



Distribution planning of relief commodities considering the features of demand areas: A robust multi-objective approach

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Abstract. Logistics planning plays an important role in providing services to disaster-stricken areas. In this study, a scenario-based multi-objective model is presented to locate distribution and evacuation centers and distribute relief commodities with appropriate allocation. It aims to serve the earthquake-stricken areas that are classified according to their construction qualities. The objective functions of cost, responsiveness, and demand coverage are considered in the proposed optimization model. Moreover, due to the uncertain nature of a disaster and uncertainty in some parameters of the model, a robust optimization approach is utilized. A revised multi-choice goal programming method is applied to solve the multi-objective model. The proposed model is validated through a case study conducted in the city of Amol. The computational results show the efficiency of the proposed model in a real-world disaster situation.

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1. Introduction

Natural disasters, such as earthquake, flood, and drought, harm thousands of people every year and damage residential areas and assets [1]. Over the last century, due to the human intervention in nature as well as deliberate cutting and burning of plants in forests or woodlands to create fields, natural disasters have occurred more frequently [2]. In recent years, many natural disasters have stricken different places around the world, e.g., the devastating earthquake in Bam in 2003, a huge tsunami of the Indian Ocean in 2004, which affected fourteen counties, Pakistan floods in 2010, east Azerbaijan earthquakes in 2012, and

Pakistan earthquake in 2015. More specifically, during 2004 to 2013, the total number of reported disasters was approximately 6,525, and the total number of people killed was 1,059,072 [3].

Earthquake may be one of the most devastating natural disasters. Unfortunately, it often strikes a large area with several regions. It should be noted that direct mortality caused by the earthquake is relatively low. However, it may significantly increase due to lack of planning to serve the victims. In fact, the proper planning will lessen the damage of disasters; this is the ultimate purpose of “Disaster Management” defined as “all actions done by human beings to deal with disasters and their effects before, during, and after the disaster”. Researchers have proposed four phases for relief actions: mitigation, preparedness, response, and recovery. Preparedness and response phases are of special importance. Moreover, relief logistics as new knowledge helps humans deal with disasters in preparedness and response phases [4].

However, uncertain environment is one of the

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Figure 1. Evacuation Centers (ECs) and Distribution Centers (DCs).

most important features of the relief logistics problems. However, quickly responding to the victims in a situation with high uncertainty is very important. Thus, relief logistics planning coordinates the relief operations with delivery of the relief commodities to reduce the response time [5,6]. Moreover, locating an appropriate location (selecting among the existing ones) in different situations is one of the most important decisions in order to utilize optimally the facilities during a disaster. Response time and fatality rate may increase due to the lack of preparation and planning which may translate to failure in properly identifying Evacuation Centers (ECs) and Distribution Centers (DCs), insufficient supply, etc. Figure 1 illustrates an example of ECs and DCs.

Moreover, one of the decisions of logistics planning that plays a strategic role in managing disasters is locating the warehouses and storing commodities. It should be noted that location and the number of these centers depend on the characteristics of each region [5]. Therefore, affected areas can be clustered according to the strength of buildings in that region. This factor is of great importance in an earthquake disaster. Likewise, the issues that have received less attention include locating the ECs before the disaster. Introducing these places to people and planning for transportation of relief supplies from the DCs to the ECs during the disaster may improve the service quality to the victims.

Furthermore, determining the location and number of ECs and DCs is a significant decision that the authorities in the disaster management headquarters face. Generally, selecting appropriate locations for ECs and DCs has the following advantages for disaster control managers. It can improve the response time, minimize the intervention of the DCs to make efficient use of these centers, and appropriately assign the DCs to a region considering the setup and operating costs, responsiveness, and demand coverage under different scenarios [7].

In this study, a multi-objective optimization model for the supply and distribution of relief commodities for disaster-stricken regions under environmental uncertainty is presented. A robust model is proposed to cope with uncertainty, and a Revised Multi-Choice Goal Programming (RMCGP) method is utilized for solving the proposed multi-objective model.

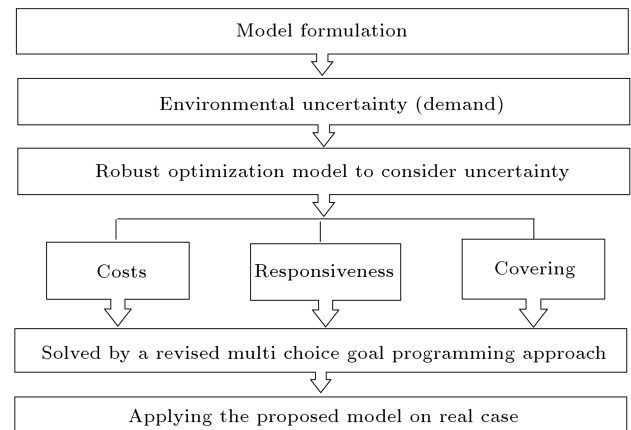


Figure 2. Diagram of solution approach for the proposed model.

Finally, the model is validated through a case study. Moreover, Figure 2 shows the procedure of applied solution approach in this research.

The rest of this paper is organized as follows. Section 2 gives an overview of the related research in the field of relief logistics. In Section 3, a mathematical model for a three-level relief chain is formulated, and a linearization procedure is explained, too. In order to solve the proposed model under uncertainty, a robust optimization approach is explained in Section 4. In Section 5, the multi-objective model is solved through RMCGP method and the procedure is described. Computational results and “what if ...?” analyses are discussed through a case study in Section 6. Finally, conclusions and areas for further research are provided in Section 7.

2. Literature review and research gap

Operations research has been widely applied to disaster management [8]. Because of the high importance of relief logistics, numerous research studies have been done in this field. Besides, plenty of decisions have been/are improvised during disasters [9]. However, only a few studies have been focused on locating the DCs and distributing relief commodities, simultaneously. Current studies related to disaster management can be categorized according to the considered objective (cost, responsiveness, covering), environmental condi-

tion (deterministic, stochastic), decision level (supply, distribution, and demand), and located facility (DCs, ECs).

Toregas et al. (1971) conducted one of the first studies on locating the relief facilities [10]. They studied the location of the relief facilities and demand coverage in the response phase. In this field, Alçada-Almeida et al. (2009) [11] focused on the evacuation as one of the most important centers, and proposed a model for evacuation planning during a disaster. Their proposed model includes locating shelters as well as evacuation of primary and backup paths. This model is also applicable to other cases of disaster such as floods and earthquakes.

Mete and Zabinsky (2010) [12] considered the cost and demand uncertainty and presented a stochastic model for the distribution and storage of medical products for managing a possible disaster. In their model, the location of warehouses and inventory levels were considered, too. In another research, Rawls and Turnquist (2011) [13] provided a location and distribution model for relief commodities under uncertainty. They proposed a two-stage approach. The first step locates and determines the storage capacity of relief commodities, and the second step determines the flow of relief commodities in the network.

Caunhye et al. (2012) [14] reviewed the optimization models utilized in the emergency logistics. Based on this paper, since the first adoption of research studies on maritime disaster situations in the 1970s, they have considered three separate parts: facility location, relief distribution and casualty transportation, and other operations. They considered short-notice evacuation, facility location, and stock pre-positioning as the main pre-disaster operations, while relief distribution and casualty transportation were categorized as post-disaster operations.

