



Novel Real-time Calibration and Alignment Procedure for LHCb Run II

Claire Prouve, on behalf of the LHCb collaboration
University of Bristol

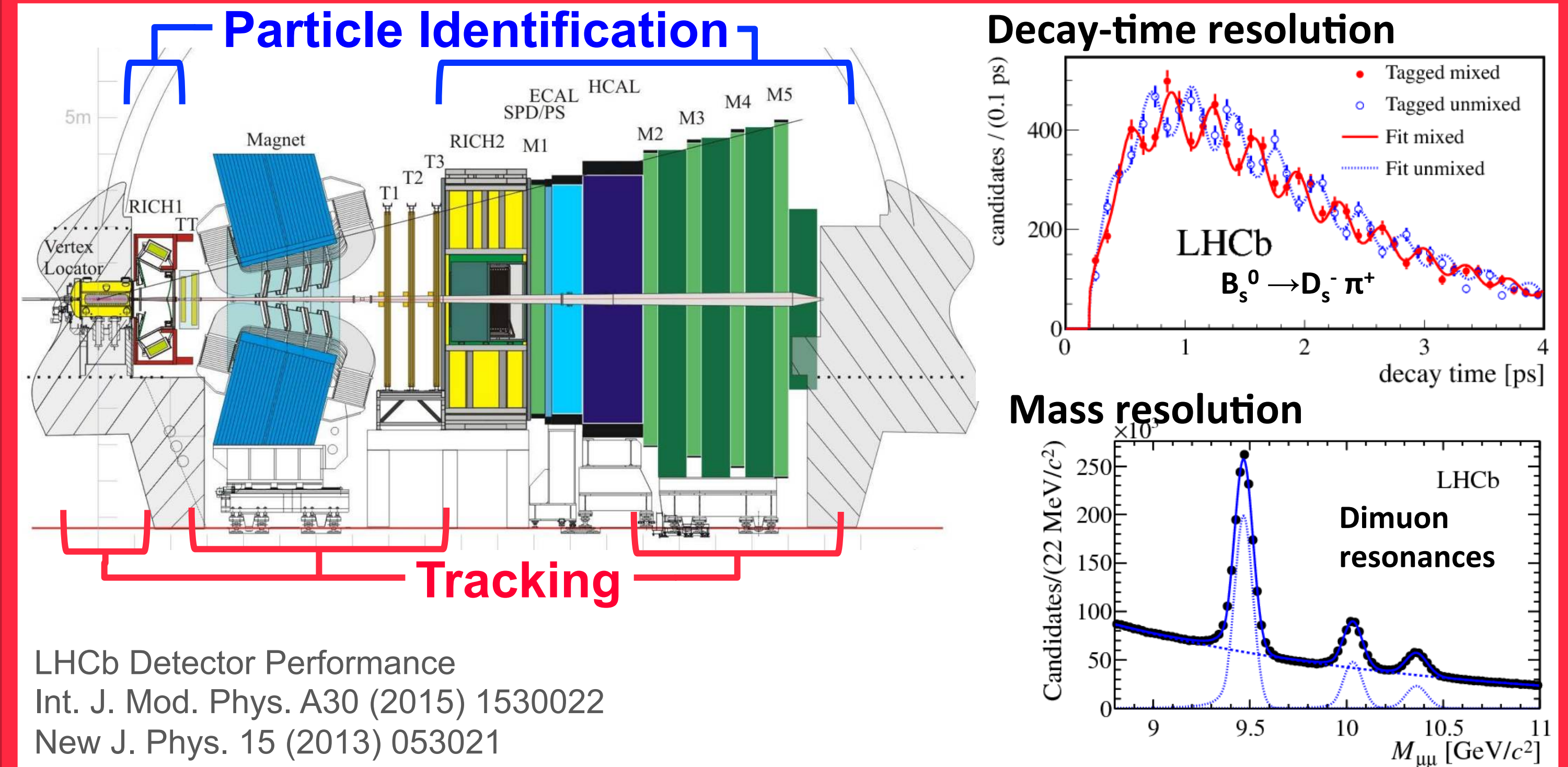
New challenges in Run II

- Increase in energy:
 $\sqrt{s} = 7(8) \text{ TeV} \Rightarrow 13 \text{ TeV}$
- 15% increase of inelastic collision rate
- 20% increase of multiplicity per collision
- 60% increase of $\sigma_{b\bar{b}}$ and $\sigma_{c\bar{c}}$
- Reduced bunch spacing:
 $50 \text{ ns} \Rightarrow 25 \text{ ns}$

