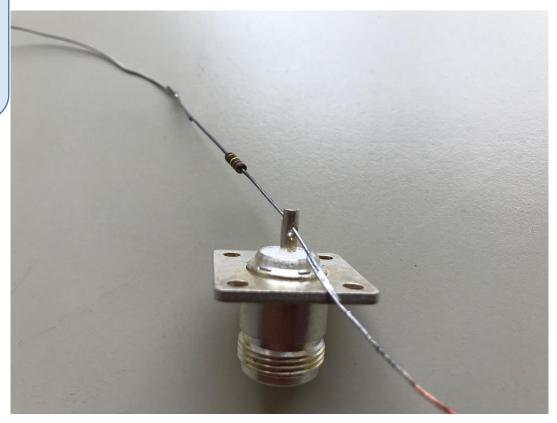
Easy method to firmly straighten the wire. Make hole in connector and solder a thin wire to the resistor.



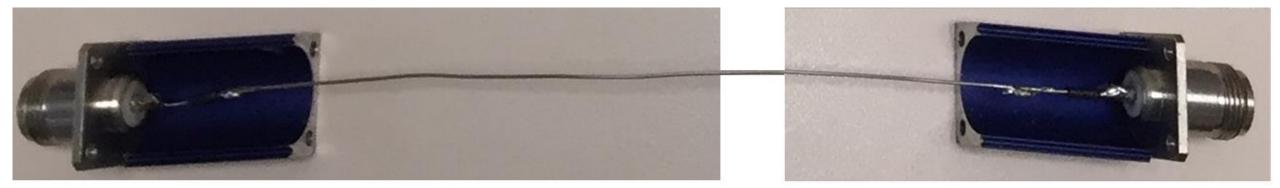
This method was invented by Muzhaffar Hazman <sup>44</sup>

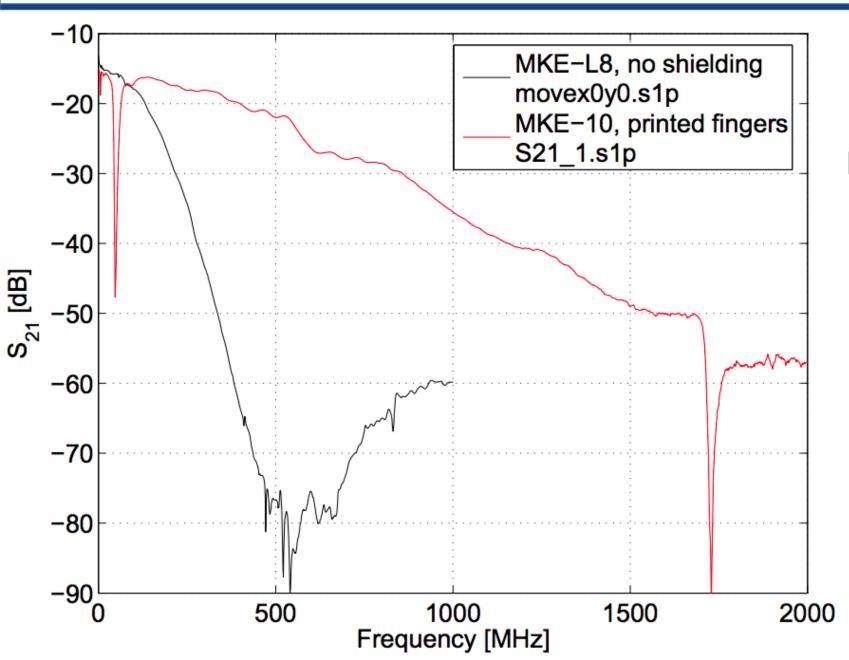
#### Easy method to firmly straighten the wire. Make hole in connector and solder a thin wire to the resistor.

When soldering the resistor to the connector, keep the other soldering cold, otherwise it will dissolve. Use plier as heat sink.



#### This method was invented by Muzhaffar Hazman <sup>45</sup>





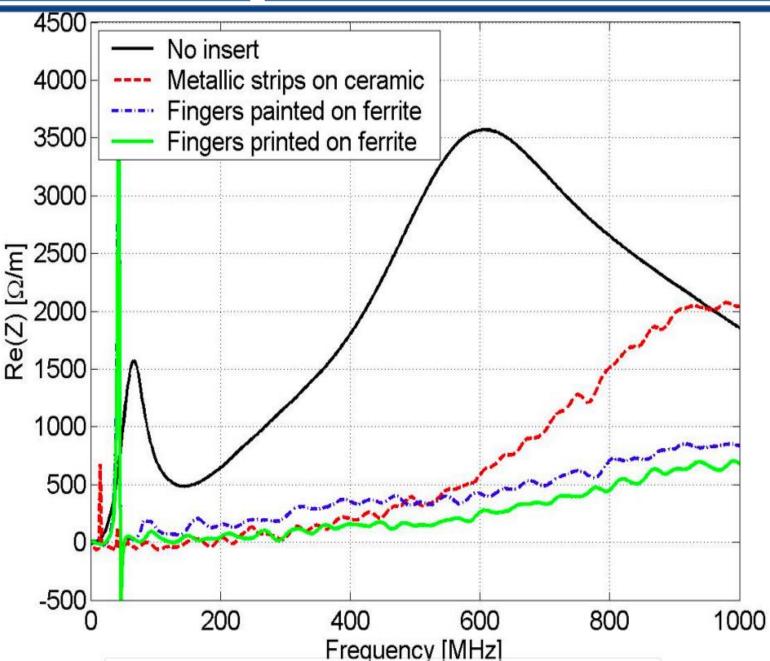
http://cds.cern.ch/record/1035461/files/ ab-note-2007-028.pdf

