

Differentially Private Release of Synthetic Graphs

Marek Eliáš

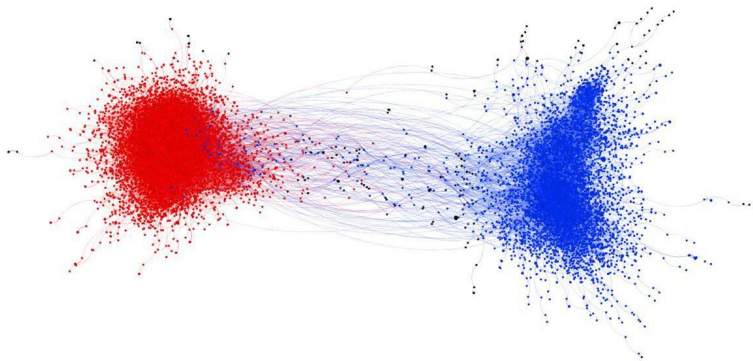
EPFL

Joint work with

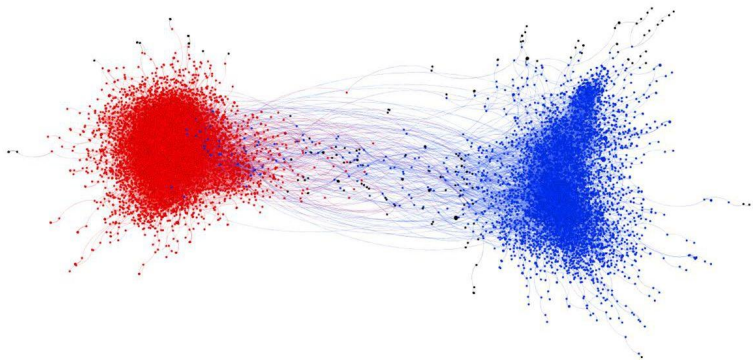
Michael Kapralov, Janardhan Kulkarni, Yin Tat Lee



Private network analysis



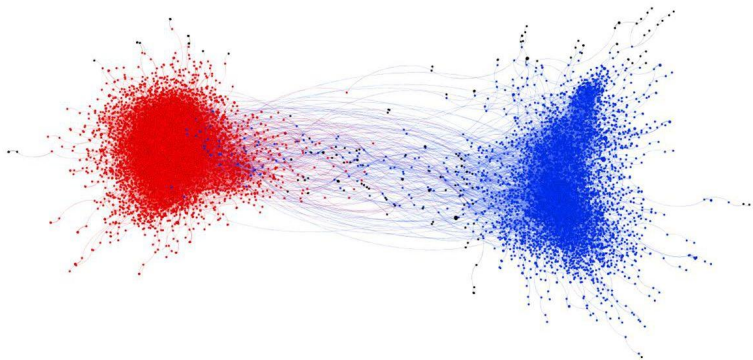
Private network analysis



Social networks:

- ▶ contain valuable information about our societies
- ▶ stability of the society, information spread

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Network analysis in a private manner?

A synthetic graph approximating all cuts

Input:

- ▶ graph $G(V, E)$ with edge-weights w

Output:

- ▶ differentially private graph \tilde{G} with weights \tilde{w}
- ▶ for any $I, J \subset V$: $\tilde{w}(I, J) \approx w(I, J)$
 - ▶ i.e., preserving weight of (I, J) -cuts

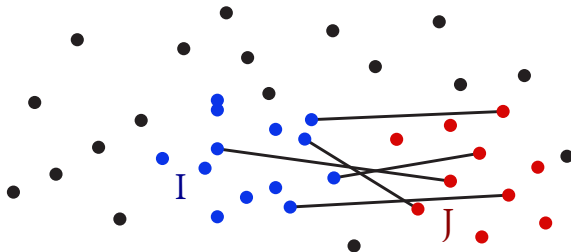
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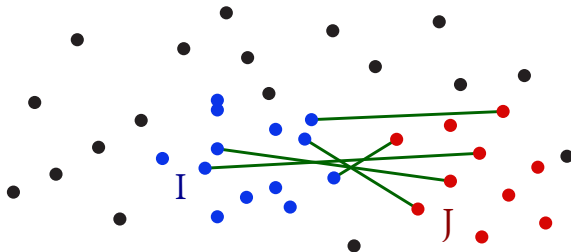
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We can analyze \tilde{G} using traditional tools