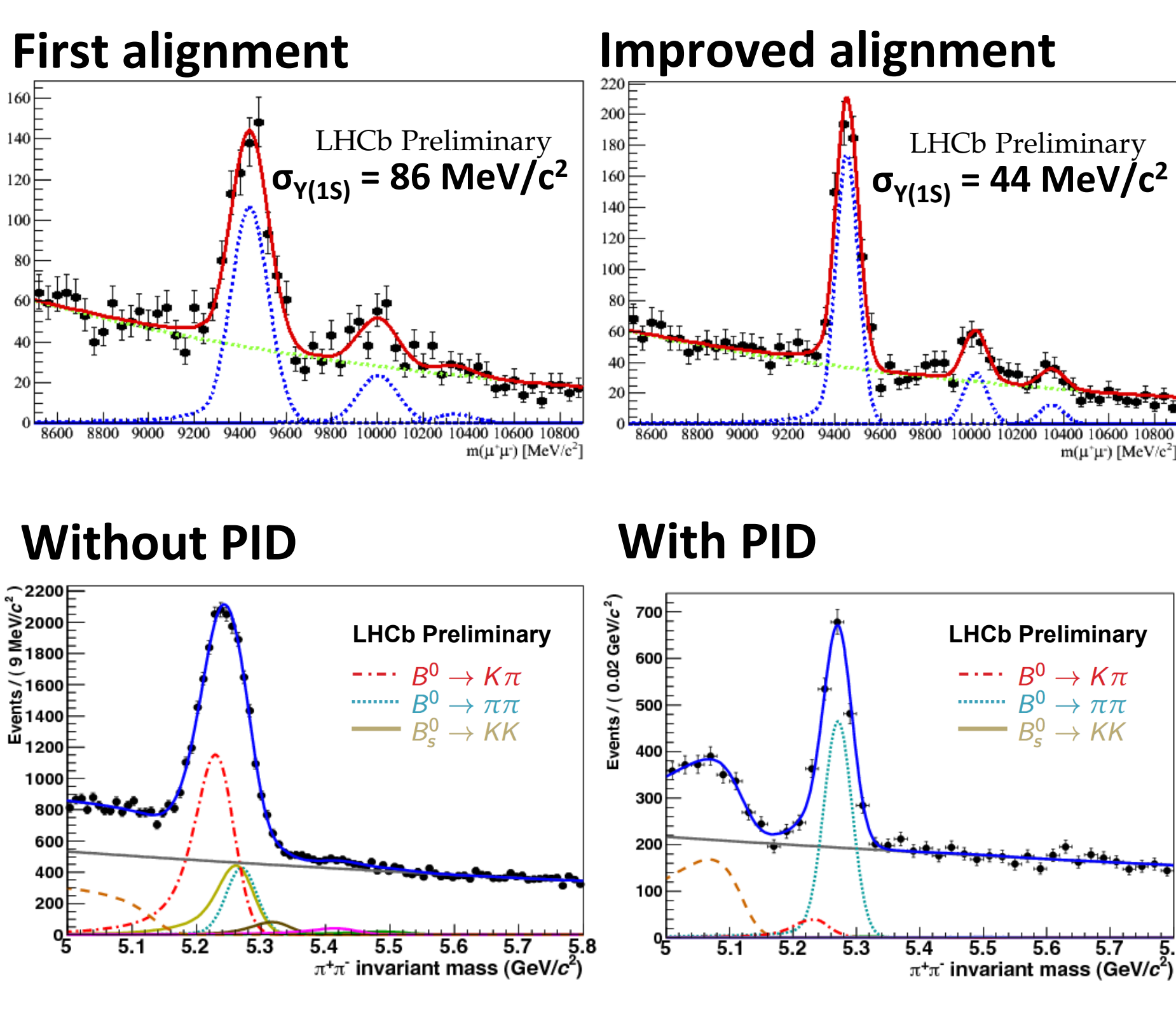
Real Time Alignment and Calibration

- Stable quality of alignment and calibration
- Particle identification useable in the high level trigger (HLT)
- Overall improved trigger efficiency
- No more differences between online and offline
- Physics analysis directly on trigger output (Turbo Stream)