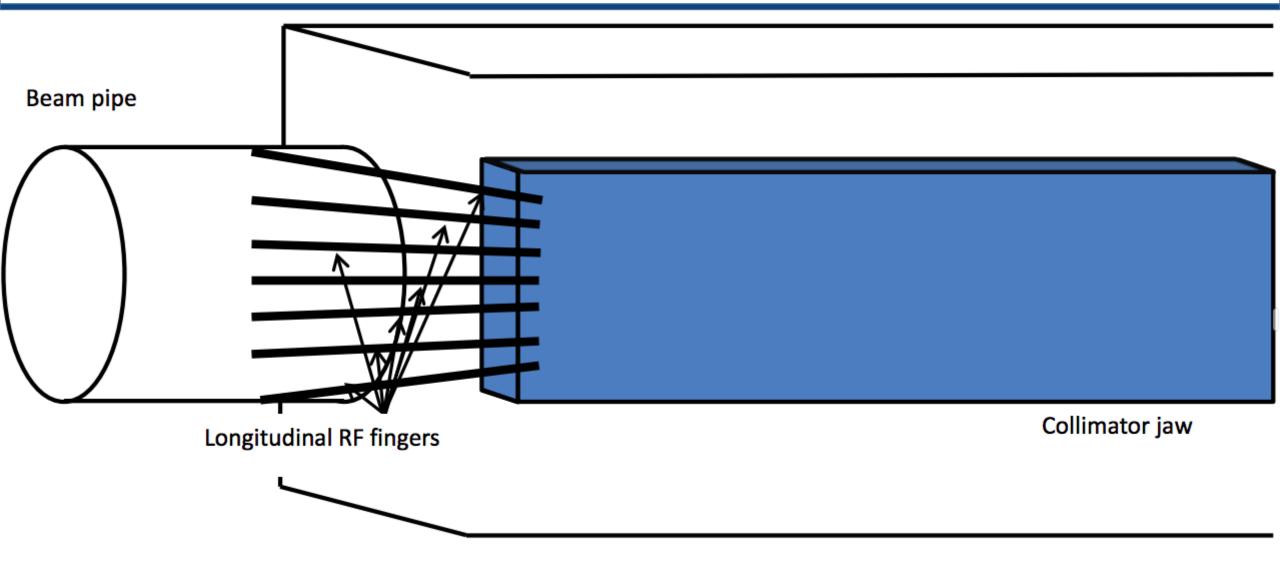
T. Kroyer, F. Caspers, E. Gaxiola

#### **MKE Kicker measurements**

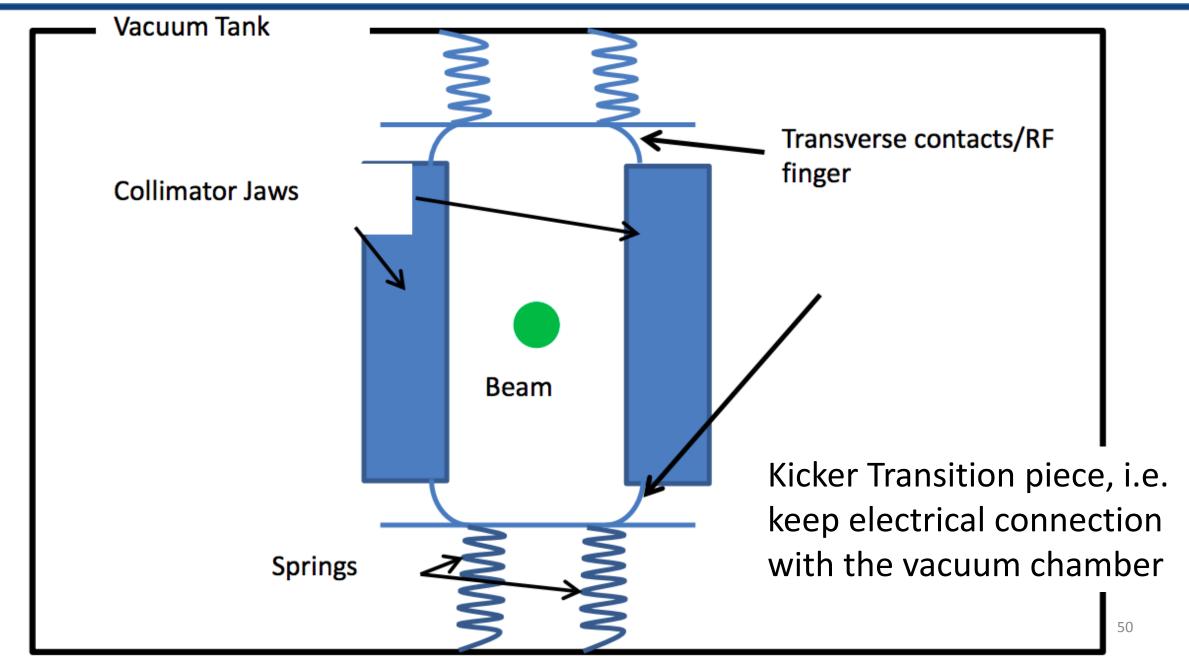


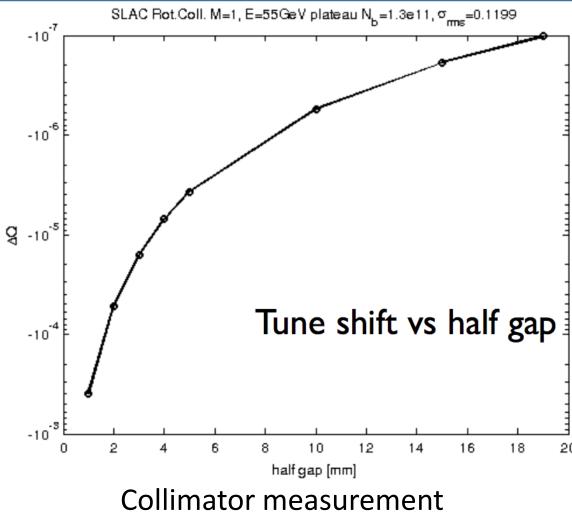
An example of serigraphy in the SPS Extraction Kicker Magnets (SPS-MKE)



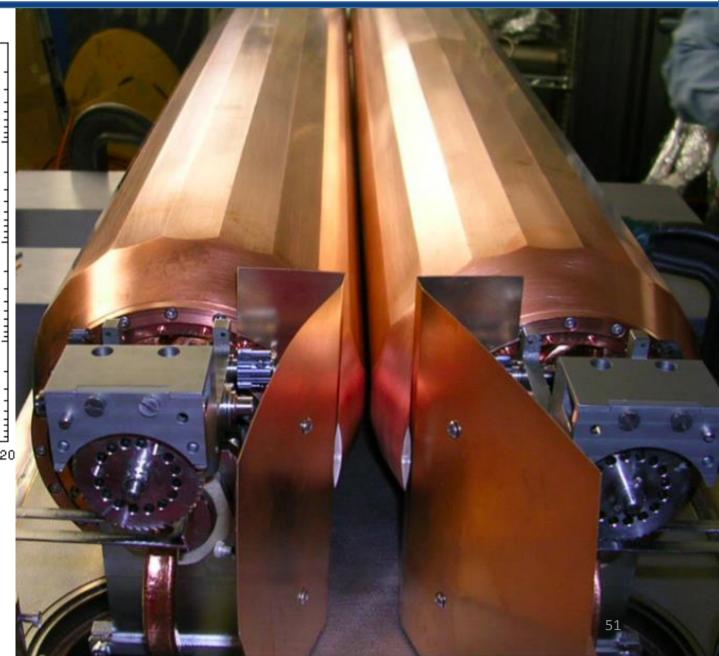


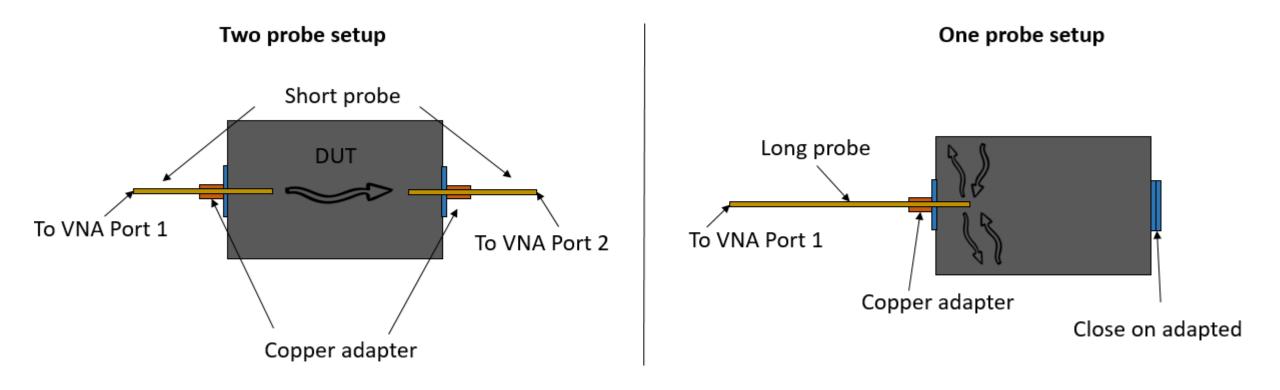
Kicker Transition piece, i.e. keep electrical connection with the vacuum chamber

