

13 October 2022 (v3, 18 October 2022)

Trigger-less readout and unbiased data quality monitoring of the CMS Drift Tubes muon detector

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Abstract

The CMS experiment 40MHz data scouting project is aimed at intercepting the data produced at the level of the detectors' front-end without the filters induced by hardware-based triggers. A first implementation is realized by the trigger-less reading and processing of a fraction of the Drift Tube (DT) muon detector, equipped with a preliminary version of the so-called Phase-2 Upgrade on-detector electronics boards. The data are transferred via high-speed optical links to back-end boards independently from the central experiment data acquisition (DAQ), permitting real-time detector status monitoring via receiving all the signals produced at the front-end level, and providing an unbiased estimate of the CMS DT hit-rate under various data-taking conditions.

Presented at TWEPP2022 Topical Workshop of Electronics for Particle Physics

- 1 PREPARED FOR SUBMISSION TO JINST
- ² TOPICAL WORKSHOP ON ELECTRONICS FOR PARTICLE PHYSICS
- 3 19-23 September, 2022
- 4 BERGEN, NORWAY

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ABSTRACT: The CMS experiment 40MHz data scouting project is aimed at intercepting the data 13 produced at the level of the detectors' front-end without the filters induced by hardware-based 14 triggers. A first implementation is realized by the trigger-less reading and processing of a fraction 15 of the Drift Tube (DT) muon detector, equipped with a preliminary version of the so-called Phase-2 16 Upgrade on-detector electronics boards. The data are transferred via high-speed optical links to 17 back-end boards independently from the central experiment data acquisition (DAQ), permitting 18 real-time detector status monitoring via receiving all the signals produced at the front-end level, 19 and providing an unbiased estimate of the CMS DT hit-rate under various data-taking conditions. 20

21 KEYWORDS: Data acquisition concepts, Trigger concepts and systems (hardware and software),

22 Data processing methods

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³⁰ 1 Trigger and detector data scouting at CMS

The High-Luminosity phase of the Large Hadron Collider (HL-LHC), currently planned to be 31 operational starting in 2029, will see a sizable increase of the instantaneous luminosity delivered 32 to the experiments, $7.5 \times 10^{34} \,\mathrm{cm}^{-2} \mathrm{sec}^{-1}$, resulting in an expected pileup of up to 200 inelastic 33 collisions per event. Overall, the HL-LHC is expected to deliver an integrated luminosity of 34 3 ab^{-1} over about twelve years of operation, totaling about ten times the integrated luminosity 35 expected to be collected after the first twelve years of the LHC operations [1]. The Compact 36 Muon Solenoid experiment (CMS) [2] will undergo a major campaign of upgrades (referred to 37 as Phase-2 Upgrade) to cope with the increased luminosity and pileup conditions and to improve 38 the detector performances. The CMS Phase-2 Upgrade will include: a full replacement of the 39 tracking system, along with a track-finder for the Level-1 trigger [3]; the installation of a new timing 40 detector [4] and new high-granularity calorimeter in the endcap region [5]; the replacement of 41 large fractions of the front-end (FE) detector electronics to improve radiation hardness and readout 42 bandwidth; and a new Level-1 trigger based on state-of-the-art FPGAs (field programmable gate 43 array electronics) capable of accepting events at a rate of 750 kHz [6]. While CMS will continue 44 to employ a two stages trigger system, the upgrades in FE electronics and trigger boards will 45 make possible to reconstruct higher-quality physics objects already at the Level-1 hardware trigger 46 level, resulting in resolutions close to the one achieved offline. The CMS 40MHz Level-1 trigger 47 scouting project [7] proposes to use spare optical outputs of Level-1 trigger boards, processing data 48 quasi-online on a set of computing resources without the latency limitations of the Level-1. Several 49 physics studies are expected to benefit from the trigger scouting system data. Notable examples 50 are processes with low trigger efficiencies due to the Level-1 trigger thresholds and rare processes, 51 both of them could benefit from the analysis of the full available statistics. Additional examples 52 include all the topologies where a non-standard reconstruction is required, such as the searches 53 for long-lived particles with lifetimes spanning multiple bunch crossings, as well as appearing- or 54 disappearing-tracks. The upgrades in the detector FE electronics will also allow CMS to extend the 55 scouting project approach, intercepting data as close as possible to the detector FEs, depending on 56

