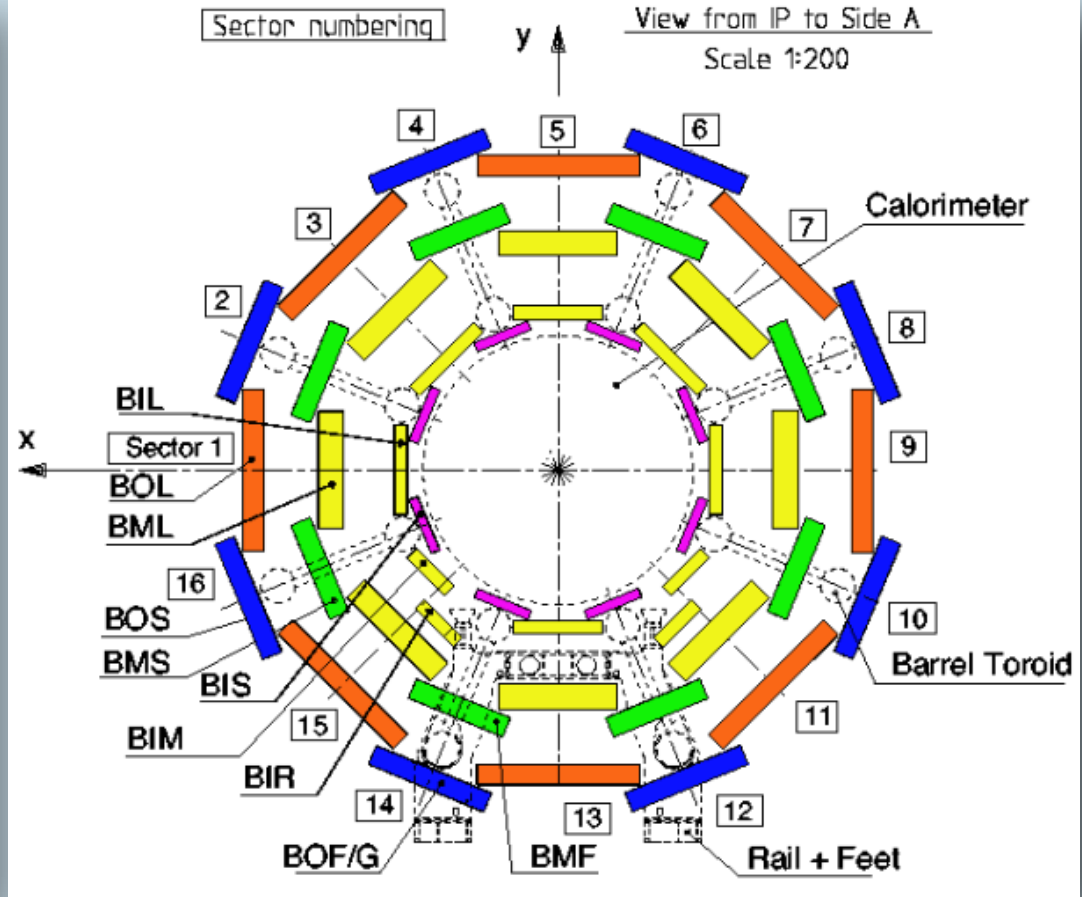
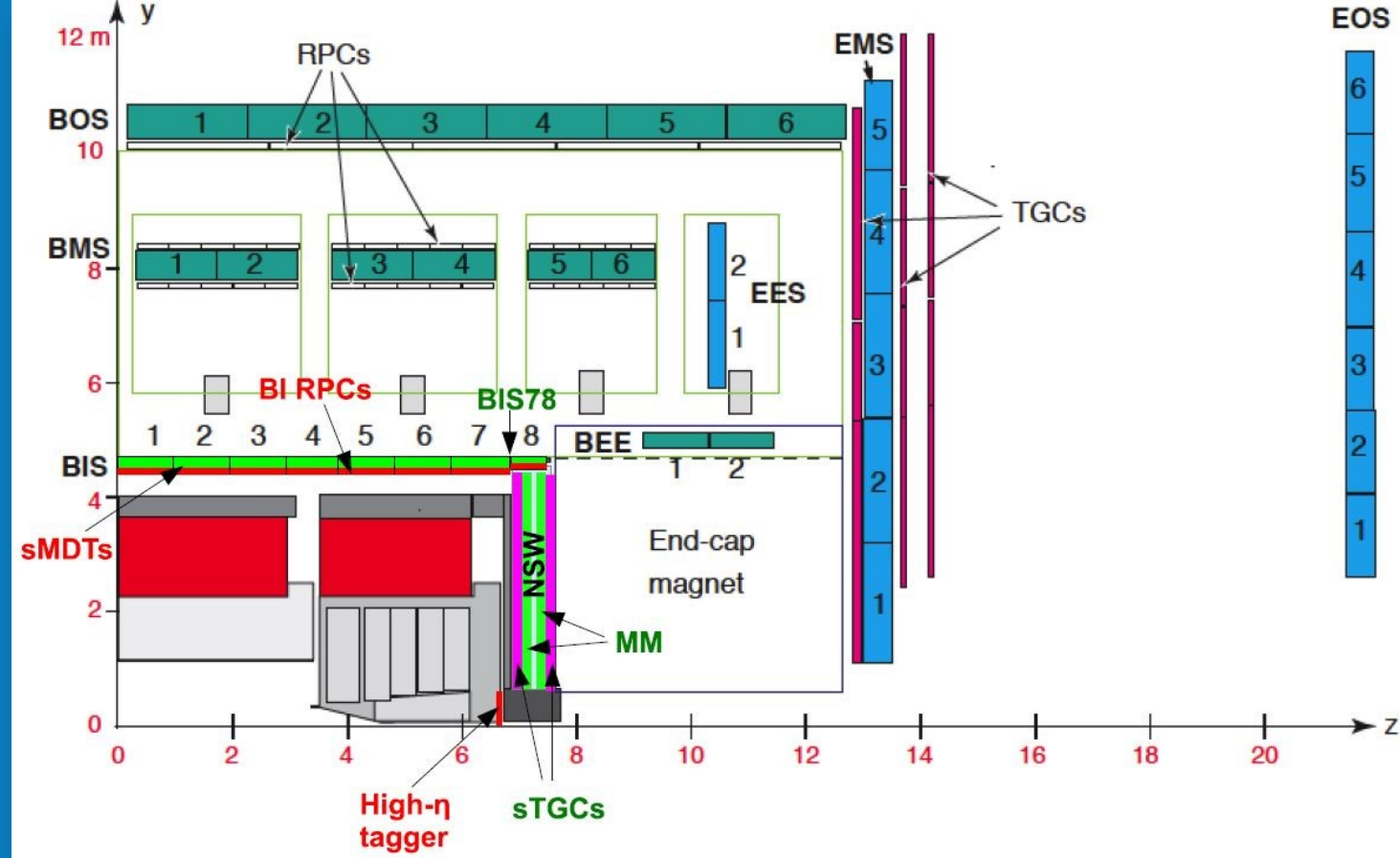
