# TEMPORAL REASONING AND TERMINATION OF PROGRAMS

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### **ABSTRACT**

This paper deals with the relationship between the termination of programs and the validity of certain modal formulas. We give a complete proof procedure for theses formulas, which will allow to bring the correctness of these programs back to a problem of automated deduction in modal logic.

Many modal logics of programs have been developped during these last years [PR, HKP, M2]. Particular attention has been paid to their ability to express many properties of programs [HKP, M2].

This paper is concerned with the relationship of termination problem for regular programs to the validity of certain formulas in modal logic.

For these formulas we present a proof procedure, very close to the resolution procedure for first-order predicate, calculus. We will use this procedure to prove the termination of programs. As in Lucid [AW] we can consider the set of modal formulas with the proof procedure as a programming language. This way of doing things permits direct reasoning about programs, from their direct manipulation, rather than indirectly via another language.

### Preliminaries

We shall consider as in [M2] the modal system S4, for reasoning about programs.

For our formalization of quantificational S4, we start with denumerably infinite lists of individual variables x1, X2, X3, ..., n-adic function symbols fn, gn, hn,..., and n-adic predicate symbols pn, qn, rn,—

Atomic formulas as well as negations of atomic formulas are called literals. We adopt the prime symbols & (conjunction), ^ (negation) L (necessity) and (xi) (universal quantification). We use the usual notions of terms and well-formel formulas. Let A, B, C, ... be arbitrary formulas. For each A, MA is defined as usual as ^L A. The axiomatization of quantificational S4 is obtained by

adding to a habitual formalization of lower predicate calculus (LPC) the following axiom schemes and the following rule of inference :

- .  $L(A \rightarrow B)$ .  $\rightarrow .LA \rightarrow LB$
- .  $LA \rightarrow A$
- . LA + LLA
- .  $(x)LA \rightarrow L(x)A$
- . A / LA

Following the example of Kripke, we define a quantificational S4 modal structure as an ordered triple (G, K, R), where K is a set, R is a relation on K and G is a distinguished element of K, together with a function Y wich assigns to each H a set y'(H), called domain in H. We shall further specify that all domaines are identical. The interpretation T of A at H is defined as in LPC by induction on the number of logical symbols in A. And F(LB,H)=t iff T(B,H')=t for every HEK such HRH\ otherwise T(LB,H)=f.

A sentece A is said to be true in a model U associated with a modal structure (G,K,R) if r(A,G)=t; it is said to be false in that model if T(A,G)=f. A is said to be valid iff it is true in all its models (for every modal structure), and unsatisfiable iff it is false in all its models.

A set of formulas is said to be consistent if there is no finite subset such that the disjunction of negations of its elements in a theorem.

## II. Programs and modalities

2.1. Assume that a program is represented by a directed graph whose nodes are the labels of this program and whose arcs represent transitions between labels. In the graphs there is only a start node (Is) and a terminal node (It) [MI]. For an arc (1|, I2) the transition has the general form as follows:

$$c_{(1_1,1_2)}(x,y) \rightarrow (z:=f_{(1_1,1_2)}(x,y)$$
 $c_{(1_1,1_2)}(x,y) \rightarrow c_{(2:=f_{(1_1,1_2)}(x,y))}$ 

where x = (x, ..., x) is the input variables,

 $\overline{y} = (y_1, \dots, y_m)$  is the program variables and  $\overline{z} = (z_1, \dots, z_h)$  is the output variables.  $C_{(1_{1}, 1_{2})}(\overline{x}, \overline{y})$  is a condition under which the assignment  $\overline{z} := f_{(1_{1}, 1_{2})}(\overline{x}, \overline{y})$  is realized. We assumed

that each note  $\mathbf{l}_i$ , one and only one of the condition, corresponding to the arcs leaving  $\mathbf{l}_i$ , is true.

Since modal logic, like classical logic [M], does not provide a direct tool for speaking about programs, such as the logics of programs [HO, S, PR], we must associate to each arc of the graph a modal formula:

where  $\operatorname{at}(1_i)$  is a proposition corresponding to the label  $1_i$ . This formula is relative to the forward assignment.

2.2. If P is a program and  $F_{\rm p}$  the set of modal formulas associated to the graph of P, then  $F_{\rm p}$  is satisfiable.

This is true since the set of formulas of  $F_P$  with the general form M(at(1) & p) is consistent [HC].

2.3. A program P is said to be totally correct with respect to the specification (p,q) if for every input  $\overline{x}_0$ , satisfying  $p(\overline{x}_0)$ , the computation of P terminates and the final values ( $\overline{z}_0$ ), upon termination, satisfy  $q(\overline{z}_0)$ . This property is expressed by the formula (noted by  $F_{TC}$ ):

$$(at(1_g) \& p(x_o)) \rightarrow M(at(1_t) \& q(\overline{z}_o))$$

In general, in order to verify this property, we need the following informations:

. the formulas describing the execution of program  $\mathbf{P}_\bullet$ 

. the formulas (noted by  $F_{\rm R})$  concerning conditions, assignments and inputs (frame axioms in [M2]) are as follows :

$$L(x > 0)$$

$$L(x = 0) v M(x \neq 0)$$

Then we can consider these formulas that express the material properties, (depending on the labels) and formal properties not depending on the labels).