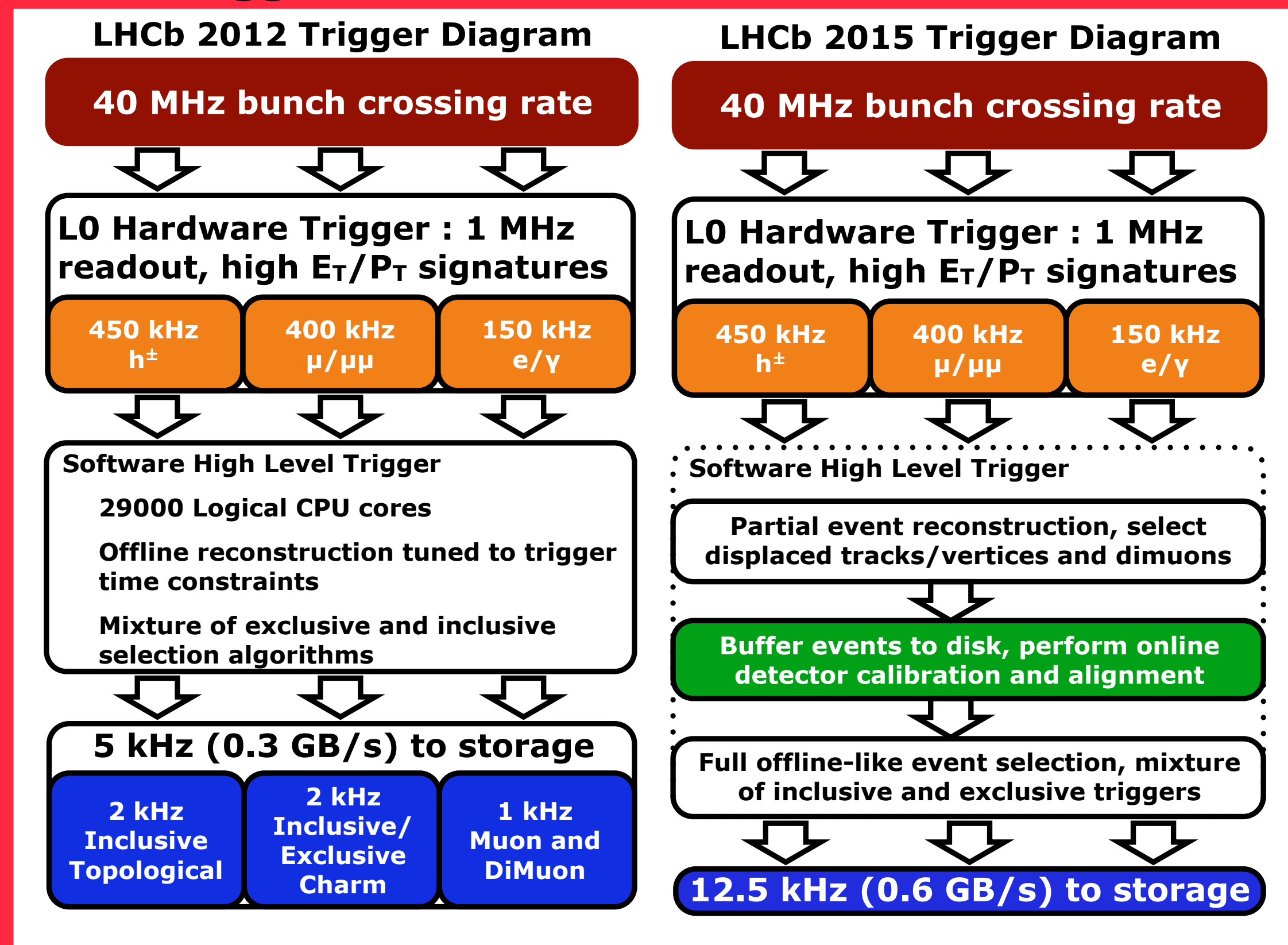
Performance of the LHCb Detector



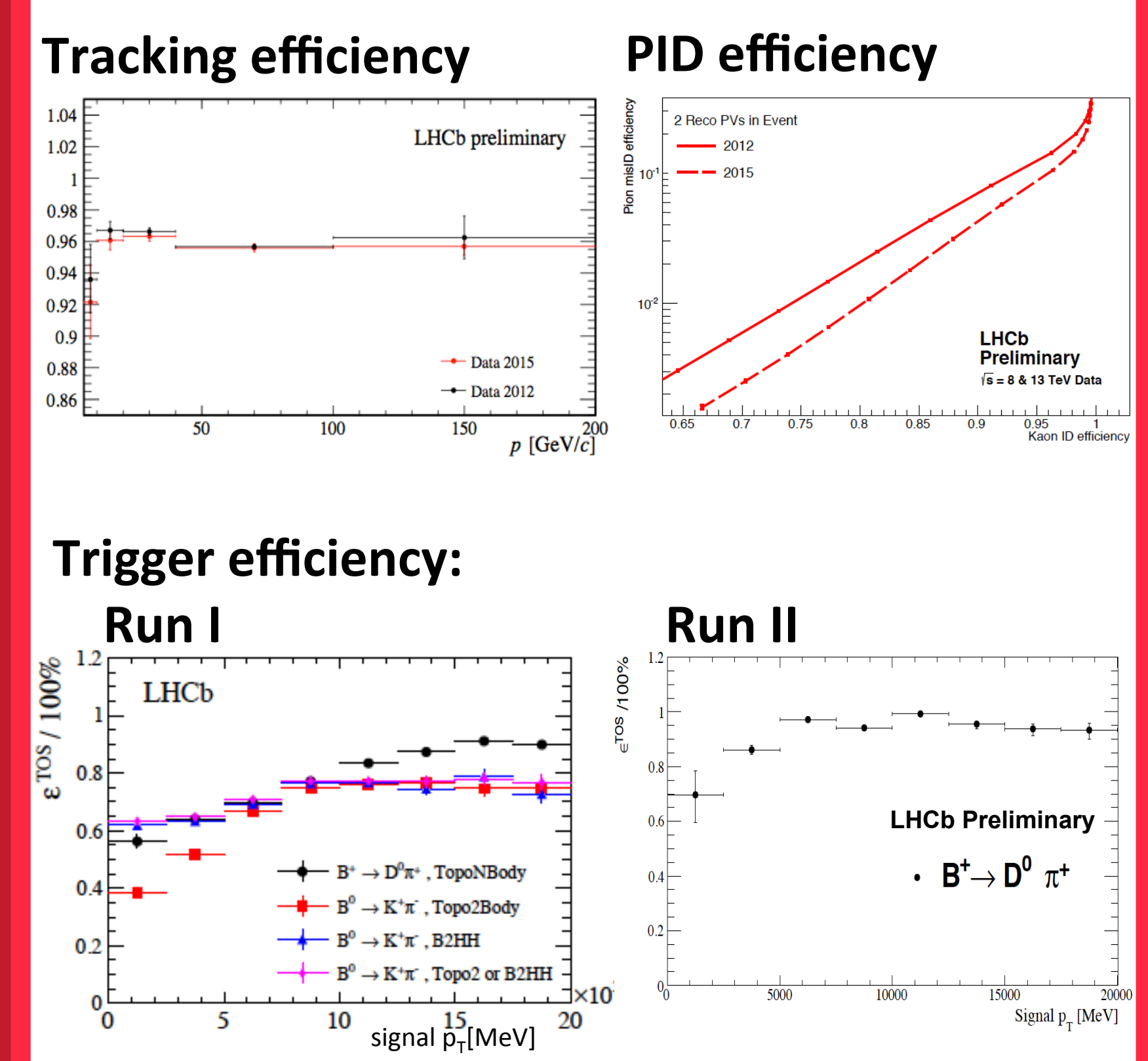
Impact on Physics



LHCb Trigger Schemes



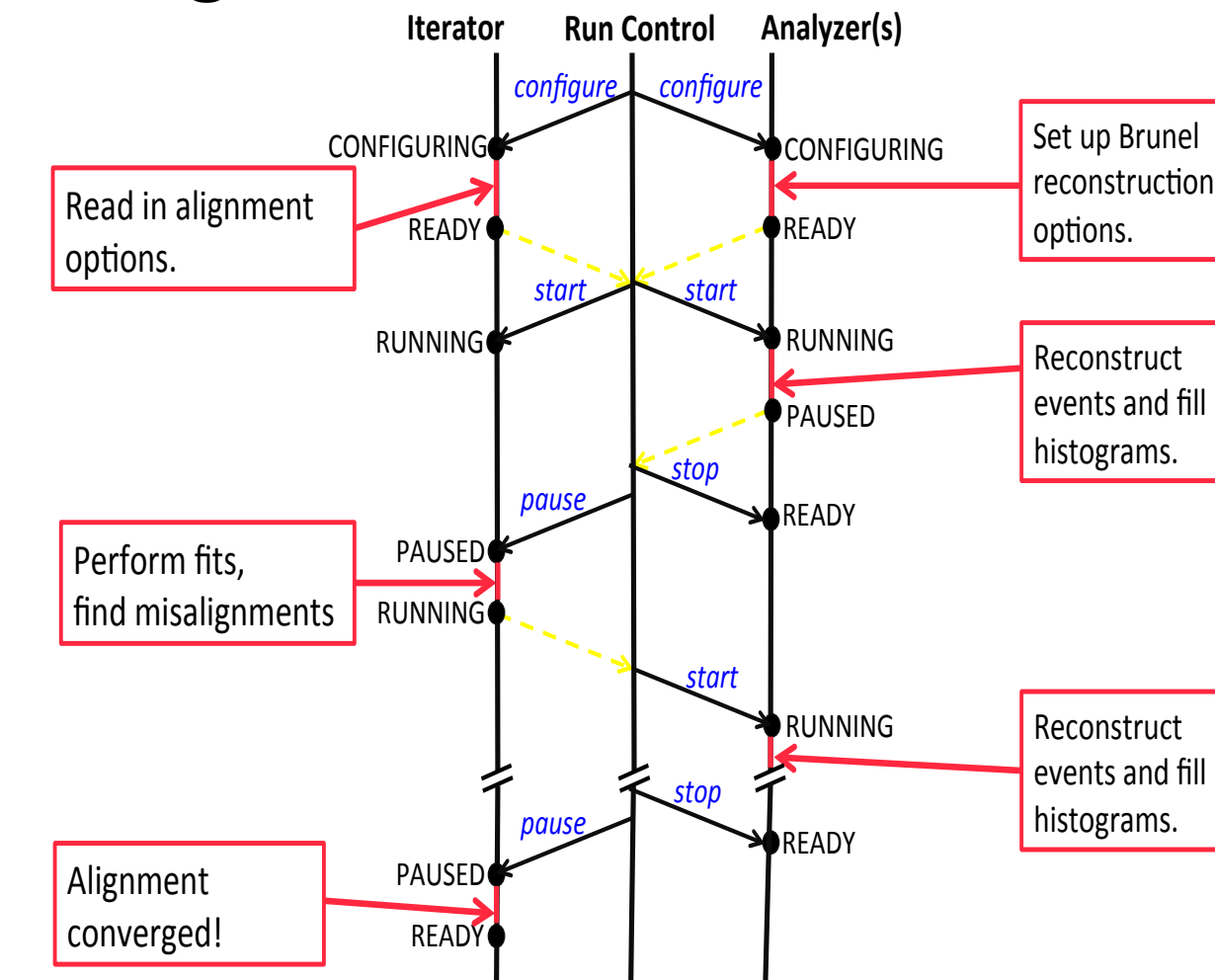
Performance in Run II



Dedicated Framework and Procedure

- Alignments performed for each fill
- Dedicated trigger line for each task
- Event reconstruction parallelised on *analysers* (1700 nodes), computing of alignment constants by *iterator* (1 node)
- Calibrations on monitoring histograms
- VELO, Tracker & calibrations: automatic update of the constants if they differ by a given value
- RICH alignment & Muon alignment: monitoring mode

