Machine Learning 10-601

Tom M. Mitchell Machine Learning Department Carnegie Mellon University

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Today:

- Graphical models
- Bayes Nets:
 - Representing distributions
 - Conditional independencies
 - Simple inference
 - Simple learning

Readings:

- Bishop chapter 8, through 8.2
- Mitchell chapter 6

Bayes Nets define Joint Probability Distribution in terms of this graph, plus parameters



 $P(X_{1^{p}}, X_{2^{p}}, X_{3^{p}}, X_{4^{p}}, X_{5^{p}}, X_{6^{p}}, X_{7^{p}}, X_{8})$ $= P(X_{1}) P(X_{2}) P(X_{3} | X_{1}) P(X_{4} | X_{2}) P(X_{5} | X_{2})$ $P(X_{6} | X_{3^{p}}, X_{4}) P(X_{7} | X_{6}) P(X_{8} | X_{5^{p}}, X_{6})$

Benefits of Bayes Nets:

- Represent the full joint distribution in fewer parameters, using prior knowledge about dependencies
- Algorithms for inference and learning

Bayesian Networks Definition



- A Bayes network represents the joint probability distribution over a collection of random variables
- A Bayes network is a directed acyclic graph and a set of conditional probability distributions (CPD's)
- Each node denotes a random variable
- Edges denote dependencies
- For each node X_i its CPD defines $P(X_i | Pa(X_i))$
- The joint distribution over all variables is defined to be

$$P(X_1 \dots X_n) = \prod_i P(X_i | Pa(X_i))$$

Pa(X) = immediate parents of X in the graph

Bayesian Network



Nodes = random variables

A conditional probability distribution (CPD) is associated with each node N, defining P(N | Parents(N))

Parents	P(W Pa)	P(¬W Pa)			
L, R	0	1.0			
L, ¬R	0	1.0			
¬L, R	0.2	0.8			
¬L, ¬R	0.9	0.1			
WindSurf					

The joint distribution over all variables:

$$P(X_1 \dots X_n) = \prod_i P(X_i | Pa(X_i))$$



Chain rule of probability:

 $\underbrace{P(S,L,R,T,W)}_{P(S,L,R,T)} = \underbrace{P(S)P(L|S)P(R|S,L)P(T|S,L,R)P(W|S,L,R,T)}_{P(S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R,T)P(W|S,L,R)P(W|S,$

But in a Bayes net: $P(X_1 \dots X_n) = \prod_i P(X_i | Pa(X_i))$ $P(S \perp R \top W) = P(S) P(L | S) P(R | S) P(T | L) P(W | L, R)$ $(\forall s \ L r \ W) P(S_{=S}, L^{=} l^{-1}) = P(S_{=S}) P(L^{=} L | S^{=} s) \cdots$



In [.]	ference	in	Baves	Nets

Parents	P(W Pa)	P(¬W Pa)
L, R	0	1.0
L, ¬R	0	1.0
¬L, R	0.2	0.8
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WindSurf

P(S=1, L=0, R=1, T=0, W=1) = P(s=1) P(L=0|s=1) P(R=1|s=1) P(T=0|L=0) P(W=1|L=0, R-1) $O_{n} Z$



Consider learning when graph structure is given, and data = { <s,l,r,t,w> } What is the MLE solution? MAP?

Algorithm for Constructing Bayes Network

- Choose an ordering over variables, e.g., $X_1, X_2, \dots X_n$
- For i=1 to n
 - Add X_i to the network
 - Select parents $Pa(X_i)$ as minimal subset of $X_1 \dots X_{i-1}$ such that $P(X_i | Pa(X_i)) = P(X_i | X_1, \dots, X_{i-1})$

Notice this choice of parents assures

$$P(X_1 \dots X_n) = \prod_i P(X_i | X_1 \dots X_{i-1}) \quad \text{(by chain rule)}$$
$$= \prod_i P(X_i | Pa(X_i)) \quad \text{(by construction)}$$

Example

• Bird flu and Allegies both cause Nasal problems

N

H

Nasal problems cause Sneezes and Headaches



What is the Bayes Network for X1,...X4 with NO assumed conditional independencies?

 $P(X, X_2, X_3, Y_4) = P(X,) P(X_2)Y,) P(X_3(X, Y_2)P(X_4|X, X_3))$



What is the Bayes Network for Naïve Bayes? $P(Y, X, X_2, X_3)$ X; LX; Y Hizs - CPD =' Y = $P(Y) P(x, (Y) P(x_2|Y) P(x_3|Y)$ ろん $P(Y_{=1}|X_{=}a, X_{=}b, X_{=}c) =$ $P(Y_{*}1, X_{,}, Y_{2}, X_{2}, X_{2}, X_{2})$ $P(Y=1, X_{1}=9, Y_{2}=b, X_{3}=c) + P(Y=0, X_{1}=9, X=b, X_{3}=c)$

What do we do if variables are mix of discrete and real valued?



