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Custom real-time ultrasonic instrumentation for simultaneous mixture and flow analysis of binary gases in the CERN ATLAS experiment

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ABSTRACT

Custom ultrasonic instruments have been developed for simultaneous monitoring of binary gas mixture and flow in the ATLAS Inner Detector. Sound transit times are measured in opposite directions in flowing gas. Flow rate and sound velocity are respectively calculated from their difference and average. Gas composition is evaluated in real-time by comparison with a sound velocity/composition database, based on the direct dependence of sound velocity on component concentrations in a mixture at known temperature and pressure. Five devices are integrated into the ATLAS Detector Control System. Three instruments monitor coolant leaks into $N₂$ envelopes of the silicon microstrip and Pixel detectors. Resolutions better than $\pm 2 \times 10^{-5}$ and $\pm 2 \times 10^{-4}$ are seen for C₃F₈ and CO₂ leak concentrations in N₂ respectively. A fourth instrument detects sub-percent levels of air ingress into the C_3F_8 condenser of the new thermosiphon coolant recirculator. Following extensive studies a fifth instrument was built as an angled sound path flowmeter to measure the high returning C₃F₈ vapour flux (\sim 1.2 kgs⁻¹). A precision of $<$ 2.3% FS for flows up to 10 ms⁻¹ was demonstrated. These instruments have many potential applications where continuous binary gas composition measurement is required, including hydrocarbon and anaesthetic gas mixtures.

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1. Introduction

Custom ultrasonic ("sonar") instruments have been developed for the measurement of binary gas mixtures. The instruments are used for continuous real-time flowmetry and leak monitoring for the cooling circuits of the Inner Detector of the ATLAS experiment

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ATLAS is a particle physics detector, consisting of a series of sub-detectors arranged around the proton beam collision point. The ATLAS Inner Detector is used for tracking charged particles, and is situated inside a 2 Tesla solenoidal magnetic field. It comprises silicon pixel and microstrip (SCT) sensors, and a Transition Radiation Tracker. The silicon sensors are maintained at a low temperature to mitigate the effects of radiation damage [\[1](#page-4-0)–[4\]](#page-4-0). The heat from the silicon substrates and their local electronics is evacuated using an evaporative cooling system based on

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Fig. 1. The locations of the ultrasonic instruments and their connecting structures within the ATLAS inner detector and thermosiphon.

octafluoropropane (C_3F_8) [\[5\]](#page-4-0). A new pixel layer, the Insertable B-Layer (IBL), was recently added closest to the beam pipe. The IBL is cooled using a $CO₂$ evaporative cooling system. Three ultrasonic instruments [\[6](#page-4-0)–[8\]](#page-4-0) monitor the nitrogen-purged anti-humidity envelopes of the SCT, Pixel and IBL subdetectors for leaks from their cooling circuits.

A new C_3F_8 thermosiphon circulation system is being commissioned in 2016 [\[9,10\]](#page-4-0) to replace the present compressor-driven system. This utilises the 90 m depth of the ATLAS experimental cavern to generate the hydrostatic pressure needed to circulate the liquid coolant through the on-detector cooling channels, where it evaporates and returns as vapour to an above-ground condenser. Two further ultrasonic instruments directly monitor the thermosiphon; one measures the flow in the ascendent vapour return tube, while another checks for air ingress into the condenser. The positions of the instruments in the ATLAS installation are shown in [Fig. 1](#page-1-0).

In this paper, the principle and design of the ultrasonic instruments are described, along with their various applications in the ATLAS cooling system. Their integration into the Detector Control System (DCS) is also discussed.

2. The instruments

The sonar instruments use transit time and sound velocity measurements to calculate binary gas compositions and flow rate. Composition measurement in a binary gas mixture exploits the relationship between sound velocity and molar composition at known temperature and pressure. This relationship is illustrated for mixtures of C_3F_8 and N_2 at several temperatures in Fig. 2 (see also Section 2.1).

The five installed instruments are based on custom electronics and hardware operating with pairs of 50 kHz capacitive ultrasonic transducers (SensComp model 600) placed within gas enclosures. The transducers operate as transceivers with a DC bias voltage of around +300 V. In transmit mode, they are excited by down-going (300 V–0 V) square-wave pulses generated from a gated LV pulse output of a DSPIC33F microcontroller. The receiving chain has two amplification stages followed by a comparator, also implemented in the microcontroller. Transmission synchronously starts a 40 MHz transit time clock in the microcontroller, which is stopped by the first pulse crossing the user-definable comparator threshold. A mode of operation based on time-of-flight, rather than resonant frequency, is chosen to allow flowmetry in the same electronics.

Synchronous analogue temperature and pressure measurements use a multiplexed ADC implemented in an ANALOG DEVICES

Fig. 2. Examples of the variation of sound velocity with molar concentration of C_3F_8 in N₂ (from the online database) at several temperatures, at a pressure of 1000 mbarabs.

