

#### 10-601 Introduction to Machine Learning

Machine Learning Department School of Computer Science Carnegie Mellon University

# Regularization

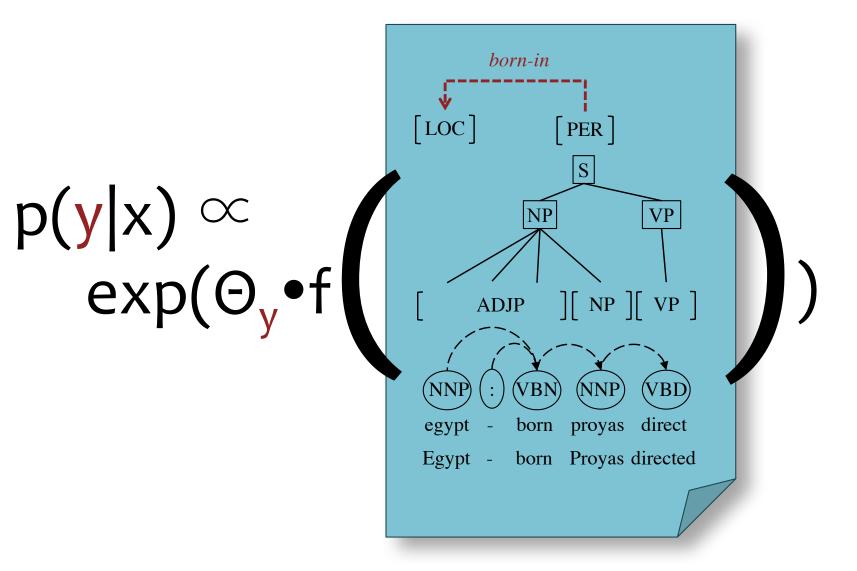
Matt Gormley Lecture 10 Feb. 19, 2018

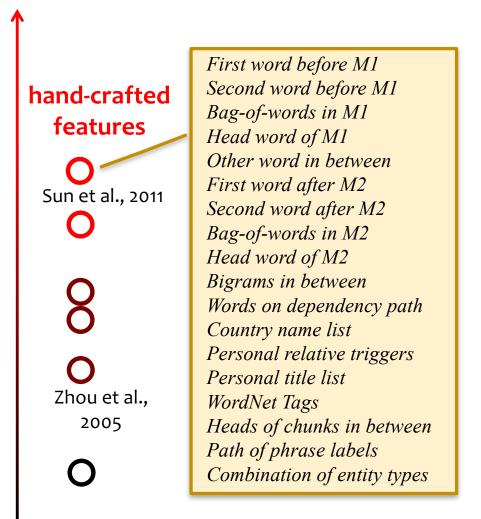
#### Reminders

- Homework 4: Logistic Regression
  - Out: Wed, Feb 14
  - Due: Fri, Feb 23 at 11:59pm
- New reading on Probabilistic Learning (reused later in the course for MLE/MAP)

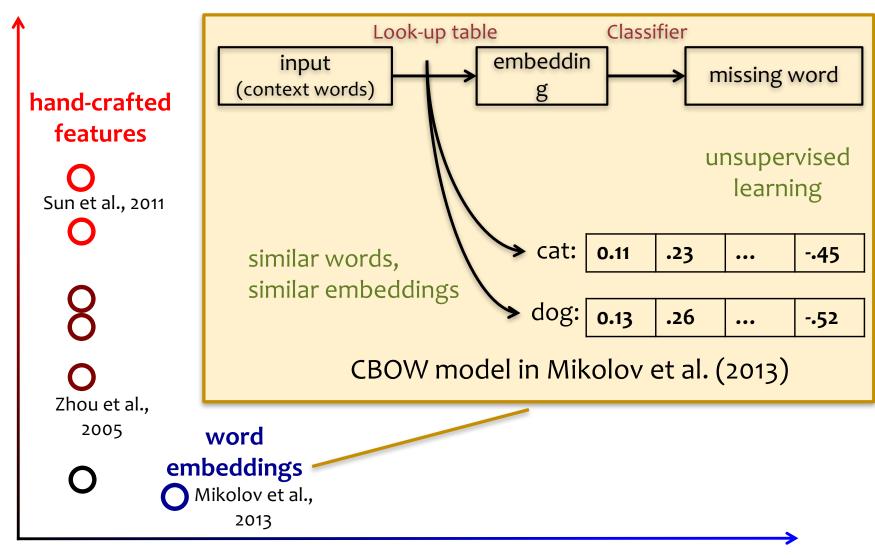
## FEATURE ENGINEERING

#### Handcrafted Features

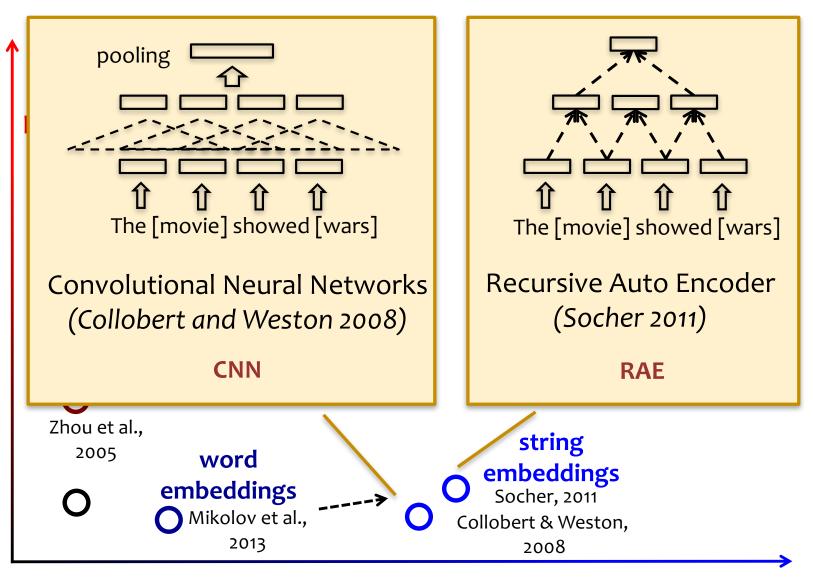




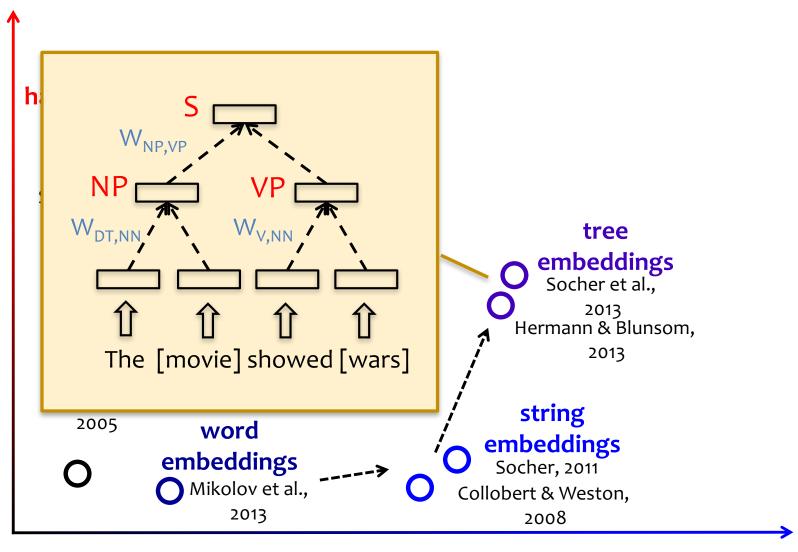
# Feature Engineering



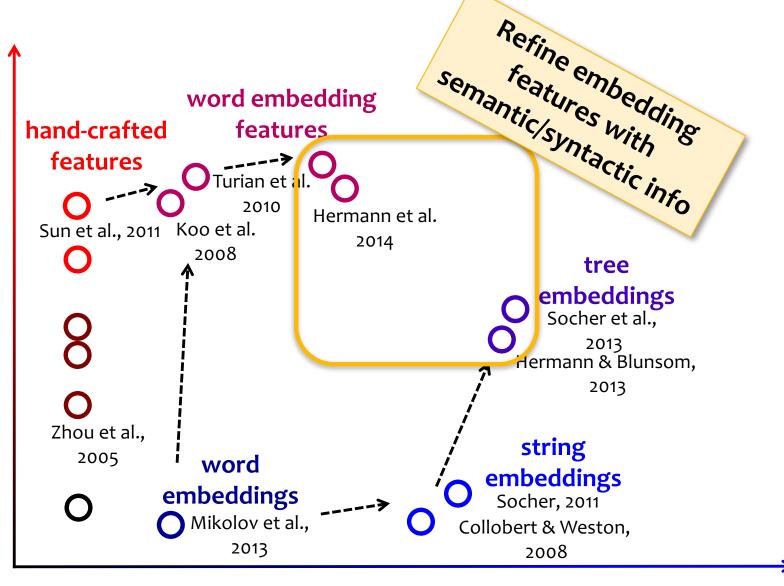
Feature Learning



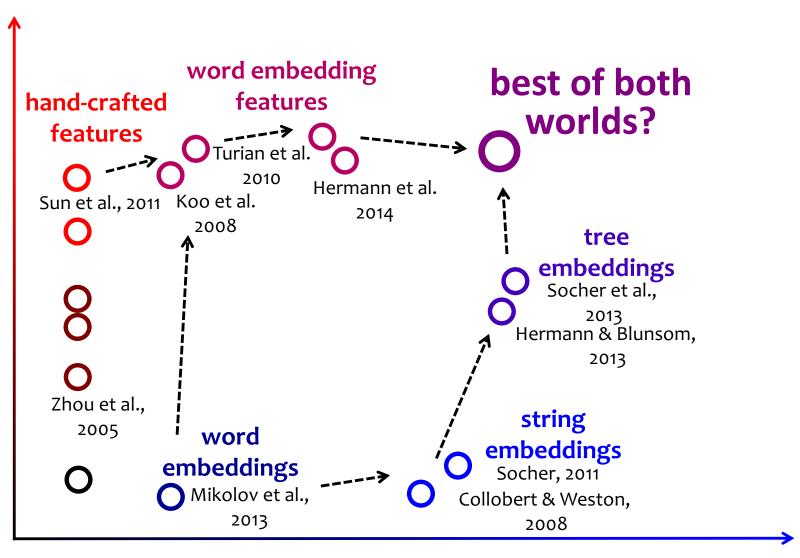
Feature Learning



Feature Learning



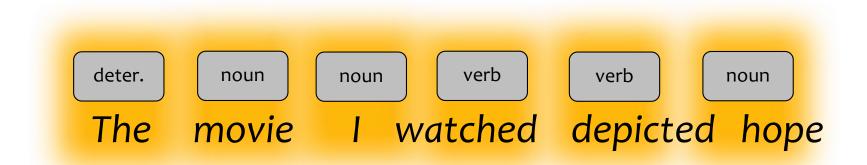
Feature Learning



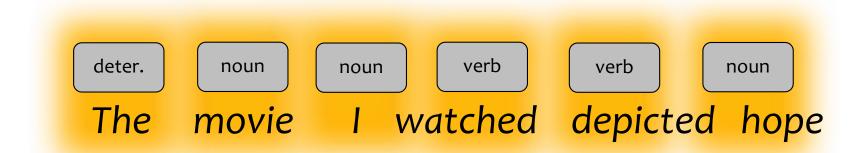
Feature Learning

Suppose you build a logistic regression model to predict a part-of-speech (POS) tag for each word in a sentence.