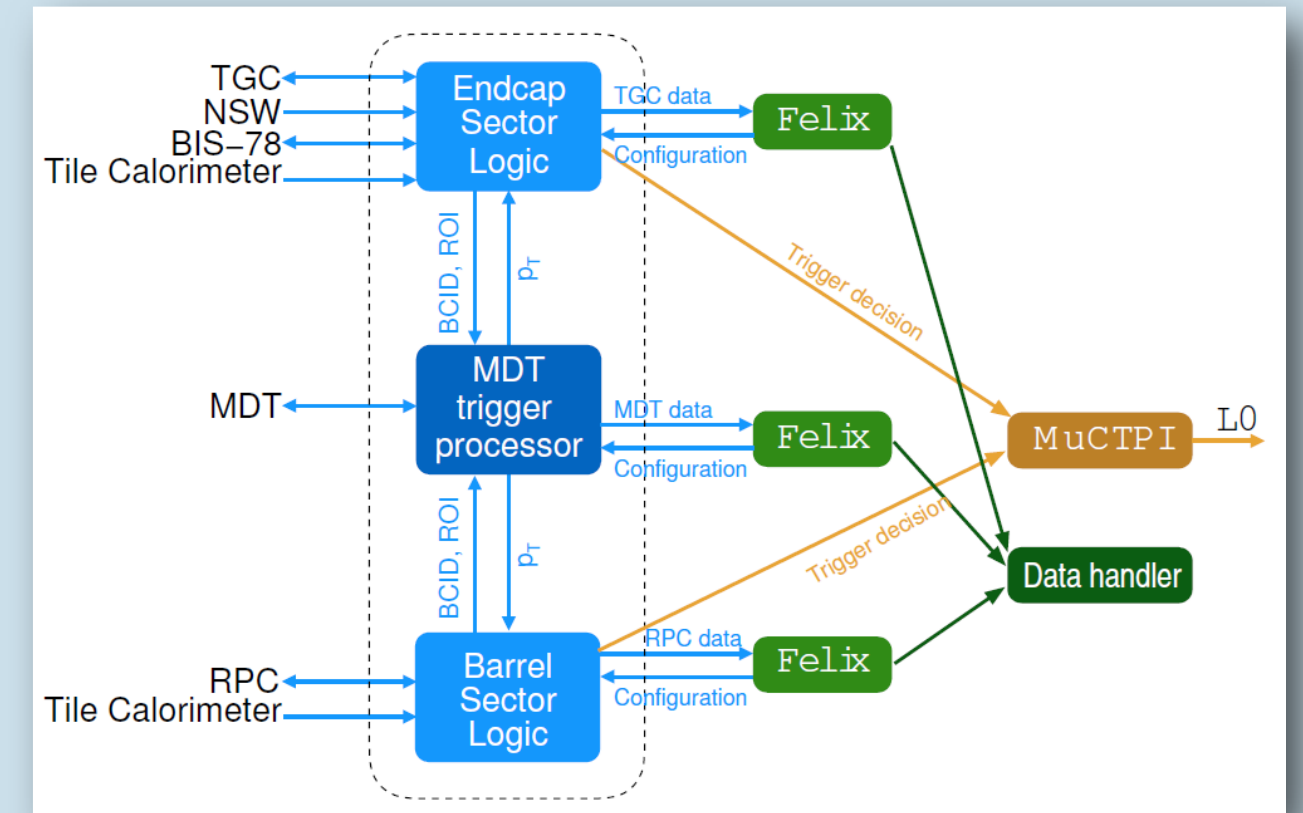