Bozorgi-Amiri et al. (2013) [15] proposed a multi-objective robust model to minimize the total cost and unfulfilled demand under uncertainty in preparedness and response phases of a disaster. Davis et al. (2013) [16] presented a probabilistic model for the distribution of relief commodities from suppliers to their distribution networks. They considered a bi-level mathematical programming approach that solved problems in two steps. In the first step, locating costs are minimized, and distribution and shortage costs are minimized in the second step. Najafi et al. (2013) [17] proposed a dynamic model for dispatching and routing vehicles in response to an earthquake. They considered a multi-objective, multimode, multi-commodity, and multi-period stochastic robust optimization model. They considered two hierarchical objective functions that are concerned with minimizing transit times for both goods and the injured people. Barzinpour and Esmaeili (2014) [18] proposed a multi-objective mixed-

integer linear programming model for preparation of disaster logistics scheduling based on demand area population and damage severity. They applied goal-programming approach to prioritize objectives in order to face the least deviation from goals. For the planning, the worst-case scenario was considered to perform the need estimation and preparation. The model showed improvement in quality of solutions when collaboration and cooperation between sub-regions were made. Rezaei-Malek and Tavakkoli-Moghaddam (2014) [19] presented an uncertain model to minimize cost and response time objectives. Their model aimed to distribute relief commodities in the response phase after locating and determining inventories.

Abounacer et al. (2014) [20] considered a three-objective location-transportation problem for disaster response. Three conflicting objectives that contain minimization of costs, minimization of number of agents, and minimization of non-covered demand were considered. They proposed an epsilon-constrained method for this problem, and proved that it generated the exact Pareto front. Finally, they proposed a heuristic algorithm for short computation times.

Hu et al. (2015) [21] presented a mathematical model for flood relief logistics. They considered minimizing the total cost and shortage risk. Givler and Mitchel (2018) [22] proposed a model for the equitable distribution of relief commodities in the response phase. It considered the risks involved in locating the DCs. Bozorgi-Amiri and Khorsi (2016) [23] proposed a multi-objective dynamic stochastic programming model for a humanitarian relief logistics problem where decisions are made to deal with pre- and post-disaster incidents. Their model proposed three objectives: minimizing the maximum amount of shortages among the affected areas in all periods, the total travel time, and the sum of pre- and post-disaster costs. The proposed model is solved as a single-objective mixed-integer programming model by applying the ϵ -constrained method. Gutjahr and Dzibur (2016) [24] proposed a bi-level model in order to locate the distribution center considering the distribution fairness. On the first level, a number of distribution centers were selected with the aim of minimizing the costs and maximizing the coverage; on the second level, by using the distance and supply capacity criteria, the appropriate location for these facilities was selected. Finally, by utilizing the adaptive ϵ -constrained, branch and bound, and Frank-Wolf methods, the Pareto solutions were found. Zokaei et al. (2016) [25] proposed a relief logistics model for a three-echelon network consisting of supply, distribution, and demand point. They optimized the objectives of maximizing the responsive people and minimizing the total cost under scenario-based uncertainty by identifying the critical uncertain factors and providing a deterministic approximation. They presented a case

study of the Alborz province as an earthquake-prone region in Iran. Haghi et al. (2017) [26] developed a multi-objective programming model for locating relief goods distribution centers and health centers along with distributing relief goods and transferring the casualties to health centers, with pre/post-disaster budget constraints for goods and casualties logistics. They considered uncertainties in demand, supply, and cost parameters. Their proposed model maximizes the level of response to medical needs of the casualties while targeting the justly distribution of relief goods and minimizing the total costs of preparedness and response phases. Their model is solved with ϵ -constrained method and the MOGASA algorithm.

Table 1 presents some important features of the reviewed papers in the field of relief logistics. The main features and identified research gaps in the literature covered by this paper are as follows:

1. Many research studies are developed in the context of relief logistics as multi-objective. In the real-world situation, the researchers have considered responsiveness in addition to cost; these are some of the most important objectives of the problem.

However, maximizing the coverage of demand along with other objectives has been rarely studied. Maximum coverage of the demand can be achieved by locating the right DCs and ECs; this leads to improvements in responsiveness and cost reduction. Herein, objective functions of cost, responsiveness, and demand covering are considered simultaneously;

2. During a disaster, it is better to consider all factors affecting the relief chain. Therefore, all supply chain levels involved in a disaster, including supply, distribution, and the relief commodities demand, should be considered in the planning framework;
3. In this study, locating DCs and ECs optimally is considered to meet the demand. Since the strength levels of buildings in different regions are not similar, demands of different regions may depend on the resistance of buildings against severity of a disaster. Therefore, in this paper, affected areas are divided into different regions with regional demands. Hence, different regions with different building resistance quality and demand under uncertainty are considered.

Table 1. Comparative analysis of some important features of reviewed papers in the literature.

Authors	Objective			Environmental conditions		Decision levels			Location	
	Cost	Responsiveness	Covering	Deterministic	Stochastic	Supply	Distribution	Demand	DCs	ECs
Alçada-Almeida et al. [11]		*		*			*	*		*
Mete and Zabinsky [12]	*				*	*		*	*	
Rawls and Turnquist [13]	*				*		*	*	*	
Bozorgi-Amiri et al. [15]	*	*			*	*	*	*	*	
Davis et al. [16]	*				*	*	*	*	*	
Najafi et al. [17]	*	*			*	*	*	*		
Barzinpour and Esmaili [18]	*		*	*		*		*		
Rezaei-Malek and Tavakkoli-Moghaddam [19]	*				*		*	*	*	
Hu et al. [21]	*				*	*	*	*	*	
Givler and Mitchell [22]	*			*			*		*	
Haghi et al. [26]	*	*	*		*	*	*	*	*	*
Shishebori and Babadi [27]	*				*		*	*	*	*
Moreno et al. [28]	*				*	*	*	*	*	
Rezaei-Malek et al. [29]	*				*		*		*	
This paper	*	*	*		*	*	*	*	*	*

Moreover, the following question needs to be answered. Can we avoid (or at least minimize) damages of an earthquake by means of planning for it before its occurrence? The answer to this question will be discussed in the following sections.

3. Problem description

Three levels in a relief supply chain are considered in this research. The suppliers, DCs, and ECs are the main entities that play important roles in this network. Suppliers provide required relief commodities. Depending on the severity of a disaster and relief commodities demand, requested items are distributed to the identified DCs where they are sent to ECs. Figure 3 illustrates a scheme of a relief commodities supply and distribution network. Accordingly, demand points and considered ECs in each region are placed on the third level.

Some of the assumptions in the proposed model are as follows:

1. Suppliers' locations are fixed, while there are alternative locations for DCs and ECs;
2. There are several types of relief commodities;
3. Relief commodities demand is estimated independently for each region;
4. Capacity of available ECs in each region is at least equal to the number of required ECs in that region. Required ECs in each region are calculated according to the number of residents in that region;
5. If the number of items delivered to an EC is more than the relief commodities demand, inventory cost for extra relief commodities will be considered.

