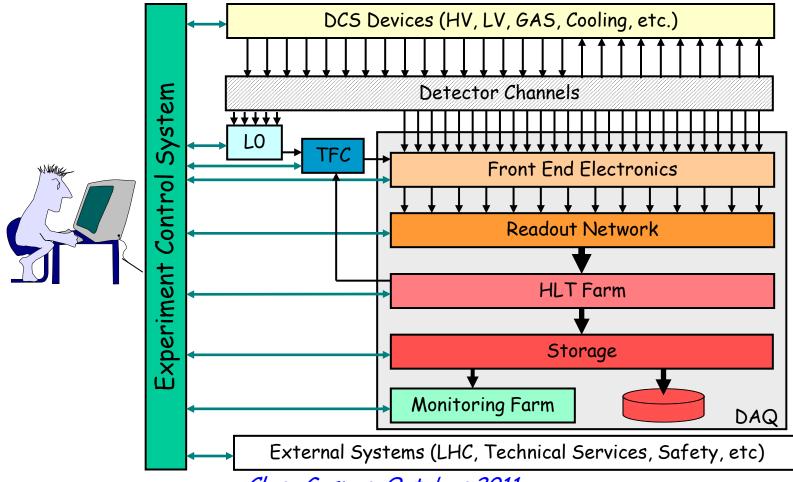


The LHCb Experiment Control System:

On the path to full automation

Hick The Experiment Control System

Is in charge of the Control and Monitoring of all areas of the experiment

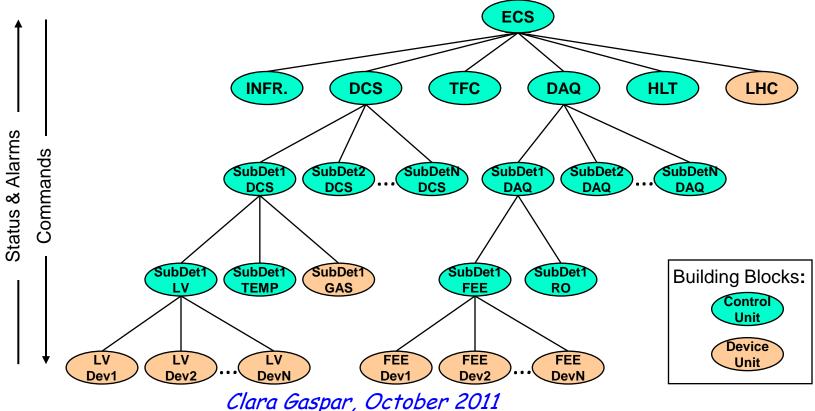


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Here Homogeneity

Same architecture and same tools used throughout the Control System.

Generic Architecture:



Heck The Control Framework

The JCOP* Framework is based on:

SCADA System - PVSSII for:

- I Device Description (Run-time Database)
- Device Access (OPC, Profibus, drivers) +DIM
- I Alarm Handling (Generation, Filtering, Masking, etc)
 - Archiving, Logging, Scripting, Trending
- I User Interface Builder
- Alarm Display, Access Control, etc.

SMI++ providing:

Device Units

Control Units

- I Abstract behavior modeling (Finite State Machines)
- I Automation & Error Recovery (Rule based system)

* - The Joint COntrols Project (between the 4 LHC exp. and the CERN Control Group)

LHCP Device Units Unit

Provide access to "real" devices:

- The FW provides interfaces to all necessary types of devices:
 - I LHCb devices: HV channels, Read Out boards, Trigger processes running in the HLT farm or Monitoring tasks for data quality, etc.
 - I External devices: the LHC, a gas system, etc.
- Each device is modeled as a Finite State Machine:
 - I It's main interface to the outside world is a "State" and a (small) set of "Actions".