2.4. Let P be a program. P terminate iff  $F_P \ \& \ F_R \ \& \ {}^F_{TC}$  is unsatisfiable.

The proof can be obtained by a similar reasoning to [MI].

## III. Deduction

3.1. We will now give a deduction method for the formulas of quantificational S4, whose variables in the scope of the modal operators are free (noted by  $S4^+$ ).

We consider the formulas in the Skolem normal form :

$$(x_1), \dots, (x_n) \quad (A_1 \ \delta \dots \ \delta \ A_m)$$

- where each  $(x_i)$  is an universal quantifier (the existential quantifiers have been eliminated by Skolem functions in the usual way [RS]) and:

- n ≥ 0

- each  $A_i$   $1 \le i \le m$  (clause in the classical terminology [R]) is a disjunction of the form :

- where each  $P_i$  1  $\leqslant$  i  $\leqslant$  k" is a literal, each  $F_i$  1  $\leqslant$  i  $\leqslant$  k' is a conjunction of terms possessing the general form of the clauses, and each  $D_i$  1  $\leqslant$  i  $\leqslant$  k is a disjunction that possesses the general form of the clauses.

3.2. There is an effective procedure, for constructing, for any given formula of \$4<sup>+</sup>, an equivalent formula in Skolem normal form.

3.3. Let  $E = \{E_1, \ldots, E_n\}$  1  $\in$  n < w, be a finite set of expressions. A substitution  $\sigma$  is called a unifier of the set E if  $E_i\sigma = E_j\sigma$  for  $i,j \in \{1,\ldots,n\}$ . A unifier  $\sigma$  is called the most general unifier if for any unifier  $\sigma'$  of E there is a substitution  $\sigma''$  such that  $\sigma' = \sigma$ .  $\sigma''$   $\{R\}$ .

3.4. We consider the set of rules  $\Sigma_i$  i=1,. # and  $\Gamma_i$  i=1,2 defined recursively as follows:

1. Elementary rule :

$$\Sigma_{i}[(D_{1},D_{2}) ; F] = (\Sigma_{i}[D_{1} ; F] . D_{2})$$
provided . is v or &

2. Extending rules :

 $\Sigma_2[LD$  ;  $\Delta F]$  =  $\Delta(\Sigma_i[D$  ; F]) provided  $\Delta$  is L, M or the empty symbol

 $\Gamma_{1}[A\{M(D \& F)\}] = A\{M(\Sigma_{1}[D ; F])\}$   $A\{M(D \& F)\} \text{ means that } M(D \& F) \text{ is a subfor-}$ 

mula of A.3. Transforming rule :

$$\Sigma_3[LD ; F] = \Sigma_i[LLD ; F]$$

4. Classical rule :

$$\Sigma_4[p; \sim p] = \emptyset$$

5. Elimination of Ø:

$$\Gamma_{2}[\emptyset \& F] = \emptyset$$

$$\Gamma_{2}[\emptyset \lor D] = D$$

 $\Gamma_7 \wedge [\emptyset] = \emptyset$  provided  $\wedge$  is L or M.

Let  $A_1$  and  $A_2$  be two clauses. We say that  $A_1$  and  $A_2$  are resolvable if  $\mathcal{E}_i\left[A_1:A_2\right]$  is defined (i.q. the classical rule is used).

Let  $A_i$  be a clause. We say that  $A_i$  is resolvable if  $\Gamma_i \left\{ A_i \right\}$  is defined.

The remaining term obtains from A<sub>1</sub> (A<sub>1</sub> and A<sub>2</sub>) after application of  $\Gamma_i$  and (or  $\Sigma_i$ ) is represented by  $\Gamma_1$  [A<sub>1</sub>] ( $\Sigma_i$  [A<sub>1</sub>]; A<sub>2</sub>])

3.5. Let A v  $A_1$  and A' v  $A_{-1}^1$  be two clauses with no variables in common. The inference rules

$$1. \qquad \frac{A \ v \ A_1 \ , \ A' \ v \ A_1'}{\sigma \Sigma_1 \left[A_1 A' \right] \ v \ \sigma A_1 \ v \ \sigma A_1'}$$

2. 
$$\frac{A \vee A_1 \vee A_2}{\sigma \Sigma_i [A] \vee \sigma A_1}$$

will be applied if A and A' (or A) are (is) resolvable. Where  $\sigma$  is the most general unifier used in the classical rule.

3.6. Let A v A<sub>1</sub> v A<sub>2</sub> be a clause.

The inference rule:

3. 
$$\frac{\mathbf{A} \mathbf{v} \mathbf{A}_1 \mathbf{v} \mathbf{A}_2}{\mathbf{A} \mathbf{\sigma} \mathbf{v} \mathbf{A}_1 \mathbf{\sigma}}$$

will be applied if  $\boldsymbol{A}_1$  and  $\boldsymbol{A}_2$  have most general unifier  $\sigma.$ 

3.4. Let S be a finite set of clauses, a deduction of A from S is a finite sequence of clauses  $A_1,\ldots,A_n$ , such that :

 $-A_i$  1  $i \le n$  is

. an element of S, or

. a factor (rule 3) of A;, j < i, or

. a resolvent (rules 1 and 2) of  $A_j$  and  $A_k$  or j, k < i

3.5. A set S of clauses is unsatisfiable iff there is a deduction of the empty clause from S.

The proof can be obtained as in [F] or [0].