3.1. Indices

- i Existing suppliers ($i = 1, 2, \dots, I$);
- j Potential DCs ($j = 1, 2, \dots, J$);
- k Potential ECs ($k = 1, 2, \dots, K$);
- c Relief commodities ($c = 1, 2, \dots, C$);

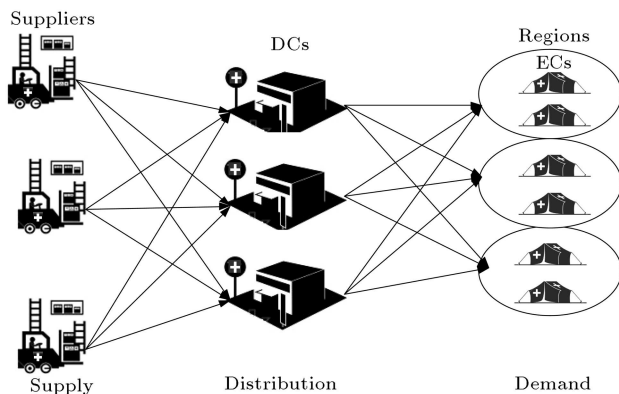


Figure 3. A schema for relief commodities flow.

- o Regions ($o = 1, 2, \dots, O$);
- h Quality of a construction ($h = 1, 2, \dots, H$);
- s Scenarios for disaster intensity ($s = 1, 2, \dots, S$).

3.2. Certain parameters

- p_s Probability of the occurrence of scenario s ;
- package_c Number of relief commodities c in one package;
- v_c Required space for one package of relief commodity c ;
- γ_{oh} 1 if region o has quality of construction h , 0 otherwise;
- pop_o Population of region o ;
- dis_{jk} Distance between DC j and EC k ;
- φ_{ic} Purchase cost for a package of relief commodity c from supplier i ;
- $C1_{ijc}$ Transportation cost for a package of relief commodity c from supplier i to DC j ;
- $\text{Cap}D_j$ Capacity of the DC j (m^3);
- FD_j Setup cost of DC j ;
- F_k Setup cost of EC k ;
- cov Maximum coverage distance per unit volume DC;
- $S1_{ic}$ Number of packages of relief commodity c supplied from supplier i ;
- $h1_c$ Inventory holding cost for a package of relief commodity c before the disaster;
- DCO_j Maximum coverage distance for DC j , $DCO_j = \text{Cap}D_j * \text{cov}$;
- $N_{o \in O} \{k\}$ Set of potential ECs k in region o ;
- $N_{j \in J} \{k\}$ Set of ECs k located at the covering distance of DC j , $N = \{k : \text{dis}_{jk} \leq DCO_j\}$;
- $N_{k \in K} \{j\}$ Set of DCs j that covers EC k , $N = \{j : \text{dis}_{jk} \leq DCO_j\}$;
- M A sufficiently large positive number.

3.3. Uncertain parameters

- CC_{jkcs} Unit transportation cost of one package of relief commodity c from DC j to EC k in scenario s ;
- q_{hcs} Per person demand for relief commodity c in region with the quality of construction h under scenario s ;
- β_{hs} Percentage of population in region with the quality of construction h who need EC under scenario s ;

D_{ocs} Demand for package of relief commodity c in region o under scenario s , $D_{ocs} = \left[\sum_h \left[\frac{pop_o \times \beta_{hs} \times q_{hcs}}{package_c} \right] \gamma_{oh} \right]$;
 π_{cs} Penalty cost for each package of relief commodity c under scenario s ;
 $h2_{cs}$ Inventory holding cost of one package of relief commodity c under scenario s .

3.4. Decision variables

X_{ijc} Number of packages of relief commodity c transferred from supplier i to DC j ;
 Y_{jkcs} Number of packages of relief commodity c transferred from DC j to EC k under scenario s ;
 ZD_j 1 if DC j is opened; 0 otherwise;
 ZS_k 1 if EC k is opened; 0 otherwise;
 I_{ocs} Number of packages of relief commodity c held in region o under scenario s ;
 B_{ocs} Number of packages of shortage relief commodity c in region o under scenario s ;
 W_{jk} 1 if DC j is assigned to EC k .

3.5. Mathematical formulation

$$\begin{aligned} \min \quad z_{1s} = & \sum_j FD_j ZD_j + \sum_k F_k ZS_k \\ & + \sum_i \sum_j \sum_c \varphi_{ic} X_{ijc} \\ & + \sum_i \sum_j \sum_c (C1_{ijc} + h1_c) X_{ijc} \\ & + \sum_j \sum_k \sum_c CC_{jkcs} Y_{jkcs} \\ & + \sum_j \sum_c h2_{cs} I_{jcs}, \end{aligned} \tag{1}$$

$$\min \quad z_{2s} = \sum_c \max_{o \in O} \{B_{ocs}\}, \tag{2}$$

$$\begin{aligned} \max \quad z_{3s} = & \sum_o \sum_h \left[(pop_o \beta_{hs} \gamma_{oh}) \right. \\ & \left. * \left(\sum_{k \in N_o} \sum_{j \in N_k} W_{jk} \right) \right], \end{aligned} \tag{3}$$

s.t.:

$$\sum_j \sum_{k \in N_o} Y_{jkcs} + B_{ocs} = D_{ocs} \quad \forall o, c, s, \tag{4}$$

$$\sum_i X_{ijc} = \sum_k Y_{jkcs} + I_{jcs} \quad \forall j, c, s, \tag{5}$$

$$\sum_c \sum_i V_c X_{ijc} \leq CapD_j ZD_j \quad \forall j, \tag{6}$$

$$\sum_j X_{ijc} \leq S1_{ic} \quad \forall i, c, \tag{7}$$

$$ZS_k \leq \sum_{j \in N_k} W_{jk} \quad \forall k, \tag{8}$$

$$2 \times W_{jk} \leq ZD_j + ZS_k \quad \forall j, k, \tag{9}$$

$$\sum_c Y_{jkcs} \leq M \times W_{jk} \quad \forall j, k, s, \tag{10}$$

$$ZD_j, ZS_k, W_{jk} \in \{0, 1\} \quad \forall j, k, \tag{11}$$

$$X_{ijc}, Y_{jkcs}, I_{ocs}, B_{ocs} \geq 0 \quad \forall o, i, j, c, k, s. \tag{12}$$

In this model, Objective Function (1) minimizes the total cost that is composed of the following components. The first term computes the setup cost of DCs before a disaster; the second term calculates the setup cost of an EC before the disaster. The third term is procurement cost before a disaster. The fourth term is the transportation cost from the supplier to DC and inventory holding before a disaster. The fifth term calculates the transportation cost from DC to EC during a disaster. The last term is the cost of holding inventory during a disaster. Objective Function (2) minimizes the maximum number of shortage of relief commodities in each region. This translates to responsiveness maximization. Objective Function (3) maximizes the demand coverage; in fact, this objective is different from the second one as it increases coverage quality of responsibility; however, the second objective caused equity of responsibility.