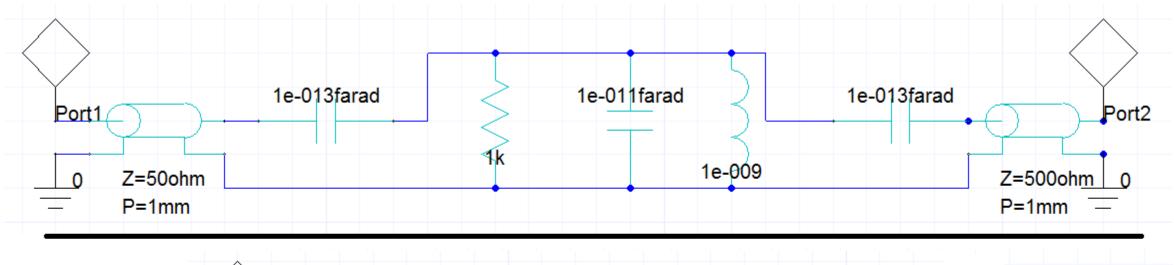


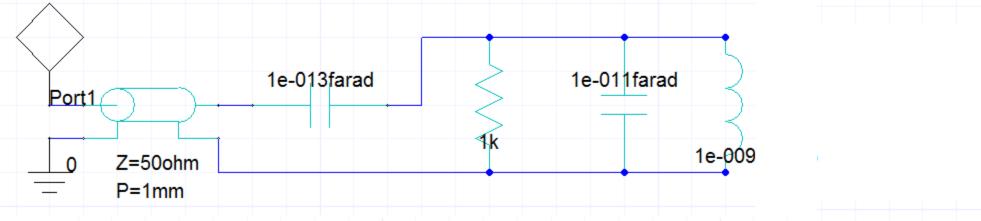


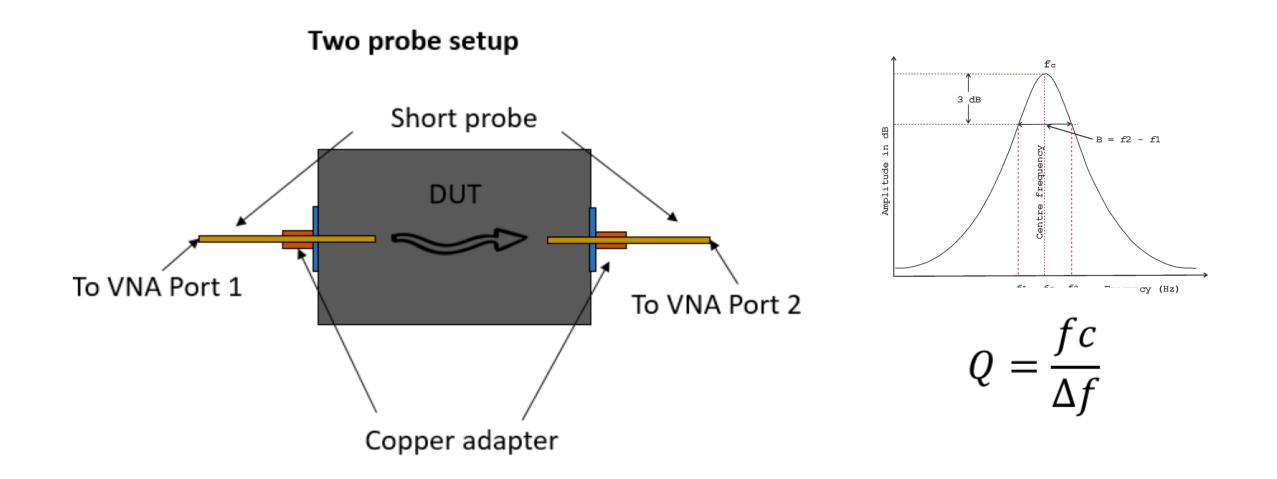
https://indico.cern.ch/event/436682/contributions/107 6818/attachments/1140261/1633077/SLAC\_RC\_SPS\_pla n.pdf N. Biancacci, P. Gradassi, T. Markiewicz, S. Redaelli, B. Salvant, G. Valentino