the expected throughput. The 40MHz *data scouting* is an additional CMS project investigating the possibility of collecting and processing the data stream at the level of the detectors' FE before any trigger stage, performing the online reconstruction at full resolution. An additional advantage of the data scouting project is the continuous monitoring and diagnostic of the experiment conditions, based on the totality of the signals produced by the detector without any suppression induced by the trigger chain.

63 2 Data scouting implementation

The first implementation of the 40MHz data scouting has been deployed in CMS in 2022. The Drift 64 Tube (DT) detector sub-system [8] was chosen for the first deployment, as four chambers (MB1 to 65 MB4 of the DT sector 12 of wheel +2) have been instrumented with Phase-2 On-Board DT readout 66 boards (OBDT) [9], performing the Time-to-Digital Conversions of the DT hits time in FPGA with 67 nanosecond resolution. In total, the DT Phase-2 Upgrade demonstrator is equipped with 13 OBDT 68 boards, and 3120 individual channels. The streams of hits produced by the OBDTs are shipped 69 via high-speed optical links using the GBT [10] protocol to back-end (BE) devices, where they are 70 collected and processed in parallel to the standard CMS data acquisition (DAO) and trigger chains. 71 to enable an event-by-event comparison of the legacy and the upgrade demonstrator systems. Two 72 Xilinx KCU1500 development boards, equipped with a Kintex UltraScale XCKU115-2FLVB2104E 73 FPGA, are used as BE devices. Each BE board is equipped with two OSFP transceivers and is 74 capable of receiving up to 8 OBDT input links. The BE boards are installed in a dedicated Dell 75 PowerEdge R730 server using the PCIe Gen3 x8 interfaces on a bifurcated x16 edge connector. 76 The FPGA firmware implements the links deserialization with the GBTx-FPGA protocol [11] and 77 the gearboxing of all links into a single data stream. The data transfers to memory are performed 78 through a Direct Memory Access (DMA) engine via the Advanced eXtensible Interface (AXI) 79 stream protocol over the PCIe Gen 3 bus to avoid burdening the server CPU. The data stream 80 is further continuously transferred to a computing farm where it is processed on-the-fly. Two 81 alternative architectures for the transfer and online processing of data have been designed and 82 implemented. 83

84 2.1 Distributed processing and messaging systems

A first architecture (see Figure 1a) is designed based on the usage of horizontally scalable distributed 85 computing frameworks for both the brokerage and processing of the FE signals. Dask [12] is used as 86 the distributed processing engine to schedule the data reconstruction workload over a set of worker 87 nodes. Apache Kafka [13], a distributed event streaming platform based on a pub-sub messaging 88 model, is used as the data brokerage system to efficiently serve data from the BE units to the Dask 89 worker nodes. In each BE unit, an Apache Kafka producer process continuously polls the server 90 memory and publishes the new data to a remote topic, distributed in several partitions over a cluster 91 of remote broker nodes. The cluster of Dask worker nodes acts as a set of consumers, continuously 92 reading from the Apache Kafka partitions to collect raw data and create distributed data structures. 93 The producer/consumer architecture entirely decouples the writing and reading processes, thus 94 permitting the Dask worker nodes to read and process data independently from the BE readout of 95 the FE data, while using the Apache Kafka brokers as a buffering stage. This processing model is 96

