

1 **Upslope-verging back thrusts developed during**
2 **downslope-directed slumping of Mass Transport Deposits**

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10 **Abstract**

11 While much research has recently been focussed on downslope-verging systems of gravity-
12 driven fold and thrust belts within mass transport deposits (MTDs), rather less attention has
13 been paid to back thrusts, which are defined as displaying the opposite vergence to the main
14 transport direction in thrust systems. A fundamental question arises over whether back thrusts
15 in downslope-verging MTDs record actual movement back upslope. In order to address this
16 issue, we have examined exceptional outcrops of Pleistocene fold and thrust systems
17 developed in MTDs around the Dead Sea Basin. Back thrusts can be interpreted in terms of a
18 ‘*downslope-directed underthrust model*’, where material moves down slope and is driven into
19 the footwall of the back thrust resulting in the ‘jacking up’ of the largely passive hangingwall.
20 Our data support this underthrust model and include the observation that stratigraphic units
21 may be markedly thickened (up to 250%) in the footwall of back thrusts. This thickening is a
22 consequence of pure shear lateral compaction as the ‘wedge’ of sediment is driven into the
23 footwall to create an underthrust. In addition, back thrusts may be rotated as new back thrusts
24 form in their footwalls, ultimately resulting in overturned thrusts. The observation that
25 steeper back thrusts typically accommodate less displacement than gently-dipping back
26 thrusts suggests that steepening occurred during back thrusting, and is therefore a
27 consequence of ‘footwall wedging’. Contrary to some recent interpretations, we demonstrate
28 that back thrusts can develop in gravity-driven systems and cannot therefore be used to
29 distinguish different emplacement mechanisms for MTDs.

30 **Keywords:** back thrust, MTD, slump, Dead Sea Basin

31
32 **1. Introduction**

33 While much research has recently been focussed on downslope-verging systems of gravity-
34 driven fold and thrust belts within mass transport deposits (MTDs), rather less attention has
35 been paid to back thrusts developed within such systems. Although this may be partially due
36 to back thrusts being apparently absent from some seismic sections across MTD’s from
37 offshore Namibia (e.g. Butler and Paton, 2010; Scarselli et al., 2016) or offshore Brazil (e.g.
38 Reis et al., 2016), they are undoubtedly imaged and well developed in others settings such as
39 the Storegga Slide in the North Sea where oppositely verging thrusts create ‘pop-up’ blocks
40 in the MTD (e.g. Bull et al., 2009, p.1146) or back thrusts in the Niger Delta (e.g. Corredor et
41 al., 2005; Morley et al., 2011; Jolley et al., 2016). Back thrusts are also imaged on detailed
42 seismic sections through mass movement induced fold and thrust belts in unconsolidated
43 lacustrine sediments (e.g. Schnellmann et al., 2005). The presence of back thrusts observed in
44 outcrop studies of thrust systems in orogenic belts (e.g. Butler, 1987) and gravity-driven
45 slump systems (e.g. Farrell, 1984; Strachan and Alsop, 2006; Garci-Tortosa et al., 2011) is

46 however long established and indisputable. Indeed, more than a quarter of all thrusts recorded
47 by Garci-Tortosa et al. (2011) in a gravity-driven slump system from California are back
48 thrusts.

49 Despite the widespread occurrence of back thrusts in slump systems and MTDs, the
50 geometry and mechanics of these apparently anomalous structures, that verge back up the
51 regional slope, have not been discussed in detail. Farrell (1984, p.733) working on slump
52 sheets noted that “folds associated with upslope propagating faults will verge upslope” and
53 that “faults which propagate in the opposite direction to the bulk transport direction are
54 analogous to back thrusts in orogenic belts”. Back thrusts have previously been defined in
55 text books as those thrusts that “travel with the opposite sense” (i.e. towards the hinterland)
56 (e.g. Ghosh, 1993, p.445), while more recently, Fossen (2016, p. 474) defines a back thrust as
57 a “Thrust displacing the hangingwall toward the hinterland, i.e. opposite to the general
58 thrusting direction”. A simple question then arises of whether back thrusts in downslope-
59 verging slump systems record actual movement back upslope? (i.e. opposite to the general
60 thrusting direction). Interpreting the mechanism by which back thrusts have developed within
61 MTDs is clearly critical when evaluating and distinguishing models of sediment deformation.
62 Indeed, Myrow and Chen (2015, p. 641) note that “Thrusting of parts of brittle deformed beds
63 took place in multiple orientations, although, in many cases, this was nearly oppositely
64 oriented which is evidence against slope-generated gravity-driven transport and consistent
65 with seismic deformation”. A follow-up question may then be posed of the role that thrust
66 geometries play in distinguishing different triggers and mechanisms of sediment deformation.

67 Slumps and MTDs are developed across a range of scales and settings and nearly all
68 are considered to be gravity-driven. Although movement of material up the regional slope
69 may be locally achieved by slumping off distinct palaeo-highs, tilted fault blocks and pre-
70 existing structural culminations (e.g. Alsop and Marco, 2011), this mechanism fails to
71 account for the more general development of back thrusts in otherwise downslope-verging
72 and gravity-driven fold and thrust systems.

73 In order to distinguish back thrusts from downslope-directed fore thrusts, *a priori*
74 knowledge of the general direction of thrust transport is required, which in the case of
75 gravity-driven MTDs is considered downslope. While this direction may be relatively simple
76 to ascertain in modern or recent basins, it becomes increasingly debateable in ancient
77 settings. We have therefore chosen to analyse a recent MTD system around the Dead Sea
78 Basin in which there is no dispute about downslope directions and consequently what
79 constitutes a downslope-directed fore thrust or upslope-verging back thrust (e.g. Alsop et al.,
80 2016a) (Fig. 1). Our research focuses on some fundamental questions regarding back thrusts
81 in gravity-driven MTDs, including:

82

- 83 *i) Do back thrusts typically form in the central or downslope toe regions of MTDs?*
- 84 *ii) What controls the development of back thrusts in gravity-driven MTDs?*
- 85 *iii) What are the displacement patterns along back thrusts?*
- 86 *iv) When do back thrusts form within the thrust sequence?*
- 87 *v) How do back thrusts in MTDs compare to those in lithified rocks?*
- 88 *vi) Do back thrusts in gravity-driven MTDs record movement back upslope?*

89 2. Geological Setting

90 The Dead Sea Basin is a pull-apart basin developed between two left-stepping, parallel fault
91 strands that define the sinistral Dead Sea Fault (Garfunkel, 1981; Garfunkel and Ben-
92 Avraham, 1996) (Fig. 1a.). The Dead Sea Fault has been active since the Miocene (Nuriel et
93 al., 2017) and during deposition of the Lisan Formation in the late Pleistocene (70-15 ka)
94 (Haase-Schramm et al., 2004). The Lisan Formation comprises a sequence of alternating
95 aragonite-rich and detrital-rich laminae on a sub-mm scale that are thought to represent
96 annual varve-like cycles (Begin et al., 1974). Varve counting combined with isotopic dating
97 suggests that the average sedimentation rate of the Lisan Formation is ~1 mm per year
98 (Prasad et al., 2009). Activity along the Dead Sea Fault system has resulted in numerous
99 earthquakes with which to trigger co-seismic deformation (e.g. Levi et al., 2006, 2008;
100 Weinberger et al., 2016) as well as soft-sediment deformation and slumping (e.g. El-Isa and
101 Mustafa, 1986; Marco et al., 1996; Alsop and Marco 2012b, Alsop et al., 2016a). Individual
102 MTDs within the Lisan Formation are typically <1.5 m thick and are capped by undeformed
103 horizontal beds, indicating that fold and thrust systems formed at the sediment surface (e.g.
104 Alsop and Marco, 2013).

105 The Peratzim case study area (N 31°0449.6 E 35°2104.2) is located on the Am'iaz
106 Plain, which is a down-faulted block positioned between the Dead Sea western border fault
107 zone, which bounds the Cretaceous basin margin ~2 km to the west, and the upstanding 10
108 km long ridge formed by the Sedom salt wall 3 km further east (e.g. Alsop et al., 2015,
109 2016b) (Fig. 1b, c). This area is ideal for the present case study concerning back thrusts
110 cutting un lithified sediments of MTDs as it is well exposed and accessible along incised wadi
111 walls. The varved lacustrine sequence permits high resolution mm-scale correlation of
112 sequences across back thrusts. In addition, the nature of the surficial slumping, where
113 overburden has not exceeded a few metres (e.g. Alsop et al., 2016a), removes many
114 complications associated with changes in geometries and angles arising from subsequent
115 compaction of sediments. The Lisan Formation is considered to have been water-saturated at
116 the time of deformation, meaning that in general it is susceptible to loss of shear strength
117 during seismicity (e.g. see Maltman, 1994a, b and references therein).

118

119 2.1. Gravity-driven downslope slumping around the Dead Sea Basin.

120 Deformation associated with co-seismic slip along bedding planes in the Lisan
121 Formation has recently been documented by Weinberger et al. (2016). Horizontal shearing
122 (marked by the offset of vertical clastic dykes) is developed ~15 m below the sediment
123 surface and is considered to be created by simple shear deformation triggered by surface and
124 S waves generated by earthquakes (Weinberger et al., 2016). Several bedding-parallel slip
125 surfaces associated with the horizontal shearing during presumed Holocene earthquakes are
126 developed, although none appear to generate folding within the Lisan Formation.

127 Together with the development of such horizontal slip surfaces created by co-seismic
128 deformation during the Holocene, the older slumps and MTDs within the Lisan Formation are
129 also considered to be triggered by seismic events (e.g. El Isa and Mustafa, 1986; Alsop and
130 Marco, 2011). However, following the initial earthquake that triggers slope failure, these
131 slumped horizons then undergo gravity-driven downslope movement toward the depocentre
132 of the basin. This assertion is based on a number of lines of evidence outlined below.

133 Firstly, >90% of folds and thrusts in the study areas verge towards the NE (Alsop and
134 Marco, 2012a). These structures are developed in six separate slumps sheets that display
135 consistently oriented structures (Alsop et al., 2016a). Such uniformity is consistent with
136 gravity-driven slumping, but much less likely with co-seismic deformation triggered by
137 multiple earthquakes in different locations with potentially different focal mechanisms,
138 directivity and magnitudes.

139 Secondly, MTDs collectively display a radial pattern of transport centred toward the
140 Dead Sea Basin (Alsop and Marco, 2012a) (Fig. 1b). Slumps in the north are transported
141 towards the SE, while those in the south (in the present study area) are directed towards the
142 NE (Fig. 1b). In addition, slumping on the eastern side of the Dead Sea Basin is toward the
143 west (El-Isa and Mustafa, 1986) and this completes the radial distribution of MTD transport
144 (Alsop and Marco, 2012a). While such systematic regional patterns are entirely consistent
145 with MTD emplacement being controlled by gravity-driven movement toward the depocentre
146 of a basin, they would be highly unlikely if driven by co-seismic shearing and deformation.

147 Thirdly, analysis of drill cores from the central part of the Dead Sea Basin reveals that
148 the Lisan Formation is three times thicker than its onshore equivalent (Marco and Kagan,
149 2014). This increase in thickness is attributed to the emplacement of multiple MTDs that
150 translated downslope towards the depocentre of the basin. Such an increase in thickness
151 supports large-scale gravity-driven transport of MTDs, resulting in the transfer of significant
152 amounts of sediment into the deep basin.

153 Fourthly, fold and thrust systems define intricate relationships, with small scale
154 systems being marked by upslope (SW) extension and attenuation, while the downslope (NE)
155 domain is marked by contractional thrusts (e.g. Alsop and Marco, 2014;). On the scale of
156 individual MTDs, the amount of contraction has also been shown to systematically decrease
157 downslope towards the 'open-ended' toe (Alsop et al., 2016a). While such systematic spatial
158 arrangement of deformational domains is consistent with gravity-driven MTDs across a range
159 of scales and settings, they are not characteristic of co-seismic shearing where extension and
160 contraction would be more variably orientated and distributed.

161 Although the very gentle or 'negligible' slopes ($<1^\circ$) recorded in the Lisan Formation
162 (Alsop and Marco, 2013) could be considered insufficient to drive slumping, they are
163 consistent with slumping down similar low-angle slopes frequently recognised elsewhere
164 (e.g. Lewis, 1971; Almagor and Garfunkel, 1979; Gibert et al., 2005; Garci-Tortosa et al.,
165 2011; Gladkov et al., 2016). In some cases on modern slopes, gradients as low as 0.25° are
166 marked by gravity-driven downslope movement (e.g. Wells et al., 1980; Field et al., 1982)
167 thereby demonstrating that such low angles are not an issue to downslope movement.
168 Furthermore, it has also been demonstrated via analogue experiments (e.g. Owen, 1996) that
169 such low gradients are capable of driving sediment deformation.