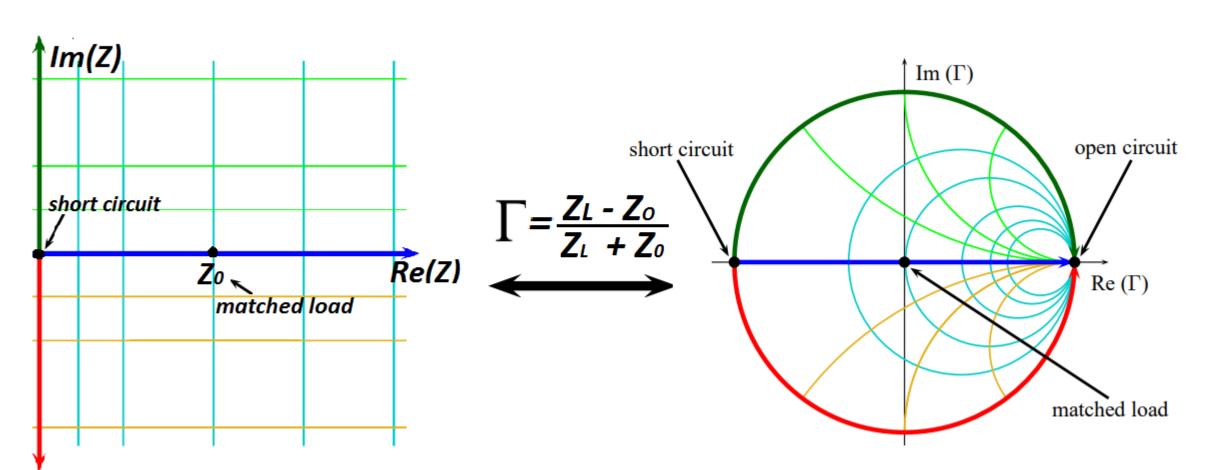




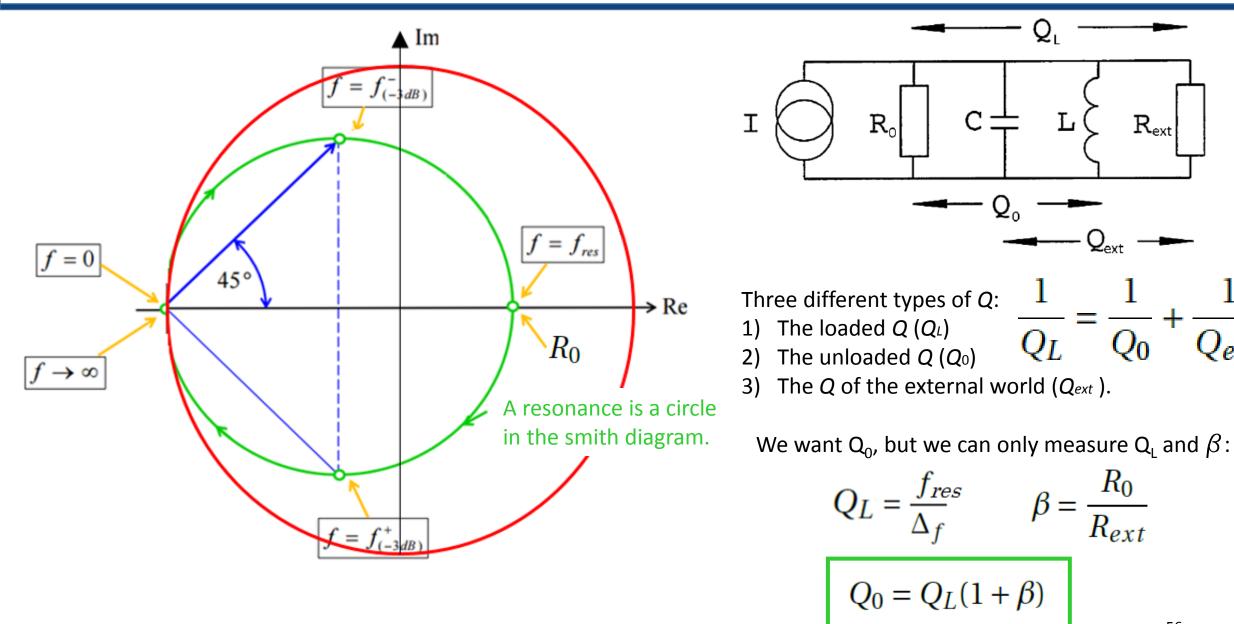




smith chart



#### Lab measurements. Measure Q reflection. Probe #5



56

Qext

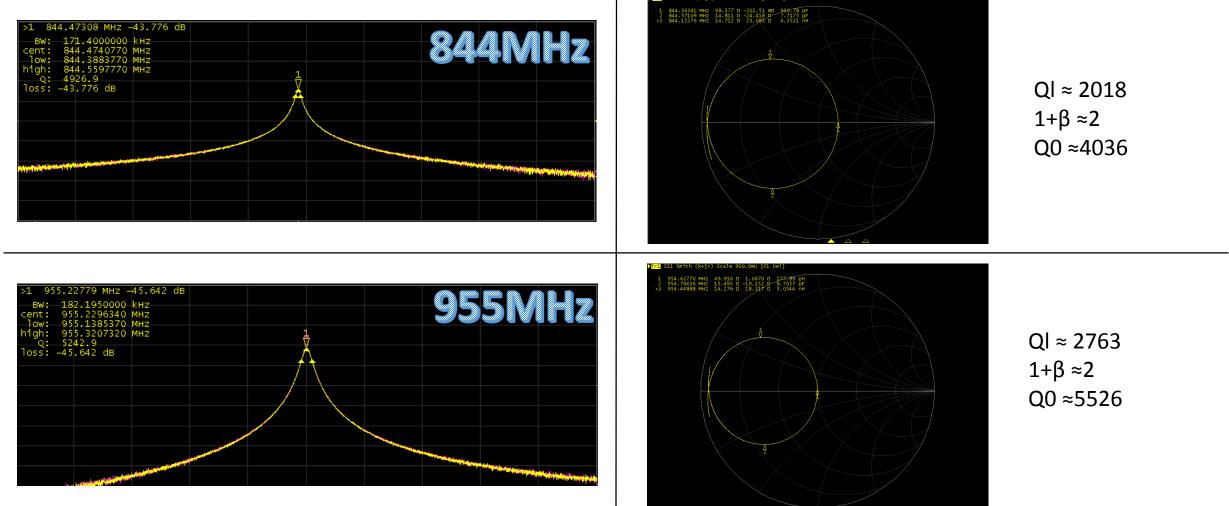
 $R_{\text{ext}}$ 

 $Q_{ext}$ 

 $\frac{1}{Q_L} = \frac{1}{Q_0}$ 

 $Q_L$ 

# Lab measurements. Measure Q reflection. Probe #6



Courtesy of C.Vollinger and T.Kaltenbacher

#### Beam impedance presentation. Lanzhou - China

# 感谢您的关注

1] <u>Measurement of transverse kick in CLIC accelerating structure in FACET</u> Hao Zha, Andrea Latina, Alexej Grudiev

[2] Holomorphic decomposition. John Jowett

\\cern.ch\dfs\Projects\ILHC\MathematicaExamples\Accelerator\MultipoleFields.nb

[3] On single wire technique for transverse coupling impedance measurement. H. Tsutsui <u>http://cds.cern.ch/record/702715/files/sl-note-2002-034.pdf</u>

[4] Longitudinal instability of a coasting beam above transition, due to the action of lumped discontinuities V. Vaccaro <u>https://cds.cern.ch/record/1216806/files/isr-66-35.pdf</u>

[5] Wake Fields and Instabilities Mauro Migliorati

https://indico.cern.ch/event/683638/contributions/2801720/attachments/1589041/2513889/Migliorati-2018\_wake\_fields.pdf

[6] G.Rumolo, CAS Advanced Accelerator Physics Trondheim, Norway 18–29 August 2013

https://cds.cern.ch/record/1507631/files/CERN-2014-009.pdf

[7] THE STRETCHED WIRE METHOD: A COMPARATIVE ANALYSIS PERFORMED BY MEANS OF THE MODE MATCHING TECHNIQUE M.R.Masullo, V.G.Vaccaro, M.Panniello

https://accelconf.web.cern.ch/accelconf/LINAC2010/papers/thp081.pdf

[7] Two Wire Wakefield Measurements of the DARHT Accelerator Cell. Scott D. Nelson, Michael Vella

https://e-reports-ext.llnl.gov/pdf/236163.pdf

[8] Shunt impedance, RLC-circuit definition, Accelerator definition, Alexej Grudiev

https://impedance.web.cern.ch/lhc-impedance/Collimators/RLC\_050211.ppt

[9] A.Mostacci

http://pcaen1.ing2.uniroma1.it/mostacci/wire\_method/care\_impedance.ppt

[10] COUPLING IMPEDANCE MEASUREMENTS: AN IMPROVED WIRE METHOD V.Vaccaro

http://cdsweb.cern.ch/record/276443/files/SCAN-9502087.tif

[11] Interpretation of coupling impedance bench measurements H. Hahn

https://journals.aps.org/prstab/pdf/10.1103/PhysRevSTAB.7.012001

[12] Measurement of coupling impedance of accelerator devices with the wire-method J.G. Wang, S.Y. Zhang

[13] Longitudinal and Transverse Wire Measurements for the Evaluation of Impedance Reduction Measures on the MKE Extraction Kickers. Kroyer, T ; Caspers, Friedhelm ; Gaxiola, E <u>http://cds.cern.ch/record/1035461/files/ab-note-2007-028.pdf</u>