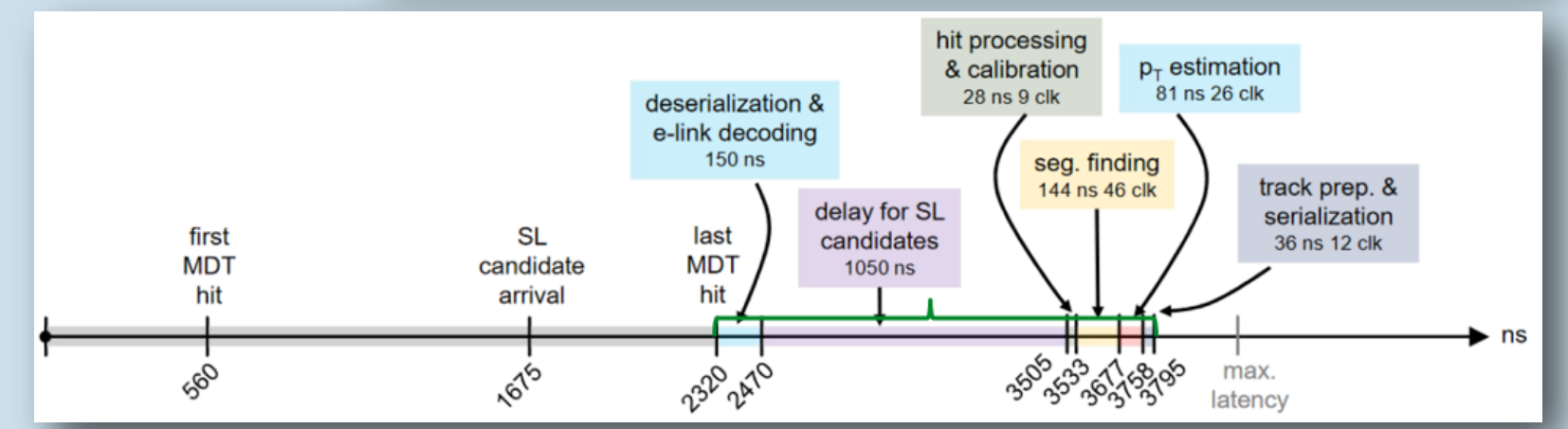
Motivation & Main Characteristics

The new **first-level muon trigger (LOMuon)** of the ATLAS experiment will be upgraded to operate in the substantially increased luminosity environment of the **HL-LHC**. The selectivity of the current system is limited by the moderate spatial resolution of **Resistive Plate Chambers (RPC)** and **Thin Gap Chambers (TGC)** trigger chambers.

- The upgrade will make use of the high-resolution tracking capabilities of the **Monitored Drift Tubes (MDT)**.
- Improvement in the sharpness of the muon trigger efficiency turn-on curves with the new improved p_T resolution.



- **64 MDT Trigger Processor (MDT-TP) boards**, one per sector: **16 sectors** in phi for, **2 regions** (barrel and endcap) and 2 sides.
- Each sector, side and region is divided in **3 stations**.
- The MDT-TP also provides the means to **read out the hits on the MDT chambers**. In addition to the trigger and readout, the MDT-TP is responsible for **configuring the MDT front-end electronics**.
- **Fixed latency of 1.764μs** in response to the incoming muon trigger candidate.



MDT-TP Hardware

Based on open-source **Apollo platform**[1], comprised of two PCB modules:

Service Module (SM): common to all Apollo applications.