170 The observations listed above collectively confirm the gravity-driven mechanism of
171 MTD emplacement around the Dead Sea Basin (Alsop et al., 2016a, 2017). While initial
172 slope failure is triggered by an earthquake which perhaps just lasts in the order of seconds
173 (e.g. see Shani-Kadmiel et al., 2014), downslope slumping subsequently takes place under the
174 control of gravity and generates the observed fold and thrust systems that create consistent
175 local and regional geometries. This gravity-driven deformation, which may commence during
176 the earthquake-triggered shaking, is completed prior to deposition of an overlying

177 sedimentary ‘cap’ that is deposited out of suspension from ensuing seiche or tsunami waves,
178 perhaps “in a matter of just hours or days” (Alsop et al., 2016a, p. 80). The case study area
179 therefore allows us to further test recent assertions regarding the use of thrust structures (and
180 back thrusts in particular) to discriminate MTDs created by seismic waves (in which back
181 thrusts are believed to develop) from gravity-driven systems in which back thrusts are not
182 thought to be significant (e.g. see Myrow and Chen, 2015).

183

184 **3. Orientation of thrusts and back thrusts**

185 Fold and thrust systems developed in gravity-driven slumps and MTD’s are considered to
186 display a systematic geometric relationship to the downslope direction that presumably
187 controlled their development (e.g. Woodcock, 1976a, b, 1979) (Fig. 2). Within most MTDs,
188 thrusts and associated fault propagation folds are considered to generally trend parallel to the
189 strike of the palaeoslope, and verge in the downslope direction (e.g. Ortiz-Karpf et al., 2016)
190 (Fig. 2). However, the recognition that back thrusts may form in such gravity-driven systems
191 means that in these cases, the structures actually verge back up the palaeoslope (Farrell,
192 1984) (Fig. 2). Back thrusts which root downwards onto the same floor detachment as fore
193 thrusts are considered to be ‘primary’ and are equivalent to ‘pop up back thrusts’ of Elliot
194 (1981) (see also Butler, 1982, p.244) (Fig. 2). They generally form coeval with fore thrusts at
195 the leading edge of the propagating thrust system. ‘Secondary’ back thrusts typically develop
196 off fore thrust ramps, and are considered to be related to accommodation in the hangingwall
197 anticline of fore thrusts (Fig. 2). Secondary back thrusts are equivalent to the ‘antithetic back
198 thrusts’ of Mandle and Crans (1981) and are discussed further by Butler (1982, p. 244). A
199 significant difference is that ‘secondary back thrusts’ do not root onto the main detachment,
200 but rather on to the downslope-verging ramp of the fore thrust (Fig. 2).

201 Our data regarding back thrusts in MTDs is focussed on slump 4 of the Alsop et al.
202 (2016a) sequence from the Peratzim area (Fig. 1c). Concentrating on back thrusts from this
203 single event has the advantage that downslope slumping directions are well constrained,
204 while potential inconsistencies arising from variable lithologies are reduced, thereby allowing
205 greater focus on structural controls. We have analysed thrust and fault propagation fold
206 geometries from wadi cuttings that are parallel to the calculated transport direction within the
207 slump sheet, thereby removing complications associated with oblique views (see Alsop et al.,
208 2017 for details). Back thrusts display similar strikes to fore thrusts, with the sections
209 therefore providing ideal views of both of these sets of structures (Fig. 3a-f). In the first
210 section, the normal to mean fold hinges trends 048° , while normals to associated axial planes
211 and thrusts both strike 040° , which suggests the transport direction is sub-parallel ($\sim 2^\circ$
212 anticlockwise) to the 045° trending wadi wall (Fig. 3a-f). In the second section, less than 100
213 m further east, the normal to mean fold hinges trends 096° , while normals to associated mean
214 axial planes and thrusts strike 101° and 105° respectively, which suggests the transport
215 direction is sub-parallel ($\sim 10^\circ$ clockwise) to the 090° trending wadi wall (Fig. 3g-j). The
216 direction of MTD transport is considered to vary between the two sites due to the flow
217 diverging at the toe of the slump (Alsop et al., 2016a). Our observations from wadi walls,
218 which are parallel to the local fold and thrust transport direction, therefore provide good
219 geometric sections across back thrusts and associated structures.

220

221 **4. Structural analysis of upslope-verging back thrusts and folds**

222 Back thrusts and associated fault propagation folds develop both in defined sequences
223 where several related back thrusts are present in the same system (Fig. 4a, b, c), or as
224 individual structures (e.g. Fig. 4e). In some instances, fore thrust ‘flats’ are observed to gently
225 transect and cut through underlying stratigraphy resulting in downslope-directed footwall cut-
226 offs (Fig. 4b, c). Sequences of back thrusts are developed upslope of these gentle ramps (Fig.
227 4a, b, c). Fore thrusts display average dip angles of 25° (with a maximum of 50°), while the
228 adjacent primary back thrusts that ‘root’ onto the same flat have average dips of 45°
229 (maximum dip of 75°) and are consistently steeper than ramps in adjacent fore thrusts (Fig.
230 5a). Steeper fore thrusts are associated with steeper adjacent back thrusts (Fig. 5a). In
231 addition, steeper fore thrusts and back thrusts generally accommodate less displacement, with
232 back thrusts showing less displacement than for equivalent angles of fore thrusts (Fig. 5b).
233 Where sequences of fore thrusts and back thrusts form, they typically display progressive
234 rotations and steepening indicating piggyback systems of fore thrusts (that steepen upslope)
235 (Fig. 2, 4a, f) and back thrusts (that steepen downslope) (Fig. 2, 4a, b). In detail, primary back
236 thrusts are planar (e.g. Fig. 4a, b, 6a, c, g), or concave-up (i.e. steepen upwards towards the
237 fault tip) (e.g. Fig. 2, 4a, 6e), whereas fore thrusts are more generally planar (e.g. Fig. 3a, c, e,
238 4a), or convex-up (i.e. flatten upwards towards the fault tip) (Fig. 2, 3c, g, i, 4c, d). Back
239 thrusts are also observed to flatten into the underlying basal detachment, so that the footwall
240 resembles the curving shovel of a ‘bulldozer’ or ‘snowplough’ (Fig. 2, 3i, 6e).

241

242 **5. Displacement-distance graphs through back thrusts**

243 In displacement-distance (D-D) analysis, we measure the distance along the hangingwall of a
244 back thrust from a fixed reference point (‘R’ near the fault tip) to a marker horizon, and
245 compare this distance with the displacement of that marker by measuring the amount of offset
246 to the same horizon in the footwall (Muraoka and Kamata, 1983; Williams and Chapman,
247 1983). The process is then repeated for different markers along the length of the back thrust
248 to create a displacement-distance (D-D) graph for that fault. As displacement on faults is
249 typically assumed to be time-dependent, then older portions of faults accumulate the greatest
250 displacement meaning that the point of maximum displacement on a D-D plot is typically
251 interpreted to represent the site of fault nucleation (e.g. Ellis and Dunlap, 1988; Hedlund,
252 1997; Ferrill et al., 2016). In general, gentle gradients on D-D plots are interpreted to
253 represent more rapid propagation of the thrust tip relative to slip, whereas steeper gradients
254 represent slower propagation relative to slip (e.g. Williams and Chapman, 1983; Ferrill et al.,
255 2016).

256 In the case study, displacement-distance (D-D) graphs of primary back thrusts display
257 a range of relationships including simple linear patterns, with displacement increasing
258 progressively downwards away from the fault tip and towards the underlying basal
259 detachment (Fig 6a, b). D-D graphs may also display non-linear patterns, with displacement
260 gradients reducing markedly towards the underlying detachment (Fig 6 c, d). In other cases,
261 there are distinctive jumps in displacement where the back thrust cuts thickened units in its
262 footwall, with footwall thickening causing pronounced displacement gradients (Fig 6 e, f, g,

263 h). In some cases the sequence in the footwall of the back thrust displays extreme thickening
264 when compared to the same units in the hangingwall, ranging between 100% (Fig. 3i), 170%
265 (Fig. 6c) and 250% (Fig. 6e) thickening. These values equate to the relative stretch (ϵ_r) which
266 can be calculated by measuring the ratio of the measured lengths of the hangingwall (l_h) and
267 footwall (l_f) cut-offs parallel to the thrust, (where $\epsilon_r = l_h$ over l_f) (e.g. Noble and Dixon, 2011,
268 p.72). Values of 100% thickening represent ϵ_r 0.5, 170% is equivalent to ϵ_r 0.37, while 250%
269 thickening equates to ϵ_r 0.28.

270 In all the back thrusts that were analysed, the greatest displacement is developed
271 where the back thrust branches from the underlying basal detachment, suggesting that back
272 thrusts propagate upwards from this lower detachment. These relationships are different to
273 those analysed in fore thrusts, where the greatest displacement may develop where the fore
274 thrust cuts a competent unit in the hangingwall of the detachment (Alsop et al., 2017). In
275 addition, back thrusts frequently lack well-developed footwall synclines, especially low down
276 next to the basal detachment, although footwall synclines become more pronounced higher
277 up the back thrust (Fig. 6a, c, e).

278

279 **6. Back thrust sequences**

280 *6.1. Downslope-directed piggyback sequences*

281 Piggyback (or 'in sequence') thrusting develops where new thrusts form in the footwall of
282 existing thrusts (Fig. 2). In the case study, primary back thrusts propagating from the basal
283 detachment may cut (e.g. Fig. 4f) or simply back-steepen adjacent up slope fore thrust ramps
284 thereby confirming the overall piggyback relationships (Fig. 4d, 3g,). Back thrusts that form
285 near the termination of the upslope fore thrust suggest a degree of influence from the upslope
286 thrust, and thereby also support a piggyback sequence (e.g. Fig. 4d, e). Secondary back
287 thrusts die out upwards into tip folds that clearly fold and back steepen the next upslope
288 thrust ramp (Fig 7a, 8a) i.e. the back thrusts post-date the upslope ramp which in a piggyback
289 system would be the previous ramp to form. These observations are consistent with overall
290 downslope-directed piggyback thrust sequences.

291

292 *6.2. Downslope-directed out-of-sequence thrusting*

293 Out-of-sequence (or 'break-back') thrusting develops where new thrusts do not get
294 systematically younger towards the foreland (Fossen, 2016, p.485), and in fact such thrusts
295 tend to form in the hangingwall of existing thrusts. In the case study, some back thrusts,
296 which locally display an upslope-verging piggyback sequence, are themselves over-steepened
297 by downslope-verging folds and fore thrusts, indicating deformation has transferred back
298 upslope and is out-of-sequence (Fig. 7b, c, d, 8b). This may result in some back thrusts being
299 rotated through the vertical to now display extensional geometries (Fig. 4a, 7f). In addition,
300 individual back thrusts are also steepened by upslope fore thrusts (Fig. 4e). This back-
301 steepening suggests continued movement of the upslope portion of the slump after the back
302 thrusts had formed. This is consistent with out-of-sequence deformation (i.e. thrusting and
303 shortening continue upslope).

304

305 *6.3. Upslope-directed piggyback sequences*

306 Where more than one back thrust is developed, then the lower (upslope) back thrust is more
307 gently-dipping while the upper (downslope) back thrust is steeper (up to 50°) (Fig. 4a, b, 6c,
308 7e,f, 8c). Over-steepened back thrusts suggest new back thrusts form in the footwall of older
309 back thrusts thereby creating upslope-propagating piggyback sequence of back thrusts, Fig.
310 2). It is notable that some secondary back thrusts and folds develop in the hangingwall
311 adjacent to where the fore thrust ramp cuts the more competent detrital marker in the footwall
312 (Fig 3i, 4b,). These secondary back thrusts must form after the main thrust cuts the competent
313 layer, and are therefore out-of-sequence with respect to the main fore thrusts.
314

315 *6.4. Raising of hangingwall blocks*

316 Back thrusts may raise their hangingwall above the general stratigraphic level within the
317 slump sheet (e.g. Fig. 7g, h, 8d). Raising of the hangingwall is marked by a thinner detrital
318 horizon forming the overlying sedimentary cap. This sedimentary cap was deposited from
319 suspension following the slump event (e.g. Alsop et al., 2016a). Raising of the hangingwall
320 of back thrusts that causes less detrital material to be deposited above it (Fig. 7g) suggests
321 that actual uplift of the hangingwall block has occurred. It is notable that this steep secondary
322 back thrust propagates from the point where the underlying fore thrust ramp cuts a competent
323 unit in its footwall, suggesting that it formed in its present position (i.e. it has not been
324 transported by the underlying fore thrust (Fig. 7g). In addition, the observation that the basal
325 detachment and overlying stratigraphy immediately upslope of the back thrust are lower than
326 'regional' and are in fact tilted downslope suggests that the whole footwall to the back thrust
327 is being depressed and rotated during continued downslope movement from behind (Fig. 7g,
328 8d). It is noticeable that the footwall of some back thrusts are tilted downslope, with the
329 underlying basal detachment then cutting through footwall stratigraphy resulting in footwall
330 cut-offs in the downslope direction (Fig. 7c, 6e). Basal detachments cutting through tilted
331 sequences indicates continued downslope movement on the basal detachment following
332 creation of the back thrust.
333

334 **7. Discussion**

335 *7.1. Do back thrusts typically form in the central or downslope toe regions of MTDs?*

336 Back thrusts within gravity-driven slump systems have been shown by Garci-Tortosa et al.
337 (2011), where the basal detachment develops along a weak (sepiolite-rich) clay horizon.
338 Eight out of the 28 thrusts described by Garci-Tortosa et al. (2011) are back thrusts, with
339 most of these being in the central zone of the slump, while the toe itself is dominated by
340 downslope-verging thrusts. The development of back thrusts in the central portion of any
341 slump could reflect weaker sediments in this area, corresponding to the point where slope
342 failure initiates. The slump may locally decelerate downslope of the initial failure to create
343 back thrusts, while fore thrusts are located at the toe of the slump as it potentially becomes
344 emergent and accelerates over the sediment surface (Fig. 9a). Back thrusts would develop
345 where there is a deceleration along the basal detachment (Fig. 9a), although fold and thrust
346 vergence (up or down the slope) is clearly not dependent on the direction that the
347 compressive phase migrates (see Alsop and Marco, 2011, p.435).