Constraint (4) represents balance constraint for each region that determines the number of relief commodities distributed from each DC to each region according to the amount of demand. Constraint (5) represents the total number of relief commodities shipped to a DC. Constraint (6) enforces the fact that the total number of relief commodities shipped to a DC cannot exceed the DC capacity. Constraint (7) imposes that the number of relief commodities supplied from a supplier cannot exceed the supplier's capacity. One DC should cover the EC at least. This is modeled through Constraint (8). Constraint (9) expresses that, if DC and EC are opened, then they can be assigned. Constraint (10) models the fact that when there is a flow between DC and EC, relief commodities can be shipped. Constraints (11) and (12) enforce the range of variables.

3.6. Linearization

The proposed optimization model includes non-linear terms. Objective Function (2) is a non-linear one that may be transformed into a linear function using a new positive auxiliary variable, E_{cs} . The original non-linear objective function is replaced with the constraints given in Eqs. (13) to (15):

$$\min z_{2s} = \sum_c E_{cs}, \tag{13}$$

$$E_{cs} \geq B_{ocs} \quad \forall o, c, s, \tag{14}$$

$$E_{cs} \geq 0 \quad \forall c, s. \tag{15}$$

4. Robust optimization

4.1. The robust optimization framework

Two broad categories of risk can be defined that affect the supply chain management and design. The first category is concerned with uncertainty embedded in the model parameters, influencing the problem of balancing the supply and demand. The second category of risks may arise from natural disasters, strikes and economic disruptions, terrorist attacks, etc. The existing uncertainties in the demand and costs refer to the first category of risks. A Robust Optimization (RO) approach can be considered as an alternative approach for dealing with the first category of risk in the case where there are not enough historical data to estimate the probability distribution of the uncertain parameters. Robust optimization has been one of the most common methods for dealing with optimization problems under uncertainty since the 1990s [30,31]. Mulvey et al. [32] presented an approach for robust optimization considering both the solution and model robustness. It means that the solution remains almost feasible and almost optimal under all scenarios. Model infeasibility is measured by a penalty function. Moreover, their robust optimization model considered the analyses of model and solution robustness. It is formulated as follows:

$$\min c^T x + d^T y, \tag{16}$$

s.t.:

$$Ax = b, \tag{17}$$

$$Bx + Cy = e, \tag{18}$$

$$x, y \geq 0, \tag{19}$$

where x is a vector of design variables, and y is a vector of control variables. Constraint (17) is the structural constraint for which the coefficients are constant, noise-free and deterministic (certain coefficients). Constraint (18) is a control constraint for

which the coefficients are noisy and deterministic (uncertain coefficients). Constraint (19) represents the type of the variables. To define the problem of robust optimization, a set of scenarios $\Omega = \{1, 2, \dots, s\}$ is considered.

The set of uncertain parameters $\{B_s, C_s, e_s\}$ is determined under each scenario, and the probability of each scenario, s , is represented by p_s where the summation of all scenarios should be equal to one.

However, it is impossible to find a feasible and optimal solution to Model (16) under all scenarios in Ω . Since the control variable, y , changes after realizing a new scenario, it can be represented by y_s . Due to the uncertainty of parameters, the model may be infeasible for some scenarios. The variable η_s represents the infeasibility of the model under each scenario, s . If the model is feasible, then η_s is zero.

The model should make a trade-off between solution robustness and model robustness. Mulvey et al. [32] presented a robust optimization model to evaluate this trade-off. The general model of the scenario-based robust optimization is as follows:

$$\min \sigma(x, y_1, y_2, \dots, y_s) + \gamma p(\eta_1, \eta_2, \dots, \eta_s), \tag{20}$$

s.t.:

$$Ax = b, \tag{21}$$

$$B_s x + C_s y_s + \eta_s = e_s \quad \forall s \in \Omega, \tag{22}$$

$$x, y_s, \eta_s \geq 0 \quad \forall s \in \Omega. \tag{23}$$

There are two terms in Objective Function (20). The first term shows the solution robustness, and the second calculates the model robustness. The objective function is notated by $\xi_s = f(x, y_s)$ for scenario s . Mulvey et al. [32] used the following expression to represent solution robustness where δ is defined as the weight assigned to solution variations and γ is weight of robustness.

$$\sigma(o) = \sum_{s \in \Omega} p_s \xi_s + \delta \sum_{s \in \Omega} p_s \left(\xi_s - \sum_{s \in \Omega} p'_s \xi'_s \right)^2.$$

Recently, Yu and Li [33] extended the model to the following:

$$\begin{aligned} \min \quad & \sum_{s \in \Omega} p_s \xi_s + \delta \\ & * \left[\sum_{s \in \Omega} p_s \left(\left(\xi_s - \sum_{s \in \Omega} p_s \xi_s \right) + 2\theta_s \right) \right] \\ & + \gamma \sum_{s \in \Omega} p_s \eta_s, \end{aligned} \tag{24}$$

s.t.:

$$\xi_s - \sum_{s \in \Omega} p_s \xi_s + \theta_s \geq 0 \quad \forall s \in \Omega, \quad (25)$$

$$\theta_s \geq 0 \quad \forall s \in \Omega, \quad (26)$$

where θ_s is utilized for linearization.

4.2. The proposed robust optimization model

Following the aforementioned robust optimization approach, the proposed model is incorporated with the scenario-based uncertainty, and the following model is obtained.

$$\begin{aligned} \min \quad z_1 = & \sum_{s \in \Omega} p_s z_{1s} + \delta \\ & * \sum_{s \in \Omega} p_s \left(z_{1s} - \sum_{s \in \Omega} p_s z_{1s} + 2\theta_{1s} \right) \\ & + \sum_s \sum_o \sum_c p_s \pi_{cs} B_{ocs}, \end{aligned} \quad (27)$$

$$\begin{aligned} \min \quad z_2 = & \sum_{s \in \Omega} p_s z_{2s} + \delta \\ & * \sum_{s \in \Omega} p_s \left(z_{2s} - \sum_{s \in \Omega} p_s z_{2s} + 2\theta_{2s} \right), \end{aligned} \quad (28)$$

$$\max \quad z_3 = \sum_{s \in \Omega} p_s z_{3s}, \quad (29)$$

s.t.:

$$z_{1s} - \sum_{s \in \Omega} p_s z_{1s} + \theta_{1s} \geq 0 \quad \forall s, \quad (30)$$

$$z_{2s} - \sum_{s \in \Omega} p_s z_{2s} + \theta_{2s} \geq 0 \quad \forall s, \quad (31)$$

$$\theta_{1s}, \theta_{2s} \geq 0 \quad \forall s. \quad (32)$$

The first terms in Objective Functions (27), (28), and (29) are the mean values, and the second terms in Objective Functions (27) and (28) are the variance of total costs, measuring the solution robustness. The third term in Eq. (27) measures the robustness of the model.

5. Multi-choice goal programming method

In this research, Multi-Choice Goal Programming (MCGP) is implemented to solve the proposed model. Goal Programming (GP), as one of multi-objective optimization methods, is one of the most famous decision-making techniques first employed by Charnes et al [34].