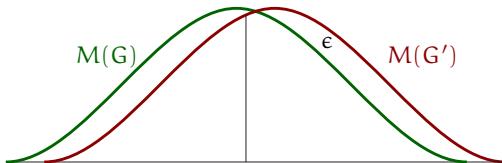
- ▶ we need to keep in mind the error guarantee

Differential privacy: definition

ϵ -Differential privacy:

- ▶ randomized mechanism $M: \mathcal{G} \rightarrow \mathcal{G}$
- ▶ for any pair of neighboring graphs $G, G' \in \mathcal{G}$
 - ▶ G and G' differ in a single edge: $\|w - w'\|_1 \leq 1$
 - ▶ (edge-level privacy)
- ▶ for any $S \subseteq \mathcal{G}$

$$\mathbb{P}(M(G) \in S) \leq \exp(\epsilon) \cdot \mathbb{P}(M(G') \in S)$$



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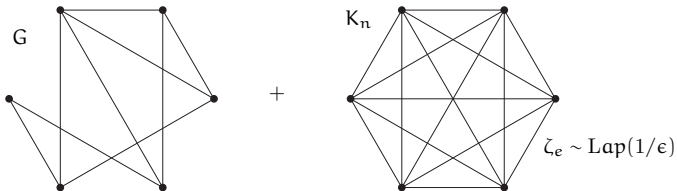
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(ϵ, δ) -Differential privacy:

$$\mathbb{P}(M(G) \in S) \leq \exp(\epsilon) \cdot \mathbb{P}(M(G') \in S) + \delta$$

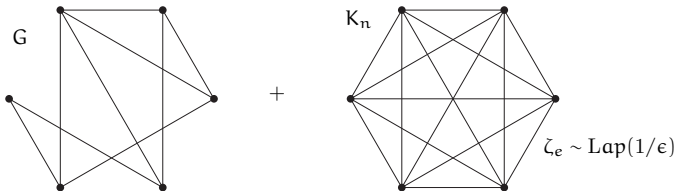
Randomized response

- ▶ Gupta, Roth, Ullman'12
- ▶ $w'_e = w_e + \zeta_e$, where $\zeta_e \sim \text{Lap}(1/\epsilon)$ i.i.d.
- ▶ additive error: $O(n^{3/2})$
- ▶ useful only for graphs with $\gg n^{3/2}$ edges



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Other results

- ▶ Blocki, Blum, Datta, Sheffet '12; Upadhyay '13

Exponential mechanism: Naïve version

- ▶ score $\Theta(\exp(n^2))$ possible output graphs by their error
- ▶ return a sample from this distribution
- ▶ error proportional to n^2

¹Only for cuts of type $(S, V \setminus S)$

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Exponential mechanism: Improved version

- ▶ fundamental result: existence of sparsifiers
 - ▶ preserve cut sizes¹ with a small multiplicative error
 - ▶ number of edges: $O(n)$

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Exponential mechanism: Improved version

- ▶ fundamental result: existence of sparsifiers
 - ▶ preserve cut sizes¹ with a small multiplicative error
 - ▶ number of edges: $O(n)$
 - ▶ only $\exp(O(n \log n))$ possible sparsifiers!
- ▶ additive error: $n \log n$, multiplicative error due to sparsification
- ▶ Drawback: exponential time!

¹Only for cuts of type $(S, V \setminus S)$

Our result

- ▶ polynomial-time mechanism

Input:

- ▶ graph G^* s.t. $\sum_e w_e^* = m$

Output:

- ▶ (ϵ, δ) -DP synthetic graph G with weights w
- ▶ with probability $(1 - \gamma)$:
 - ▶ for all $I, J \subset V$: $|w(I, J) - w^*(I, J)| \leq \tilde{O}(\sqrt{mn})$
- ▶ i.e. purely additive error

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Lower bounds for purely additive error

$$\Omega(\sqrt{mn/\epsilon})$$

Should we use sparsification?