Example of alignment sequence using a Finite State Machine

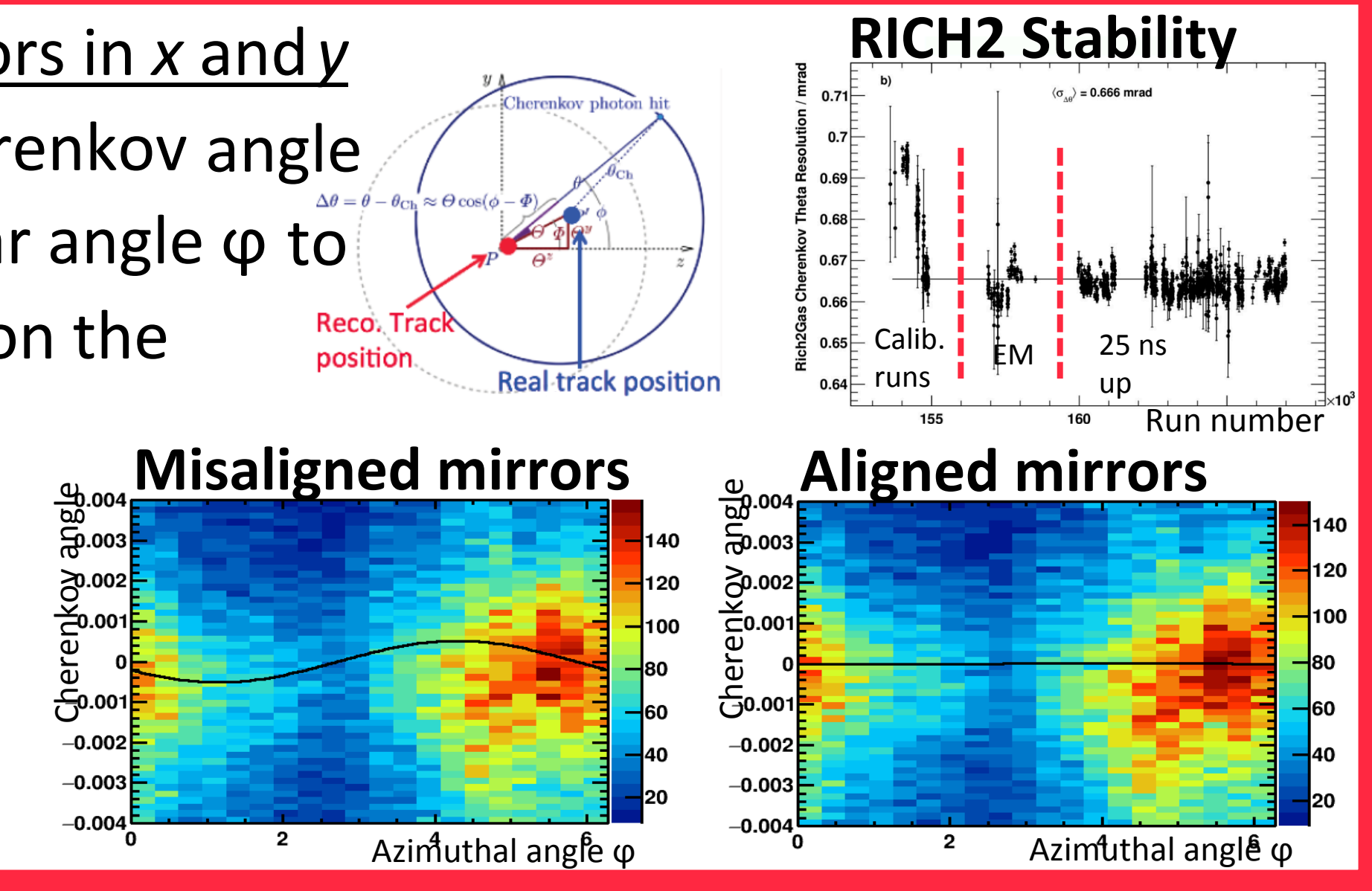


RICH Mirror Alignment

Orientation of the RICH mirrors in x and y

- Fit the variation of the Cherenkov angle $\Delta\theta$ as a function of the polar angle φ to extract the misalignments on the detector plane (Θ_x, Θ_y)