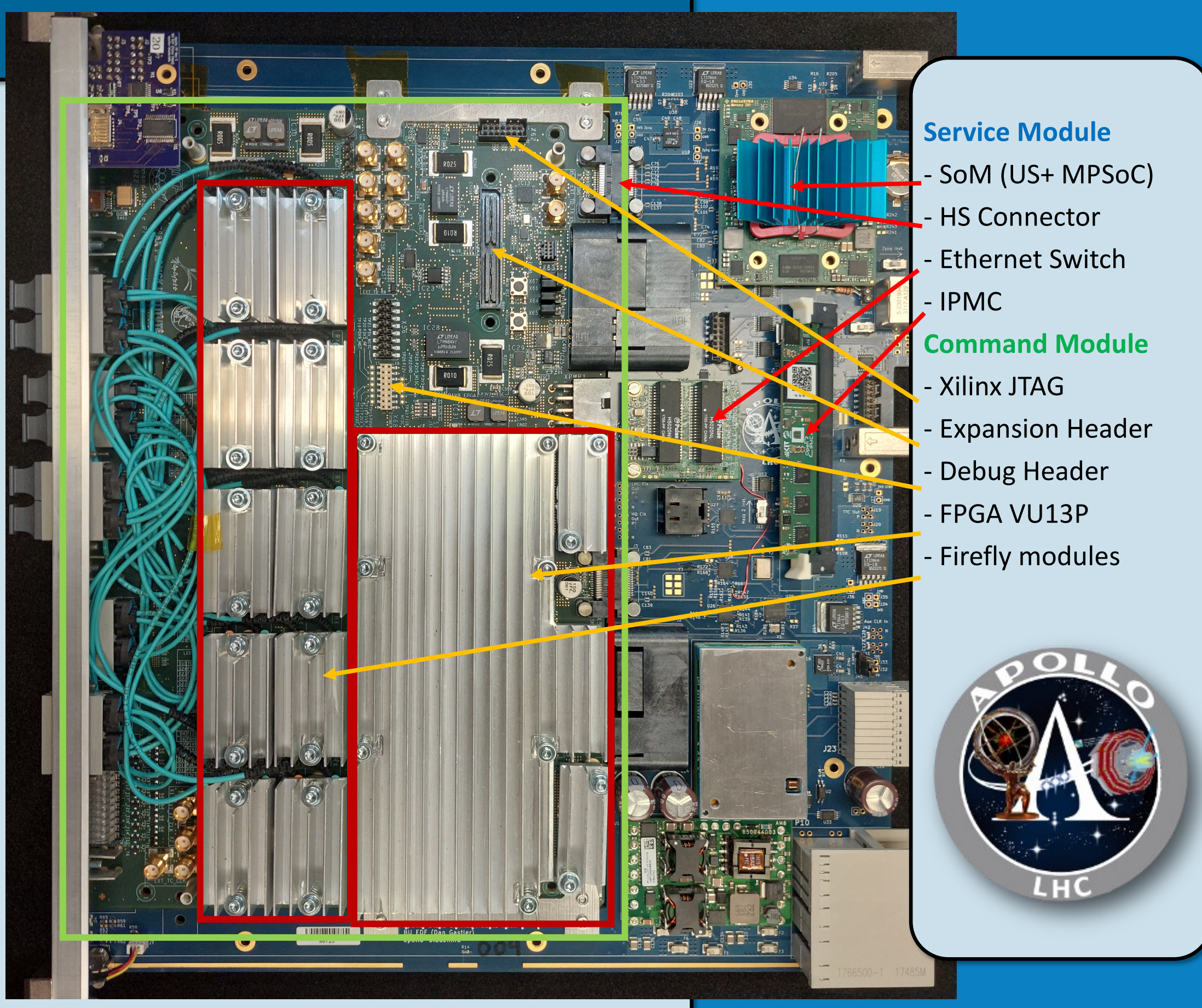
- provides **ATCA Intelligent Platform Management Controller (IPMC)**.
- **power** entry and conditioning.
- powerful system-on-module (**SoM**) computer, Enclustra Mercury+.
- **flexible clock and communications infrastructure**.

Command Module (CM): application-specific module, provides the processing FPGA.

- Optical Transceivers for communication with other ATLAS systems.

CM production:

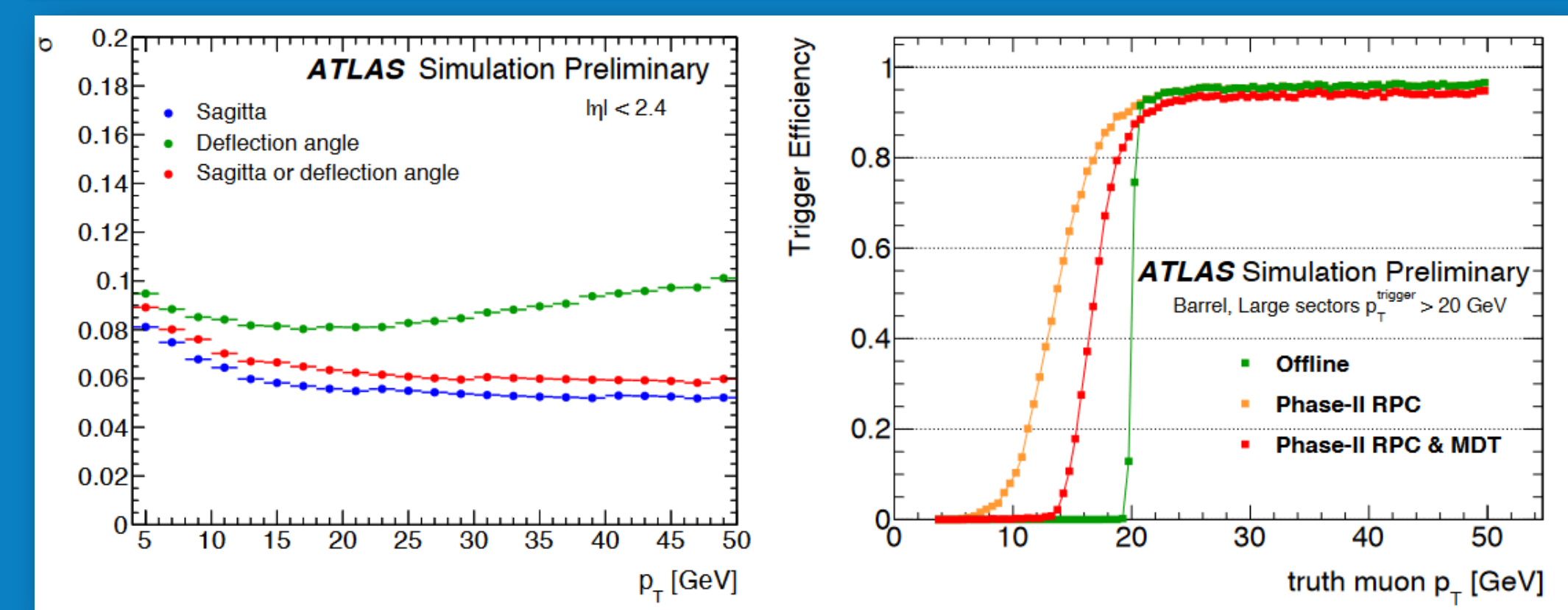
- **4 Demonstrators** (KU15p & ZU11EG) for technology and capabilities validation.
- **2 Prototypes** (VU13P) which are currently being integrated and tested to validate the design.