#### Energy loss when beam pass through an equipment

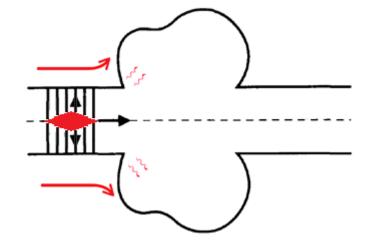
#### Shunt impedance

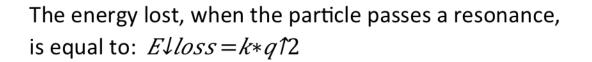
The energy lost, when the particle passes a resonance, **RLC-circuit definition:** R is equal to:  $E \downarrow loss = k * q \uparrow 2$ Accelerator definition: r  $Z_{i}(\omega) = \int W_{i}(\tau) e^{j\omega \tau} d\tau$  Where k is the loss factor, which is equal to:  $V = \int_{0}^{\infty} E_{z} e^{j \frac{dz}{c}} dz$  $k \downarrow loss factor = \omega \downarrow 0 / 2 \cdot R/Q$  $r = \frac{V^2}{P}; Q = \frac{\omega_0 U}{P}; \frac{r}{Q} = \frac{V^2}{\omega_0 U}$  $k_{i} = \frac{1}{\pi} \int_{0}^{\infty} \Re\{Z_{i}(\omega)\} d\omega$ And q is the charge of the particle.  $\omega_0 = \frac{1}{\sqrt{IC}}$ ; Q = R.  $\frac{A}{T}$  syou can see, the bigger R over Q, the bigger the energy  $V = 2qk_1; k_1 = \frac{U}{a^2}; k_1 = \frac{V^2}{4II}$  $k_i = \frac{\omega_0}{4} \frac{r}{O}$ Wake Loss Factor  $Z_{l}(\omega) = \frac{1}{1 + iO(\omega/\omega_{0} - \omega_{0})}$ The wake loss factor (k) for the longitudinal component is calculated by: https://impedance.web.cern.ch/lhc-impedance/Collimators/RL Shunt impedance, RLC-circuit definition, Accelerator definition, Alexej Grudiev r = 2R  $k_i = \frac{1}{2} \frac{1}{2}$  $k = -\int \lambda(s) W_{\parallel}(s) \, ds$ were lambda(s) describes the normed charge distribution function over s (to ob to multiply this function by q1). It is given in [V / pC].

#### Use loss(kick) factor instead of impedance

of the equipment,

# Beam impedance modelled by lumped impedance

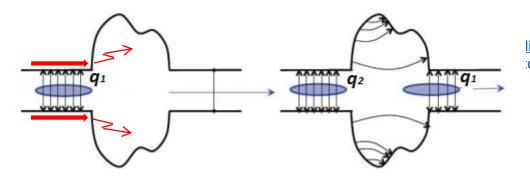




Where k is the loss factor, which is equal to:  $k \downarrow loss factor = \omega \downarrow 0 / 2 \cdot R/Q$ 

And q is the charge of the particle.

As you can see, the bigger R over Q, the bigger the energy <u>limators/RLC\_050211.ppt</u> or definition, Alexej Grudiev



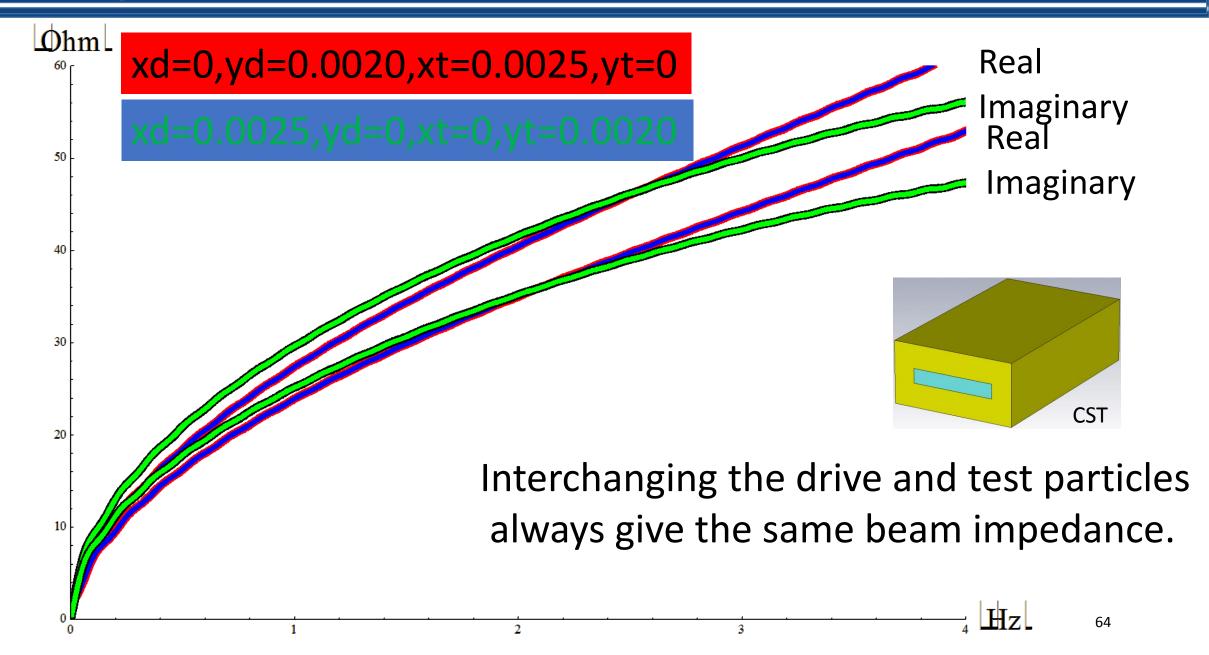
#### The longitudinal beam impedance have 8 parameters

The beam impedance is now decomposed into **13** parameters : Z<sub>||</sub>[xd, xt, yd, yt] = Z0 +Z1XD xd+Z1XT xt+Z1YD yd+Z1YT yt +Z2XYDXYD (xd<sup>2</sup>-yd<sup>2</sup>)+Z2XYTXYT (xt<sup>2</sup>- yt<sup>2</sup>) +Z2XDXT xd xt+Z2XDYD xd yd+Z2XDYT xd yt +Z2XTYD xt yd+Z2XTYT xt yt+Z2YDYT yd yt

The new formula is identical to the previous from Tsutsui:

$$Z = Z_{0,0} + (x_1 - jy_1)Z_{1,0} + (x_1 + jy_1)Z_{-1,0} + (x_2 + jy_2)Z_{0,1} + (x_2 - jy_2)Z_{0,-1} + (x_1 - jy_1)^2 Z_{2,0} + (x_1 - jy_1)(x_2 - jy_2)Z_{1,-1} + (x_2 - jy_2)^2 Z_{0,-2} + (x_1 - jy_1)(x_2 + jy_2)Z_{1,1} + (x_1 + jy_1)(x_2 - jy_2)Z_{-1,-1} + (x_1 + jy_1)^2 Z_{-2,0} + (x_1 + jy_1)(x_2 + jy_2)Z_{-1,1} + (x_2 + jy_2)^2 Z_{0,2} + O((x_1, y_1, x_2, y_2)^3).$$