$$\Delta\theta = \Theta_x \sin\varphi + \Theta_y \cos\varphi$$

- Updated $O(10)$ per year
- ~ 30 minutes per task

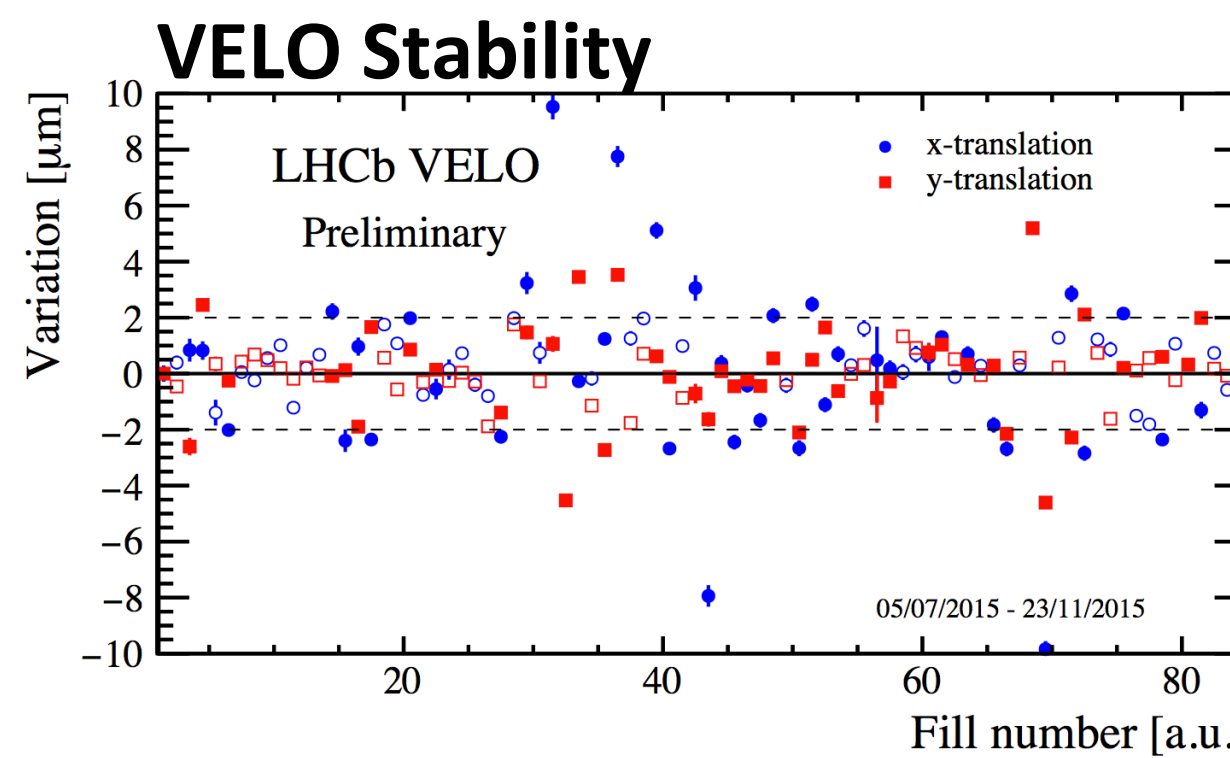


Tracker Alignment: VELO, Tracker, Muon System

Position and orientation of the full tracking system (700 elements)