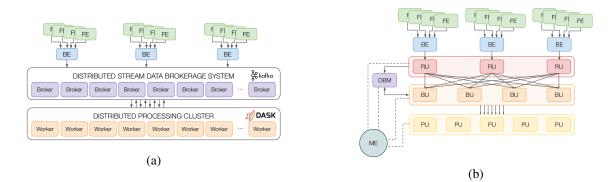


Figure 1: Schematic representations of (a) the distributed processing data scouting architecture and (b) the multistage data scouting architecture. FE: front-end devices; BE: back-end devices; RU: readout units; BU: builder units; PU: processing units; OBM: orbit manager; ME: master entity process.

designed to accommodate the asynchronous nature of the 40MHz data scouting readout and to avoid 97 inducing back-pressure to the earlier stages of the readout chain. Simple aggregated quantities, 98 useful for the monitoring of the detector, are computed directly by exploiting the data-analytic 99 functionalities of the distributed computing framework. An event-building stage is performed in 100 parallel by subdividing the data batches by the LHC Orbit ID (where a LHC orbit corresponds to 101 3564 divisions of 25 ns each). Both the distributed data brokerage and the processing systems have 102 been tested to efficiently scale their performance with the number of computing nodes, as discussed 103 in detail in [14]. 104

105 2.2 Multistage architecture

A multi-stage data aggregation architecture (see Figure 1b) has been developed as an alternative to 106 the distributed cluster-based system. This design is focused on merging data fragments collected 107 by several BE devices to create self-consistent data structures (events), before serving those to the 108 processing units. As the 40MHz data scouting system is continuously and asynchronously collecting 109 data from several FE devices, no event-like structure can be identified before the processing of the 110 collected signals. The LHC orbit identifier is thus used as the main event "key". Several Readout 111 Units (RUs), deployed directly in the servers hosting the BE boards, act as in-memory key-value 112 stores by temporarily caching the collected DT hits into arrays indexed by LHC Orbit ID. A single 113 Orbit Manager process (OBM) performs the bookkeeping of the LHC Orbits IDs available on the 114 entire set of allocated RUs. This is achieved by the RUs by sending a new message to the OBM 115 every time a new Index is created into the RUs cache. Another set of processes is in charge of 116 merging all hits pertaining to a given LHC orbit, stored in the cache of multiple RUs, thus creating 117 a single collection consistent with a given LHC Orbit ID. Each such process, named Builder Unit 118 (BU), is a multi-threaded process interfacing directly with both the Orbit ID list managed by the 119 OBM, and with the RUs to fetch the cache records. Upon completion of the event-building phase, 120 the BUs push the aggregated sets of hits to a number of Processing Units (PUs). The individual 121 PUs are finally the processes performing the analysis of the consistent set of hits, reconstructing 122 all the features corresponding to the passage of the muons through the detector. To control all the 123

other processes (RU, BU, PU, OBM) a Master Entity (ME) process is instantiated. The ME exposes a programming interface acting as the entry point to interact with all the system's components, including the start/stop of data taking, and the collection of the metrics from all processes. In this architecture, all communications both inter- and intra-processes are handled via the ZeroMQ [15] messaging library.

129 **3** Unbiased data quality Monitoring of the CMS DT

The scouting readout is completely opportunistic, as the data can be collected independently from the central DAQ and trigger chain of the experiment. During a scouting data acquisition run, the entire stream of DT hits produced by the FE devices is acquired and processed on-the-fly without any online filter. So far, the system has been already used to collect and process data under several LHC filling scheme conditions. Figure 2 shows the data collected during five minutes of the first LHC collisions of 2022 (LHC fill number 7920). The data highlights both the presence of the two bunches colliding at the LHC Interaction Point 5, as well as the effects of beam halo induced by the passage of non-colliding bunches. The nature of the data collected with this trigger-less

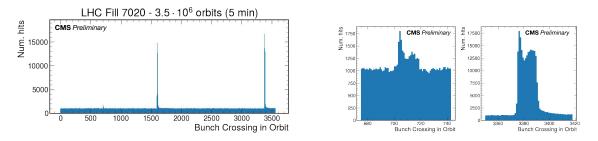


Figure 2: Left: projection of the hits collected during five minutes of the first LHC Fill (7920) in 2022, with three circulating bunches and two colliding at the LHC Interaction Point 5. The counts of all collected hits are projected in bins of bunch crossing within the LHC orbits, highlighting the filling scheme. Right: the hits clustering around colliding and a circulating bunches are shown. The patterns formed by the hits collection times are compatible with the drift time of muons crossing the DT detectors.