348 In the present case study, back thrusts are developed within ~ 100 m of the exposed
349 toe of slump 4 (Alsop et al., 2016a), and may partially relate to the arrest of downslope
350 movement within the MTD. As the toe of the slump system decelerates, the more central
351 portion where the slump actually initiated (presumably in the weakest sediments) continues to
352 move more rapidly downslope resulting in contraction at the toe driven from ‘behind’ by the
353 upslope portion of the slump (Fig. 9b). This is supported by the observation that the frontal
354 portions of slumps in the case study are not emergent, but rather are ‘open-ended’ with
355 deformation being distributed via lateral compaction into downslope sediments (Fig. 9b) (see
356 Alsop et al., 2016a).

357

358 *7.2. What controls the development of back thrusts in gravity-driven MTDs?*

359 *7.2.1. Local Thrust Pinning*

360 Coward (1988, p.5) suggests that back thrusts in orogenic systems could develop at tip zones
361 where “there is a high resistance to shear and/or fault propagation”. Similarly, Verges et al.
362 (1992, p.261) suggest that a passive back thrust in the Pyrenees develops where basal friction
363 is increased along an underlying detachment due to the removal of a lubricating salt layer. An
364 increase in basal friction causes the overlying sequence to be driven as a footwall wedge
365 below the passive back thrust which is consequently uplifted. Strachan and Alsop (2006,
366 p.466) have suggested that within slump systems, back thrusts and folds may develop where
367 the basal detachment is temporarily ‘pinned’ (Fig. 10a). Such back thrusts truncate
368 downslope-verging folds in their footwall, while the hangingwall of the back thrust preserves
369 folds with atypical vergence back up the slope (Strachan and Alsop, 2006). No local pinning
370 is observed within the case study, although it could be argued that the overall positioning of
371 the back thrusts within 100 m of the toe of the slump (see section 7.1. above) is in itself a
372 reflection of large scale ‘pinning’ brought about by a reduction in downslope movement
373 towards the ‘open-ended’ toe.

374

375 *7.2.2. Downslope buttress*

376 The role of pre-existing geometries in ‘buttressing’ contractional deformation, thereby
377 leading to the development of back thrusts in the internal portions of fold and thrust belts has
378 been modelled by McClay and Buchanan (1992). Auchter et al. (2016) have suggested that
379 pre-existing sedimentary architecture may control the position of back thrusts in MTDs (Fig.
380 10b). They suggest that irregular sedimentary units may act as a ‘buttress’ resulting in back
381 thrusts forming in the upslope area of the obstruction. There is no evidence of such
382 sedimentary variation acting as a buttress in the study area. Alternatively, Fossen (2016,
383 p.360) suggests that back thrusts form “as a result of geometric complications in ramp
384 locations and seem to be favoured by steep ramps” (along underlying decollements) that
385 would act as a buttress. In the study area, footwall cut-offs are indeed occasionally observed
386 along the basal detachment immediately down slope of back thrust sequences (Fig. 4c).

387

388 *7.2.3. Angle of slope*

389 While significant downslope gradients may encourage forward propagation of fore thrusts in
390 a piggyback sequence (Fig. 10c), a reduction in slope angle such that it becomes negligible
391 ($<1^\circ$) will hinder forward propagation and facilitate back thrusting (Fig. 10d). Garcia-Tortosa

392 et al. (2011) record numerous back thrusts developed in slump systems formed on very gentle
393 ($<1^\circ$) slopes in lacustrine settings. Similarly, Gladkov et al. (2016) have also recorded both
394 fore thrusts and back thrusts on gentle slopes (1° - 3°) in lacustrine settings, and suggested that
395 these events are seismically triggered. Very gentle or negligible gradients ($<1^\circ$) apply in the
396 present system (Alsop and Marco, 2013). We suggest that the well-developed stratigraphy
397 formed in lacustrine settings, coupled with a seismic trigger on a gentle slope, may encourage
398 back thrusting to develop during gravity-driven downslope movement (Fig. 10d). Low or
399 negligible gradients will hinder the forward propagation of the slump toe, thereby
400 encouraging shortening and back thrusting driven by continued downslope movement from
401 behind the toe (see section 7.1.) (Fig. 10d).

402

403 *7.2.4. Weak basal detachment*

404 Some studies suggest that back thrusts form when there is very low viscosity/friction along
405 basal decollement. Lui et al. (1992) ran analogue experiments and noted that the number of
406 back thrusts associated with each foreland-vergent thrust decreases with an increase in basal
407 friction. Low values of basal friction resulted in deformation being split equally into fore
408 thrusts and back thrusts. Mastrogiacomo et al. (2012) studied back thrusts developed in
409 slumps in carbonates and suggest a lithological control with thinner slumps in laminated
410 muds seemingly favouring back thrusts due to different boundary conditions along the base
411 of the slump sheet. Weak basal detachments have been invoked in the present case study area
412 (Alsop and Marco, 2014;) and together with very low gradients (Alsop and Marco, 2013),
413 appear to be the most significant controls (Fig. 10d).

414

415 *7.3. What are the displacement patterns along back thrusts?*

416 Primary back thrusts in unlithified sediments display displacement-distance (D-D)
417 patterns marked by the largest displacement being adjacent to the underlying detachment
418 (Fig. 6a-h). This pattern suggests that the back thrust initiates from near this basal
419 detachment, and propagates upwards with decreasing displacement. In general, steeper back
420 thrusts have less displacement, despite being developed in the same stratigraphic sequence as
421 fore thrusts in slump 4 (Fig. 5b). For instance, back thrusts shown in Figs 6a and 6g dip at
422 35° and 30° and accommodate displacement of 390 mm and 1042 mm respectively, whereas
423 steeper back thrusts (Figs. 6b and 6e) dipping at 75° and 63° accommodate displacement of
424 just 124 mm and 313 mm respectively. If rotation were a later process that developed after
425 the back thrust had formed, for instance during sequential piggyback thrusting, then its highly
426 unlikely that such a relationship would be preserved (as larger back thrusts do not 'know'
427 how much they will be subsequently rotated). However, if the back thrust rotated and
428 steepened as it underwent displacement, then it is likely that displacement will diminish as
429 the rotating back thrust becomes less favourably orientated and less effective at
430 accommodating shortening (see Butler, 1987, p. 629). If steepening of back thrusts occurs at
431 the same time as they are displacing markers, then this can only develop by wedging and
432 thickening of sediment in the footwall of the back thrust (see section 7.6).

433

434 *7.4. When do back thrusts form within the thrust sequence?*

435 Ramsay and Huber (1987, p.522) note that back thrusts form more frequently “at a late stage
436 of tectonic evolution of the main reversed fault structure”, while Strachan (2002, p.18)
437 suggests that thrusts are in general a late stage feature in MTDs linked to ‘rapid arrest’ of
438 downslope movement at the slump toe. However, physical models run by Lui et al. (1992)
439 show that back thrusts form sequentially immediately after each foreland vergent thrust.
440 These experiments showed that “foreland –vergent thrusts nucleate at angles of 20-25° and
441 are always accompanied by a back thrust (initial angles 35-40°) at their tips” (Lui et al. 1992,
442 p.75). More recently, Dotare et al. (2016, p.154) have shown from analogue models that in
443 piggyback thrust sequences, “the location of the new frontal front seems to be constrained by
444 its associated back-thrust”, with back thrusts forming at broadly the same time as fore thrusts.
445 In addition, Dotare et al. (2016, p.153) note that back thrusts form at the foot of the surface
446 slope created by the previous fore thrust.

447 In the case study, back thrusts also form near the tips of the upslope fore thrusts (e.g.
448 Figs 4d, e), suggesting that local slopes created by the thrusts, together with additional
449 loading from the upslope thrust sheet, may help drive back thrusting in piggyback sequences.
450 Our observations that primary back thrusts may locally steepen up slope fore thrusts suggest
451 that back thrusts form at the same time as adjacent down slope fore thrusts in an overall
452 downslope-propagating piggyback sequence. If back thrusts are steepened by continued
453 downslope movement (e.g. Fig. 6e) then this does not deform the overlying cap and so cannot
454 be attributed to longer term creep as suggested in some slumps within carbonates (e.g. Ortner
455 and Kilian, 2016) and larger MTDs (e.g. Sobiesiak et al., 2016, 2017).

456

457 *7.5. How do back thrusts in MTDs compare to those in lithified rocks?*

458 Boyer and Elliot (1982) note that thrust faults in lithified sequences form with dip angles of
459 23° to 45° to bedding, with angles of 25° being most common. Previous work in orogenic
460 belts has also shown that back thrusts have steeper dips and higher cut-offs relative to
461 bedding than fore thrusts (e.g. Chapple, 1978; Davis et al., 1983; Xu et al., 2015). These
462 angles are similar to observations of thrusts cutting unlithified sediments in the case study
463 with primary back thrust ramps also being generally steeper than fore thrusts (e.g. Fig. 3, 4a,
464 b, 5a) (Alsop et al., 2017).

465 Back thrusts in the case study display extreme values of footwall thickening that
466 range between 100% and 250% when compared to the equivalent sequence in the
467 hangingwall (Fig. 3i, 6c, 6e). These values are comparable to relative stretch (ϵ_r), which
468 compares the relative lengths of hangingwall and footwall cut-offs (e.g. Noble and Dixon,
469 2011, p.72). Values of relative stretch across back thrusts in the case study of between ϵ_r 0.5
470 and 0.28 are significantly less than observed from thrusts cutting lithified rocks. For instance,
471 Williams and Chapman (1983) recorded relative stretch values of between 0.5 and 0.89 from
472 thrusts cutting lithified rocks, while general values of between 0.5 and 1 are quoted by
473 Chapman and Williams (1984). These extreme values of relative stretch adjacent to back
474 thrusts in the case study are considered to reflect the ability of sediments to flow and thicken
475 compared to lithified sequences (see Alsop et al., 2017).

476 Van der Pluijm and Marshak (2004, p.457) suggest that (secondary) back thrusts may
477 form in the hangingwall above a ramp in the underlying decollement. Secondary back thrusts
478 have also been recognised in seismic across large-scale fold and thrust belts with de Vera et

479 al (2010, p.230) noting that “back thrusts typically nucleate from existing kink surfaces
480 developed at the transition from the thrust ramp to the basal detachment”. These are
481 consistent with ‘secondary’ back thrusts in the present study, which generally form where the
482 underlying fore thrust undergoes a change in ramp angle. Alternatively, back thrusts may
483 form “where the front of a thrust sheet wedges between layers of strata in the foreland as it
484 moves up and over a footwall ramp” (Van der Pluijm and Marshak (2004, p.457). In the
485 present study there is very little evidence of ramping in the underlying detachment. Using
486 analogue experiments, Saha et al. (2016, p.111) suggest that back vergent thrusts “must be
487 related to lower-order thrusting at the deep level” (i.e. all back thrusts are therefore
488 secondary). This is clearly different to observations in gravity-driven thrusts in MTDs where
489 ‘deeper level’ thrusting is not present. Back thrusts and fore thrusts in orogenic and MTD
490 systems exhibit similar angular and geometric relationships to one another, but with back
491 thrusts in MTD’s displaying significantly greater footwall thickening.