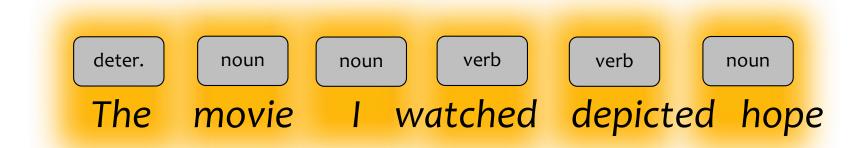
#### What features should you use?



#### **Per-word Features:**



#### **Context Features:**



#### **Context Features:**

 $w_{i-2} == "I"$ 

 $\chi(1)$ ••• •••

 $X^{(2)}$ 

 $X^{(3)}$ 

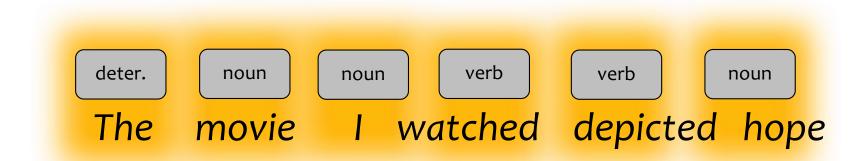
 $X^{(4)}$  $\chi$ (5)

 $X^{(6)}$ 

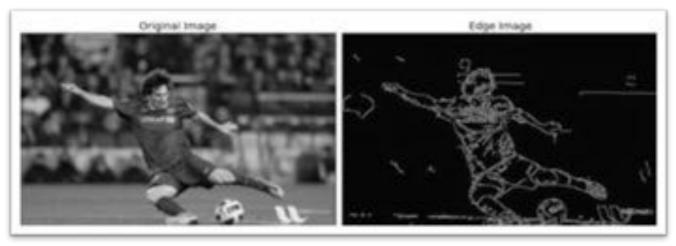
deter. verb verb noun noun noun movie I watched depicted hope The

**Table 3.** Tagging accuracies with different feature templates and other changes on the WSJ 19-21 development set.

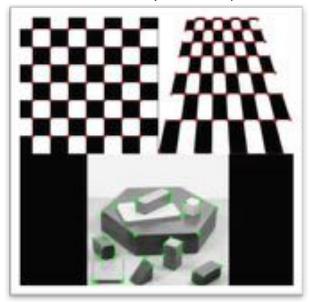
Model	Feature Templates	#	Sent.	Token	Unk.
		Feats	Acc.	Acc.	Acc.
3GRAMMEMM	See text	248,798	52.07%	96.92%	88.99%
NAACL $2003$	See text and [1]	$460,\!552$	55.31%	97.15%	88.61%
Replication	See text and [1]	$460,\!551$	55.62%	97.18%	88.92%
Replication'	+rareFeatureThresh = 5	$482,\!364$	55.67%	97.19%	88.96%
$5 \mathrm{W}$	$+\langle t_0, w_{-2}\rangle, \langle t_0, w_2\rangle$	730,178	56.23%	97.20%	89.03%
5wShapes	$+\langle t_0, s_{-1}\rangle, \langle t_0, s_0\rangle, \langle t_0, s_{+1}\rangle$	731,661	56.52%	97.25%	89.81%
5wShapesDS	+ distributional similarity	737,955	56.79%	97.28%	90.46%



Edge detection (Canny)

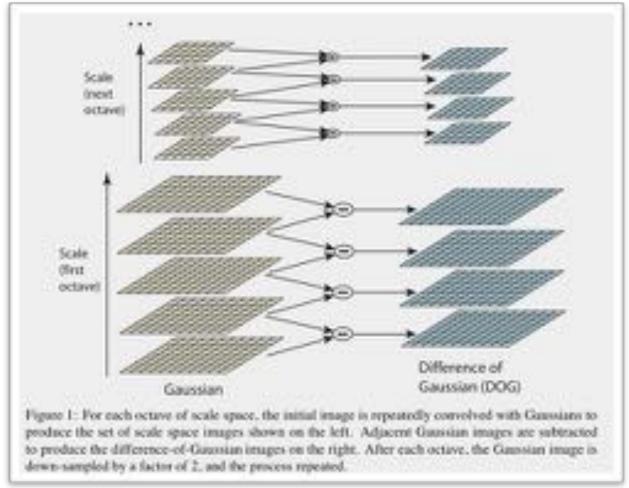


Corner Detection (Harris)



## Scale Invariant Feature Transform (SIFT)





## **NON-LINEAR FEATURES**

#### Nonlinear Features

- aka. "nonlinear basis functions"
- So far, input was always  $\mathbf{x} = [x_1, \dots, x_M]$
- **Key Idea:** let input be some function of **x** 
  - $\begin{array}{ll} & \text{original input:} & \mathbf{x} \in \mathbb{R}^M \\ & \text{new input:} & \mathbf{x}' \in \mathbb{R}^{M'} \end{array} \text{ where } M' > M \text{ (usually)}$

  - define  $\mathbf{x}' = b(\mathbf{x}) = [b_1(\mathbf{x}), b_2(\mathbf{x}), \dots, b_{M'}(\mathbf{x})]$ 
    - where  $b_i: \mathbb{R}^M \to \mathbb{R}$  is any function
- Examples: (M = 1)

$$b_j(x) = x^j \quad \forall j \in \{1, \dots, J\}$$

radial basis function

$$b_j(x) = \exp\left(\frac{-(x-\mu_j)^2}{2\sigma_j^2}\right)$$

sigmoid

$$b_j(x) = \frac{1}{1 + \exp(-\omega_j x)}$$

log

$$b_j(x) = \log(x)$$

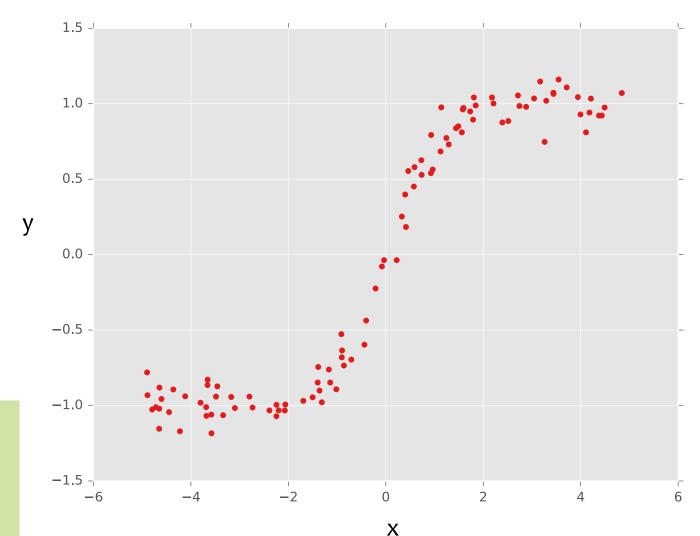
For a linear model: still a linear function of b(x) even though a nonlinear function of X

#### **Examples:**

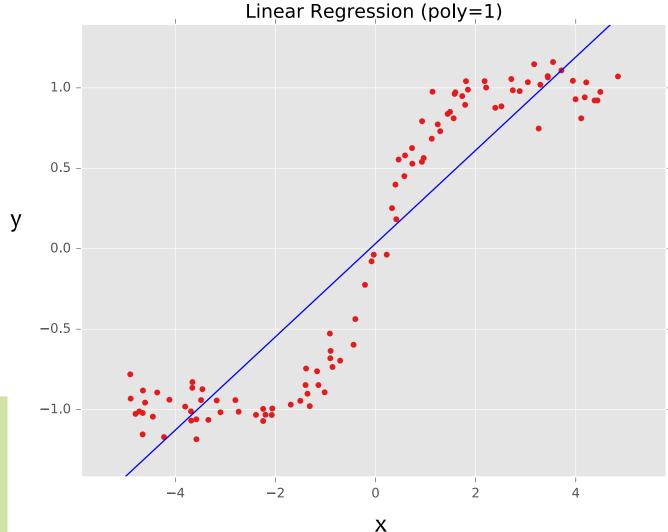
- Perceptron
- Linear regression
- Logistic regression