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DAQ offers the opportunity to develop data quality monitoring studies based on 100% of the 138 hits produced by the detectors' FE, and completely unbiased thanks to the absence of dedicated 139 trigger selection logic. For instance, the 40MHz data scouting readout will provide CMS with an 140 alternative unbiased monitor of the instantaneous luminosity delivered by the accelerator based on 141 the raw counts of all the detectors' signals. In addition, it can enable the in-situ measurement of the 142 detector occupancy both using the data collected in collisions and outside LHC bunches collisions, 143 as shown in Figure 3. The off-collision data can also be used to perform an unbiased estimation of 144 the detectors' background noise rate, and its evolution with the integrated luminosity. Finally, the 145 trigger-less data scouting opens up the possibility to investigate transient detector effects such as 146 the aftermath of the accelerator dumps, as shown in Figure 4. 147

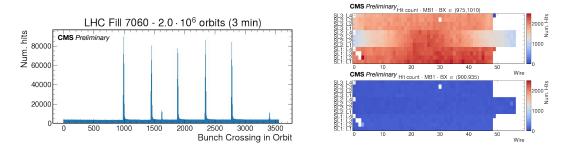


Figure 3: Left: projection of the hits collected during three minutes of the LHC Fill 7960. At the LHC Interaction Point 5, five trains of 12 contiguous bunches (spaced by 25 ns), and two single bunches were provided for collisions. Right: the occupancy of one DT chamber comparing a window of bunch crossings (BX) compatible with the collision of a train of LHC bunches (from BX 975 to 1010) and in a window with no collisions (from BX 900 to 935).

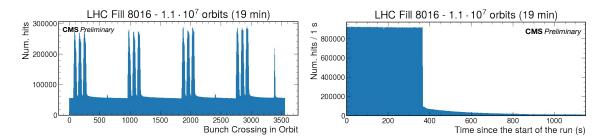


Figure 4: Left: projection of the hits collected during 19 minutes of the LHC Fill 8016. At the LHC Interaction Point 5, 13 trains of 48 contiguous bunches (spaced by 25 ns) and two single bunches were provided for collisions. Right: the number of hits collected per unit of time as a function of the time since the start of the scouting data acquisition run. The LHC Fill 8016 was dumped after about six minutes, and the dump aftermath is visible as a decaying trend of the number of hits collected with time, as the result of the experiment's material activation.

148 4 Summary

The first implementation of the 40MHz data scouting system of the CMS experiment has been 149 presented. The system is designed to read raw data from the front-end of the detector, before 150 the filters of the Level-1 trigger, and with the full detector resolution. Two alternative processing 151 architectures have been implemented to analyze the data stream on-the-fly. The 40MHz data 152 scouting system has been deployed in CMS during 2022, reading the data produced by the Phase-2 153 Upgrade demonstrator of the Drift Tube detector. This system is independent of the central CMS 154 DAQ and trigger systems, not interfering with the operations of the experiment. A number of 155 physics channels currently limited by low trigger efficiency, or the impossibility of performing an 156 online selection within the bounds of bandwidth and latency, are expected to benefit significantly 157 from the sophisticated on-the-fly data analyses. The data scouting system is also going to be an 158 invaluable tool for the live monitoring of the detectors, benefiting from unbiased and unlimited 159 statistics. A preliminary set of data quality monitoring studies have been presented with the first 160 data collected during the early Run-3 operations of the LHC in 2022. 161

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