492 *7.6. Do back thrusts in gravity-driven slump systems record movement back upslope?*

493 Van der Pluijm and Marshak (2004, p.446) define a back thrust as “a thrust on which the
494 transport direction is opposite to the regional transport direction”. This general concept has
495 also found its way into common usage such that the Oxford dictionary of Earth Sciences
496 defines a back thrust as a “thrust in which displacement is in an opposite direction to that of
497 the main thrust propagation” (Allaby, 2008, p.50). So, is it feasible for back thrusts in
498 gravity-driven mass transport deposits to transport material back up the slope in a direction
499 opposite to the regional downslope movement? Myrow and Chen (2015 p. 632) note that
500 “hangingwall blocks show significant up-dip transport ... which suggests that thrusting was
501 not a response to gravitationally induced slope failure”. Clearly, the correct interpretation of
502 back thrust mechanisms can have major implications for the interpretation and genesis of a
503 range of MTD structures and complexes.

504 We now discuss evidence of whether back thrusts conform to either the ‘*upslope-*
505 *directed overthrust model*’, where the hangingwall of the back thrust is actively translated
506 back up the regional slope (Fig. 11a), or the ‘*downslope-directed underthrust model*’, where
507 material moves down slope and is driven into the footwall of the back thrust as a wedge of
508 sediment, while the hangingwall remains largely passive (Fig. 11b). This is equivalent to
509 passive roof back thrusts of orogenic belts and inverted sedimentary basins (e.g. Coward,
510 1994, p. 299). We also follow the terminology of Ramsay and Huber (1987, p.521) who
511 simply define an overthrust as where “an overlying thrust sheet has been displaced relative to
512 an unmoved footwall” while an underthrust is where “the footwall has moved beneath the
513 hangingwall”. As the hangingwall of a back thrust moving upslope, or its footwall moving
514 downslope, generate the same relative sense of shear, the issue actually becomes one of
515 determining absolute rather than relative movements. As such, any kinematic indicators
516 which reflect relative sense of shear are of little use, and we therefore rely on overall
517 geometries to determine absolute motion.

518

519 *7.6.1. Thickening of sequences in the footwall of back thrusts*

520 Thickening of sequences in the footwall of back thrusts has been depicted and discussed on
521 an orogenic scale by Butler (1987, p. 630), who suggests that both piggyback and out-of-

522 sequence break-back sequences of back thrusts are capable of being developed. If the forward
523 (or basin-ward) propagation of the basal detachment is restricted, then a zone of pure shear-
524 dominated deformation develops hindward (upslope) of the back thrust, resulting in layer
525 parallel compaction and thickening of units (Butler, 1987, p. 629). Such a scenario is present
526 in the back thrusts of Peratzim, where significant footwall thickening of some units occurs
527 (e.g. 250% on Fig. 6e), and is commonly marked by the downward deflection of some
528 footwall markers (e.g. Fig. 3i, 6c, e, 7f). Similar downward deflection of ‘pre-kinematic’
529 footwall markers has also been observed in sandbox models of back thrusts (e.g. fig. 8 of
530 Alsop and Marco, 2011). As equivalent beds within the case study display different
531 thicknesses on either side of the fault, then thickening must occur after the back thrust has
532 initiated (i.e. a pre-existing thickened layer has not simply been later offset by the fault) (e.g.
533 Fig. 4f, 6c). This footwall thickening supports layer parallel compaction associated with the
534 ‘*downslope-directed underthrust model*’ (Fig. 11b).

535

536 7.6.2. *Thickening of hangingwall between linked fore thrusts and back thrusts.*

537 In the ‘*upslope-directed overthrust model*’, the hangingwall of back thrusts would move back
538 up the slope in a direction opposed to the fore thrusts. Fore thrusts and back thrusts moving
539 apart in opposing directions would result in extension of the intervening hangingwall
540 sediments (Fig. 11a). However, where back thrusts and fore thrusts are developed adjacent to
541 one another, there is no evidence for such extension or normal faulting in the hangingwall.
542 Indeed, sequences between oppositely dipping thrusts are frequently thickened (e.g. Fig. 3g,
543 i). This hangingwall thickening, coupled with the lack of extension therefore supports the
544 ‘*downslope-directed underthrust model*’.

545

546 7.6.3. *Steepening of back thrusts and ‘pinched synclines’*

547 New thrusts developing in the footwall of existing thrusts may result in significant rotation of
548 older thrusts, which in some analogue experiments leads to rotation through the vertical (e.g.
549 Saha et al., 2016, p. 107) (Fig. 7f, 11a, b). Butler, (1987, p. 629) noted that within orogenic
550 fold and thrust systems, back thrusts may become steepened due to pure shear dominated
551 deformation, and therefore incapable of accommodating significant displacements. Back
552 thrusts within the case study are also notably steeper than fore thrusts (e.g. Figs. 4, 5a, 7c, d,
553 g, h). Marked steepening of back thrusts results in some thrusts actually being rotated through
554 the vertical and now displaying apparent extensional geometries (Fig. 6c, 7c, 7f). We
555 attribute the steeper back thrusts to continued down slope movement that drives a wedge of
556 sediment into the footwall of the back thrust (Fig. 11b). New back thrusts developing in the
557 footwall of existing back thrusts may ‘steepen’ the existing back thrust, before the entire
558 system is back rotated by continued downslope movement of the footwall. This steepening
559 and rotation of back thrusts leads to a ‘pinching’ of synclines between the hangingwall of the
560 back thrusts and downslope fore thrust (Fig. 3i, 4e, 7c, g 11b). Similar patterns have recently
561 been shown for fore thrusts in analogue modelling experiments by Saha et al. (2016, p.111).
562 We suggest that the down slope fore thrust was already present, and acted a local ‘buttress’
563 which effectively closed the ‘vice’ from the opposite side (Fig. 11b). This steepening of back
564 thrusts through the vertical, coupled with ‘pinching’ of synclines supports the ‘*downslope-*
565 *directed underthrust model*’.

566

567 *7.6.4. Footwall synclines*

568 The observation that footwall synclines are generally not well developed in primary back
569 thrusts suggests a different mechanism to fore thrusts. Footwall synclines are actually least
570 well developed where displacements on the back thrusts are greater (i.e. toward the basal
571 detachment) (Fig. 6a-h). We suggest that footwall synclines are therefore not the product of
572 frictional drag, where increased rotation and folding of beds would be generated by greater
573 displacement (see discussion in Ferrill et al., 2012). It has been suggested previously that
574 footwall synclines form where the fault is propagating downwards (see Ferrill et al., 2016,
575 p.9). In some cases, footwall synclines may therefore fail to develop in the lower portions of
576 back thrusts because the fault tip was propagating upwards from the basal detachment (Fig.
577 11b).

578

579 *7.6.5. 'Jacking up' of back thrust hangingwall*

580 The observation that some hangingwalls to back thrusts are raised above the general elevation
581 is shown by a) thinning of overlying deformed layers, b) reduction in the thickness of
582 sedimentary caps deposited from suspension above these structural highs (Fig. 7g, 8d).
583 Similar thinning of 'syn-kinematic' layers above back thrusts has been observed in sandbox
584 models of thrust systems (e.g. see fig. 8 of Alsop and Marco, 2011). In addition, the same
585 'syn-kinematic' layers are thickened in the footwall of the back thrusts, supporting the notion
586 that they are actually subsiding and being driven down as a 'footwall wedge'. Raising of
587 hangingwalls could be achieved by either a) back thrusts actively moving the hangingwall
588 upslope (Fig. 11a), or b) continued downslope movement upslope of back thrust i.e. several
589 thrusts were active simultaneously to 'wedge' more sediment into the footwall (Fig. 11b).
590 The observation of structural highs above back thrusts can not therefore be used to
591 independently separate active back thrusting of the hangingwall up the slope from the
592 '*downslope-directed underthrust model.*'

593

594 *7.6.6. Summary*

595 We argue that back thrusts do not displace material upslope because a) the footwall sequence
596 undergoes pure shear thickening and lateral compaction as it is 'wedged in' from upslope, b)
597 linked fore thrust to back thrust systems do not display attenuation or extension of
598 intervening hangingwall stratigraphy as would occur if two thrusts moved in opposite
599 directions, c) back thrusts are over steepened (to the point of overturn) due to a sediment
600 wedge being driven in to the footwall. This results in material being expelled from between
601 the steepened back thrust and fore thrust as the intervening syncline is 'pinched' closed (Fig.
602 11b). Thus, although the hangingwall is 'jacked up' by footwall wedging resulting in it lying
603 above the 'regional' level, this need not involve actual upslope lateral movement of the
604 hangingwall (e.g. Fig. 7g). Finally, we note the relationships where steeper back thrusts
605 display less displacement (section 7.3, Fig. 5b). If the hangingwall of the back thrust were
606 actively displaced upslope during sequential piggyback overthrusting, then no such
607 displacement-steepening relationships would develop as movement on the earlier thrust
608 would cease before the new back thrust started to back steepen it. However, these dip-

609 displacement relationships are consistent with wedging and thickening of sediment in the
610 footwall of the active back thrust *during* downslope-directed underthrusting.

611

612 **8. Conclusions**

613 While the initial trigger for slope failure is considered to be seismicity along the Dead Sea
614 Fault, fore thrust and back thrust development within MTDs reflects subsequent gravity-
615 driven movement down the low-angle slope. The presence of a weak detachment horizon
616 coupled with very low gradients ($<1^\circ$) is the main control on back thrust development. Back
617 thrusts typically form towards the toe of MTDs, where downslope translation has reduced,
618 while movement in the upslope portion continues and/or is more rapid. Over-steepened back
619 thrusts indicate that basin-directed movement continued upslope of the back thrusts. Back
620 thrusts form at the same time as the overall downslope-verging thrust sequence and pre-date
621 creation of the overlying sedimentary cap deposited from suspension. Extreme thickness
622 variations in the footwall of back thrusts (compared to thrusts cutting lithified rocks), reflects
623 lateral compaction during continued downslope movement.

624 We suggest that back thrusts in gravity-driven fold and thrust systems do not
625 represent active displacement back up the slope, but rather the driving-in of the footwall
626 ‘wedge’ in a ‘*downslope-directed underthrust model*’. In the case of MTDs, this causes a
627 ‘jacking up’ and steepening of the largely passive hangingwall to the back thrust. Back
628 thrusts that are steeply dipping typically display less displacement, suggesting that they
629 rotated (and therefore became ineffective) during ‘footwall wedging’. Contrary to some
630 recent assertions by Myrow and Chen (2015 p.639) that variably oriented thrust planes “are
631 inconsistent with downslope, gravity-driven failure”, we have demonstrated that back thrusts
632 with directly opposing senses of apparent displacement to adjacent fore thrusts may develop
633 in gravity-driven systems. The further implication of our work is that the presence of back
634 thrusts cannot therefore be used to distinguish gravity-driven fold and thrust systems in
635 MTDs from other seismic mechanisms.

636

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641

642 **Figures**

643 **Fig. 1** a) Tectonic plates in the Middle East. General tectonic map showing the location of the
644 present Dead Sea Fault (DSF). b) Map of the current Dead Sea showing the position of
645 localities referred to in the text. The arrows within the Lisan Formation represent the
646 direction of slumping in MTD’s that forms a semi-radial pattern around the Dead Sea Basin.
647 c) Image of the light-coloured Lisan Formation at Wadi Peratzim, with the brownish
648 Cretaceous margin to the west and the Sedom salt wall to the east.

649 **Fig. 2** Schematic cartoon illustrating the main structural parameters and definitions of fore
650 thrusts (T) and back thrusts (BT) within a downslope-directed Mass Transport Deposit.

651 Systems of fore thrusts and back thrusts may form downslope- and upslope-directed
652 piggyback sequences, respectively, where T1 develops before T2 etc.

653 **Fig. 3** Photographs (a, c, e, g, i) and associated stereonet of structural data (b, d, f, h, j) from
654 slump 4 at Peratzim (N 31°0449.6 E 35°2104.2). b) Stereonets of thrust planes (N=6), and
655 folds (N=11), showing fold hinges (mean 2/316), axial planes (mean 127/21SW) and thrust
656 planes (mean strike 121°). d) Stereonets of thrust planes (N=3), and folds (N=8), showing
657 fold hinges (mean 4/323), axial planes (mean 153/17SW) and thrust planes (mean strike
658 144°). f) Stereonets of thrust planes (N=5), and folds (N=11), showing fold hinges (mean
659 1/317), axial planes (mean 116/11SW) and thrust planes (mean strike 134°). h) Stereonets of
660 thrust planes (N=6), and folds (N=8), showing fold hinges (mean 0/013), axial planes (mean
661 strike 022°) and thrust planes (mean strike 012°). j) Stereonets of thrust planes (N=5), and
662 folds (N=8), showing fold hinges (mean 1/180), axial planes (mean strike 179°) and thrust
663 planes (mean strike 018°). Structural data on each stereonet is represented as follows: fold
664 hinges (solid red circles), poles to fold axial planes (open blue squares), thrust planes (red
665 great circles), poles to thrust planes (solid red squares). Calculated slump transport directions
666 based on fold data (blue arrows) and thrust data (red arrows) are subparallel to the trend of
667 the outcrop section (black arrows).