The purpose of GP is to minimize the unnecessary deviations of the objective from the expected level, also known as primary conservative level. However, the primary conservative level is usually difficult to determine [35]. Therefore, Chang introduced an MCGP method for solving multi-objective decision-making problems with multiple expected levels for each goal. MCGP method allows decision-makers to offer a set of expected levels for each goal. Mathematical formulation of the MCGP is as follows [36]:

$$\min \quad \sum_{i=1}^n w_i (d_i^+ + d_i^-), \quad (33)$$

s.t.:

$$h_k(x) = (\leq \text{ or } \geq) 0 \quad \forall k = 1, \dots, q, \quad (34)$$

$$f_i(x) + d_i^- - d_i^+ = \sum_{j=1}^m g_{ij} z_{ij} \quad \forall i = 1, \dots, n, \quad (35)$$

$$\sum_{j=1}^m z_{ij} = 1 \quad \forall i = 1, \dots, n, \quad (36)$$

$$\begin{aligned} d_i^+, d_i^- \geq 0, \quad z_{ij} \in \{0, 1\} \quad \forall i = 1, \dots, n \\ \forall j = 1, \dots, m. \end{aligned} \quad (37)$$

In the above formulation, $h_k(x)$ is the k th systematic constraint, $f_i(x)$ is the i th objective function, g_{ij} is the j th expected level of objective function i , d_i^+ is the positive deviation from the i th objective value, and variable d_i^- is the negative deviation from the i th objective value. Also, z_{ij} is a binary variable and is 1 if the j th expected level of objective function i is selected, and is 0 otherwise. Each objective function may have only one expected level. Moreover, w_i is the positive weight for (d_i^+, d_i^-) .

In MCGP, solution time may rise as the number of binary variables increase. To enhance the computation time, Chang [36] proposed a Revised MCGP (RMCGP) method described as follows. In this method similar to GP, the purpose is to minimize the unnecessary deviation of the objective from the expected level and minimize the unnecessary deviation of the expected level from its ranges.

$$\min \quad \sum_{i=1}^n [w_i (d_i^+ + d_i^-) + \alpha_i (e_i^+ + e_i^-)], \quad (38)$$

s.t.:

$$h_k(x) = (\leq \text{ or } \geq) 0 \quad \forall k = 1, \dots, q, \quad (39)$$

$$f_i(x) + d_i^- - d_i^+ = y_i \quad \forall i = 1, \dots, n, \quad (40)$$

$$y_i + e_i^- - e_i^+ = g_{i.\max} \quad \text{or} \quad y_i + e_i^- - e_i^+ = g_{i.\min} \\ \forall i = 1, \dots, n, \quad (41)$$

$$g_{i.\min} \leq y_i \leq g_{i.\max} \quad \forall i = 1, \dots, n, \quad (42)$$

$$d_i^+, d_i^-, e_i^+, e_i^- \geq 0 \quad \forall i = 1, \dots, n, \quad (43)$$

where $g_{i.\max}$ and $g_{i.\min}$ are the ranges of the i th expected level, and y_i is the continuous variable. e_i^+ and e_i^- are positive and negative deviations of y_i from $g_{i.\min}$ or $g_{i.\max}$, respectively. d_i^+ and d_i^- are positive and negative deviations of $f_i(x)$ from y_i , respectively. Finally, w_i is the positive weight of (d_i^+, d_i^-) , and α_i is the positive weight of (e_i^+, e_i^-) . The first term in Constraint (41) relates to “The more, the better” (used for maximizing an objective function), and the second term relates to “The less, the better” (used for minimizing an objective function).

6. Case study

6.1. Case description

Relief logistics plays a significant role in saving human lives when disaster strikes. This is the reason for various efforts that have been made in relief logistics. However, a lot more should be done in terms of research and practice. This is mainly because disasters are usually unpredictable, and there is a lack of understanding of the costs related to such an event. Therefore, pre-disaster planning plays a major role in the successful confrontation of crises.

Furthermore, Iran is one of the earthquake-prone countries located on one of two unstable large belts, where strong earthquakes occur occasionally. In addition, Iran is among the first ten countries with a high rate of disasters (ranked sixth in the world and fourth in Asia [37]). In this research, to validate the model and justify its applicability, a study of relief program during an earthquake in the city of Amol, in the Mazandaran Province, is presented in this section. This city is under the verge of large and small earthquakes due to its proximity to Mount Damavand, the highest volcano in the Middle East and Asia and an inactive volcano with several earthquake-prone areas around. Proper relief management in the North of Iran is important due to the high dispersion of areas with high risk of earthquake, as shown in Figure 4.

In this study, in order to achieve the humanitarian and cost objectives in different disaster’s scenarios, relief planning is considered before and during a disaster. Finally, the results are analyzed.

In this study, a lot of information has been received from experts in the fields of geology and disaster management. In fact, the bulk of this study is obtained based on the Field study.



Figure 4. Dispersion of the areas with high risk of earthquakes in Iran [38].

Table 2. Population and quality of construction in each region.

	pop_o	γ_{oh}		
		Non-standard	Partly-standard	Standard
North	50,000	0	1	0
West	75,000	0	1	0
Center	45,000	0	0	1
East	65,000	0	1	0
South	35,000	1	0	0

In this study, Amol, with the population of about 270,000, is divided into five districts of north, south, west, east, and center. The population of each region is shown in Table 2. Since relief aids in a region directly relate to the strength of buildings in that region and buildings in different areas have different earthquake-resistant structures, the regions are categorized into three groups according to the building’s construction quality:

1. **Standard:** A region in which more than 70 percent of buildings conform to the construction standards;
2. **Partly standard:** A region where between 30 and 70 percent of buildings conform to the construction standards;
3. **Non-standard:** A region in which less than 30 percent of buildings conform to the construction standards.

These classifications and percentages were achieved by consulting with the experts; actually, these have been considered for Amol structure and may be different for other cities.

Some of the most important issues that may cause flouting of construction regulations are the type

Table 3. Classification of earthquakes based on severity [39].

Magnitude	Earthquake Effects	Class	Estimated number each year
2.5 or less	Usually not felt, but can be recorded by seismograph.	Minor	900,000
2.5 to 5.4	Often felt, but only causes minor damage.	Light	30,000
5.5 to 6.0	Slight damage to buildings and other structures.	Moderate	500
6.1 to 6.9	May cause a lot of damage in very populated areas.	Strong	100
7.0 to 7.9	Major earthquake. Serious damage.	Major	20
8.0 or greater	Great earthquake. Capable of totally destroying communities near the epicenter.	Great	One every 5 to 10 years

of rocks and soil, the quality of the foundation, the type of construction (concrete, steel, brick and mixed), regularity in plan and height, analysis and design of structures against earthquakes, number of floors, ground state structures, seismic coefficient in each direction of buildings, and structural weight. According to these criteria, the regions are categorized as described in Table 2.

Earthquakes are classified in categories ranging from minor to great (Table 3), depending on their magnitude. However, based on local geographical information collected, in Amol, there is no possibility of an earthquake greater than 7 Richter.

Since a major part of the planning procedure to manage the effects caused by disasters is performed beforehand and because of the lack of information about earthquake severity, three scenarios are considered:

1. The first scenario is considered for an earthquake less than 5.5 magnitude on a Richter scale that does not require great relief demand;
2. The second scenario is designed for an earthquake between 5.5 and 6 magnitude on a Richter scale that requires much more demand than the first scenario;
3. The third scenario is considered for an earthquake between 6 and 7 magnitude on a Richter scale that causes great human and financial loss. Consequently, it may request a great demand in the region.