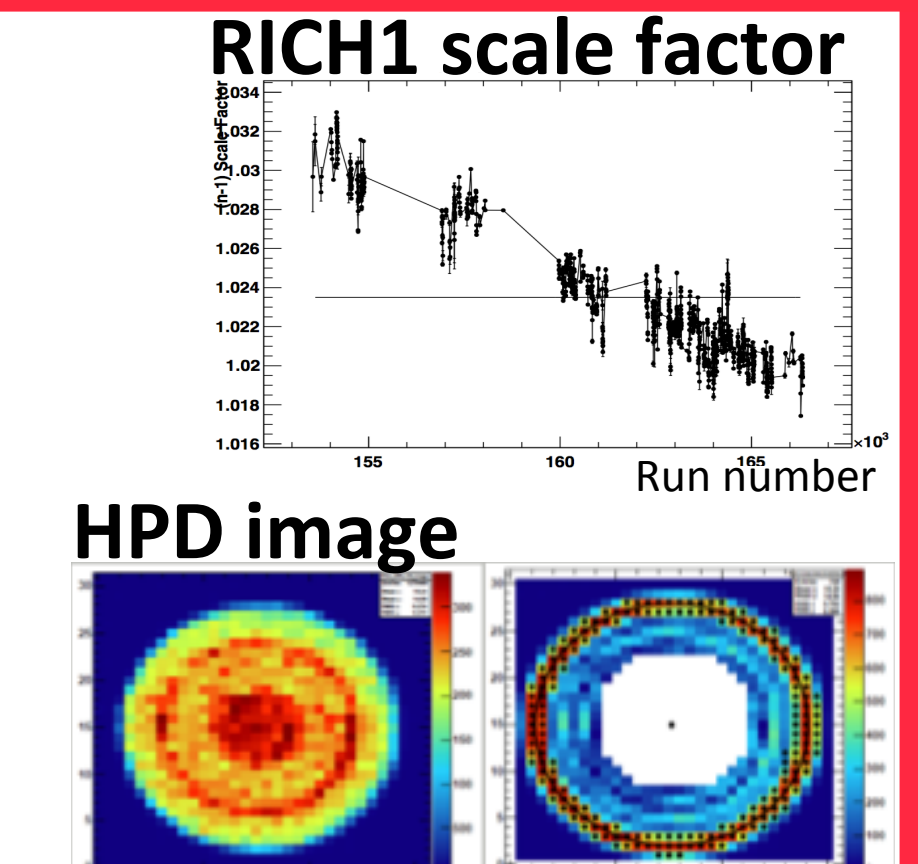
Minimisation of residual of Kalman track fit using additional constraints

- Independent alignments:
- VELO: updated every $O(1)$ fills
- Tracker: updated every $O(1)$ weeks
- Muon: updated $O(1)$ per year
- ~ 7 minutes per task



RICH Calibration

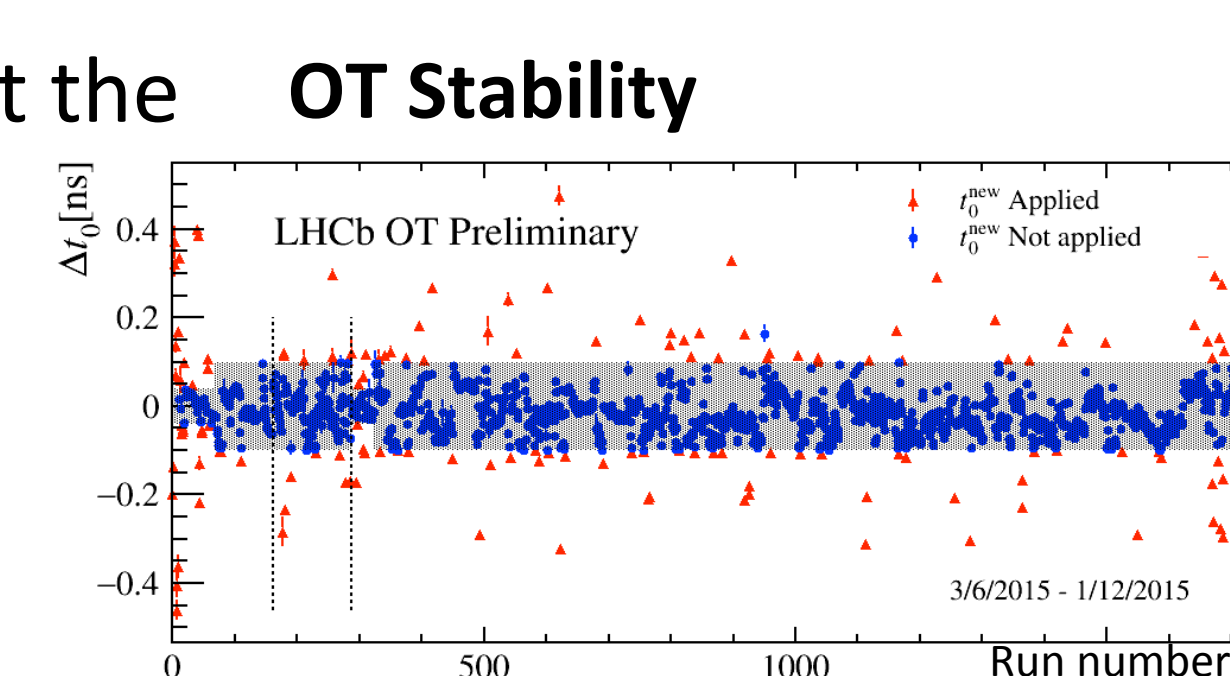
- Refractive index calibration: Fit to the reconstructed-expected Cherenkov angle yields scale factor for the refractive index
- HPD image calibration: Sobel filter applied to each HPD and used to provide calibration
- Updated every run