668 **Fig. 4** a) Piggyback sequence of fore thrusts and primary back thrusts with b) showing an
669 enlargement of the SW end of the section, while c) shows the basal detachment displaying
670 footwall cut-offs at the NE end of the section. Thrusts (T) and back thrusts (BT) are
671 sequentially numbered from oldest (1) to youngest (3). d) and e) show back thrusts that
672 locally steepen the upslope fore thrust, indicating that back thrusts formed later in a
673 (downslope) piggyback sequence. f) Primary back thrust that displaces the upslope fore
674 thrust. Layers in the footwall of the back thrust displays significant thickening.

675 **Fig. 5** a) Graph showing data from slump 4 (N=12) where the dip of back thrusts is compared
676 to adjacent fore thrusts. b) Graph showing that steeper fore thrusts and back thrusts in slump
677 4 generally accommodate less displacement (N=35).

678 **Fig. 6** Photographs (a, c, e, g) and associated displacement-distance (D-D) graphs (b, d, f, h)
679 across primary back thrusts in slump 4. In the photographs, displaced horizons are marked by
680 matching coloured squares (footwall) and circles (hangingwall), with displacement dying out
681 at the fault tip (yellow circle). The associated D-D graphs show the hangingwall cut-off
682 markers (coloured circles) defining a displacement profile drawn downwards from the fault
683 tip (yellow circle) at the origin. Photograph a) shows that primary back thrusts may develop
684 secondary back thrusts in their own hangingwall, while c) and e) illustrate how back thrusts
685 may be progressively steepened and rotated as new back thrusts form in their footwalls.

686 **Fig. 7** a) Back thrust (BT3) causing steepening of up slope fore thrust (FT1) indicating a
687 downslope propagating sequence. Fore thrust (FT2) ramp angles display typical reductions
688 upwards to define convex-up geometries. b) Over-steepened back thrust develops in the
689 hangingwall of a fore thrust. c) Over-steepened back thrust and pinched syncline indicate out-
690 of-sequence thrusting and/or continued downslope movement. d) Stereonets of thrust plane,
691 and folds (N=9), showing fold hinges (mean 3/316), axial planes (mean 145/9SW) and thrust
692 plane (mean strike 142°). e) Primary back thrusts undergo sequential steepening indicating a
693 'piggyback sequence' and continued downslope movement from behind. f) Over-steepened
694 and inverted back thrust indicates out-of-sequence thrusting and/or continued downslope
695 movement. g) Back thrust lifts hangingwall above 'regional' level and causes upslope
696 syncline to pinch close. h) Stereonets of thrust plane, and folds (N=10), showing fold hinges
697 (mean 5/313), axial planes (mean 148/15SW) and thrust plane (mean strike 165°). Structural
698 data on each stereonet (d, h) is represented as follows: fold hinges (solid red circles), poles to

699 fold axial planes (open blue squares), thrust planes (red great circles), poles to thrust planes
700 (solid red squares). Calculated slump transport directions based on fold data (blue arrows)
701 and thrust data (red arrows) are subparallel to the trend of the outcrop section (black arrows).
702

703 **Fig. 8** Summary cartoons illustrating sequential relationships between fore thrusts (T) and
704 back thrusts (BT). Thrusts may display a) downslope-directed piggyback sequences, b)
705 downslope-directed out-of-sequence thrusting, c) upslope-directed piggyback sequences, d)
706 continuing downslope movement that raises the hangingwalls of back thrusts.

707 **Fig. 9** a) Summary cartoon illustrating how slumps initiate where sediment is weakest and
708 undergo deceleration downslope leading to back thrusts. Frontally-emergent toes are
709 generally marked by acceleration and fore thrusts. b) Downslope deceleration associated with
710 'open-ended' toes results in back thrusts in the downslope toe area.

711 **Fig. 10** Summary cartoons illustrating mechanisms for the development of fore thrusts (T)
712 and back thrusts (BT) in mass transport deposits. Back thrusts may be encouraged by a)
713 downslope pinning of the detachment tip, b) sedimentary or structural buttress that inhibits
714 downslope propagation of fore thrusts. Significant slope angles encourage fore thrusts to
715 develop (c), whereas negligible slopes coupled with weak basal detachments encourage back
716 thrusts (d).

717 **Fig. 11** Summary cartoon illustrating a) upslope-directed overthrust model, and b)
718 downslope-directed underthrust model of thrust (T) and back thrust (BT) development within
719 mass transport deposits. Systems of back thrusts may form upslope-directed piggyback
720 sequences respectively, where BT1 develops before BT2 etc. Rather than upslope movement
721 of the hangingwall, back thrusts are considered to reflect 'wedging' of the footwall as it
722 undergoes downslope-directed underthrusting.

723

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Figure 1

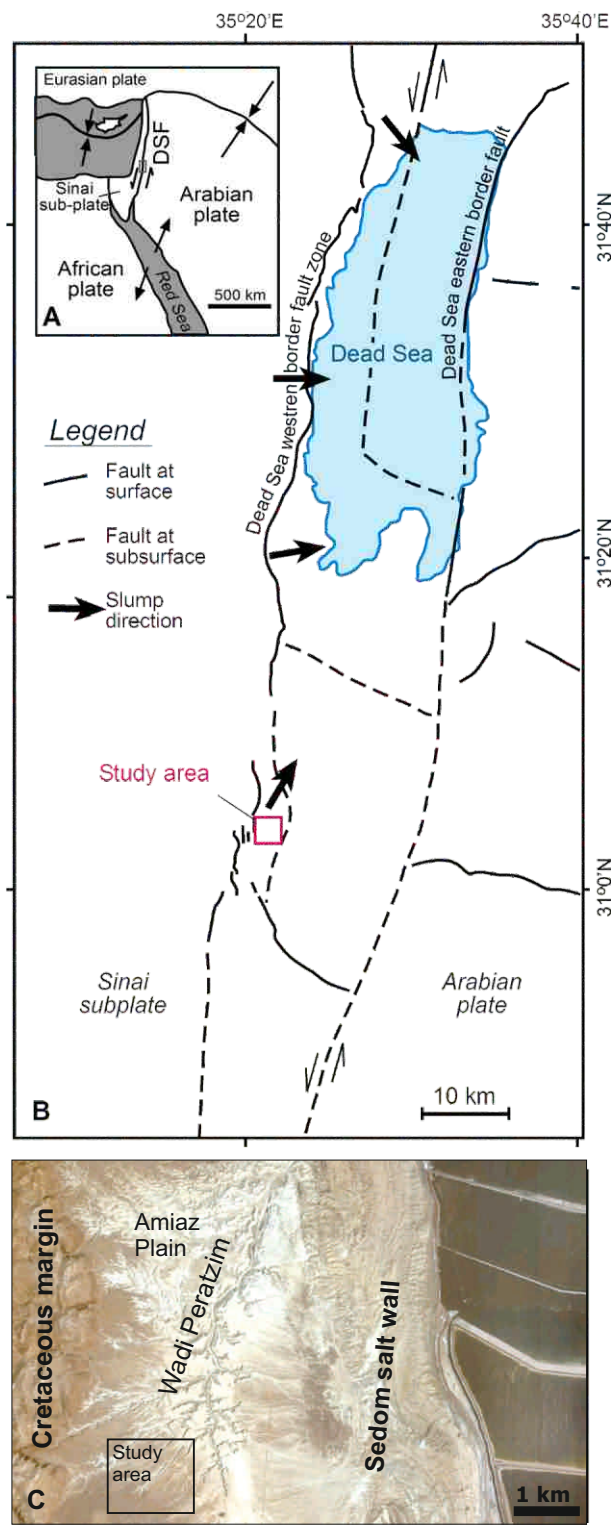
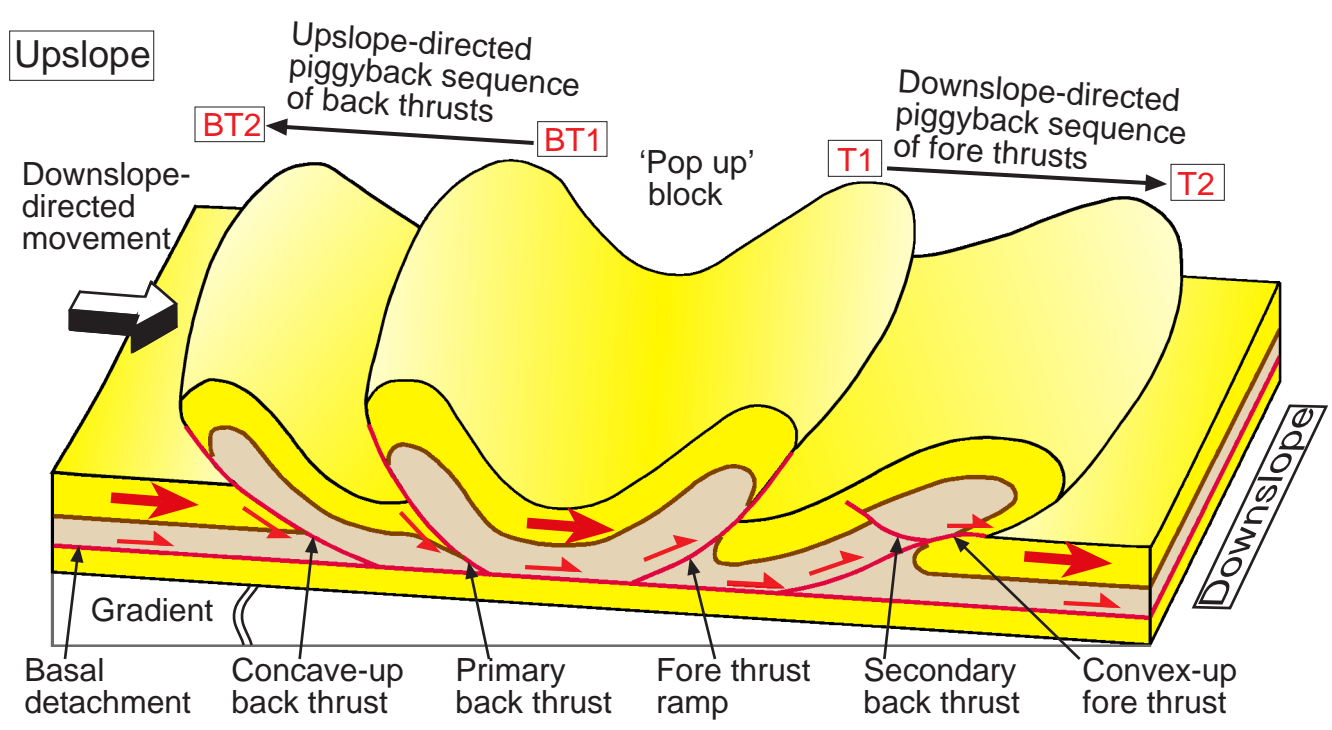