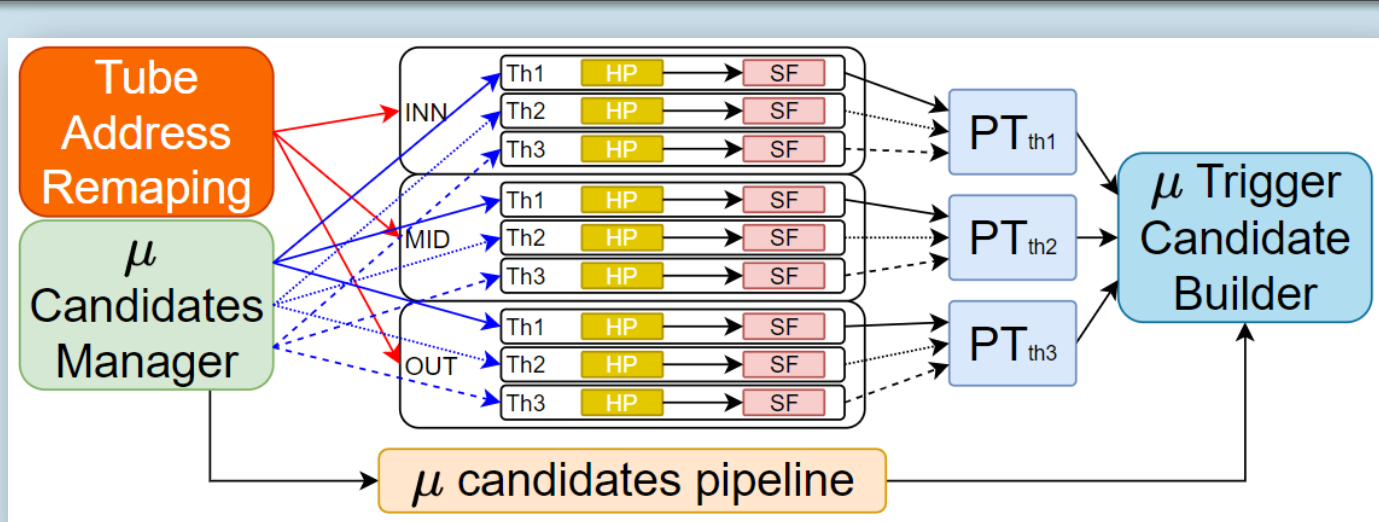
Performance[2]

The MDT-TP trigger algorithm will:

- help to **reject fake SL candidates**.
- increase the momentum resolution.
- **Reduce the output rate ~50-70%** while keeping high efficiency for muons with momenta above the 20 GeV threshold.



Algorithm (Trigger & DAQ)



Trigger path:

- capable of processing 3 simultaneous candidates.
- candidates received while system is busy are ignored.

1a. Tube Address Remapping (TAR)

- MDT hits coordinates are calculated.
- pipelined waiting for the candidate to arrive.

1b. Muon Candidate Manager (UCM)

- **sorts the candidates** from the **Sector Logic (SL)**.
- manages the multithreaded architecture.
- **processes** the candidates to obtain the track angle and crossing position at each MDT station from the **SL RPC/TGC seeds**.

2. Hit Processor (HP):

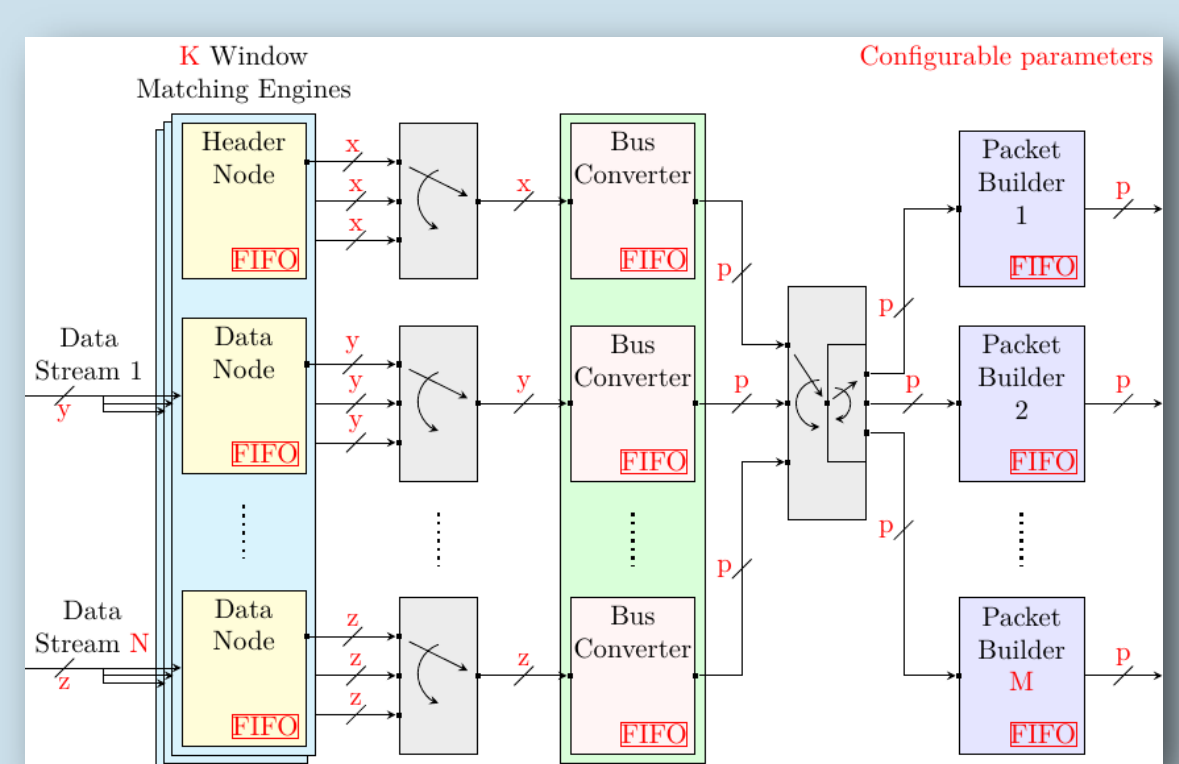
- Filters the MDT hits in space and time using the candidate information to define the boundaries of the filters.
- The valid hits are then processed to obtain their drift radius
- Calculates local position of the tube respect the ROI Z window origin.