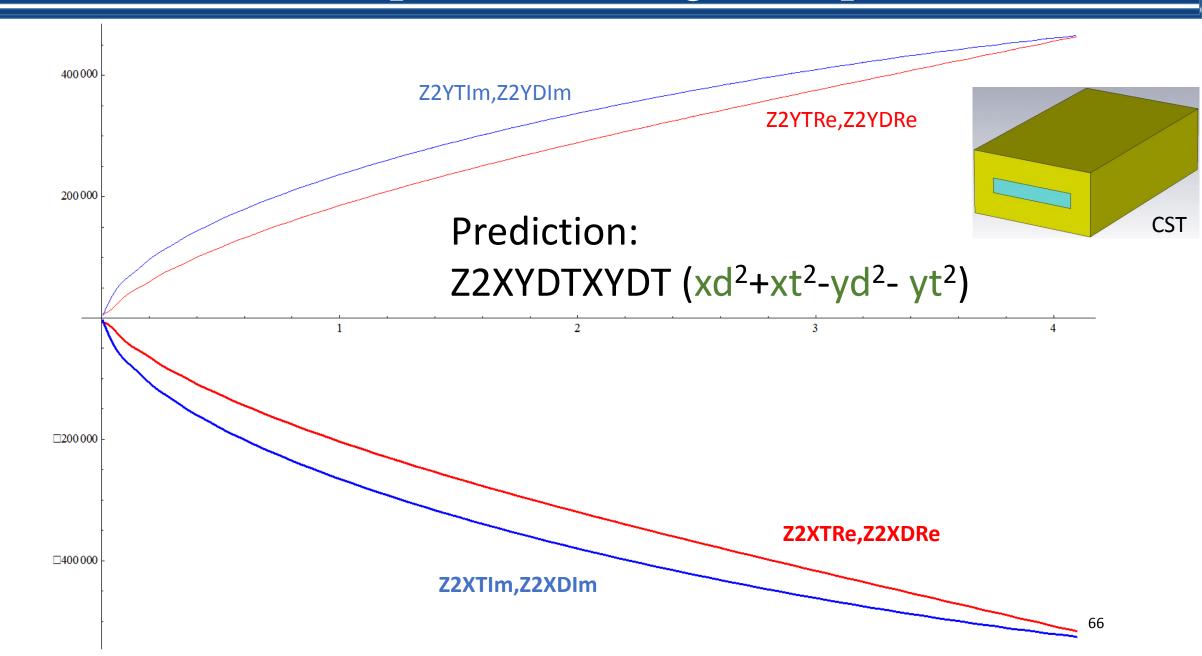
#### The longitudinal beam impedance have 8 parameters



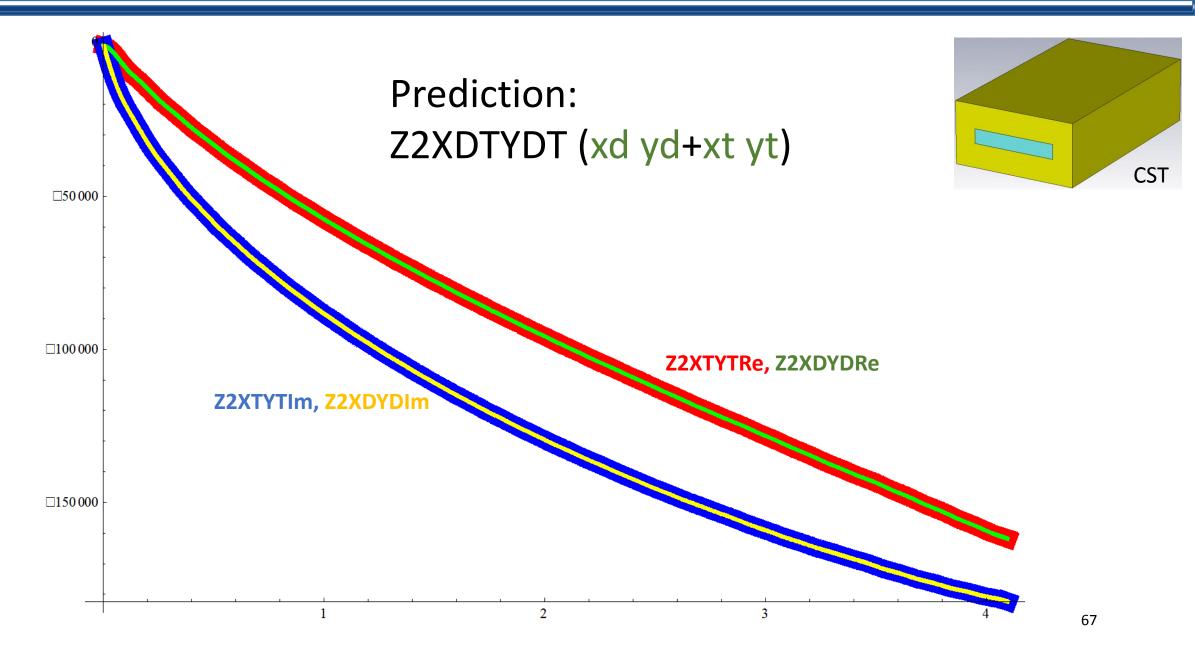
The longitudinal beam impedance have 8 parameters

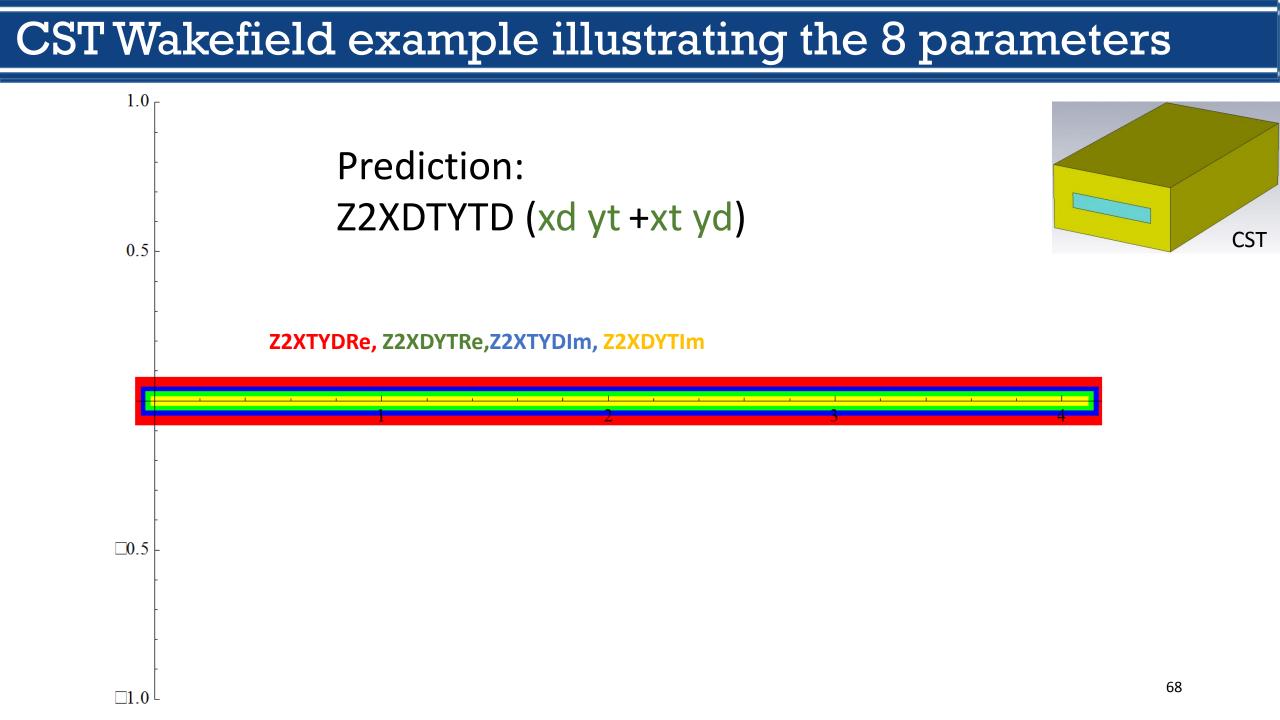
 $Z_{||}[xd, xt, yd, yt] =$ 70 +Z1X(xd+xt)+Z1Y(yd+yt)+Z2XYDTXYDT (xd<sup>2</sup>+xt<sup>2</sup>-yd<sup>2</sup>- yt<sup>2</sup>) +Z2XDTYDT (xd yd+xt yt) +Z2XDTYTD (xd yt +xt yd) +Z2XDXT xd xt+Z2YDYT yd yt