Figure 2



*Figure 3

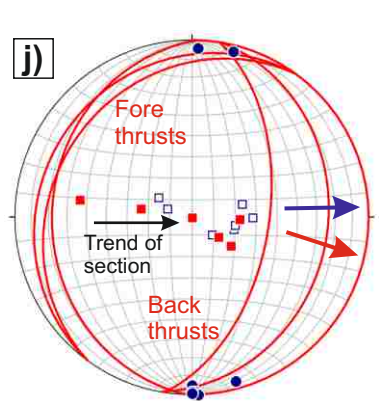
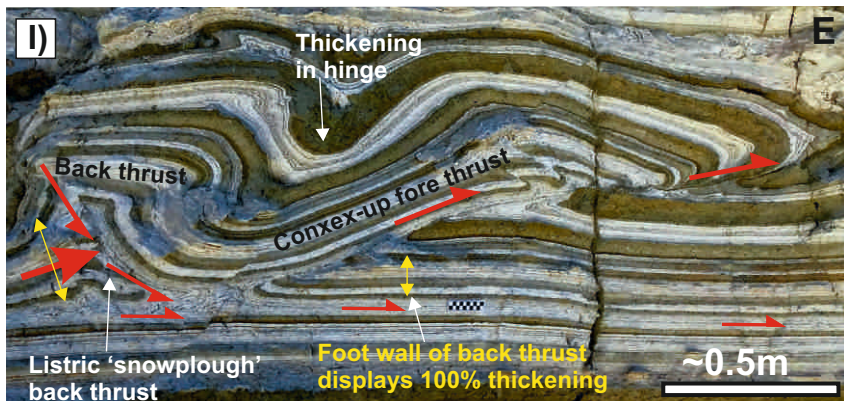
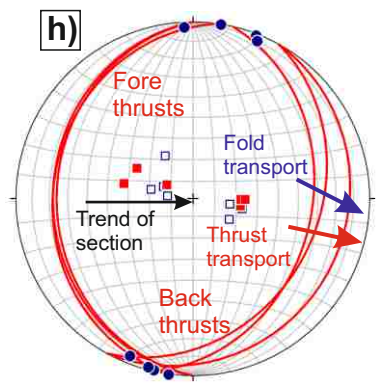
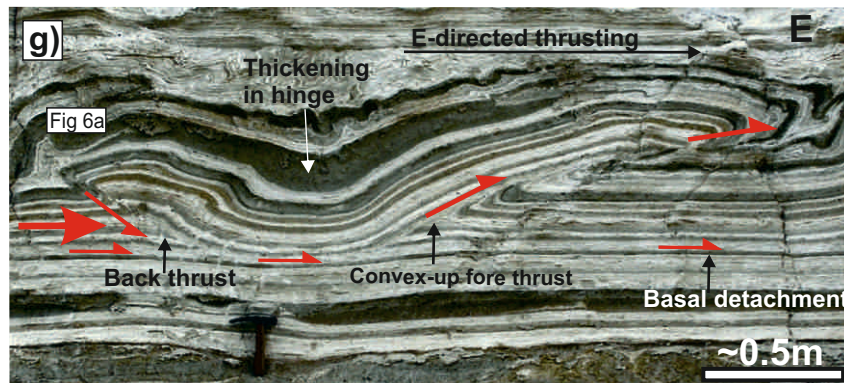
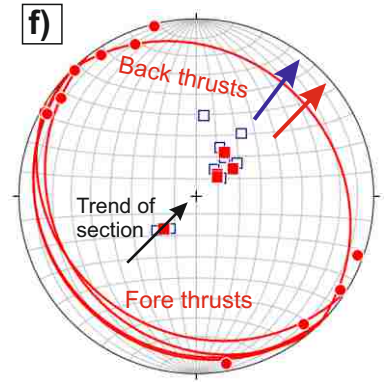
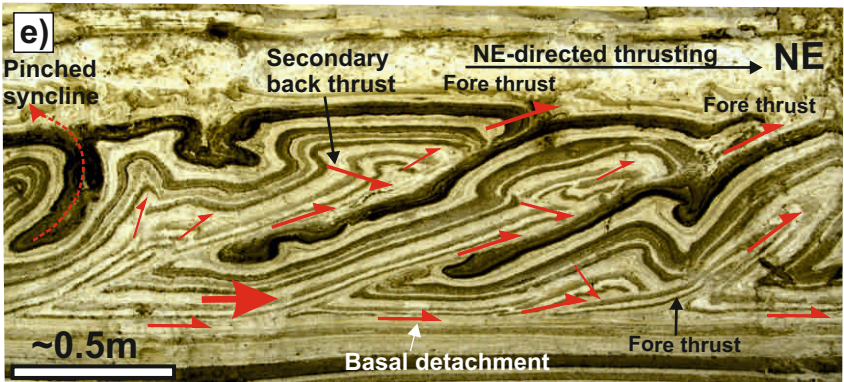
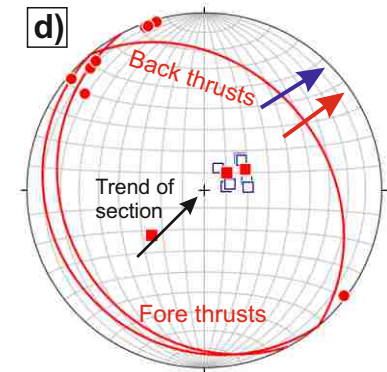
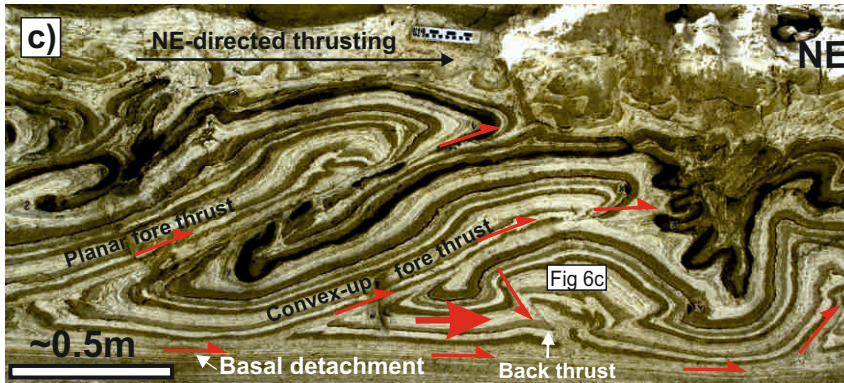
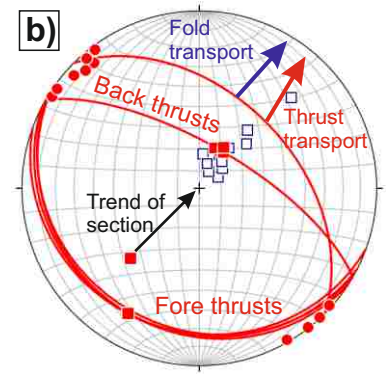
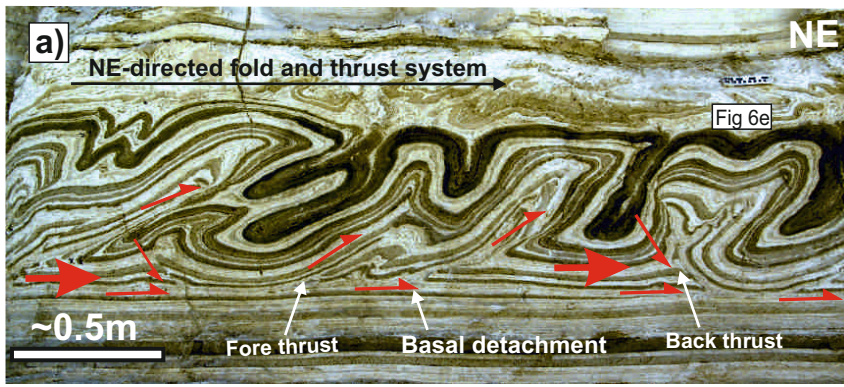


Figure 4

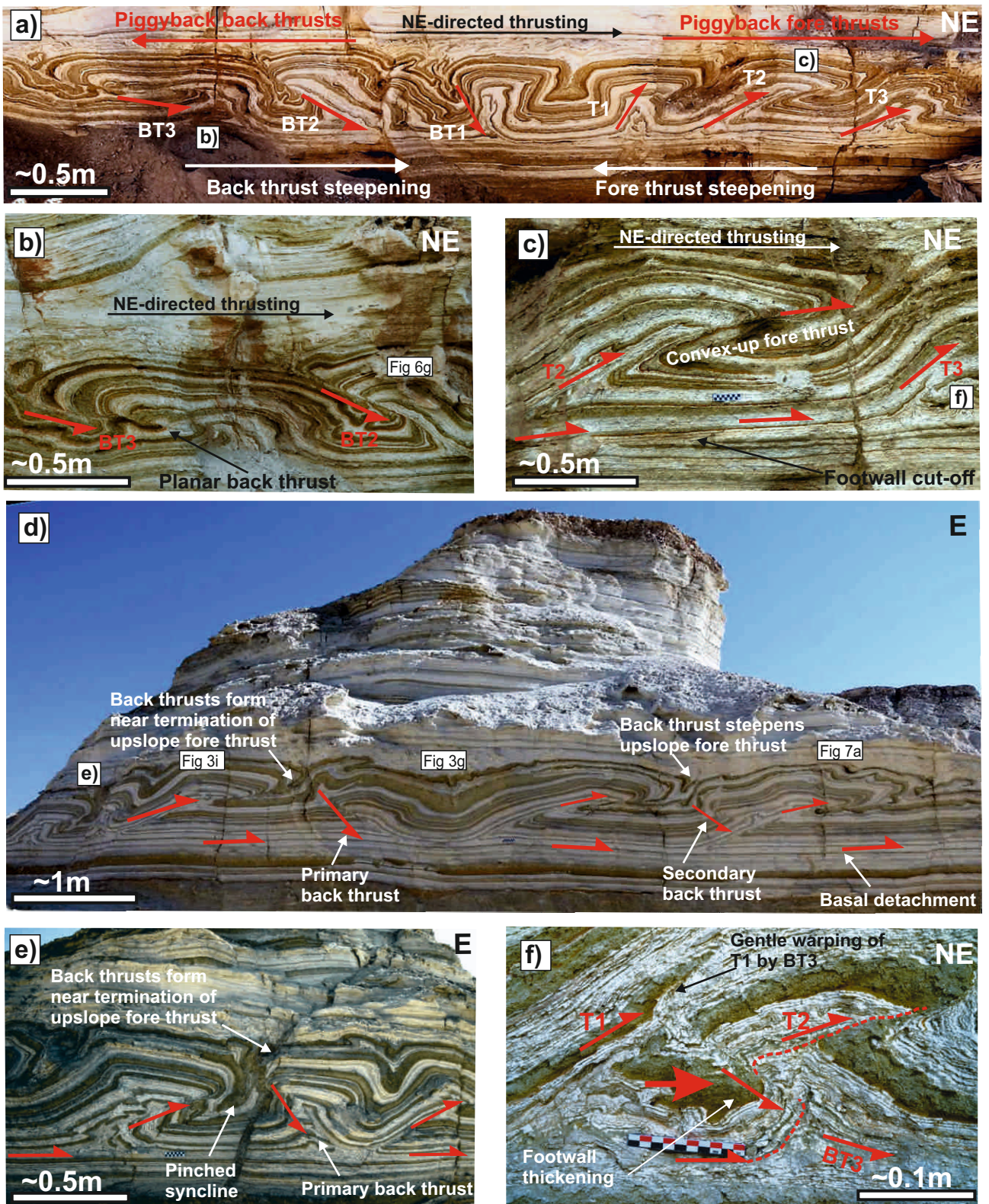


Figure 5

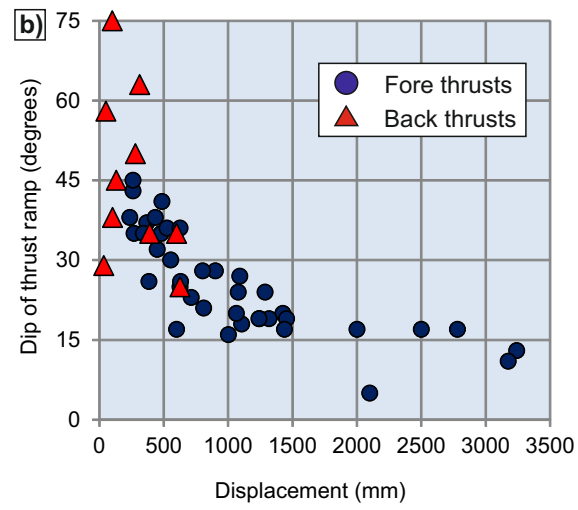
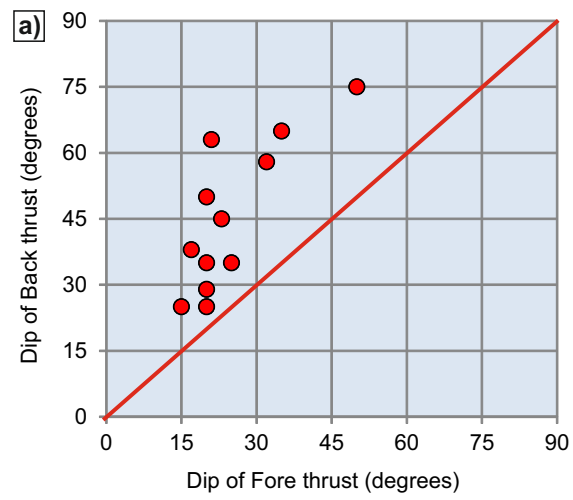