3. Segment Finder (SF):

- calculates the segment at each station.
- sends the position and angle to the momentum estimation block.
- Two different implementations are available with different algorithms: **Legendre Transform SF (CSF)** and **Compact SF (CSF)**.

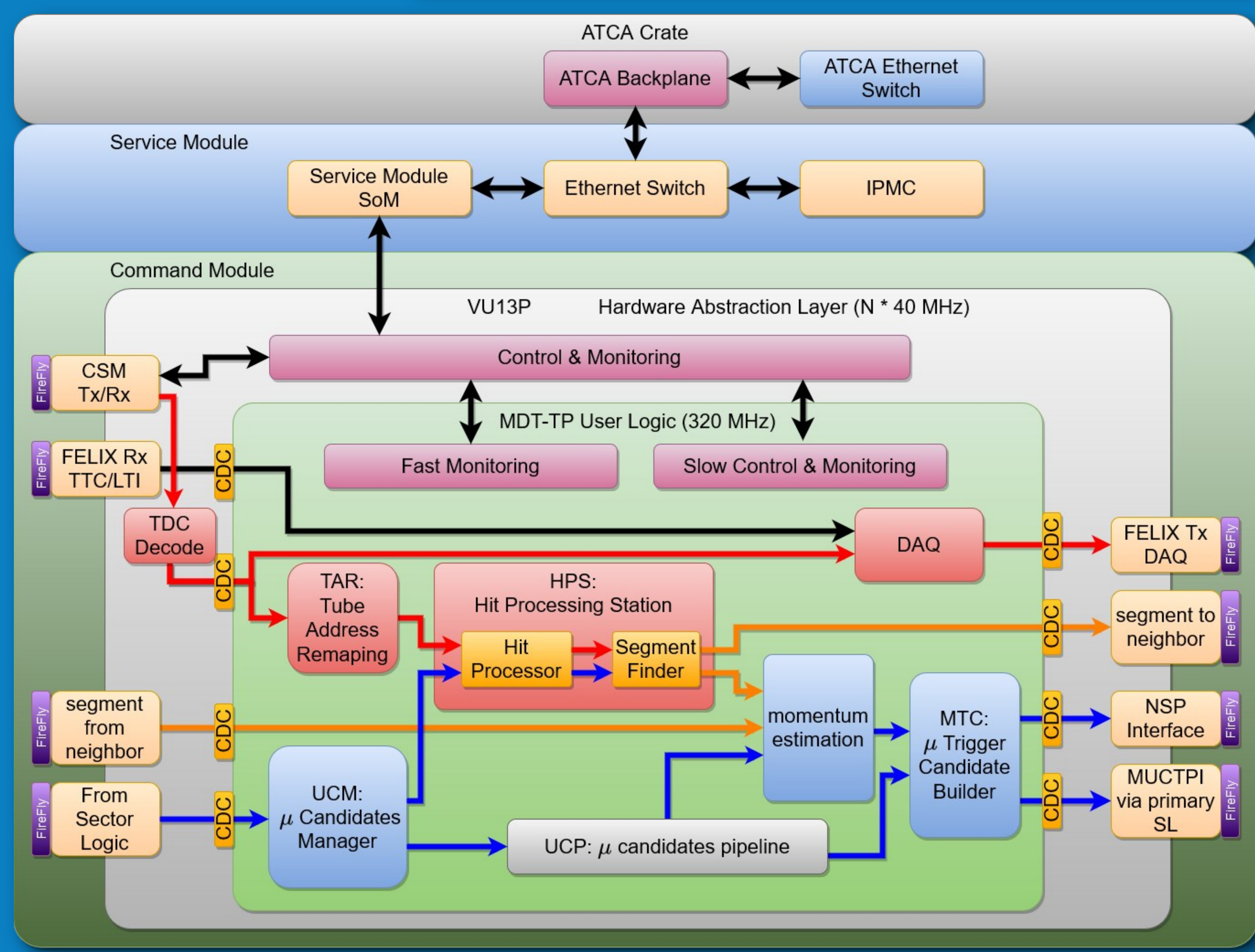
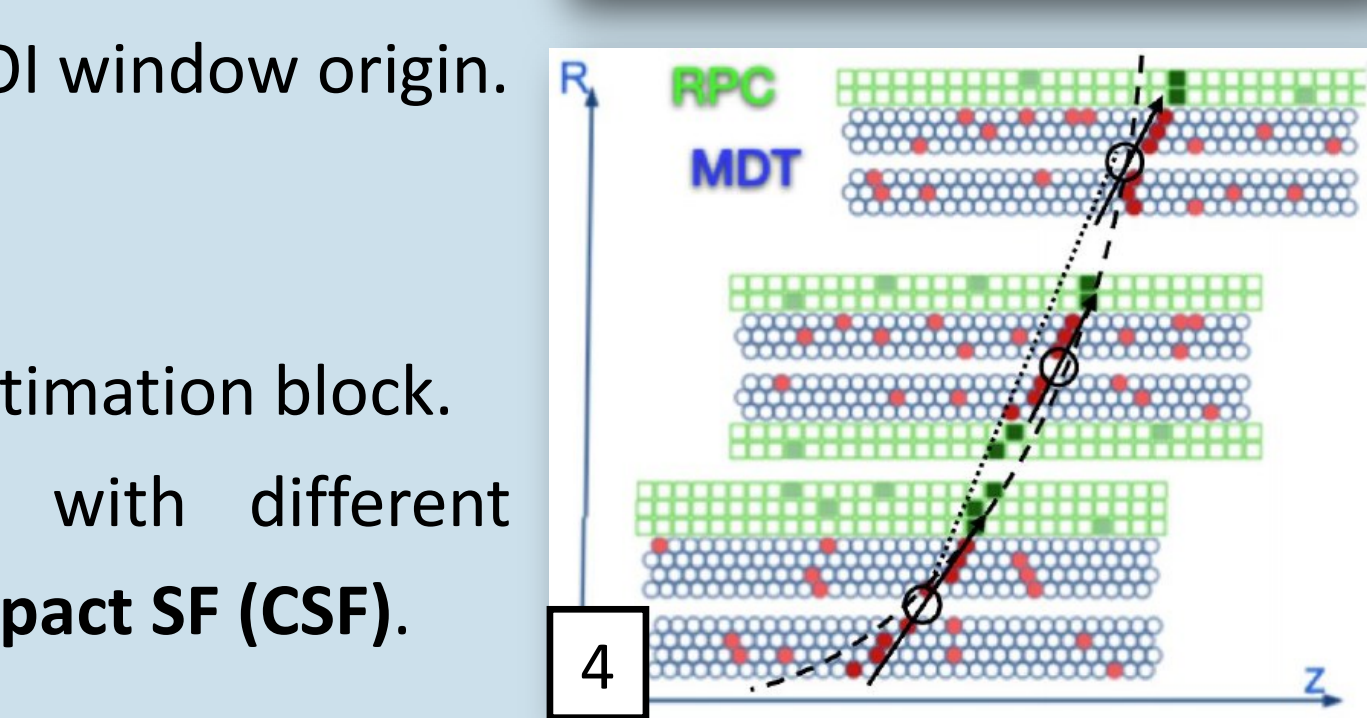
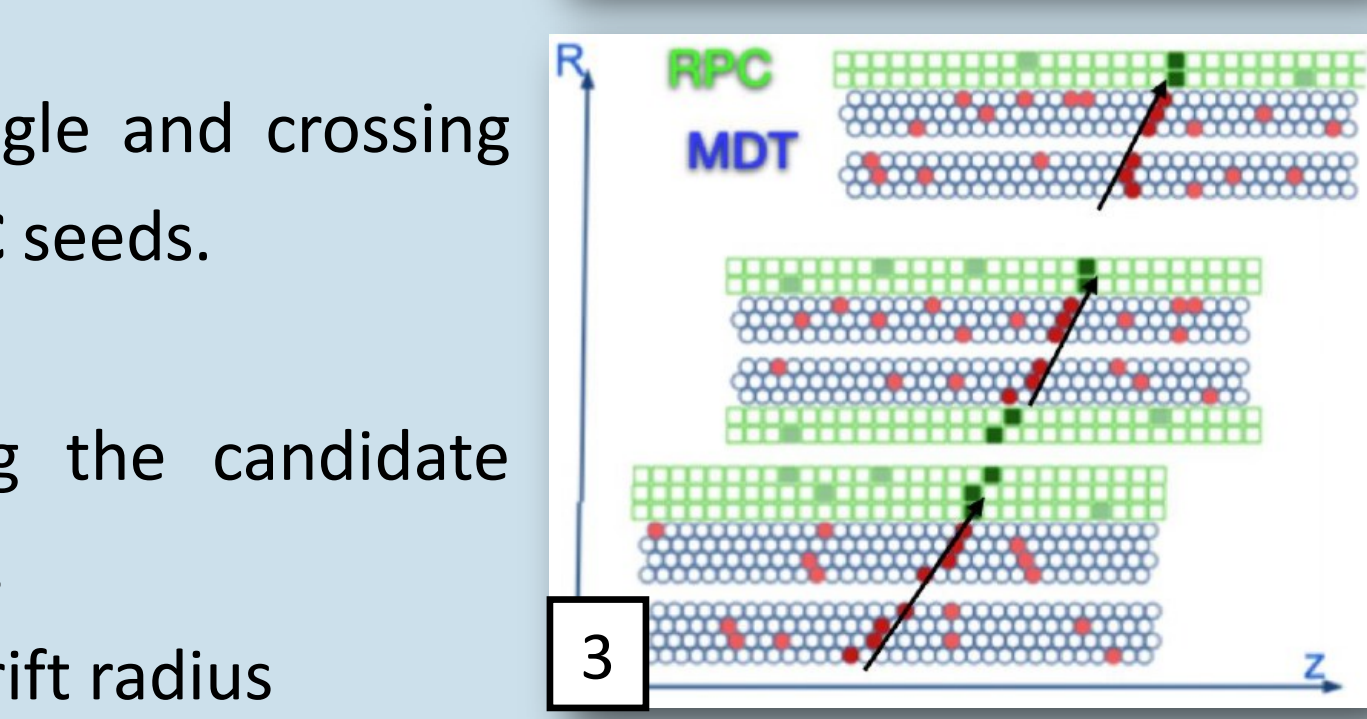
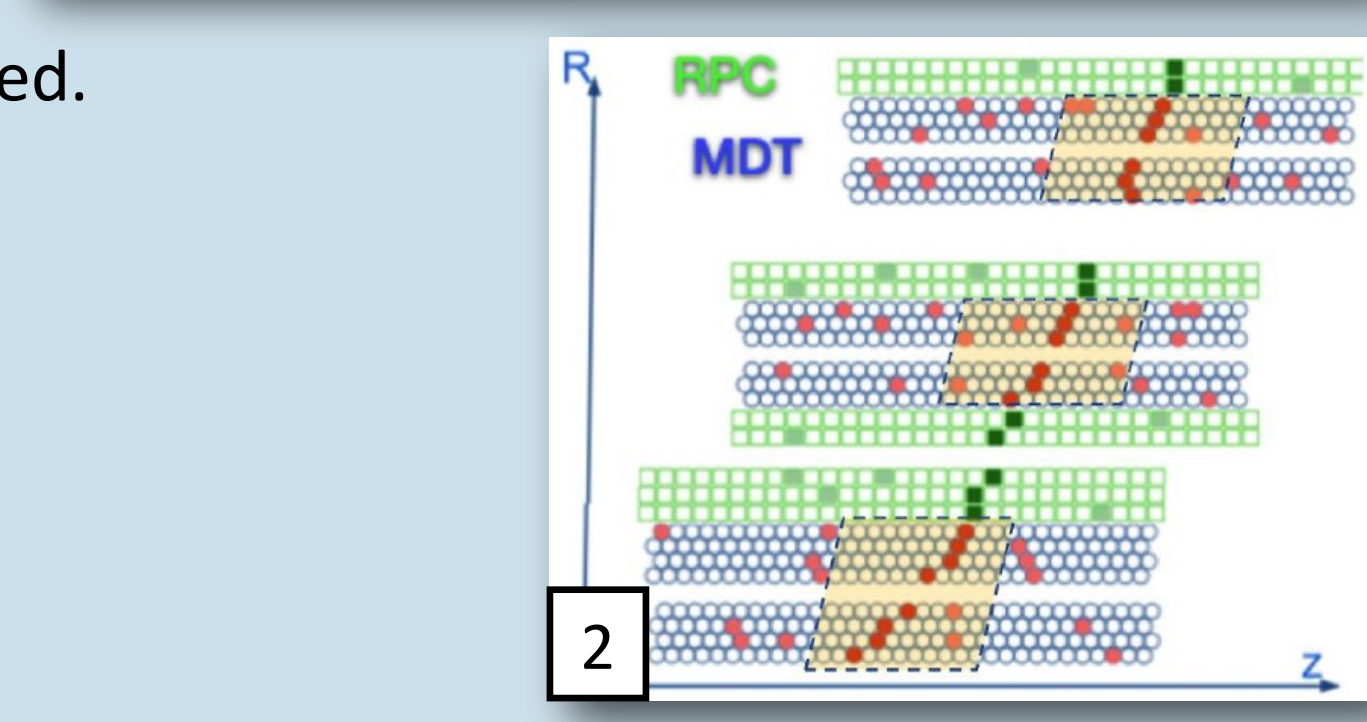
4. pT estimator:

- muon track segments are combined to obtain the track momentum.
- Two algorithms used depending on number of available segments: when **3 segments Sagitta** algorithm and when **2 segments the deflection angle**.



DAQ Level-0/1 Accept module:

- parametrizable and flexible concurrent timestamp-based data selection and packet formatting.
- For each station of the MDT-TP project it is configured with 1 data stream, 4 output links, and 32 simultaneous searches.



Status of Developments

Firmware

- All firmware blocks are developed and being debugged, tested and validated.
- Validation done with VHDL testbench & cocoTB framework.
- Continuous integration of Firmware is implemented using **Hog (HDL-on-Git)**[3].
- Algorithm resources are within parameters.
- Progress to complete integration of FW blocks and meet timing.
- Integrating control & monitoring blocks, including fast monitoring system, to spy the internal buses and perform playback tests.

Hardware

- Prototype being tested, including optical links, SM-CM C2C, etc.
- Integration with others systems in progress.

Software on Service Module SoM

- LO MDT services as core of board operations, control and monitoring is being developed.
- Core elements in place to help testing.
- Integration of external systems as Run Control & DCS in progress.

First FELIX computers with Phase 2 FELIX [4] prototypes cards expected soon to start integration. Test stands at institutes and CERN ready and working.