Bayes Network for a Hidden Markov Model

Implies the future is conditionally independent of the past, given the present



 $P(S_{t-2}, O_{t-2}, S_{t-1}, \dots, O_{t+2}) =$

Conditional Independence, Revisited

- We said:
 - Each node is conditionally independent of its non-descendents, given its immediate parents.
- Does this rule give us all of the conditional independence relations implied by the Bayes network?
 - No!
 - E.g., X1 and X4 are conditionally indep given {X2, X3}
 - But X1 and X4 not conditionally indep given X3
 - For this, we need to understand D-separation



Easy Network 1: Head to Tail
$$P(A = a)$$

prove A cond indep of B given C?
ie., $p(a,b|c) = p(a|c) p(b|c)$
 $P(ab|c) = P(a|c) P(b|c) = A \perp B \mid c$
 $P(ab|c) = \frac{P(abc)}{P(c)} = \frac{P(c) P(c|a)}{P(c)} P(b|c)$
 $P(ab|c) = \frac{P(abc)}{P(c)} = \frac{P(c) P(c|a)}{P(c)} P(b|c)$

let's use p(a,b) as shorthand for p(A=a, B=b)

Easy Network 2: Tail to Tail prove A cond indep of B given C? ie., p(a,b|c) = p(a|c) p(b|c)

let's use p(a,b) as shorthand for p(A=a, B=b)

Easy Network 3: Head to Head
prove A cond indep of B given C? ie.,
$$p(a,b|c) = p(a|c) p(b|c)$$

 $N = \cdot F = I = c - P(a = b(c) \neq P(a|c) P(b|c)$
Bull $P(a,b) = P(a) P(b)$
 $P(a,b) = P(A = a, B = b, C = b) + P(A = a, B = b, C = 1)$
 $P(a)P(b)P(c = b|a,b) + P(c)P(b)P(c = b|a,b)$
 $P(ab) = P(a)P(b)[P(c = b|a,b) + P(c)P(c = b|a,b)]$

let's use p(a,b) as shorthand for p(A=a, B=b)

Easy Network 3: Head to Head

prove A cond indep of B given C? NO!

Summary:

- p(a,b)=p(a)p(b)
- p(a,b|c) NotEqual p(a|c)p(b|c)

Explaining away.

e.g.,

- A=earthquake
- B=breakIn
- C=motionAlarm



X and Y are conditionally independent given Z, <u>if and only if</u> X and Y are D-separated by Z. [Bishop, 8.2.2]

Suppose we have three sets of random variables: X, Y and Z

X and Y are <u>**D-separated</u>** by Z (and therefore conditionally indep, given Z) iff every path from every variable in X to every variable in Y is <u>**blocked**</u></u>

A path from variable X to variable Y is **blocked** if it includes a node in Z such that either

1. arrows on the path meet either head-to-tail or tail-to-tail at the node and this node is in Z

B

2. or, the arrows meet head-to-head at the node, and neither the node, nor any of its descendants, is in Z



B

X and Y are **<u>D-separated</u>** by Z (and therefore conditionally indep, given Z) iff every path from every variable in X to every variable in Y is **<u>blocked</u>**

A path from variable A to variable B is **blocked** if it includes a node such that either

1.arrows on the path meet either head-to-tail or tail-to-tail at the node and this node is in Z

2.or, the arrows meet head-to-head at the node, and neither the node, nor any of its descendants, is in Z

X1 indep of X3 given X2?X3 indep of X1 given X2?X4 indep of X1 given X2?



X and Y are **<u>D-separated</u>** by Z (and therefore conditionally indep, given Z) iff every path from any variable in X to any variable in Y is **<u>blocked</u>** by Z

A path from variable A to variable B is **blocked** by Z if it includes a node such that either

1.arrows on the path meet either head-to-tail or tail-to-tail at the node and this node is in Z $(A \rightarrow Z \rightarrow B)$ $(A \rightarrow Z \rightarrow B)$

2.the arrows meet head-to-head at the node, and neither the node, nor any of its descendants, is in Z $A \rightarrow C \rightarrow B$

X1

Х3

Χ4

X2

D

X4 indep of X1 given X3? N

X4 indep of X1 given {X3, X2}? $\frac{1}{5}$

X4 indep of X1 given {}? γ_{z}

X and Y are **<u>D-separated</u>** by Z (and therefore conditionally indep, given Z) iff every path from any variable in X to any variable in Y is **<u>blocked</u>**

A path from variable A to variable B is **blocked** if it includes a node such that either

1. arrows on the path meet either head-to-tail or tail-to-tail at the node and this node is in Z

2. or, the arrows meet head-to-head at the node, and neither the node, nor any of its descendants, is in Z

a indep of b given c?

a indep of b given f?



Markov Blanket

The Markov blanket of a node x_i comprises the set of parents, children and co-parents of the node. It has the property that the conditional distribution of x_i , conditioned on all the remaining variables in the graph, is dependent only on the variables in the Markov blanket.

from [Bishop, 8.2]

 x_i

What You Should Know

- Bayes nets are convenient representation for encoding dependencies / conditional independence
- BN = Graph plus parameters of CPD's
 - Defines joint distribution over variables
 - Can calculate everything else from that
 - Though inference may be intractable
- Reading conditional independence relations from the graph
 - Each node is cond indep of non-descendents, given only its parents
 - D-separation
 - 'Explaining away'

Inference in Bayes Nets

- In general, intractable (NP-complete)
- For certain cases, tractable
 - Assigning probability to fully observed set of variables
 - Or if just one variable unobserved
 - Or for singly connected graphs (ie., no undirected loops)
 - Belief propagation
- For multiply connected graphs
 - Junction tree
- Sometimes use Monte Carlo methods
 - Generate many samples according to the Bayes Net distribution, then count up the results
- Variational methods for tractable approximate solutions