Fig. 3. The ultrasonic flowmeter installed in the C_3F_8 vapour return tube to the thermosiphon condenser. The acoustic path crosses the gas flow at 45°.

 $AD\mu C$ 847 microcontroller. Transit times, temperatures and pressures are averaged, time-stamped and pipelined by a FIFO memory implemented in a dsPIC33F microcontroller for transmission to a SCADA (Supervisory Control and Data Acquisition) computer. Communication uses MODBUS TCP/IP over ethernet, implemented using the MBED LPC1768 platform.

Mixture and flow calculations are made on a DELL POWEREDGE R610 SCADA computer using custom software implemented in SIEMENS SIMATIC WINCC [\[11\]](#page-4-0) running on LINUX. This software allows control of the instruments and archiving of data.

The installed instruments use two different configurations of acoustic path relative to the gas flow direction: co-axial and angled-crossing. Four instruments in co-axial geometry are optimised for binary concentration measurements in static gas or at low flow. The fifth instrument, shown in Fig. 3, has an acoustic path crossing the gas flow at 45°. It is optimised for flowmetry at high C_3F_8 flow speeds of around 22 ms⁻¹, corresponding to mass flow rates of around 1.2 kgs^{-1} .

2.1. Gas composition analysis

Binary gas composition is determined by comparison of the measured sound velocity with a stored database of sound velocity as a function of composition for the gas pairs over a range of temperature and pressure covering the process conditions [\[8\].](#page-4-0)

In an instrument containing either static gas, or where the moving gas fills the entire acoustic path length, L, the sound velocity, v_s , can be determined from the bidirectional transit times t_{up} and t_{down} of the sound pulses as

$$
v_{s} = \frac{2L(t_{\text{up}} + t_{\text{down}})}{4t_{\text{up}}t_{\text{down}}}.
$$
\n(1)

The three aspirating sonars and the degassing sonar of the thermosiphon condenser ([Fig. 1\)](#page-1-0) use a co-axial geometry.

The measured values of temperature, pressure and sound velocity are then compared to a database of measured values created with NIST REFPROP [\[12\]](#page-4-0) to determine the gas composition. In the case of C_3F_8 in N₂, the database is created in temperature and pressure intervals of 0.5 °C and 20 mbar. An on-line algorithm implemented in WinCC interpolates between the values in the database that are closest to the measured temperature and

pressure to calculate the molar composition of the binary mixture. This requires an interpolation in two dimensions using four values retrieved from the database

The precision with which the gas composition can be measured depends on the difference between the molecular weights of the two gas components and on the precision of the sound velocity measurement. The latter depends on the precisions of the known transducer spacing $(± 0.1$ mm), the temperature and pressure in the sonar instrument (\pm 0.1 °C and \pm 1 mbar, respectively) and the precision of the transit time measurement $(\pm 25 \text{ ns})$. Their combination results in an uncertainty on the measured sound velocity, δv_s , of ± 0.025 ms⁻¹. The uncertainty on the gas composition measurement can be defined as δ (conc) = $\delta v_s/m$, where *m* is the local gradient of the curve of sound velocity against concentration. The average gradient for C_3F_8 in N_2 in the interval 0–0.1% concentration is -12.55 ms⁻¹ per percent of C₃F₈ ([Fig. 2](#page-2-0)). From this the precision of the concentration measurement is determined to be $\pm 0.002\%$.

2.2. Gas flow calculation

The difference between the transit times in opposite directions is used to calculate the gas flow rate. For the angled ultrasonic flowmeter installed in the return vapour path to the thermosiphon condenser ([Fig. 3](#page-2-0)), the moving gas acoustic path segment is at an angle $\alpha = 45^{\circ}$ to the gas flow. The length of this acoustic path is defined as $D_{\text{main}}/\sin \alpha$, where D_{main} is the diameter of the return gas tube, which is around 135 mm. The remaining length of the sound path, L' , has components L_1 and L_2 on either side of the gas flow tube.

The gas flow velocity, $v_{\rm g}$ (ms $^{-1}$), can be calculated using the sound velocity measured within the gas, v_s , as

$$
v_{\rm g} = \frac{v_{\rm s} \left(\frac{D_{\rm main}}{\sin \alpha} + L' - v_{\rm s} t_{\rm down} \right)}{\cos \alpha \left(v_{\rm s} t_{\rm down} - L' \right)}.
$$

The sound velocity can be calculated as the physical root of

$$
v_{\rm s} = \frac{A \pm \sqrt{A^2 - 16L' t_{\rm up} t_{\rm down} \left(L' + \frac{D_{\rm main}}{\sin \alpha}\right)}}{4t_{\rm up} t_{\rm down}},
$$

where the definition of A is

$$
A = (t_{\text{up}} + t_{\text{down}}) \bigg(2L' + \frac{D_{\text{main}}}{\sin \alpha} \bigg).
$$

An RMS precision of $\pm 2.3\%$ for full scale (FS) for flows up to 10 ms⁻¹ was demonstrated in pre-installation tests with air [\[8\].](#page-4-0) The flowmeter will soon be brought into operation in the closed thermosiphon circuit with C_3F_8 .