#### CST Wakefield example illustrating the 8 parameters

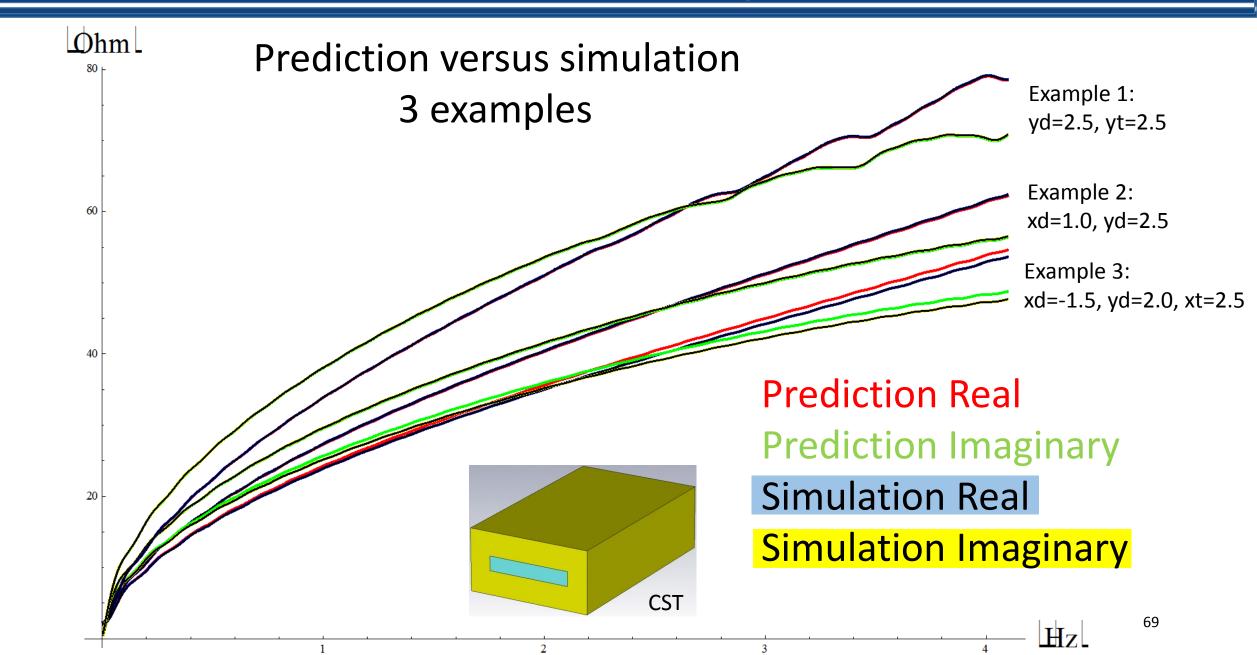


#### CST Wakefield example illustrating the 8 parameters

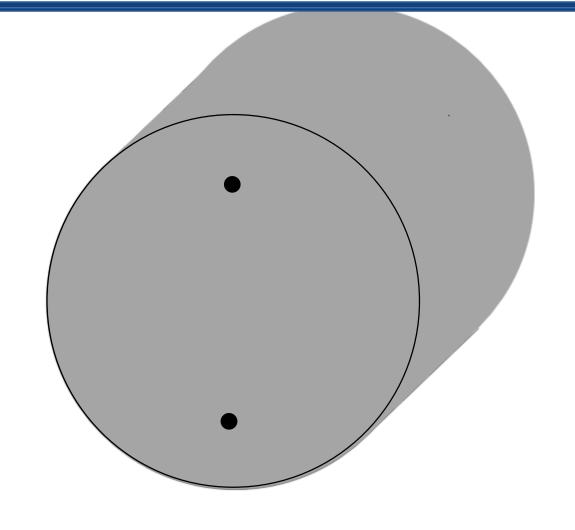




#### CST Wakefield example illustrating the 8 parameters



#### The rotating wire method



One wire represents the drive particle and the other wire represents the test particle.

In this measurement, we do not have a positive current in one wire and a negative current in the other

Both wires are measured individually i.e. single-ended

In the additional slide, it is demonstrated how this measurement can derive all 8 parameters

#### The rotating wire method

# Some implications of the new 8 parameter formula:

1) **Transverse impedance** The offset term is not automatically zero, depends on the shape of the equipment

 $Z_{\perp,x}(\boldsymbol{\omega}) = Z\mathbf{1}_x + 2Z\mathbf{2}_A \cdot xt + Z\mathbf{2}_B \cdot yt + Z\mathbf{2}_C \cdot yd + Z\mathbf{2}_D \cdot xd$  $Z_{\perp,y}(\boldsymbol{\omega}) = Z\mathbf{1}_y - 2Z\mathbf{2}_A \cdot yt + Z\mathbf{2}_B \cdot xt + Z\mathbf{2}_C \cdot xd + Z\mathbf{2}_E \cdot yd$ 

#### 2) Transverse impedance

Is it possible to shape a collimator e.g. in three-fold symmetric form so that its transvers impedance is zero up to second order?

#### 3) Transverse impedance

The beam oscillates during instability, is it possible to shape equipment in such a way that the drive position works against the instability? <sup>71</sup>