Hierarchical control

Each Control Unit:

- Is defined as one or more Finite State Machines
 - It's interface to outside is also a state and actions
- Can implement rules based on its children's states
- In general it is able to:
 - I Include/Exclude children (Partitioning)
 - I Excluded nodes can run is stand-alone
 - I Implement specific behaviour
 - & Take local decisions
 - Sequence & Automate operations
 - I Recover errors
 - I User Interfacing
 - I Present information and receive commands

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DCS

Muon

IV

Muon

DCS

Muon

GAS

Fracke

DCS

Hes FW - Graphical Editor

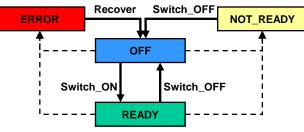
Vision_1: fwDeviceEditorNavigator \ fw [] X Device Editor & Navigator Running on: dist_40 Hardware Logical FSM	States and Actions Image: States and Actions Object Type: HVNode Panel: HVNode.pnl Simple Config Copy from Type:	SMI++ Objects
idist_40: Image: Clipboard Image: Image: Image: Clipboard Image: Image: Image: Clipboard	Object Parameters State List: Ini: NOT_READY OFF OFF OFF Object Parameters Action List: Switch_ON Do_Emergency_OFF Reset	States & Actions
∰ &SubDet2 ⊡ ∰ SubDet3	ERROR Action_editor	
E- SubDet3_H∨ - PS1 - PS2 - PS3 PD04		(PE=RUN_TYPE) \$ALL\$FwCHILDREN N not_in_state READY) then
dist_40:SubDet3_HV Type: HVNode III CU	When List: when (\$ANY\$FwCHILDREN in_state {ERROR, EMERGENCY_OFF})	-
Create/Configure FSM Object Types	when (\$ALL\$FwCHILDREN in_state READY) move_to READY when (\$ANY\$FwCHILDREN not_in_state OFF) move_to NOT_READ	
Editor mode Go to Navigator	Add Remove Type Overview Type Diff Apply OK Cancel	
Close	Parallelism, Synchronization	
	Asynchronous Rules	

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LACE Operation Domains

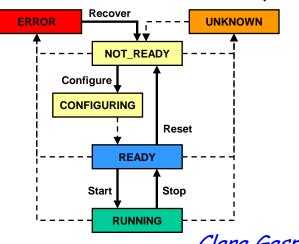
DCS Domain

Equipment operation related to a running period (Ex: GAS, Cooling)



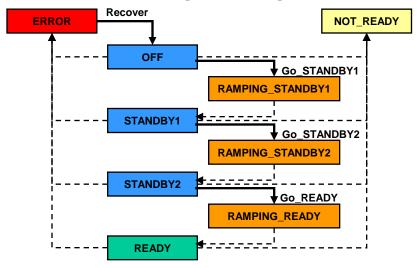
DAQ Domain

Equipment operation related to a "RUN" (Ex: RO board, HLT process)



HV Domain

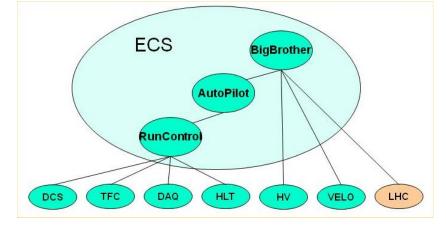
Equipment operation related to the LHC State (Ex: High Voltages)



- FSM templates distributed to all Sub-detectors
- All Devices and Sub-Systems have been implemented using one of these templates

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Hep ECS - Automation



Some Examples:

HLT Control (~1500 PCs)

- Automatically excludes misbehaving PCs (within limits)
- I Can (re)include PCs at runtime
 - (they get automatically configured and started)

RunControl

- Automatically detects and recovers SubDetector desynchronizations
- I Can Reset SDs when problems detected by monitoring