According to the international reports, the historical data, and estimations of regional and national

experts, probability of 0.7, 0.2, and 0.1 is estimated for different scenarios.

6.2. Input parameters

According to Figure 5, 10 potential DCs and 45 potential ECs are identified in the five regions mentioned in Table 2. Three types of relief batches are considered. The batches contain:

1. Water and food;
2. Hygiene and clothing;
3. Other relief commodities.

More information about the batches is presented in Table 4. In order to facilitate the transportation, each relief batch is laid in a package (a bigger box). The numbers of relief commodities in each package are 10, 5, and 1, respectively. Aid packages are sent from three suppliers to DCs:

1. Sari (capital city of Mazandaran),
2. Tehran (capital city of Iran),
3. A large warehouse in the Amol.

Table 5 represents the demand for packages for each region in each scenario. Each supplier capacity is given in Table 6. Since each DC has a different capacity, the distance coverage is different for each DC, as shown in Table 7.

One of the main relief objectives is to prevent shortages or unfulfilled demand. However, in the case of a severe disaster, it is hard to meet all the demands; hence, shortage may ensue. In this case, shortage

Table 4. Relief commodities in each batch.

Water and food	Rice	Oil	Sugar	Tea	Bean	Canned	Tuna	Water
Hygiene and clothing	Dishes	Coleman water	Gallons water and oil	Plastic tankard	Health package	Slippers	Clothing	—
Other	Relief tents	Carpet 3*2	Blankets	Nylon tent	Heater	Lantern	—	—

Table 5. Capacity for each supplier.

$S1_{ic}$	Water and food	Hygiene and clothing	Other
Amol	100	110	120
Sari	200	300	250
Tehran	400	450	350

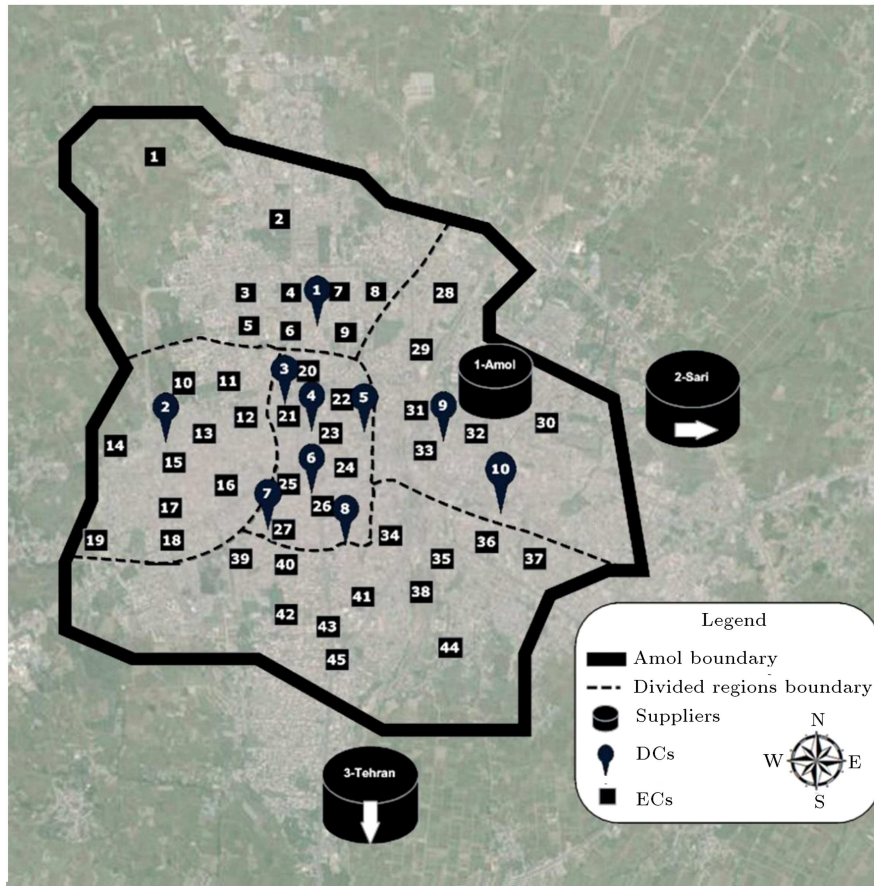


Figure 5. Urban area used for the case study divided into 5 regions (Amol).

costs per package of relief commodity are shown in Table 8. Moreover, another aspect of relief in disasters is to avoid additional costs (such as holding costs) and waste of relief commodities. Because of different storage conditions, relief commodities may decay under different scenarios. Therefore, the holding cost per package of relief commodities is different in the three scenarios, as shown in Table 8.

6.3. The results

The proposed model optimizes three objectives of minimizing the cost of relief (DCs and ECs setup cost, purchasing and transportation cost, holding and shortage cost), minimizing the maximum shortage in each region of demand, and maximizing the coverage area. In this problem, robust optimization methods are employed to consider multiple scenarios, and MCGP

method is implemented for integrating objective functions. The obtained model is as follows:

$$\begin{aligned} \min = & \left(w_1 \frac{(d_1^+ + d_1^-)}{g_{1.\min}} + \alpha_1 \frac{(e_1^+ + e_1^-)}{g_{1.\min}} \right) \\ & + \left(w_2 \frac{(d_2^+ + d_2^-)}{g_{2.\min}} + \alpha_2 \frac{(e_2^+ + e_2^-)}{g_{2.\min}} \right) \\ & + \left(w_3 \frac{(d_3^+ + d_3^-)}{g_{3.\max}} + \alpha_3 \frac{(e_3^+ + e_3^-)}{g_{3.\max}} \right), \end{aligned}$$

s.t.: Constraints (4)-(12), (14) and (15) and (27)-(32):

$$f_1(x) + d_1^- - d_1^+ = y_1,$$

$$y_1 + e_1^- - e_1^+ = g_{1.\min},$$

Table 6. Demand for each of the regions in each scenario.

<i>D_{ocs}</i>		Scenario 1	Scenario 2	Scenario 3
North	Water and food	8	57	97
	Hygiene and clothing	16	113	193
	Other	13	113	207
West	Water and food	12	85	145
	Hygiene and clothing	23	169	289
	Other	19	169	310
Center	Water and food	3	28	61
	Hygiene and clothing	5	55	122
	Other	3	34	102
East	Water and food	10	74	126
	Hygiene and clothing	20	147	251
	Other	17	147	269
South	Water and food	11	64	106
	Hygiene and clothing	22	127	211
	Other	27	211	526

Table 7. Covering distance of each DC (m).

<i>j</i>	1	2	3	4	5	6	7	8	9	10
<i>DCO_j</i>	1,250	1,800	1,300	1,450	1,600	1,400	950	1,300	2,450	1,300

Table 8. Holding and cost of lacking a package of relief commodities for scenarios (thousand Rials).