### IV. Example

Consider the program P (fig.4) over the integers, that adds an integer  $\mathbf{x}_1$  to a natural num-

ber x2.

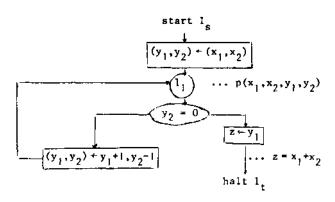


Fig. 1

The clauses as set out in 3, corresponding to this program are of the form :

1. 
$$L((\Delta at(l_s) \lor \Delta p(x_1, x_2, x_1, x_2)))$$
  
  $\lor M(at(l_1) \& p(x_1, x_2, y_1, y_2)))$ 

2. 
$$L((\text{Mat}(1_1) \text{ v } \text{My}_2>0 \text{ v } \text{Mp}(x_1, x_2, y_1+1, y_2-1))$$
  
v  $M(\text{at}(1_1) \text{ & } p(x_1, x_2, y_1, y_2)))$ 

3. 
$$L((\triangle at(1_1) \vee \triangle y_2=0 \vee \triangle p(x_1,x_2,y_1,y_2)) \vee M(at(1_1) \& p(x_1,x_2,y_1,0)))$$

where  $p(x_1, x_2, y_1, y_2)$  is the assertion  $x_1 + x_2 = y_1 + y_2$ . Using the induction formula:

4.  $M(at(1_1) \& p(x_1, x_2, y_1, 0) \& L(\triangle at(1_t) \\ v^*p(x_1, x_2, y_1, 0)) v M((\triangle at(1_1) v \triangle p(x_1, x_2, y_1, y_2)) \\ \& y_2 > 0 \& p(x_1, x_2, x_1 + 1, y_2 - 1)) v L(\triangle at(1_1) v \\ \triangle p(x_1, x_2, y_1, y_2) v M(at(1_t) \& p(x_1, x_2, y_1, 0))$ 

And the frame clauses :

5. 
$$M(x \neq 0) v L(x = 0)$$

6. 
$$L(\sim 0 \neq 0)$$

The program considered will be totally correct if this set of clauses with the following formula:

7. 
$$\gamma((\gamma_{at}(1_s) \vee \gamma_{p}(x_1, x_2, x_1, x_2)) \vee M(at(1_t) & p(x_1, x_2, y_1, 0)))$$

is unsatisfiable.

Using the method given in 3, we obtain many steps, but here we will give the alternate steps as follows:

8.  $MM(at(1_t) & p(x_1, x_2, y_1, 0) & L(\triangle t(1_t) ) v$   $p(x_1, x_2, y_1, 0))) v M((at(1_1) ) v \triangle p(x_1, x_2, y_1, y_2))$   $& at(1_1) & y_2 > 0 & p(x_1, x_2, x_1 + 1, y_2 - 1)) v$   $L(\triangle t(1_1) & v \triangle p(x_1, x_2, y_1, y_2) & v M(at(1_t) & p(x_1, x_2, y_1, y_2))$ 

from 4.,3, 5 and 6.

- 9.  $M((\triangle at(1_1) \lor \triangle p(x_1,x_2,y_1,y_2)) \& at(1_1) \& y_2>0 \& p(x_1,x_2,x_1+1,y_2-1)) \lor L(\triangle at(1_1) \lor \triangle p(x_1,x_2,y_1,y_2) \lor M(at(1_t) \& p(x_1,x_2,y_1,0))$  from 8.
- 10.  $MM(\text{vat}(1_1) \text{ v } y_2>0 \text{ v } \text{vp}(x_1,x_2,y_1+1,y_2-1) \text{ 8}$   $at(1_1) \text{ 8 } y_2>0 \text{ & } p(x_1,x_2,x_1+1,y_2-1)) \text{ v}$   $L(\text{vat}(1_1) \text{ v } \text{vp}(x_1,x_2,y_1,y_2) \text{ v } M(\text{at}(1_t) \text{ & } p(x_1,x_2,y_1,0))$  from 9. and 2.
- 11.  $^{\circ}(at(1_s) \text{ v } ^{\circ}p(x_1, x_2, y_1, y_2)$ from 10., 7. and 1.

And from II. and at( $l_s$ ) &  $p(x_1, x_2, y_1, y_2)$  we obtain the empty clause.

This proof is very close to the Lucid (AW version of intermittent assertion proofs [MW].

The different rules (concatenation, consequence...) can be obtained by putting together several steps of our method.

In general, we can consider the set of modal formulas with the proof procedure as a programming language, that permits direct reasoning about the programs, from their direct manipulation.

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