**Goal:** Learn  $y = \mathbf{w}^T f(\mathbf{x}) + \mathbf{b}$  where f(.) is a polynomial

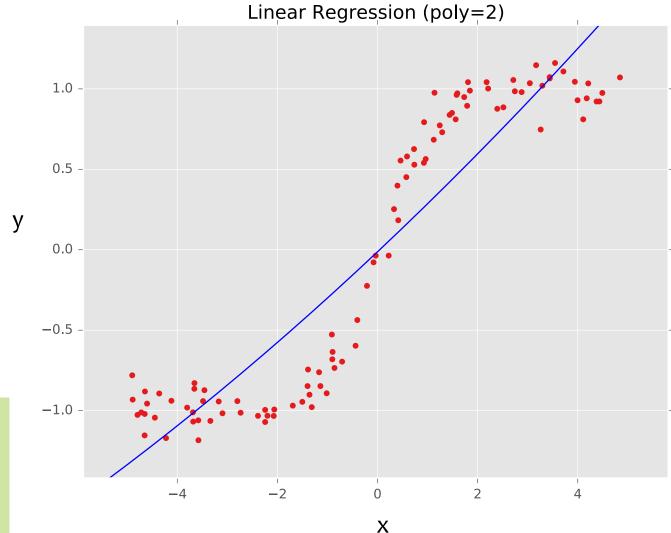
basis function



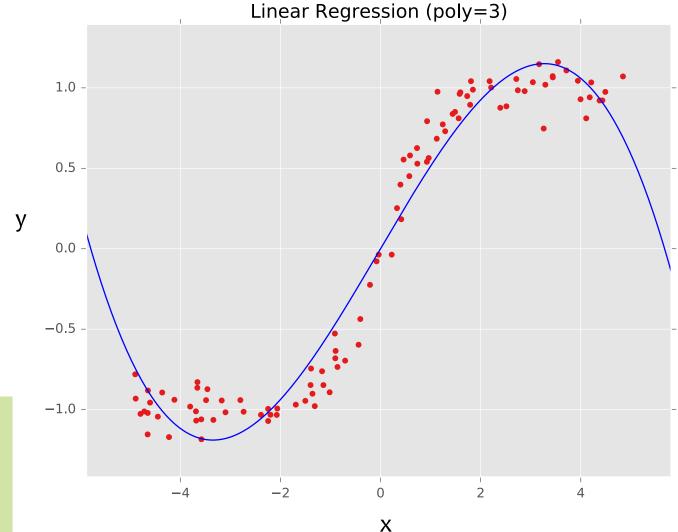
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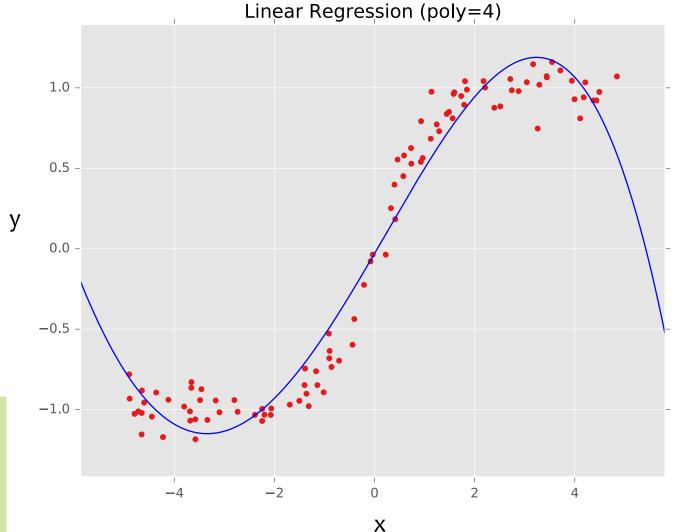
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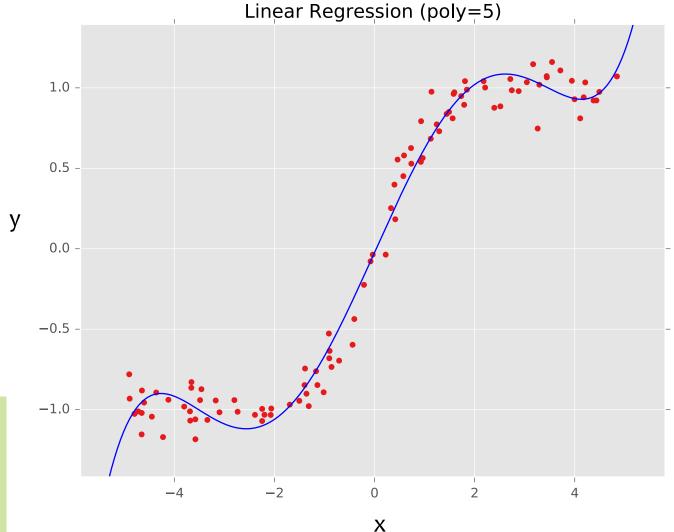
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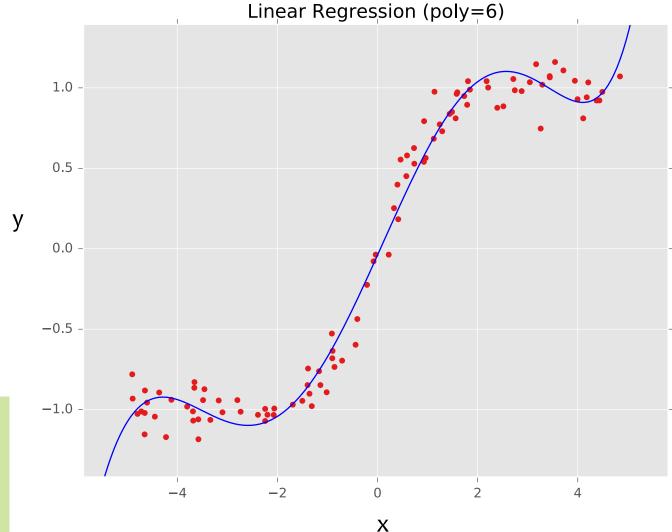
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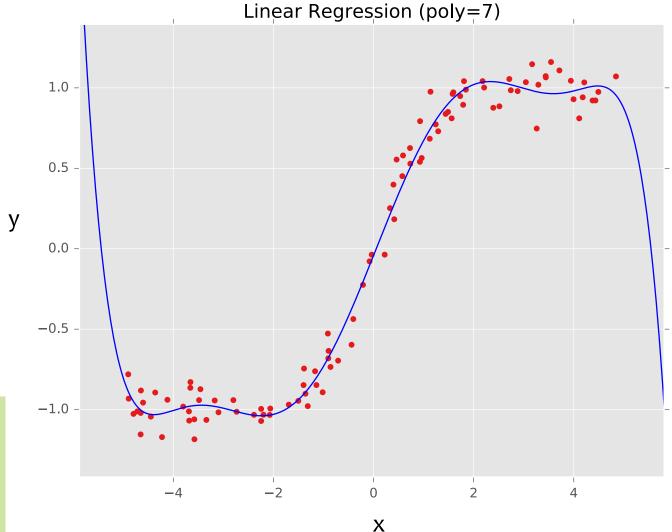
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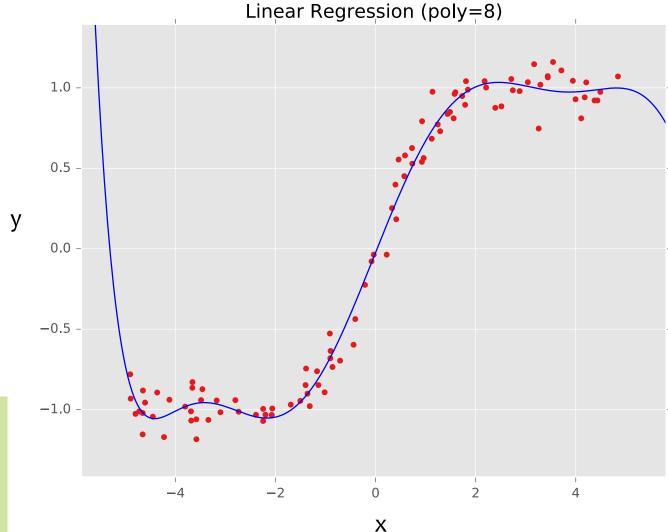
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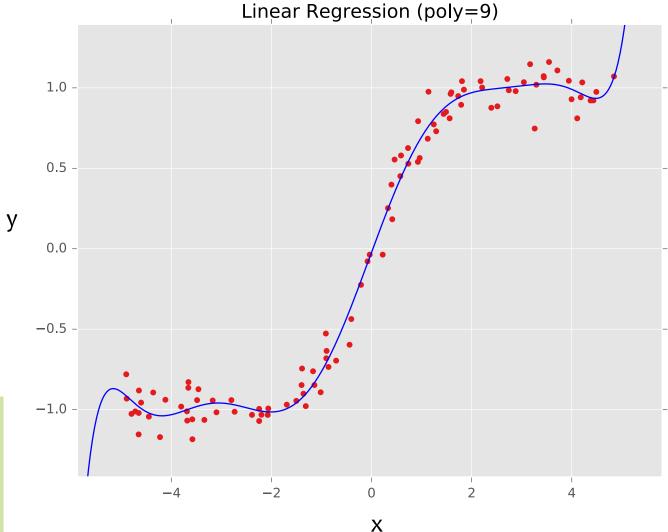
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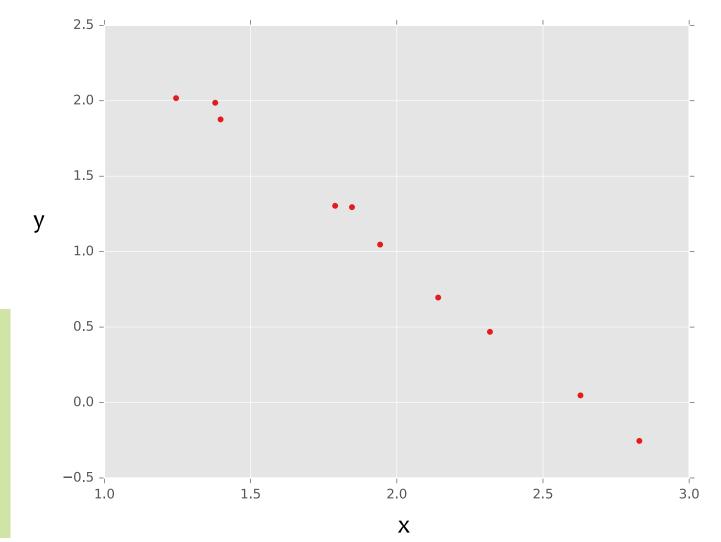