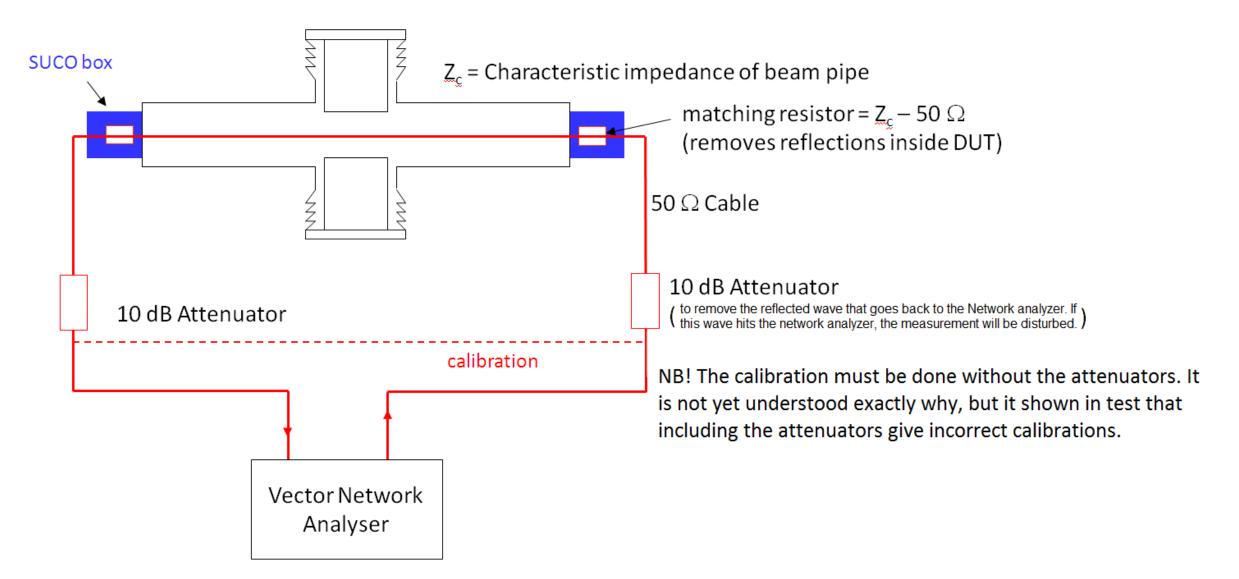
Supporting material for slide

$$\begin{aligned} & \texttt{soll} = \texttt{Solve} \Big[ \texttt{Srel} = \texttt{Exp} \Big[ \texttt{i} * \texttt{l} * \texttt{w} * \sqrt{\texttt{CC} * \texttt{L}} - \texttt{i} * \texttt{l} * \texttt{w} * \sqrt{\Big( \texttt{l} - \frac{\texttt{i} * \texttt{dZdl}}{\texttt{w} * \texttt{L}} \Big) * \texttt{CC} * \texttt{L}} \Big], \ \texttt{dZdl} \Big] \\ & \left\{ \Big\{ \texttt{dZdl} \rightarrow \frac{-2 \texttt{l} \sqrt{\texttt{CC} \texttt{L}} \texttt{w} \texttt{Log} [\texttt{Srel}] - \texttt{i} \texttt{Log} [\texttt{Srel}]^2}{\texttt{CC} \texttt{l}^2 \texttt{w}} \Big\} \Big\} \end{aligned}$$

$$-2\sqrt{\frac{L}{CC}} \log[Srel] \left(1 + \frac{i \log[Srel]}{2 l \sqrt{CC L} w}\right) = \frac{-2 l \sqrt{CC L} w \log[Srel] - i \log[Srel]^2}{CC l w}$$

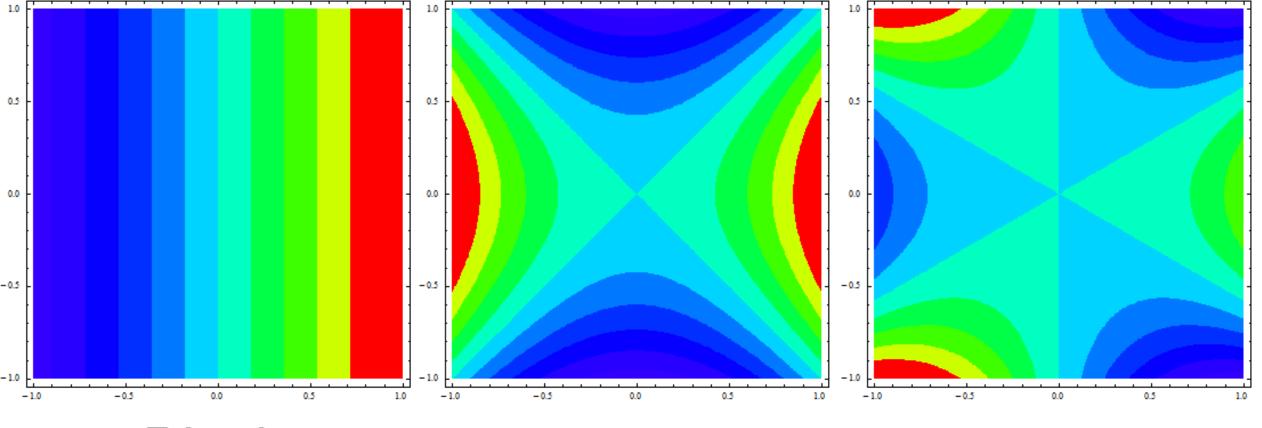
True

#### Longitudinal Beam Coupling Impedance of Device Under Test (DUT)



Vector network analyzer calibration to remove effects from cables and attenuators.

Measure transmission coefficient  $S_{21}$  (=forward transmission) and then calculate impedance.



# Dipole

# Quadrupole

Sextupole

74

Figure 3: Normal field patterns up to third order for respectively a dipole, quadrupole and sextupole magnet. The potentials are:

Dipole: x Quadrupole:  $\frac{x^2}{2} - \frac{y^2}{2}$  Sextupole:  $\frac{x^3}{3} - xy^2$ 

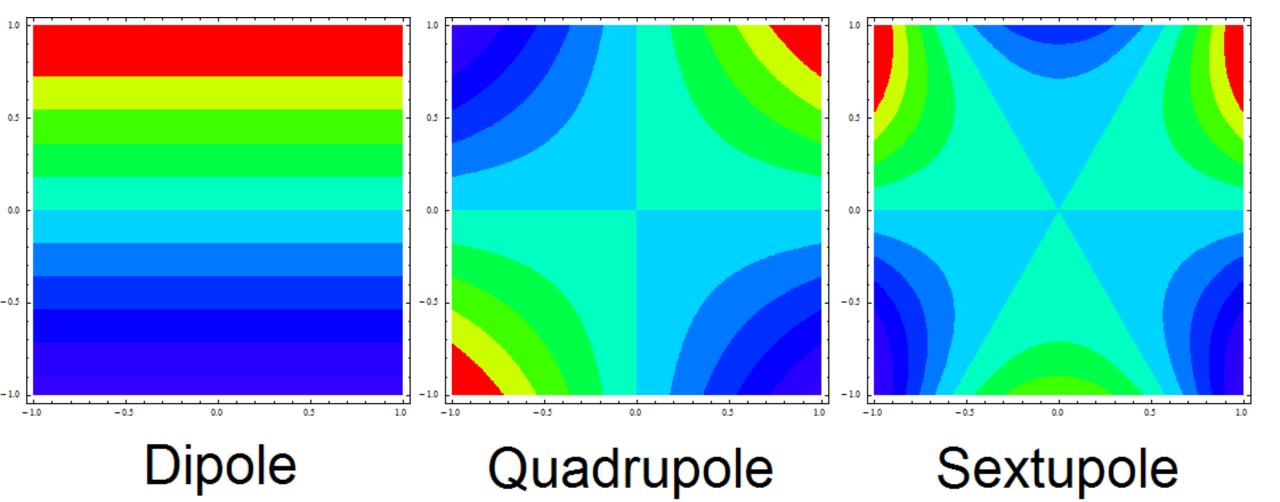


Figure 4: Skew field patterns up to third order for respectively a dipole, quadrupole and sextupole magnet. The potentials are:

Dipole: y Quadrupole:  $x \cdot y$  Sextupole:  $x^2y - \frac{y^3}{3}$