Figure 6

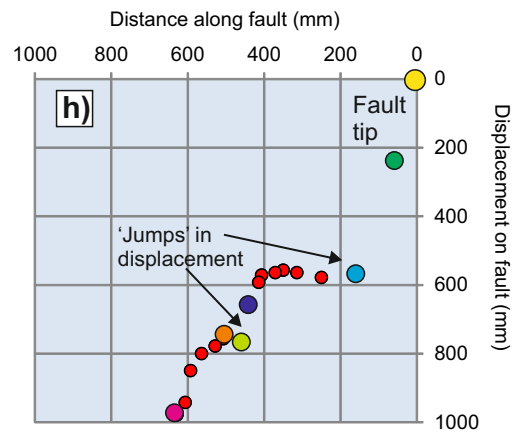
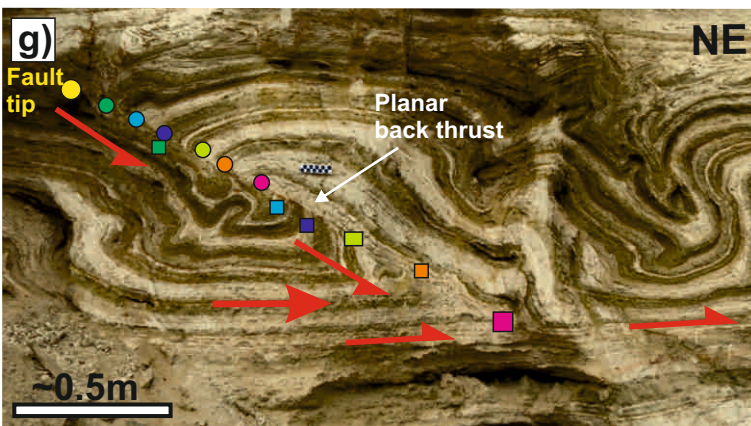
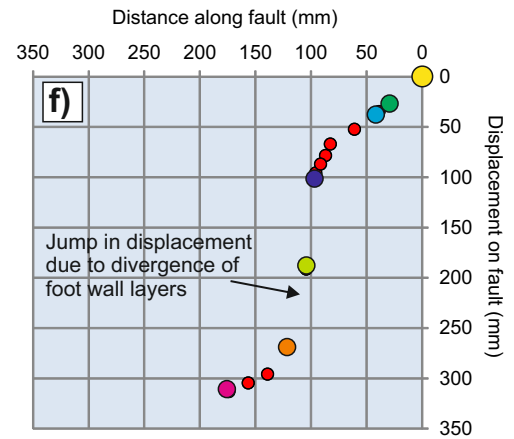
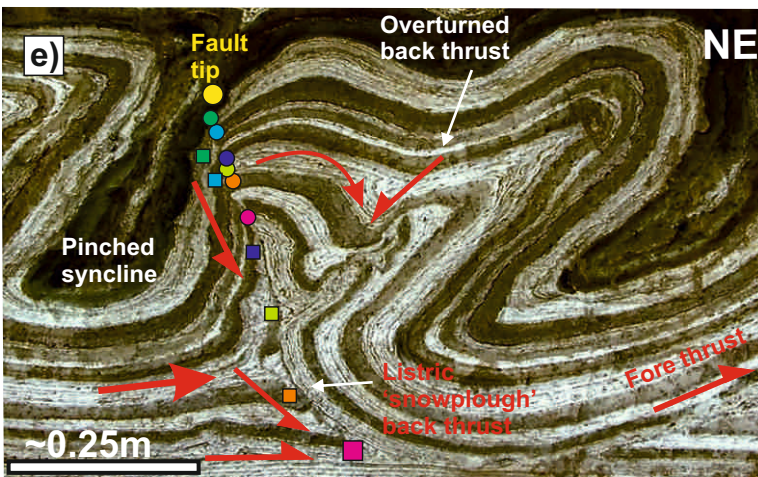
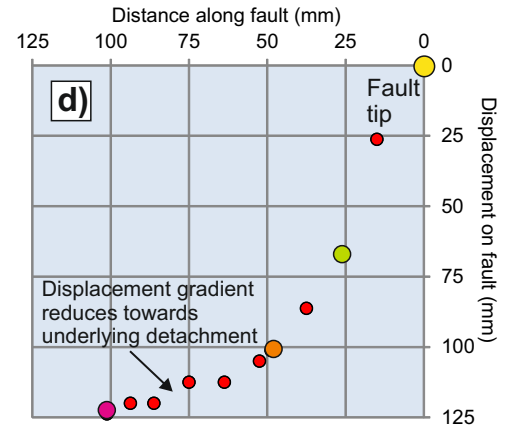
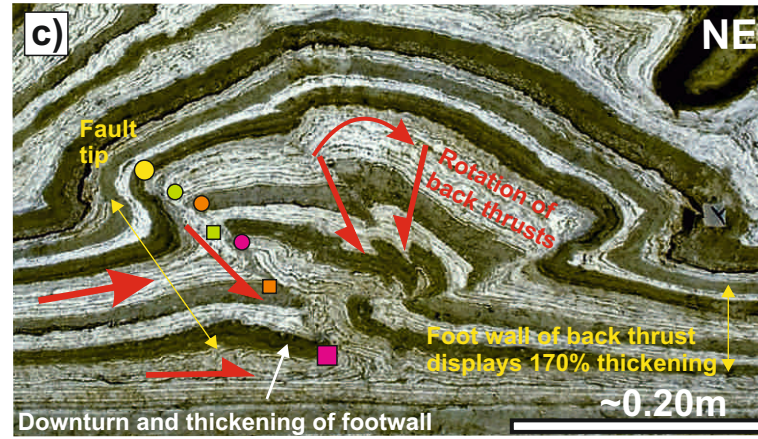
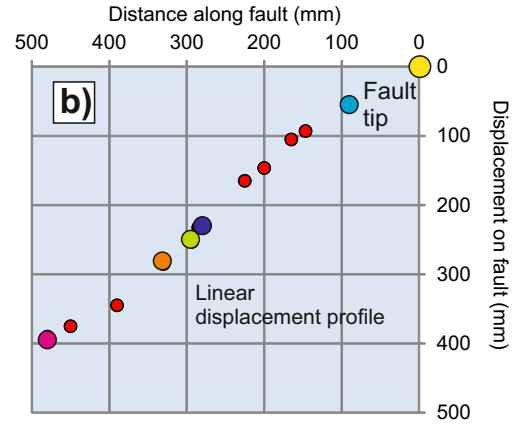
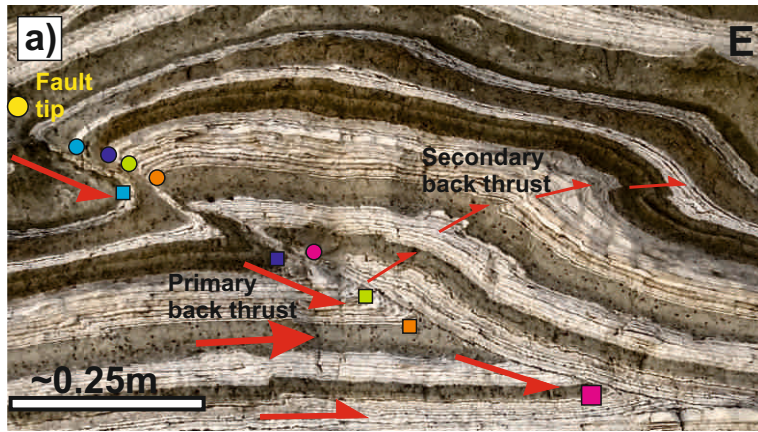