Outer Tracker Calibration

Global time alignment for all modules

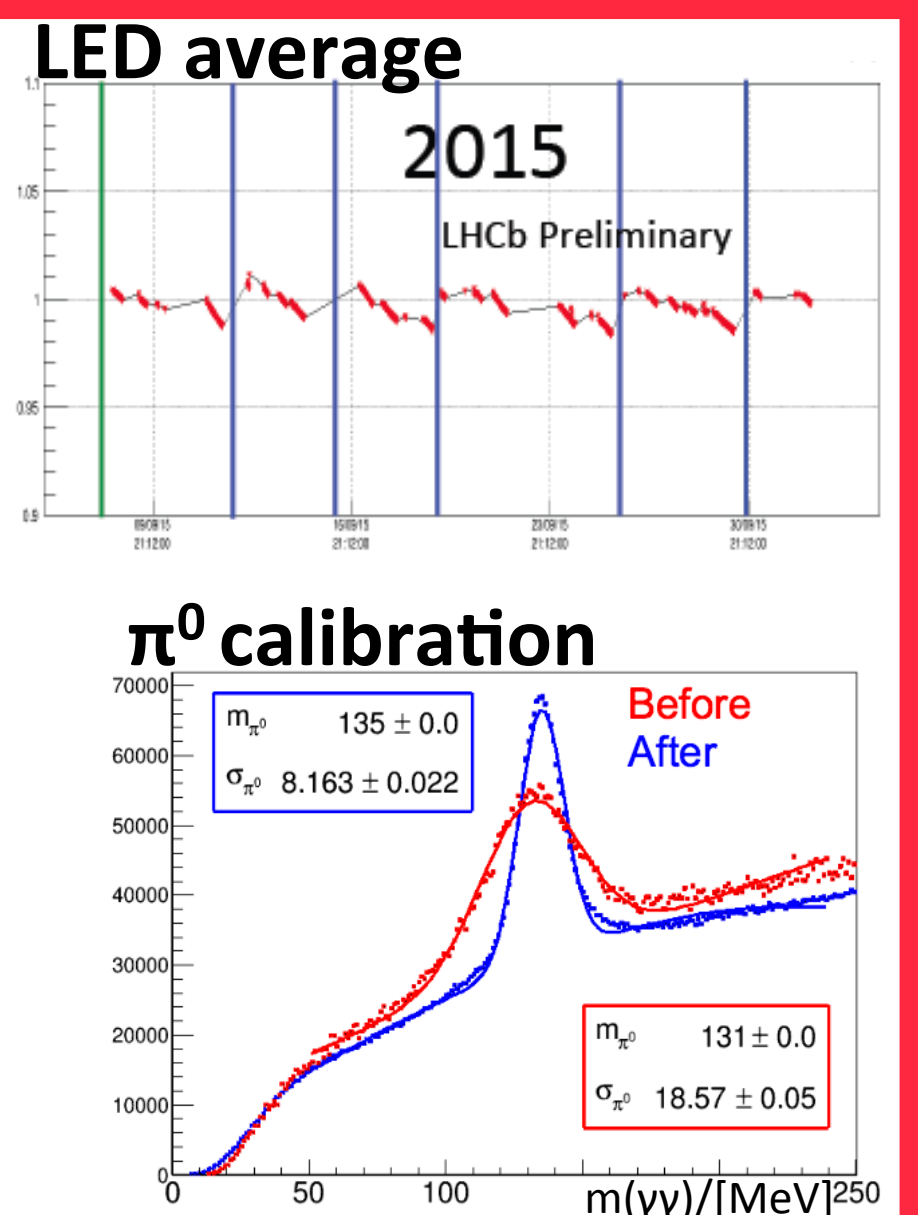
- Fit the residual of the drift time to extract the global time delay t_0 caused by readout electronics $t_{\text{meas}} = t_0 + t_{\text{flight}} + t_{\text{drift}} + t_{\text{prop}}$
- Updated every $O(10)$ runs



Calorimeter Calibration

Relative calibration for each cell

- Occupancy method and LED monitoring system: adjustment of high voltage settings to compensate for the aging of the detector
- Updated per fill



Calibrate to the neutral π mass

- Fit the π^0 mass distribution for each cell for $\pi^0 \rightarrow \gamma\gamma$
- Run on the HLT-farm during TS