	Scenario 1		Scenario 2		Scenario 3	
	<i>h1_{cs}</i>	<i>π_{cs}</i>	<i>h1_{cs}</i>	<i>π_{cs}</i>	<i>h1_{cs}</i>	<i>π_{cs}</i>
Water and food	1,000	7,000	1,500	9,000	2,000	11,000
Hygiene and clothing	100	6,000	150	8,000	200	9,000
Other	50	500	100	2,000	150	4,000

$$g_{1. \min} \leq y_1 \leq g_{1. \max},$$

$$f_2(x) + d_2^- - d_2^+ = y_2,$$

$$y_2 + e_2^- - e_2^+ = g_{2. \min},$$

$$g_{2. \min} \leq y_2 \leq g_{2. \max},$$

$$f_3(x) + d_3^- - d_3^+ = y_3,$$

$$y_3 + e_3^- - e_3^+ = g_{3. \max},$$

$$g_{3. \min} \leq y_3 \leq g_{3. \max},$$

$$d_1^+, d_1^-, d_2^+, d_2^-, d_3^+, d_3^-, e_1^+, e_1^-, e_2^+, e_2^-, e_3^+, e_3^- \geq 0.$$

Table 9. Ideal and anti-ideal values and weights of each of the objectives for the main problem.

Objective	<i>g_{min}</i>	<i>g_{max}</i>	<i>w</i>	<i>α</i>
<i>Z₁</i>	4,519,550	6,000,000	0.2	0.2
<i>Z₂</i>	36.1	100	0.5	0.5
<i>Z₃</i>	50,000	87,675	0.3	0.3

Input parameters for solving MCGP are presented in Table 9.

Herein, *g_{min}* and *g_{max}* are ideal values for minimization and maximization objectives, respectively. Moreover, *g_{max}* and *g_{min}* are anti-ideal values for minimization and maximization objectives, respectively. Thus, for the first objective function, *g_{max}* is defined as the maximum amount of budget (6,000,000 thousand

Table 10. Results of the main problem.

Objective	d^+	d^-	e^+	e^-	y	Value
Z_1	4,075,305	0	1,480,450	0	6,000,000	10,075,305
Z_2	0	0	17.86	0	53.96	53.96
Z_3	0	0	0	1,050	86,625	86,625

Rials) that can be spent. The weight of each objective is represented in Table 9. The model is solved in Lingo 9 on a PC equipped with Intel® Core™ i5 CPU and 4GB RAM running Microsoft® Windows™ 7. The results are depicted in Table 10.

According to the results, the second and third objectives are totally satisfied, because the realized values obtained from these functions lie within the expected range $[g_{min}, g_{max}]$. However, the positive deviation variable takes a non-zero value for the first objective. Accordingly, the value of this objective is 68% more than the upper limit. In other words, additional budget (68% more) is required to be within the expected range. DCs' numbers 3, 4, 7, and 8 are not set up, since $Z_{d_{3,4,7,8}} = 0$ in the central region. The obtained values are shown in Table 11.

Besides, among the potential ECs, three points (1, 44, and 45) are not set up, which may derive from the longer distances and higher costs of these ECs. As mentioned earlier, in a disaster, either the demand is met or shortage happens. Table 11 shows unfulfilled

demand and the remaining relief commodities in each region. Due to the lower demand in the first and second scenarios, the relief commodities stored in stock meet all the demands and there is surplus of inventory. However, in the third scenario, shortages occur due to the severity of the disaster and higher demand. In Table 12, the percentage of responsiveness is shown under various scenarios; percentage of responsiveness has an inverse relation with shortage of relief commodities. According to Table 12, the central region has the minimum responsiveness (17%) because of non-

Table 12. Percentage of responsiveness per region under different scenarios.

	Scenario 1	Scenario 2	Scenario 3
North	100	100	43
West	100	100	62
Center	100	100	17
East	100	100	56
South	100	100	66

Table 11. Shortage and inventory of relief commodities per region in each scenario.

		Scenario 1		Scenario 2		Scenario 3	
		B_{ocs}	I_{locs}	B_{ocs}	I_{locs}	B_{ocs}	I_{locs}
North	Water and food	0	44	0	0	45	0
	Hygiene and clothing	0	85	0	0	91	0
	Other	0	45	0	0	148	0
West	Water and food	0	73	0	0	45	0
	Hygiene and clothing	0	73	0	0	91	0
	Other	0	144	0	0	148	0
Center	Water and food	0	0	0	0	45	0
	Hygiene and clothing	0	0	0	0	91	0
	Other	0	0	0	0	102	0
East	Water and food	0	0	0	0	45	0
	Hygiene and clothing	0	0	0	0	91	0
	Other	0	0	0	0	148	0
South	Water and food	0	50	0	0	45	0
	Hygiene and clothing	0	17	0	0	91	0
	Other	0	223	0	5	148	0

standard building structures and higher cost of setting up DCs and ECs in this region.

6.4. “What if . . . ?” analysis

Because of the importance of responsiveness in a disaster situation, a plan for disaster management should be devised at the lowest possible shortage with an acceptable cost. In this section, some solutions are presented to decrease demand under fulfillment along with lowering the costs.

• **Weightless cost function**

One way to improve the responsiveness is to ignore the relative importance of the cost objective function. Thus, the weight of the first objective function (w_1, α_1) is set to zero, and the second and third objective functions’ weights are changed according to Table 13. The results are given in Table 14.

The rightmost column in Table 14 presents the gap between the optimal value and value obtained by solving the original model. This gap for the first objective is computed as follows:

$$\text{Gap\%} = \frac{\text{value} - g_{1.\min}}{g_{1.\min}} * 100.$$

Because the cost function is weightless, there is no limitation on the budget. As a result, all gaps of the problem occur in the cost objective function, and the values of gaps for other objectives become zero (Table 14). As observed in this case, the second and third objective functions take their best values, and the first objective is 133.7% larger than its upper limit. In fact, to meet the desired amount for the first objective, it needs an additional budget that translates to an increase from 6,000,000 thousand Rials to 14,024,724 thousand Rials. Unlike the first solution, all the DCs are set up in this case. In Table 15, the percentage of responsiveness for each of the regions is shown for different scenarios. Total responsiveness increases as compared to the

Table 13. Ideal and anti-ideal values and weights of each objective where $w_1 = 0$.

Objective	g_{\min}	g_{\max}	w	α
Z_1	4,519,550	6,000,000	0	0
Z_2	36.1	100	0.6	0.6
Z_3	50,000	87,675	0.4	0.4

Table 14. The results of the problem where $w_1 = 0$.

Objective	d^+	d^-	e^+	e^-	y	Value	GAP (%)
Z_1	9,505,174	0	0	0	4,519,550	14,024,724	210.3
Z_2	0	0	0	0	36.1	36.1	0
Z_3	0	0	0	0	87,675	87,675	0

Table 15. Percentage of responsiveness to each of the regions under different scenarios where $w_1 = 0$.

	Scenario 1	Scenario 2	Scenario 3
North	100	100	62
West	100	100	74
Center	100	100	50
East	100	100	71
South	100	100	77

original problem. However, it is less than 100%, and not all of the required materials are investigated. Therefore, the limitation on budget is not the only factor that hampers the total responsiveness.

In this case, the objective function of the shortage is reduced by 33% (from 53.96 to 36.1); however, the total cost increases by 39.1% as compared with the first situation (from 10,075,307 to 14,024,724).