Algorithm by Spielman and Srivastava

- ▶ sample edges by their effective resistance
- ▶ number of edges: $O(\alpha^{-2} n \log n)$
- ▶ multiplicative error: $(1 + \alpha)$

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Problem:

- ▶ only existing edges are sampled
- ▶ edge e in the output $\Rightarrow e$ was present in the input!
- ▶ not private

Our approach

Find cut approximator using convex optimization

- ▶ mirror descent
- ▶ iterative technique
- ▶ we can choose target precision

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Bound the total privacy

- ▶ Advanced composition theorem

Cut norm

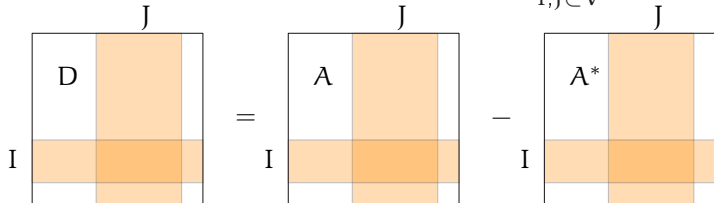
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Cut norm:

$$\|D\|_{\text{cut}} = \max \{ |x_I^T D x_J|; x_I, x_J \in \{0, 1\}^n \} = \max_{I, J \subseteq V} |w(I, J) - w^*(I, J)|$$

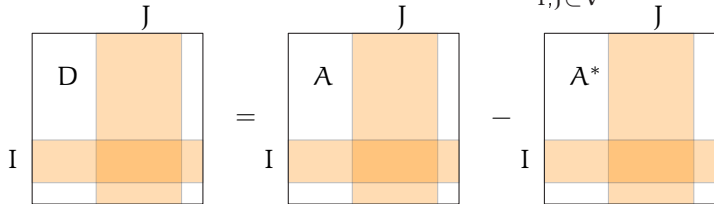


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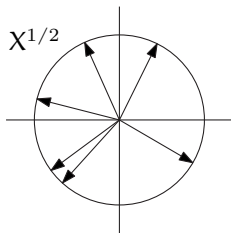
- ▶ G approximates all cuts of G^* with additive error $\leq \|D\|_{\text{cut}}$

Convex objective

Grothendieck problem:

$$F(D) = \max \left\{ \begin{pmatrix} 0 & D \\ D & 0 \end{pmatrix} \bullet X; \quad X \text{ is symmetric, } X \succeq 0, X_{ii} = 1 \forall i \right\}$$

- ▶ constant-factor approximation of $\|D\|_{\text{cut}}$ [Alon, Naor '06]
- ▶ $X_{i,j} \in [-1, 1]$ for each i, j



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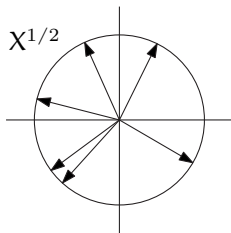
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Properties:

- ▶ $F(D)$ is convex
- ▶ $\nabla F(D) = X^*$
- ▶ $X_{i,j}^* \in [-1, 1]$ for each i, j



Minimization problem

Optimization problem:

$$\min \left\{ F(\mathcal{A}(w) - \mathcal{A}^*); \sum_e w_e = m \right\}$$

- ▶ minimization of convex function
- ▶ bounded gradient: $(\nabla F(\mathcal{D}))_{i,j} \in [-1, 1]$

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Mirror descent theorem:

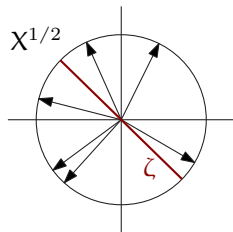
- ▶ after $T = m/n$ iterations:

$$F(A(w) - A^*) \leq \tilde{O}(\sqrt{mn})$$

Stochastic gradient

Stochastic gradient: JL transform

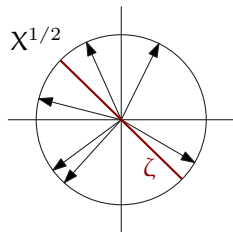
- ▶ release $X^{1/2}\zeta$, where $\zeta \sim N(0, I)$
- ▶ stochastic gradient: $S_X = X^{1/2}\zeta\zeta^T X^{1/2}$
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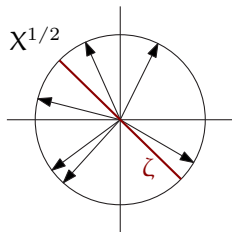
Privacy of the gradient at iteration t:

$$X = \nabla F(\mathbf{A}(w^{(t)}) - \mathbf{A}^*) \text{ and } \tilde{X} = \nabla F(\mathbf{A}(w^{(t)}) - \tilde{\mathbf{A}}^*)$$