Figure 7

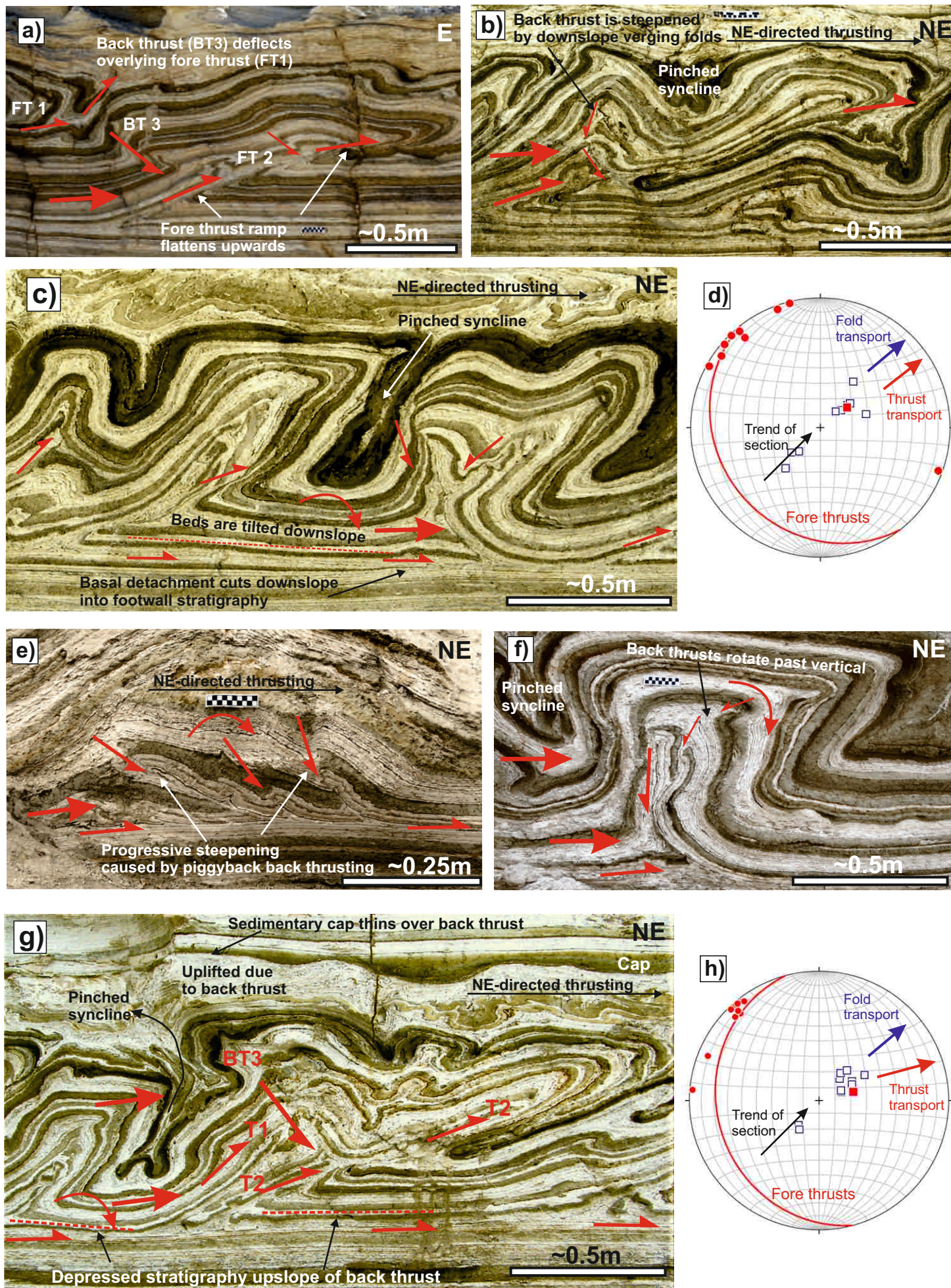


Figure 8

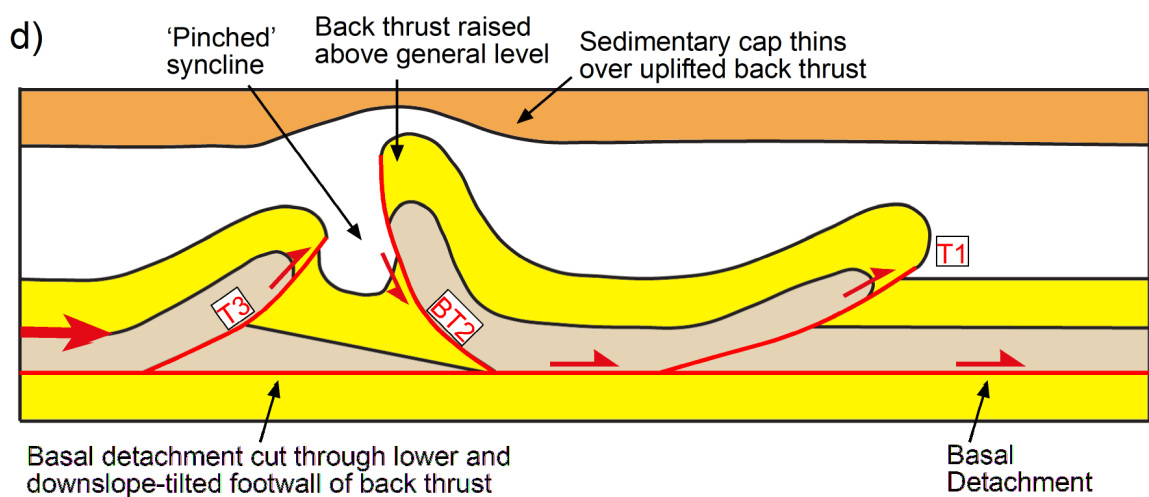
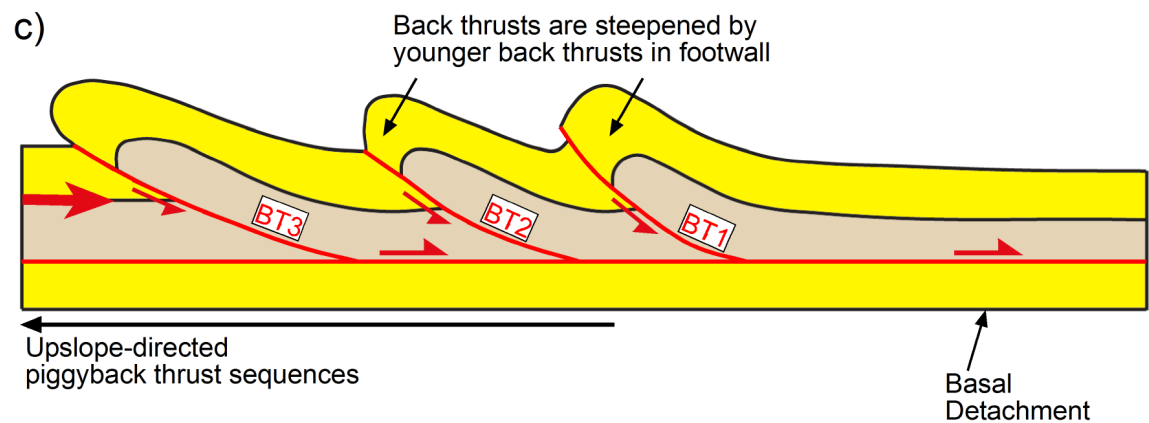
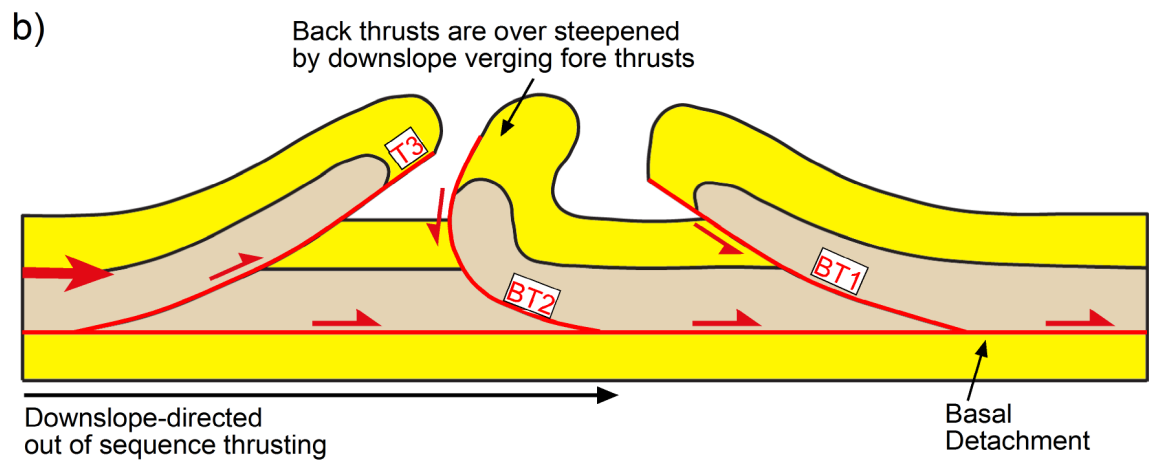
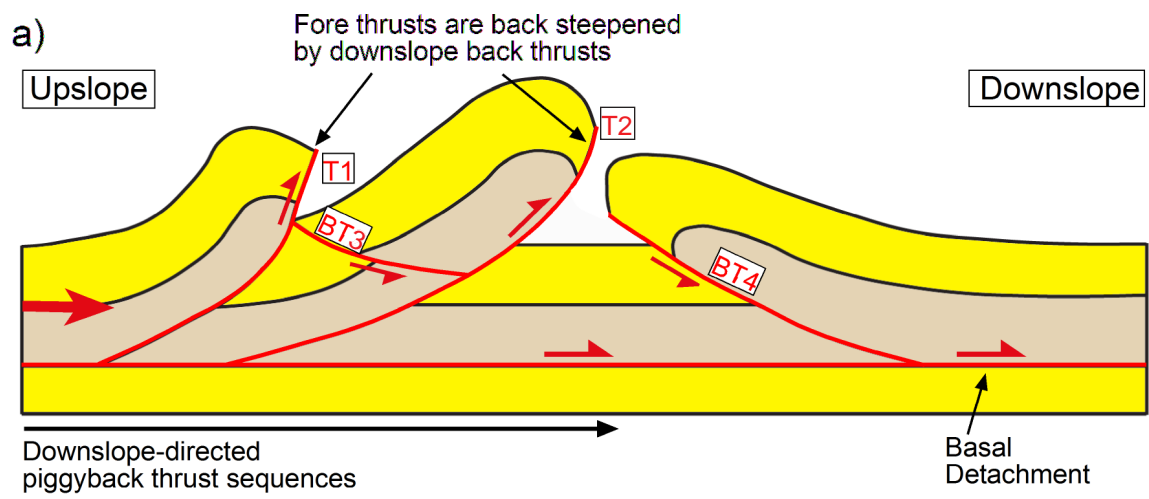


Figure 9

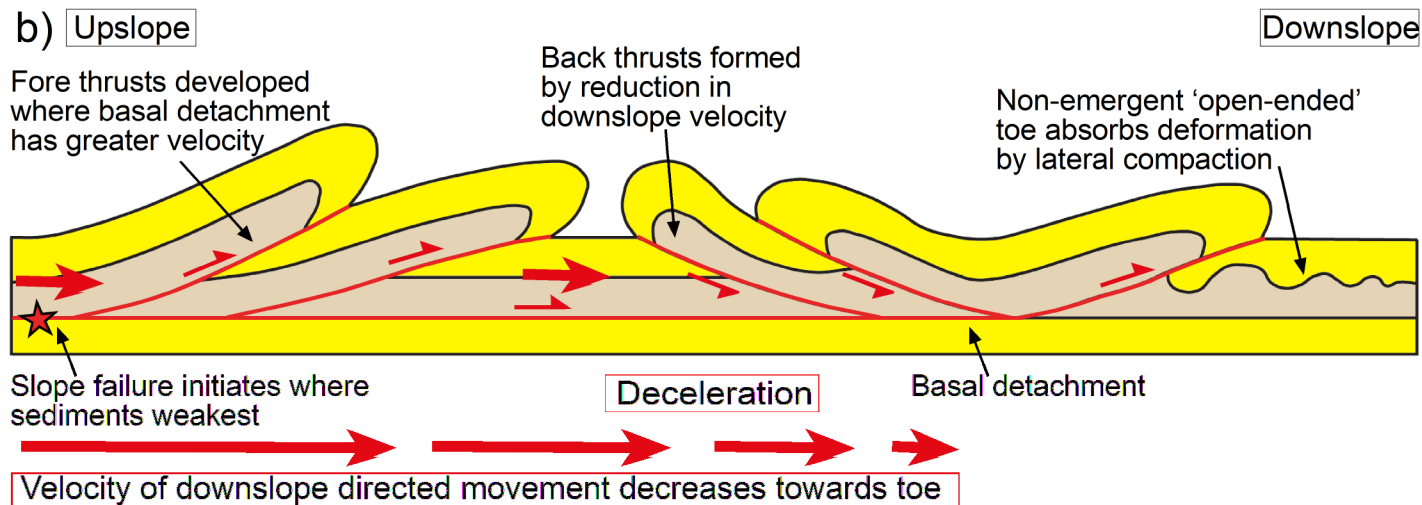
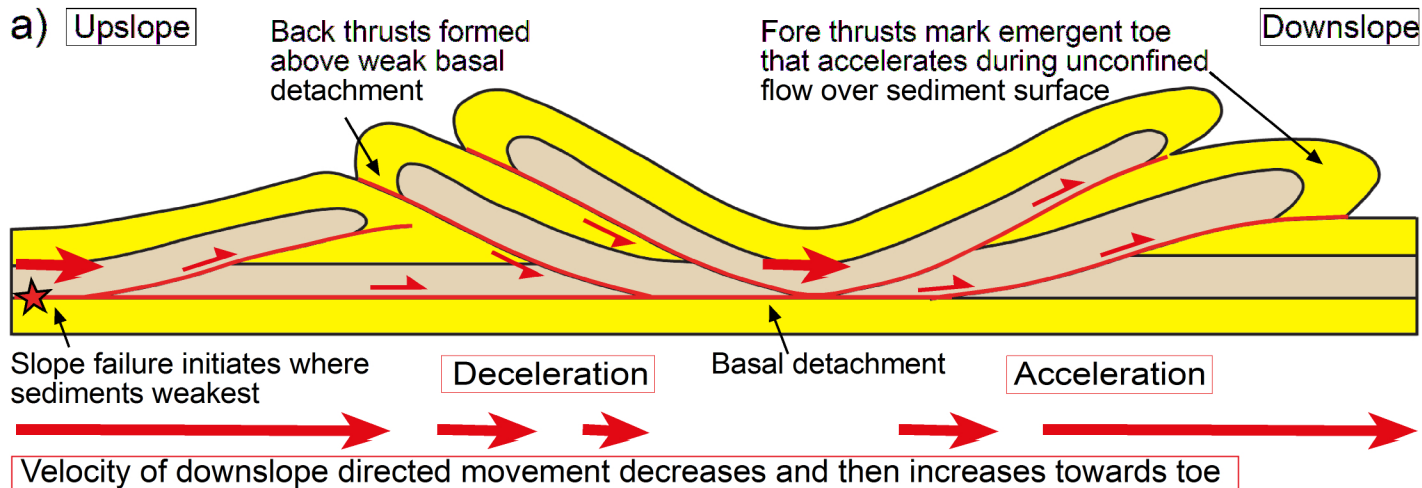


Figure 10

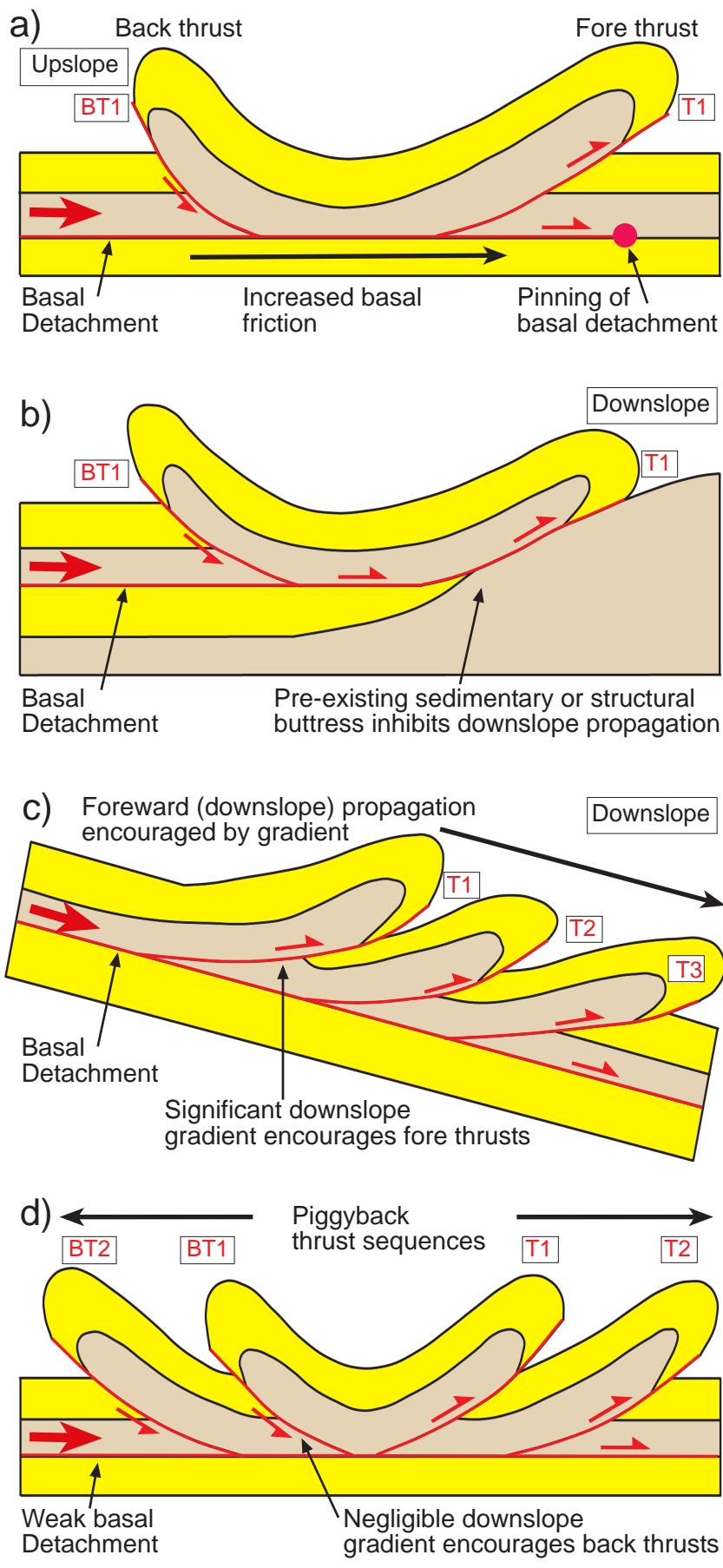


Figure 11