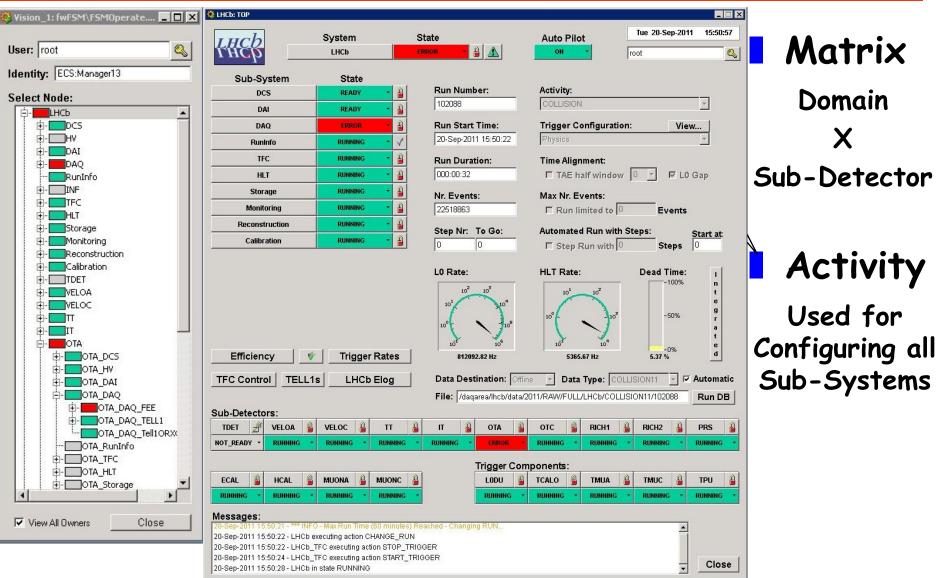
AutoPilot

Knows how to start and keep a run going from any state.

BigBrother

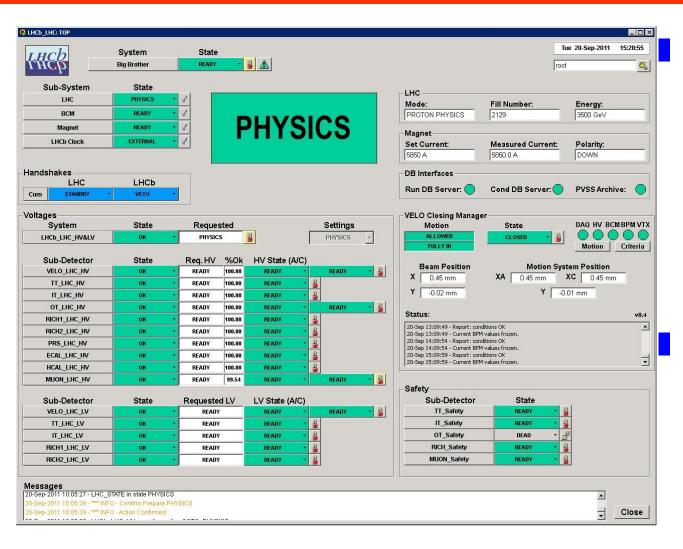
- Based on the LHC state:
 - Controls SD Voltages
 - VELO Closure
 - RunControl

Kicp Run Control



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LACE LHCb Operations



Two operators on shift:

- Data Manager
- Shift Leader has 2 views of the System:
 - Run Control
 - l Big Brother

Big Brother

- Manages LHC dependencies:
 - I SubDetector Voltages
 - I VELO Closing
 - Run Control

Hep ECS: Some numbers

Size of the Control Tree: Distributed over ~150 PCs ~100 Linux (50 for the HLT) ~50 Windows

SubDet1

DCS

SubDetN

DCS

SubDet1

DAO

SubDetN

DAO

>2000 Control Units
>50000 Device Units

Run Control Timing

- Cold Start to Running: 4 minutes
 - I Configure all Sub-detectors, Start & Configure ~40000 HLT processes (always done well before PHYSICS)
- Stop/Start Run: 6 seconds

LHCP Conclusions

- LHCb has designed and implemented a coherent and homogeneous control system
- The Experiment Control System allows to:
 - Configure, Monitor and Operate the Full Experiment
 - Run any combination of sub-detectors in parallel in standalone
- Some of its main features:
 - Partitioning, Sequencing, Error recovery, Automation
 - Come from the usage of SMI++ (integrated with PVSS)
- LHCb operations now almost completely automated
 - Operator task is easier (basically only confirmations)
 - DAQ Efficiency improved to ~98%