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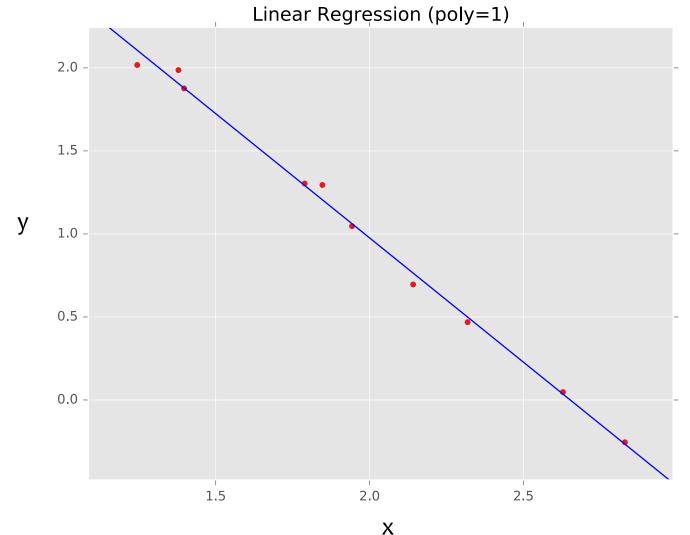
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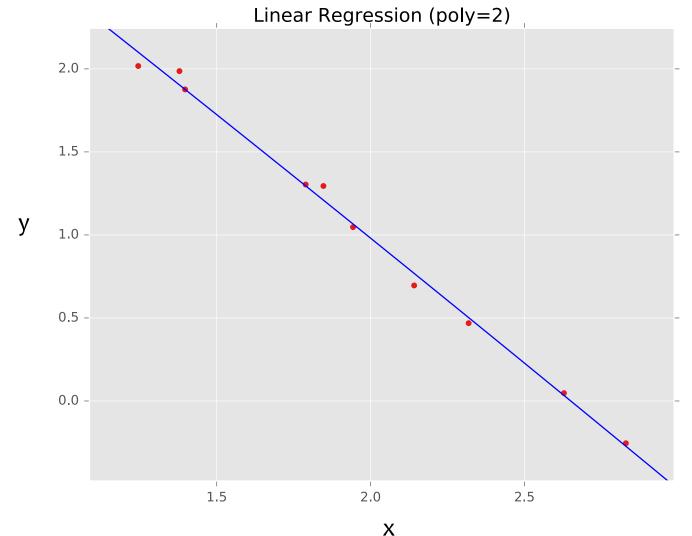
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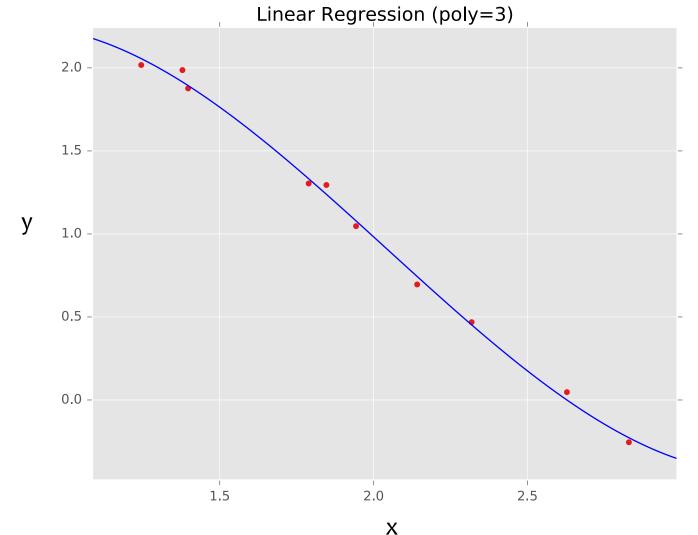
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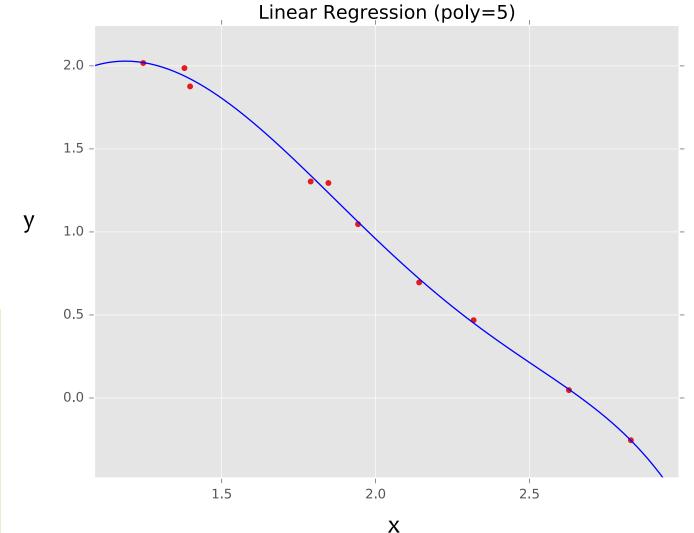
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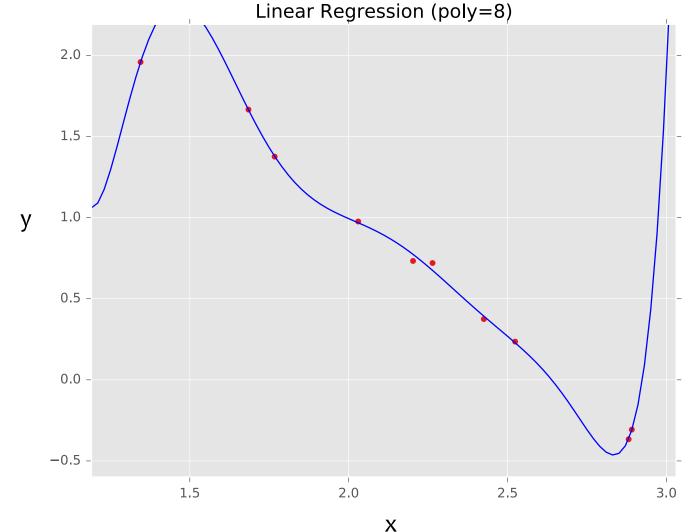


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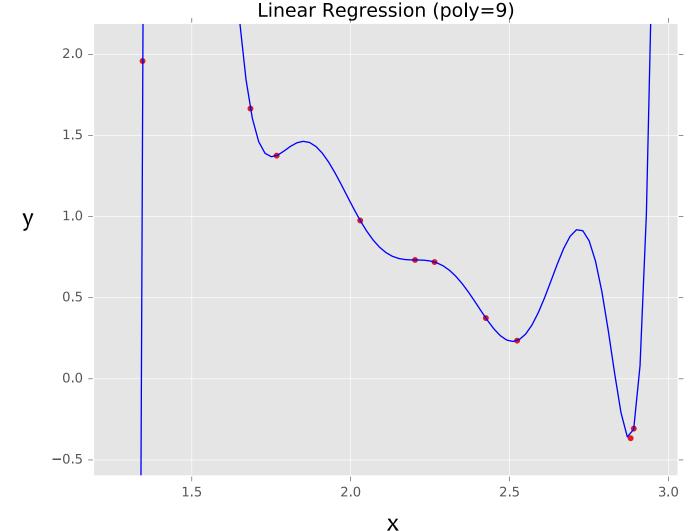
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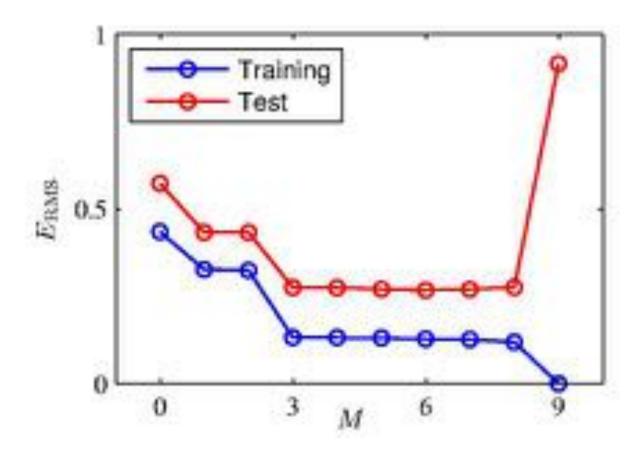
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# Over-fitting



Root-Mean-Square (RMS) Error:

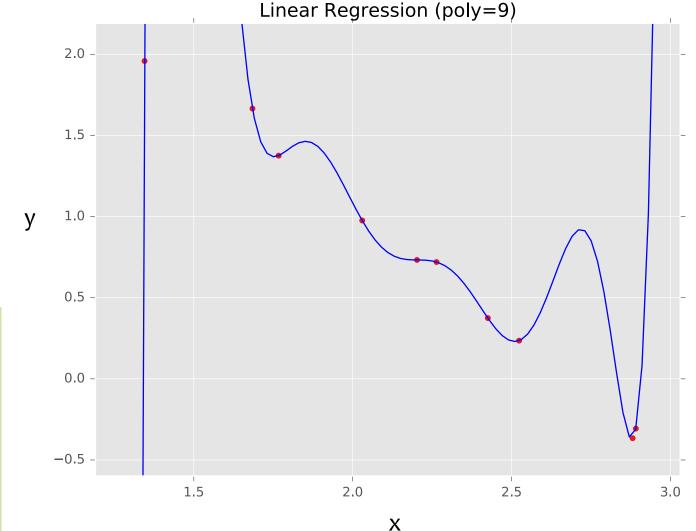
$$E_{\rm RMS} = \sqrt{2E(\mathbf{w}^{\star})/N}$$

# Polynomial Coefficients

	M = 0	M = 1	M = 3	M = 9
$\overline{\theta_0}$	0.19	0.82	0.31	0.35
$ heta_1$		-1.27	7.99	232.37
$ heta_2$			-25.43	-5321.83
$ heta_3$			17.37	48568.31
$ heta_4$				-231639.30
$ heta_5$				640042.26
$ heta_6$				-1061800.52
$ heta_7$				1042400.18
$ heta_8$				-557682.99
$ heta_9$				125201.43