• **Reinforcing the regions**

The quality of construction has a considerable impact on the damages and casualties. Reinforcement of regions before a disaster is one of the ways for improvement, which could reduce demand, thus reducing the unfulfilled demand during the disaster. Therefore, the case in which all buildings in all regions are retrofitted and, then, upgraded to a standard structure, i.e., $h = 3$, is considered here. With these changes, some fluctuations are observed in the upper and lower limits of the objective functions. The following results, as shown in Table 16, are obtained by solving the model. It should be noted that using this method requires government support, such as loan allocations to people, to improve the quality of construction.

According to the results in Table 17, the ideal objective function values are improved for all objectives except for the third objective function. In this case, all of the objectives meet their desired levels and the shortage rate is zero, i.e., all the demands are met. Therefore, it can be concluded

Table 16. Ideal and anti-ideal values and weights of each of the objectives when all regions change to $h = 3$.

Objective	g_{\min}	g_{\max}	w	α
Z_1	2,425,500	6,000,000	0.2	0.2
Z_2	0	100	0.5	0.5
Z_3	50,000	57,120	0.3	0.3

Table 17. Results of the problem when all regions change to $h = 3$.

Objective	d^+	d^-	e^+	e^-	y	Value	GAP (%)
Z_1	0	0	3,451,199	0	5,876,699	5,876,699	142.2
Z_2	0	0	0	0	0	0	0
Z_3	0	0	0	1960	55,160	55,160	3.4

Table 18. Ideal and anti-ideal values and weights for each of the objectives when capacity of suppliers is increased by 50%.

Objective	g_{min}	g_{max}	w	α
Z_1	4,519,550	6,000,000	0.2	0.2
Z_2	13.87	100	0.5	0.5
Z_3	50,000	87,675	0.3	0.3

that although retrofitting buildings before a disaster may require much costs, it can reduce the cost of disaster relief and make significant changes in the number of victims and improve the services for them. In this case, the relief cost is reduced by 41.6% and the best value for the second objective function is obtained. In addition, the coverage objective function is reduced due to the reduction of the established DCs.

• **Increasing the supply capacity**

One way to increase the responsiveness is to alleviate the limitations specific to the supply of relief commodities. This is practically very difficult, if not impossible. However, supply capacity for relief commodities can be increased. Therefore, the case in which the capacity of suppliers is increased by 50% is studied. Some fluctuations in the upper and lower limits of the objective function are shown in Table 18.

According to the results in Table 19, with a 50% increase in supply capacity, unfulfilled demands are decreased. In this case, the cost is increased by 46.5% and the shortage is reduced by 73.9% compared to the original problem.

• **Adding a DC**

One way to be more responsive is to add a DC. Specifically, there is not any DC in region 5 (South) to set up. Therefore, a DC is set up near one of the ECs, and the impacts on unfulfilled demand are studied. The results are shown in Table 20.

Table 20. Ideal and anti-ideal values and weights for each of the objectives when a DC is added.

Objective	g_{min}	g_{max}	w	α
Z_1	4,541,658	6,000,000	0.2	0.2
Z_2	36.1	100	0.5	0.5
Z_3	50,000	90,825	0.3	0.3

According to the results in Table 21, by setting up a DC near EC 43 in region 5 (South), unfulfilled demand is reduced by 9.5% and coverage is increased by 4.8%. Table 22 compares the values of the original objective functions with those of the situation studied here. The fluctuations are displayed by Δ given by the following equation for the first objective function. The gaps for other objective functions are calculated in a similar way:

$$\begin{aligned} \Delta Z_1^{1-0} &= \frac{z_1^1 - z_1^0}{z_1^0} * 100 \\ &= \frac{14024724 - 10075305}{10075305} * 100 = 39. \end{aligned}$$

Thus, according to Table 22, for the gaps of objectives one and two, “the more negative, the better”; for the gaps of objective three, “the more positive, the better”. By examining these results, the obtained solutions are ranked. The second case in which the buildings are retrofitted before a disaster is the best way to reduce the shortage and cost; however, further time and government support are required. Due to the importance of the second objective, appropriate supply and increasing capacity of the DCs are ranked second. Disregarding the relative importance of the objectives through solving the weightless model is ranked third. Moreover, the last ranked case is the one in which a DC is added. However, by consulting with the experts, it is concluded that the solution that can be easily implemented in the current situation is the last one.

Table 19. Results of the problem when the capacity of suppliers is increased by 50%.

Objective	d^+	d^-	e^+	e^-	y	Value	GAP (%)
Z_1	8,764,904	0	1,480,450	0	6,000,000	14,764,904	226.6
Z_2	0	0	0.19	0	14.06	14.06	1.3
Z_3	0	0	0	0	87,675	87,675	0

Table 21. Results of the problem when a DC is added.

Objective	d^+	d^-	e^+	e^-	y	Value	GAP (%)
Z_1	4,155,496	0	1,458,342	0	6,000,000	10,155,496	123.6
Z_2	0	0	12.73	0	48.83	48.83	35.2
Z_3	0	0	0	0	90,825	90,825	0

Table 22. Comparing the number of the main objective functions with the reviewed problem.

	Sensitive 1	Sensitive 2	Sensitive 3	Sensitive 4
ΔZ_1	39.1	-41.6	46.5	0.7
ΔZ_2	-33	-100	-73.9	-9.5
ΔZ_3	1.2	-36.3	1.2	4.8

7. Conclusions

Logistics planning is one of the most important activities in the response phase of relief chain management, and a coherent plan can increase the efficiency and responsiveness when dealing with a disaster. In order to reduce casualties, as the main objective of the relief logistics, the right amount of commodities in the right locations should be supplied to the victims. Thus, two issues of locating the appropriate places for the ECs and supplying the required relief commodities should be considered in an optimal relief plan. In this paper, three objectives of cost, responsiveness, and coverage were considered by a multi-objective model to locate the DCs and ECs and allocate relief commodities to the ECs. The model was solved utilizing a multi-choice goal programming method. Moreover, to validate the model, a study of an earthquake logistics network was conducted, and the results showed the significance of the addressed problem. This model provided a scenario-based robust optimization model to balanced costs, equity, and responsiveness in different situations. It is recommended to perform the relief logistics planning based on the structure of each region. According to the results, retrofitting the buildings in different regions before the disaster is one of the best ways to reduce the shortage and costs in a disaster.

The following suggestions can be conducted in the future along with the proposed problem:

1. Considering routing problem for disaster relief logistics between the DCs and ECs;
2. Considering the reliability of the DCs and ECs;
3. Modeling the request for a quicker response in the regions with higher priorities;
4. Designing and implementing a meta-heuristic algorithm for the large-scale problems.

One of the major problems that prevents the real-time relief after a disaster is the destruction of routes,

especially the related ways between relief facility centers. In this situation, routes that are more reliable can be identified and retrofitted before a disaster. Another suggestion in this paper is to increase the reliability of the selected centers. Each of the selected centers, according to criteria such as the age of the building and the quality of the building, has different degrees of access and resistance to the disaster. Further, its impact on different scenarios should be evaluated, and decisions on the construction of new centers or reconstruction of these centers can be made. Hence, the reliability and accessibility of these centers increases during a disaster. Minimum responsiveness level is another suggestion for future research. Considering the minimum percentage of responding to demands is of particular importance, which can be distinguished for the various commodities.

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