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- ▶ $X^{1/2}\zeta$ and $\tilde{X}^{1/2}\zeta$ have similar distribution:

$$\text{pdf}_X(x) \leq e^{\epsilon_0} \cdot \text{pdf}_{\tilde{X}}(x) \text{ w.p. } (1 - \delta_0)$$

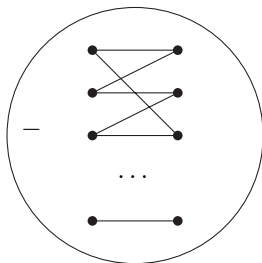
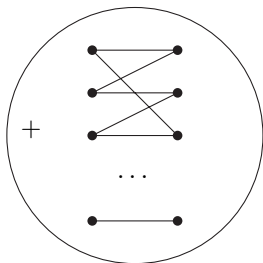
$$\epsilon_0 = O\left(\log \frac{1}{\delta_0}\right) \cdot \sqrt{\text{tr} X^{-1}(\tilde{X} - X)X^{-1}(\tilde{X} - X)}$$

- ▶ this implies that S_X is (ϵ_0, δ_0) -DP

How stable is ∇F ?

Maximizer of cut norm can change abruptly

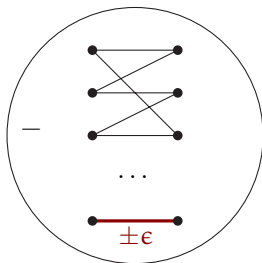
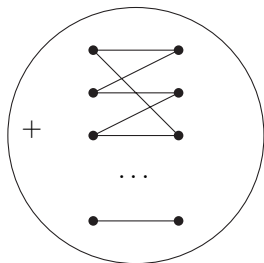
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Regularization

$$F(D) = \max \left\{ \begin{pmatrix} 0 & D \\ D & 0 \end{pmatrix} \bullet X + \Psi(X); \quad X \text{ is symmetric, } X \succeq 0, X_{ii} = 1 \right\}$$

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Why this regularizer?

- ▶ second directional derivative:

$$D^2\Psi(X)[E, E] = -\lambda \operatorname{tr} X^{-1} E X^{-1} E$$

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Claim:

- ▶ If A^* and \tilde{A}^* differ in a single edge, then

$$\sqrt{\operatorname{tr} X^{-1} (\tilde{X} - X) X^{-1} (\tilde{X} - X)} \leq O(1/\lambda)$$

Summing up

To get (ϵ, δ) -DP:

- ▶ we choose

$$\lambda \approx \epsilon^{-1} \sqrt{m/n}$$

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- ▶ using $T = m/n$ iterations of mirror descent
- ▶ privacy (by Advanced composition thm): $\frac{1}{\lambda} \sqrt{T} = \epsilon$
- ▶ error due to low number of iterations: $\tilde{O}(\sqrt{mn})$
- ▶ error due to regularization: $\lambda n \log n \leq \tilde{O}(\epsilon^{-1} \sqrt{mn})$

For (ϵ, δ) -DP mechanism M

- ▶ for $G \sim G(n, p)$,
- ▶ M cannot answer all (I, J) -cut queries with error below

$$\Omega(\sqrt{mn/\epsilon} \cdot (1 - c))$$

- ▶ connection to discrepancy by Muthukrishnan and Nikolov '12
- ▶ evaluating cut sizes is a linear function:
 - ▶ $C \in \mathbb{R}^{2^{2n} \times \binom{n}{2}}$, rows are indicator vectors of cuts
 - ▶ Cw evaluates weights of all the cuts
- ▶ error is bounded from below by (a variant of) discrepancy of C

Matching the guarantee of the exponential mechanism

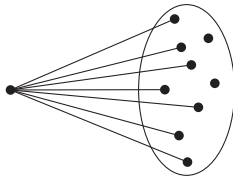
- ▶ multiplicative error $(1 + \eta)$, additive error $O(n \log n)$
- ▶ in polynomial time?

Open problems

Matching the guarantee of the exponential mechanism

- ▶ multiplicative error $(1 + \eta)$, additive error $O(n \log n)$
- ▶ in polynomial time?

Node level privacy



- ▶ neighboring graphs differ in whole vertex neighborhoods
- ▶ any upper or lower bounds?

Questions?



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