#### Example: Linear Regression

**Goal:** Learn  $y = \mathbf{w}^T f(\mathbf{x}) + b$  where f(.) is a polynomial basis function

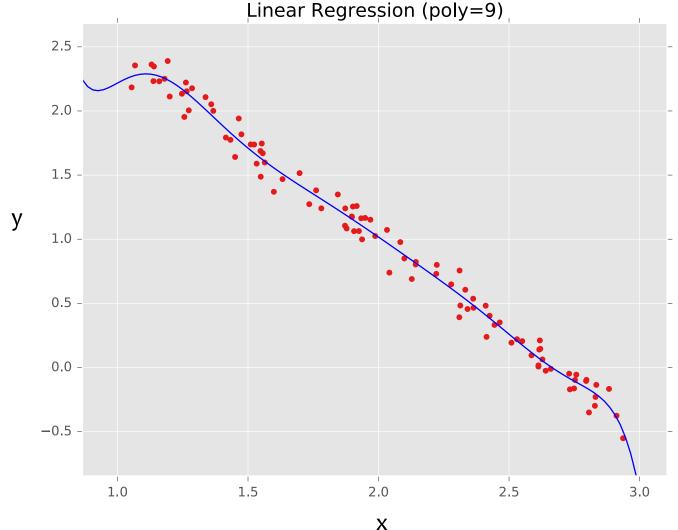


true "unknown" target function is linear with negative slope and gaussian noise

#### Example: Linear Regression

**Goal:** Learn  $y = \mathbf{w}^T f(\mathbf{x}) + \mathbf{b}$  where f(.) is a polynomial basis function

Same as before, but now with N = 100 points



true "unknown" target function is linear with negative slope and gaussian noise

#### **REGULARIZATION**

### Overfitting

**Definition:** The problem of **overfitting** is when the model captures the noise in the training data instead of the underlying structure

Overfitting can occur in all the models we've seen so far:

- KNN (e.g. when k is small)
- Naïve Bayes (e.g. without a prior)
- Linear Regression (e.g. with basis function)
- Logistic Regression (e.g. with many rare features)

#### Motivation: Regularization

#### **Example: Stock Prices**

- Suppose we wish to predict Google's stock price at time t+1
- What features should we use? (putting all computational concerns aside)
  - Stock prices of all other stocks at times t, t-1, t-2, ..., t - k
  - Mentions of Google with positive / negative sentiment words in all newspapers and social media outlets



 Do we believe that all of these features are going to be useful?

#### Motivation: Regularization

 Occam's Razor: prefer the simplest hypothesis

- What does it mean for a hypothesis (or model) to be simple?
  - small number of features (model selection)
  - small number of "important" features (shrinkage)

#### Regularization

#### Chalkboard

- L2, L1, Lo Regularization
- Example: Linear Regression

#### Regularization

#### Don't Regularize the Bias (Intercept) Parameter!

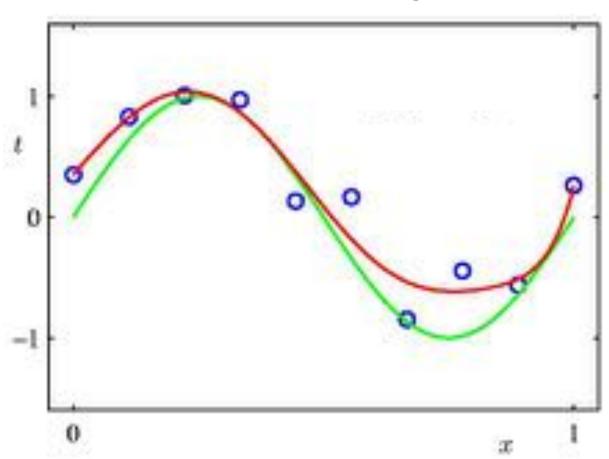
- In our models so far, the bias / intercept parameter is usually denoted by  $\theta_0$  that is, the parameter for which we fixed  $x_0=1$
- Regularizers always avoid penalizing this bias / intercept parameter
- Why? Because otherwise the learning algorithms wouldn't be invariant to a shift in the y-values

#### **Whitening Data**

- It's common to whiten each feature by subtracting its mean and dividing by its variance
- For regularization, this helps all the features be penalized in the same units (e.g. convert both centimeters and kilometers to z-scores)

# Regularization:

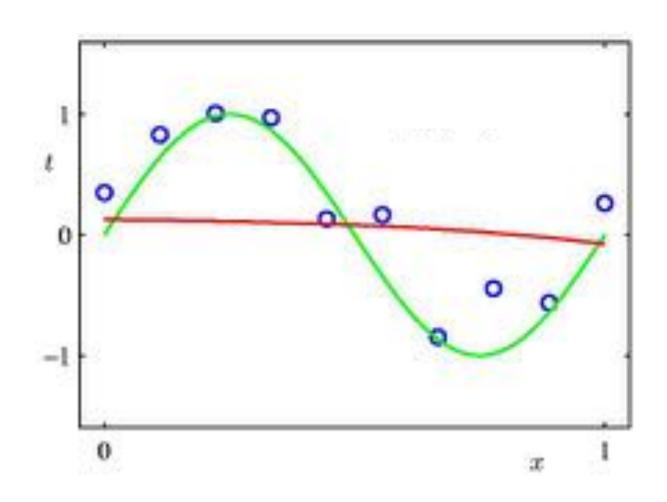
$$\ln \lambda = +18$$



# Polynomial Coefficients

	none	exp(18)	huge
$w_0^{\star}$	0.35	0.35	0.13
$w_1^{\star}$	232.37	4.74	-0.05
$w_2^{\star}$	-5321.83	-0.77	-0.06
$w_3^*$	48568.31	-31.97	-0.05
$w_4^{\star}$	-231639.30	-3.89	-0.03
$w_5^{\star}$	640042.26	55.28	-0.02
$w_6^{\star}$	-1061800.52	41.32	-0.01
$w_7^{\star}$	1042400.18	-45.95	-0.00
$w_8^*$	-557682.99	-91.53	0.00
$w_9^\star$	125201.43	72.68	0.01

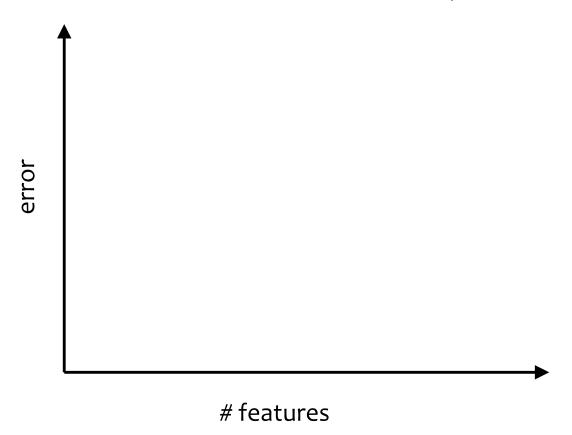
# Over Regularization:



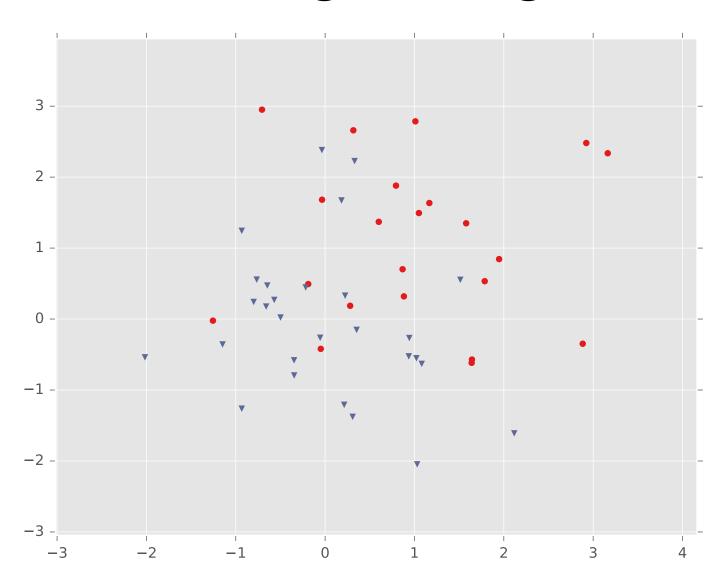
#### Regularization Exercise

#### In-class Exercise

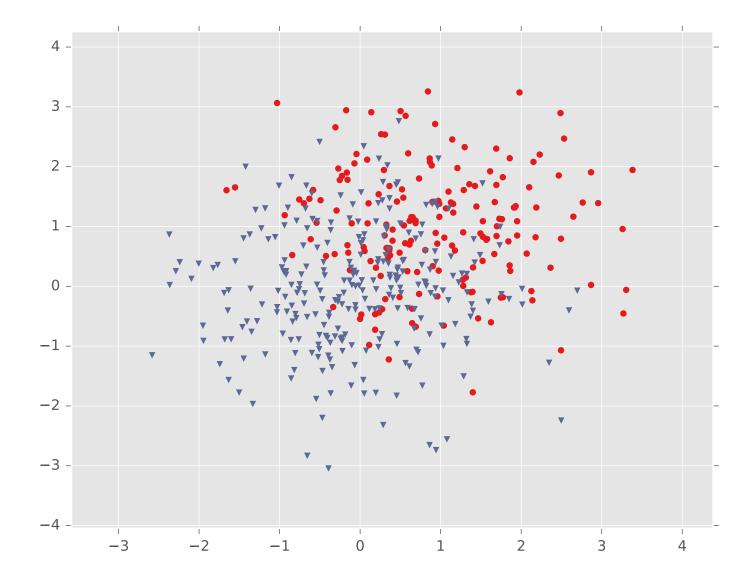
- Plot train error vs. # features (cartoon)
- 2. Plot test error vs. # features (cartoon)