3. Application in the ATLAS detector

3.1. Implementation

The configuration of the five sonar instruments deployed in the ATLAS detector is shown in [Fig. 1](#page-1-0). Three devices aspirate N_2 environmental gas from the anti-humidity enclosures of the IBL, Pixel and SCT detectors to monitor the presence of leaks from their respective cooling systems. The SCT environmental volume is monitored at four different points – two in the endcap regions, and two in the barrel region. Gas from each region is monitored for 4 hours at a time in a 16 h continuous cycle. Two sonar instruments are implemented in the new C_3F_8 thermosiphon coolant recirculation system, which is being commissioned for the Pixel and SCT detectors.

In addition to the ultrasonic flowmeter discussed in Section 2.2, a "degassing" sonar monitors C_3F_8 vapour for possible air contamination in the condenser, reducing thermosiphon performance. Air would be expected to accumulate in the condenser; not only is it the highest part of the system, but also the lowest temperature and pressure point in the cooling circuit. The degassing sonar can trigger the venting of accumulated air when this exceeds safe limits. The air/C_3F_8 molar composition is measured in the same way as described in [Section 2.1](#page-2-0).

The precision parameters and the average slope of the sound velocity vs. composition curve in the range 0–30% air in C_3F_8 over the temperature and pressure range of interest results in a mixture resolution of $\pm 9.4 \times 10^{-4}$ [\[6\].](#page-4-0)

A user interface and Finite State Machine (FSM) has been created and integrated into the ATLAS DCS. This allows the systems to be monitored and controlled. An alarm system is also in place, which warns of any anomalies, such as a large increase in coolant leak, or hardware errors.

3.2. Recent measurements

The aspirating sonar instruments monitored the switch-on of the evaporative cooling systems of the ATLAS Inner Detector silicon tracker during January 2016. The instrument monitoring the N₂-purged envelope of the IBL subdetector showed that its ondetector cooling channels were very leak-tight; no increase in $CO₂$ concentration was seen. The instruments monitoring the SCT and Pixel sub-detectors observed changes in the concentration of C_3F_8 coolant in their envelopes.

Fig. 4 shows the concentration of C_3F_8 in the N₂ flushing gas around the Pixel detector and its on-detector cooling tubes. A steep rise in C_3F_8 concentration is observed following the simultaneous start of all 88 Pixel detector cooling circuits, followed by a slower increase to a concentration of about 0.14%.

[Fig. 5](#page-4-0) shows the apparent C_3F_8 concentration in N_2 flushing gas in the four enclosures of the SCT subdetector before and after cooling restart. The SCT sonar tube was monitoring gas aspirated from the SCT barrel "level 7" during the cooling restart, revealing a sharp spike in C_3F_8 concentration as the on-detector cooling circuits were initially operated at a higher evaporation pressure before being reduced to the normal operating value of 1.8 bar_{abs}. The apparent C_3F_8 concentration in the SCT barrel increased significantly following cooling restart: from 0.005% to 0.013% in gas aspirated from the SCT barrel "level 1", and from 0.006% to 0.014% for SCT barrel "level 7". No significant increase was seen in the apparent C_3F_8 concentration in either of the SCT endcaps following

Fig. 4. C_3F_8 concentration in the N₂-flushed anti-humidity enclosure of the ATLAS Pixel detector during cooling restart on January 28, 2016.

Fig. 5. The concentration of C_3F_8 in N_2 for four different regions of the anti-humidity enclosure of the ATLAS SCT detector is observed during the cooling restart around 15:00 UTC on January 27, 2016.

cooling turn on. Endcap "A" showed a high apparent C_3F_8 concentration before and after the cooling restart, due to a known dry air ingress from the Inner Detector external envelope purge system at the time. Since binary gas analysis is a rapid hypothesisdependent diagnostic, contamination increases in a heavy "search" gas can be mimicked by higher concentrations of a lighter contaminant. Warnings given by the instrument can indicate the need for further investigation with more expensive multi-gas sensitive instrumentation, including gas chromatography.

4. Summary

Ultrasonic instrumentation for measurement and real-time monitoring of gas flow and binary gas mixture composition has been developed. Five devices are used in applications related to the evaporative cooling system of the inner detector of the ATLAS experiment, and are integrated into the ATLAS DCS. The monitoring of the cooling of the ATLAS inner detector in January 2016 allowed further validation of the effectiveness of these instruments and the online analysis software. Precisions of ± 0.022 % of CO₂ in N₂ and ± 0.002 % of C₃F₈ in N₂ have been experimentally verified. An instrument to detect air ingress into the condenser of the new thermosiphon can operate with a molar precision of $\pm 9.4 \times 10^{-4}$. Instruments of this type have other potential applications where continuous real-time flow and binary gas composition measurements are required, for instance hydrocarbon and anaesthetic gas mixture analysis.

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