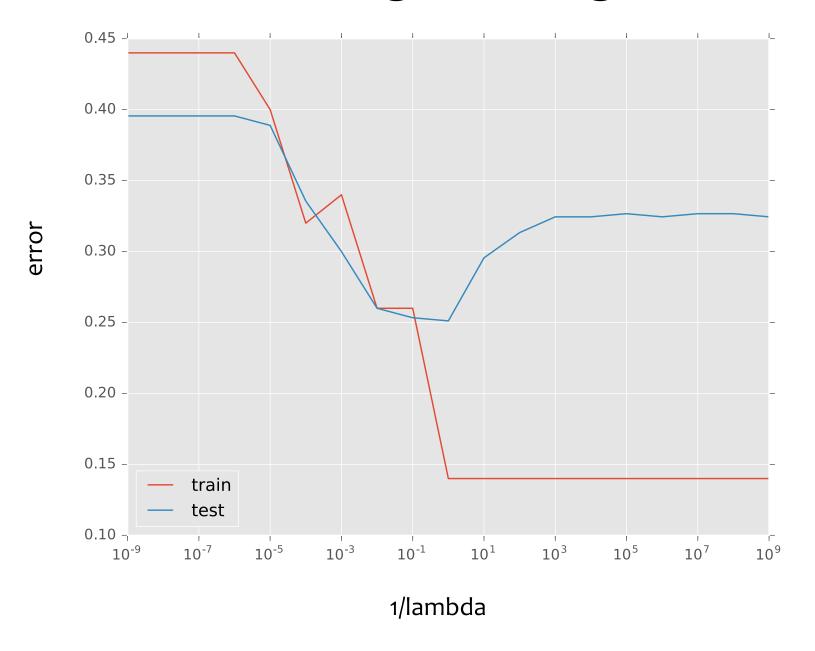


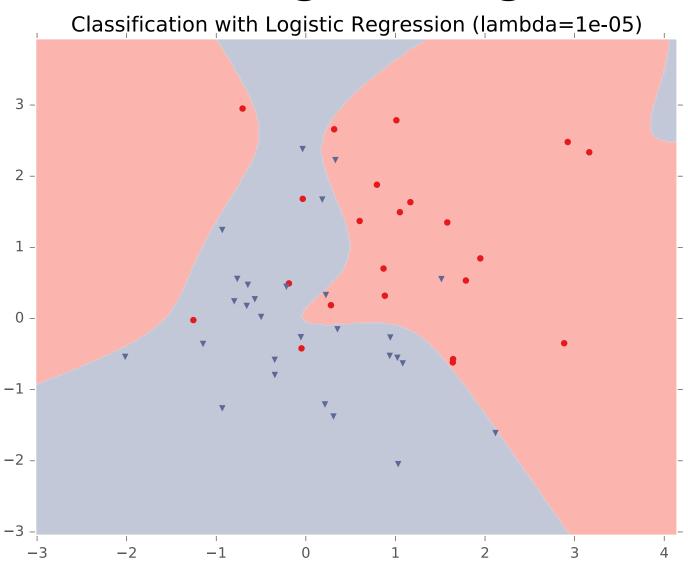
Training Data

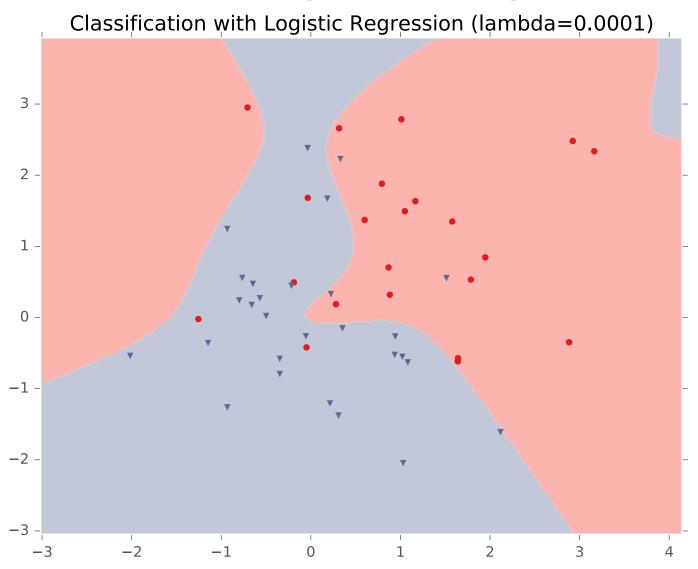


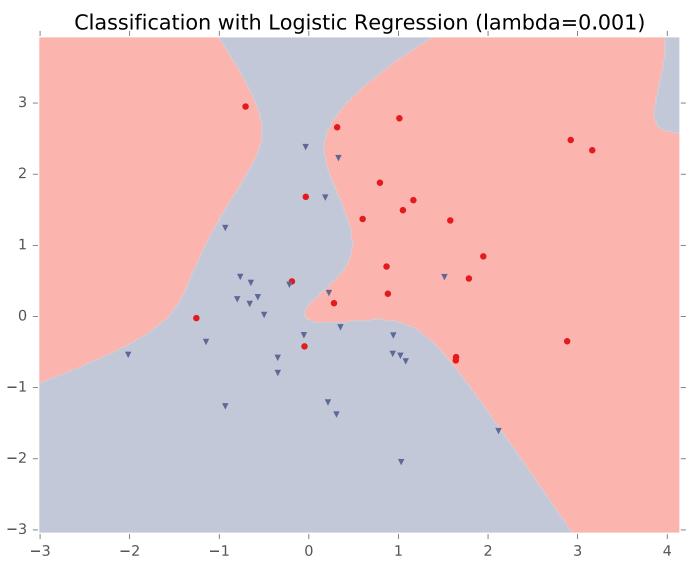


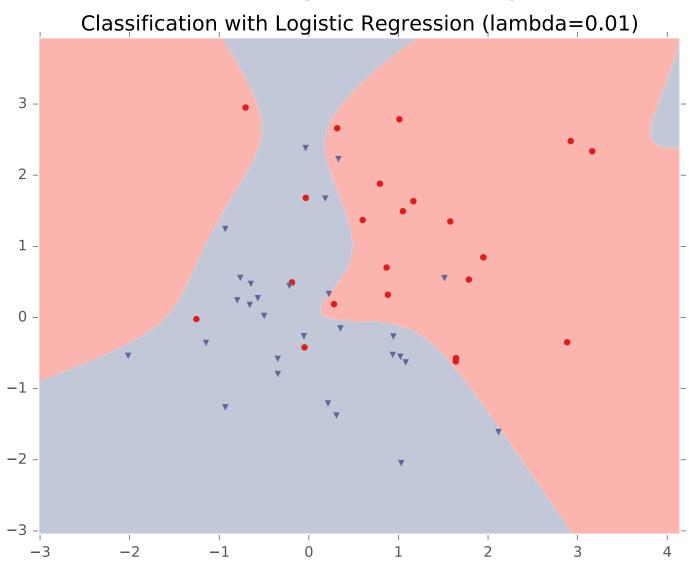


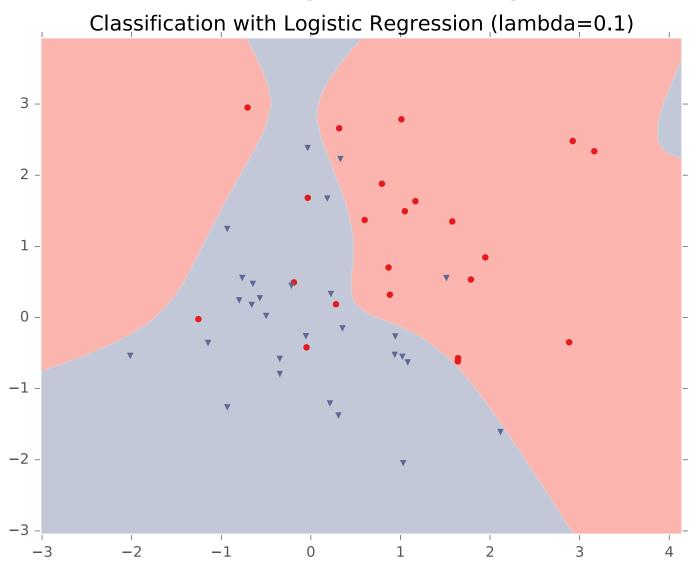


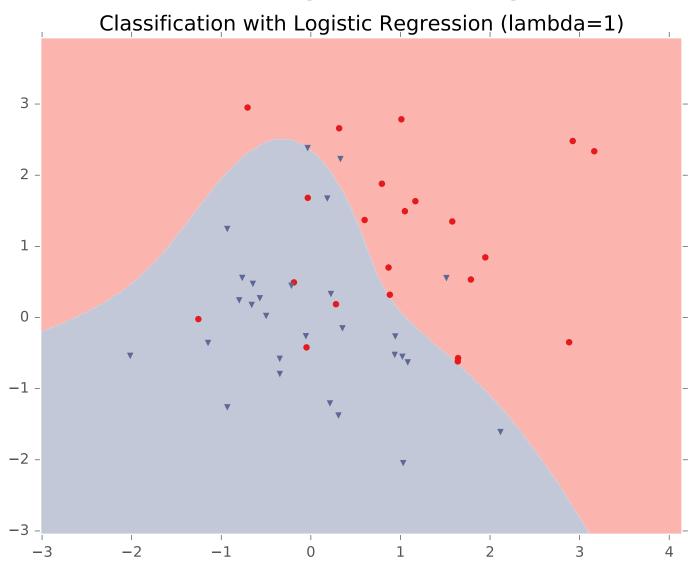


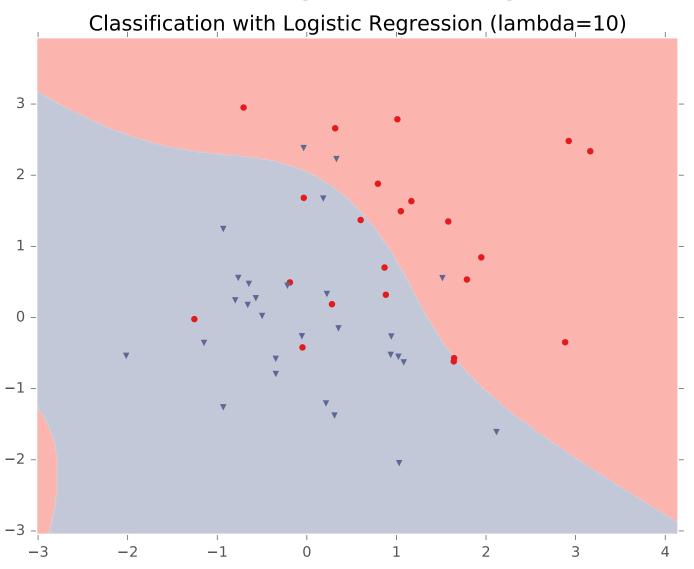


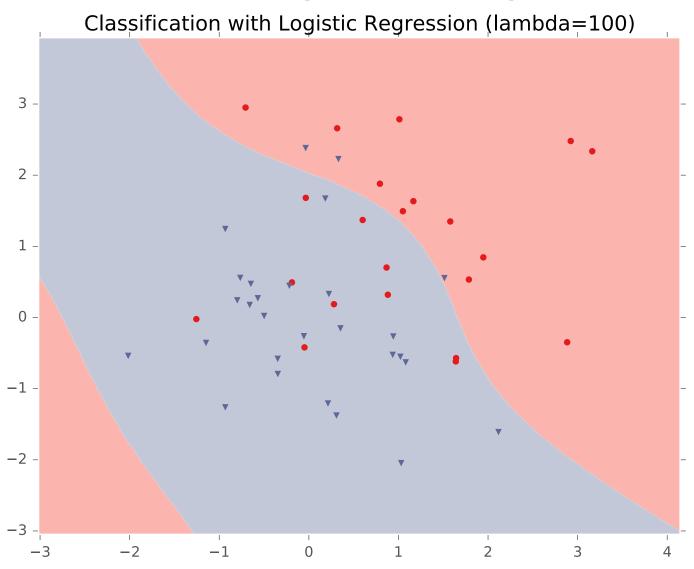


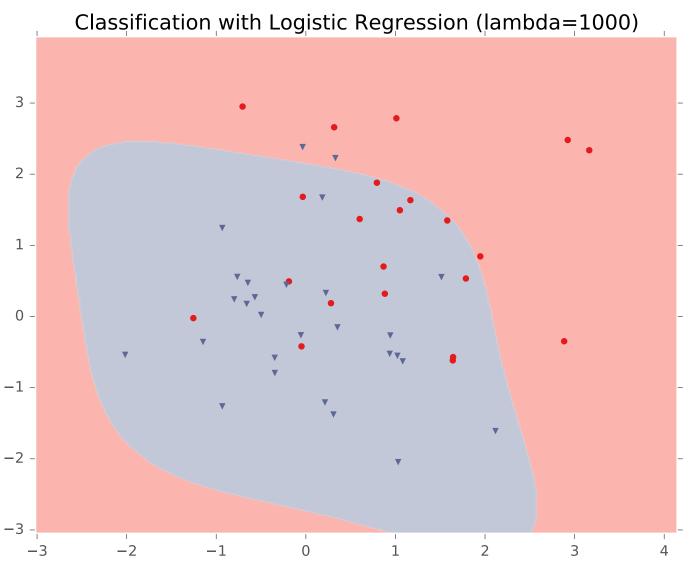


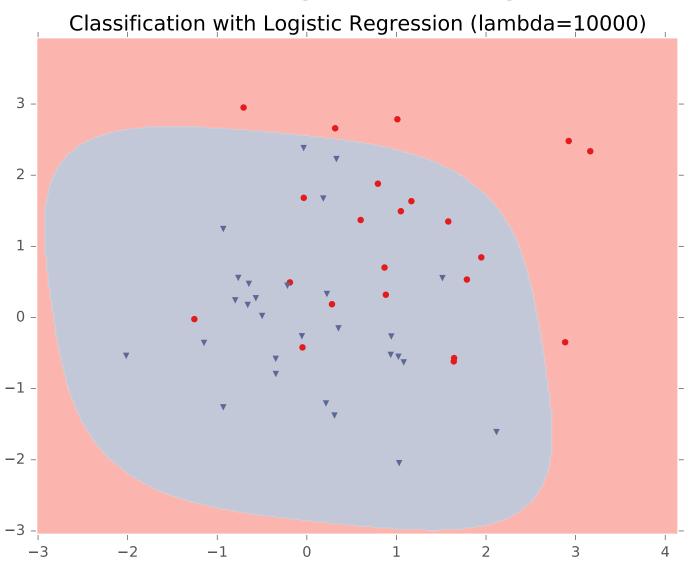


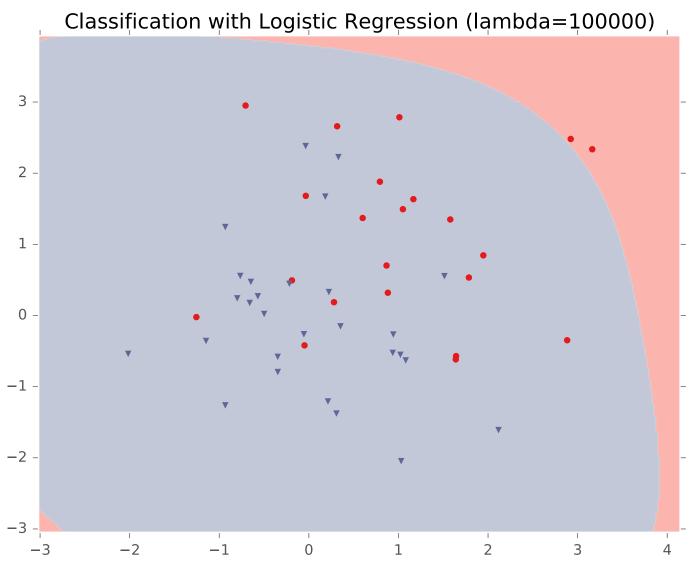


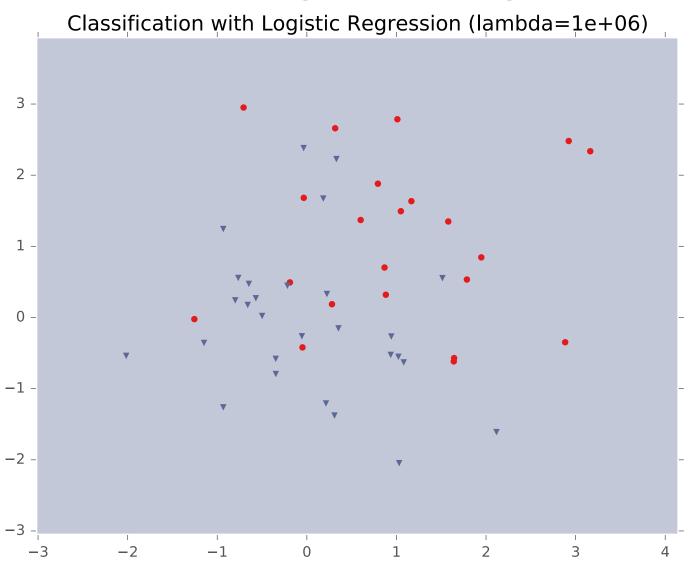


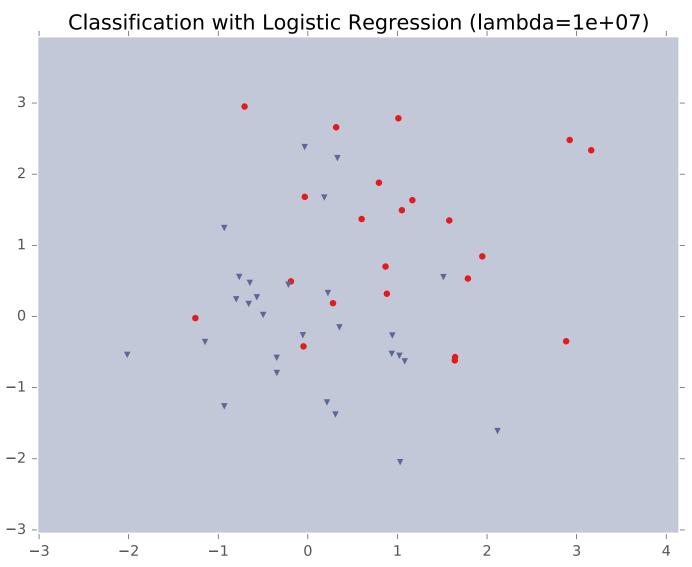


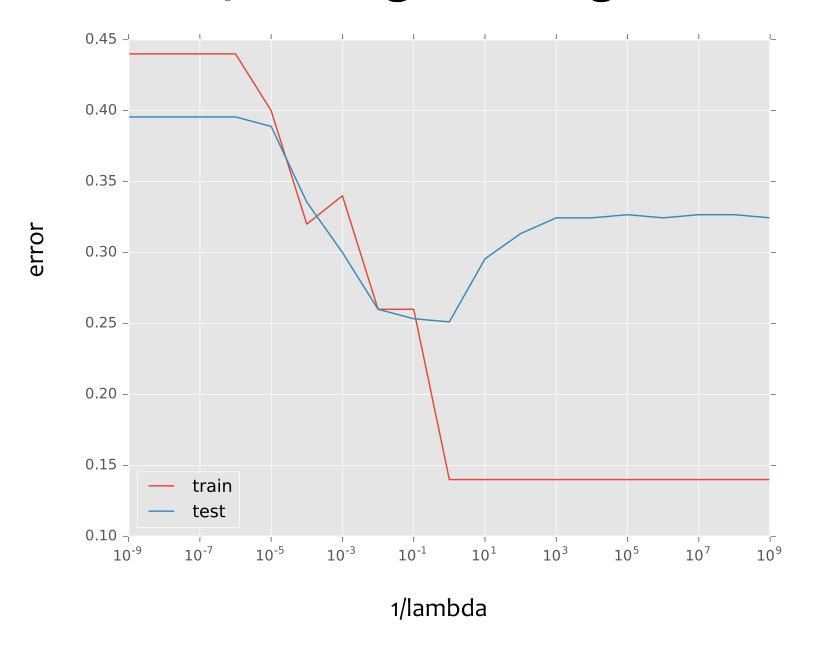












#### Regularization as MAP

- L1 and L2 regularization can be interpreted as maximum a-posteriori (MAP) estimation of the parameters
- To be discussed later in the course...

#### Takeaways

- 1. Nonlinear basis functions allow linear models (e.g. Linear Regression, Logistic Regression) to capture nonlinear aspects of the original input
- Nonlinear features are require no changes to the model (i.e. just preprocessing)
- 3. Regularization helps to avoid overfitting
- 4. Regularization and MAP estimation are equivalent for appropriately chosen priors

# Feature Engineering / Regularization Objectives

You should be able to...

- Engineer appropriate features for a new task
- Use feature selection techniques to identify and remove irrelevant features
- Identify when a model is overfitting
- Add a regularizer to an existing objective in order to combat overfitting
- Explain why we should not regularize the bias term
- Convert linearly inseparable dataset to a linearly separable dataset in higher dimensions
- Describe feature engineering in common application areas

#### Neural Networks Outline

#### Logistic Regression (Recap)

Data, Model, Learning, Prediction

#### Neural Networks

- A Recipe for Machine Learning
- Visual Notation for Neural Networks
- Example: Logistic Regression Output Surface
- 2-Layer Neural Network
- 3-Layer Neural Network

#### Neural Net Architectures

- Objective Functions
- Activation Functions

#### Backpropagation

- Basic Chain Rule (of calculus)
- Chain Rule for Arbitrary Computation Graph
- Backpropagation Algorithm
- Module-based Automatic Differentiation (Autodiff)

#### **NEURAL NETWORKS**

#### Background

# A Recipe for Machine Learning

1. Given training data:

$$\{oldsymbol{x}_i,oldsymbol{y}_i\}_{i=1}^N$$

- 2. Choose each of these:
  - Decision function

$$\hat{\boldsymbol{y}} = f_{\boldsymbol{\theta}}(\boldsymbol{x}_i)$$

Loss function

$$\ell(\hat{m{y}},m{y}_i)\in\mathbb{R}$$

Face Face Not a face

**Examples:** Linear regression, Logistic regression, Neural Network

**Examples:** Mean-squared error, Cross Entropy

#### Background

# A Recipe for Machine Learning

1. Given training data:

$$\{oldsymbol{x}_i, oldsymbol{y}_i\}_{i=1}^N$$

3. Define goal:

$$oldsymbol{ heta}^* = rg\min_{oldsymbol{ heta}} \sum_{i=1}^N \ell(f_{oldsymbol{ heta}}(oldsymbol{x}_i), oldsymbol{y}_i)$$

- 2. Choose each of these:
  - Decision function

$$\hat{\boldsymbol{y}} = f_{\boldsymbol{\theta}}(\boldsymbol{x}_i)$$

Loss function

$$\ell(\hat{oldsymbol{y}}, oldsymbol{y}_i) \in \mathbb{R}$$

4. Train with SGD:

(take small steps opposite the gradient)

$$\boldsymbol{\theta}^{(t+1)} = \boldsymbol{\theta}^{(t)} - \eta_t \nabla \ell(f_{\boldsymbol{\theta}}(\boldsymbol{x}_i), \boldsymbol{y}_i)$$

#### Background

# A Recipe for Gradients

1. Given training dat

$$\{oldsymbol{x}_i,oldsymbol{y}_i\}_{i=1}^N$$
 gradient! And it's a

- 2. Choose each of the
  - Decision function

$$\hat{\boldsymbol{y}} = f_{\boldsymbol{\theta}}(\boldsymbol{x}_i)$$

Loss function

$$\ell(\hat{y}, y_i) \in \mathbb{R}$$

**Backpropagation** can compute this gradient!

And it's a special case of a more general algorithm called reversemode automatic differentiation that can compute the gradient of any differentiable function efficiently!

opposite the gradient) 
$$oldsymbol{ heta}^{(t)} - \eta_t 
abla \ell(f_{oldsymbol{ heta}}(oldsymbol{x}_i), oldsymbol{y}_i)$$

#### A Recipe for

# Goals for Today's Lecture

- 1. Explore a **new class of decision functions** (Neural Networks)
  - 2. Consider variants of this recipe for training

#### 2. Choose each of these.

Decision function

$$\hat{\boldsymbol{y}} = f_{\boldsymbol{\theta}}(\boldsymbol{x}_i)$$

Loss function

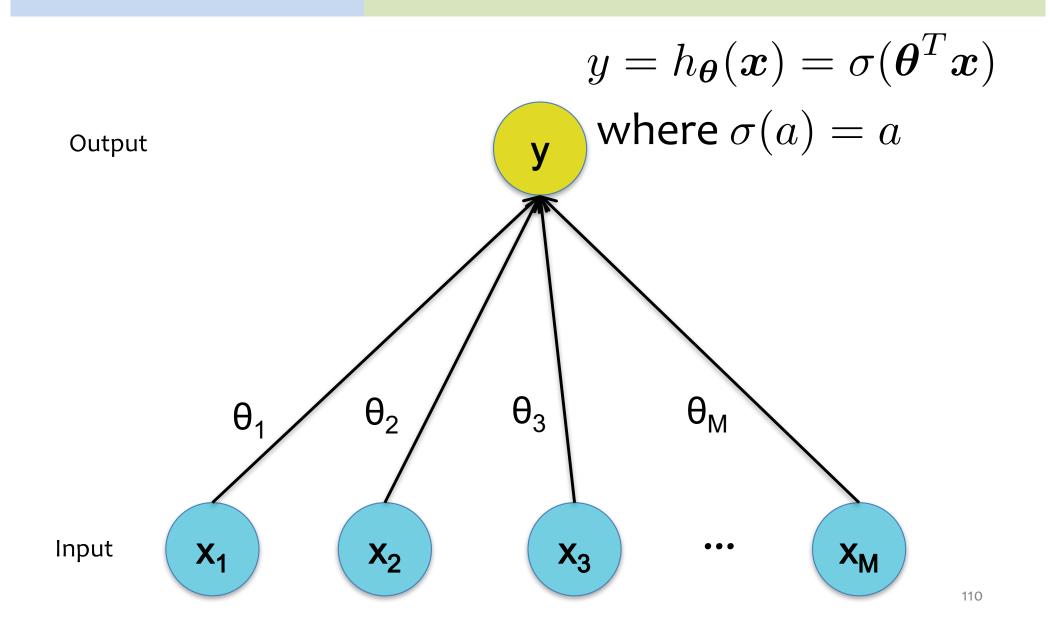
$$\ell(\hat{y}, y_i) \in \mathbb{R}$$

Train with SGD:

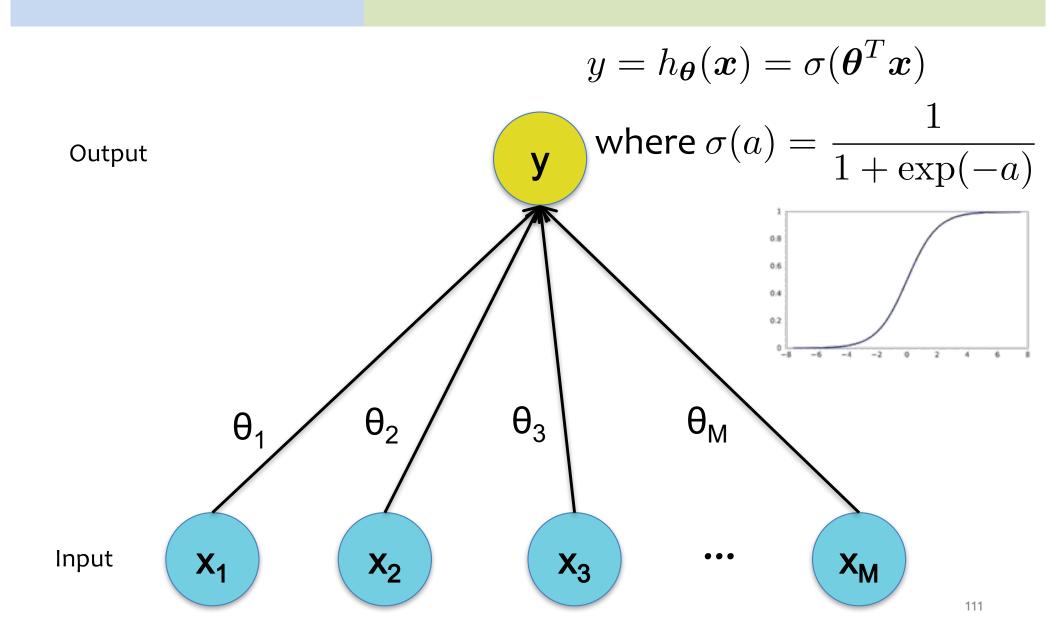
ke small steps
opposite the gradient)

$$oldsymbol{ heta}^{(t+1)} = oldsymbol{ heta}^{(t)} - \eta_t 
abla \ell(f_{oldsymbol{ heta}}(oldsymbol{x}_i), oldsymbol{y}_i)$$

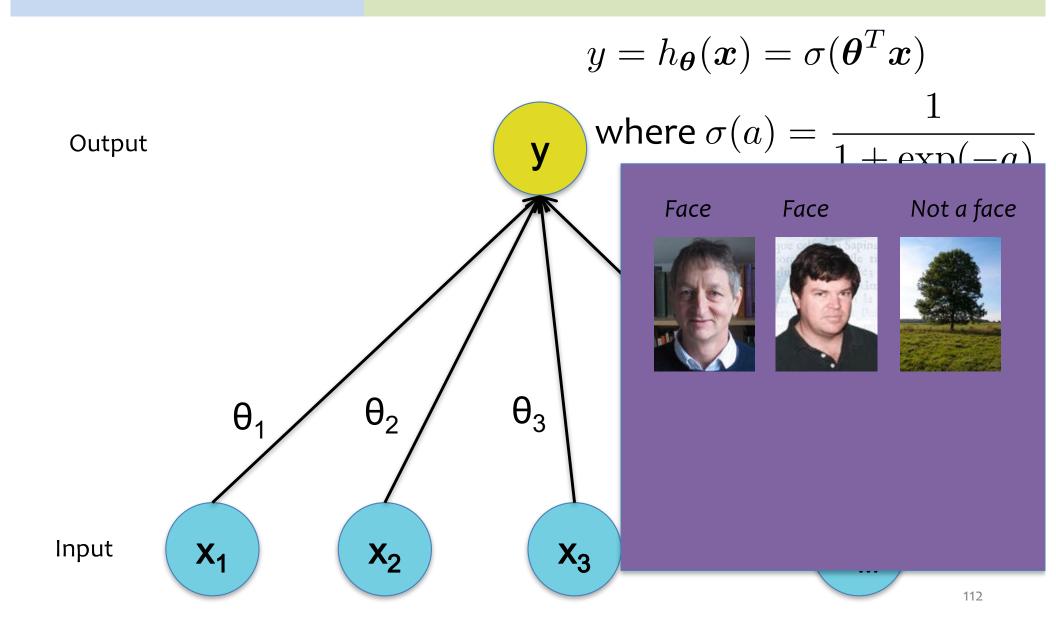
## Linear Regression



# Logistic Regression



# Logistic Regression



# Logistic Regression

