15-453

FORMAL LANGUAGES, AUTOMATA AND COMPUTABILITY Space Complexity II

**THURSDAY April 17** 

PSPACE = NPSPACE

Definition: Language B is PSPACE-complete if:

- 1. B ∈ PSPACE
- 2. Every A in PSPACE is poly-time reducible to B (i.e. B is PSPACE-hard)

QUANTIFIED BOOLEAN FORMULAS
(in prenex normal form)

Allow constants, 0 and 1, eg.  $\forall x [0 \lor \neg x]$ 

A fully quantified Boolean formula is a Boolean formula (in prenex normal form) where every variable is quantified

# TQBF = { $\phi \mid \phi$ is a true fully quantified Boolean formula}

Theorem: TQBF is PSPACE-complete

#### TOBF ∈ PSPACE

## **T(φ)**:

- 1. If  $\varphi$  has no quantifiers, then it is an expression with only constants. Evaluate  $\varphi.$  Accept iff  $\varphi$  evaluates to 1.
- 2. If  $\phi=\exists x\ \psi$ , recursively call T on  $\psi$ , first with x=0 and then with x=1. Accept iff either one of the calls accepts.
- 3. If  $\phi = \forall x \ \psi$ , recursively call T on  $\psi$ , first with x = 0 and then with x = 1. Accept iff both of the calls accept.

Claim: Every language A in PSPACE is polynomial time reducible to TQBF

We build a poly-time reduction from A to TQBF

The reduction turns a string w into a fully quantified Boolean formula  $\phi$  that simulates the PSPACE machine for A on w

Let M be a deterministic TM that decides A in space n<sup>k</sup> How do we know M exists?

nk

We design  $\phi$  to encode a simulation of M on w  $\phi$  will be true if and only if M accepts w

Given two collections of variables denoted c and d representing two configurations and t > 0, we construct a formula  $\phi_{c,d,t}$ 

If we assign c and d to actual configurations,  $\phi_{c,d,t}$  will be true if and only if M can go from c to d in t steps

We let  $\phi = \phi_{c_{start}, c_{accept}, h}$ , where  $h = 2^{e_{s(n)}}$  for a constant e chosen so that M has less than  $2^{e_{s(n)}}$  possible configurations on an input of length n Here  $s(n) = n^k$ 

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If we assign c and d to actual configurations,  $\phi_{c,d,t}$  will say:

"there exists a configuration m such that  $\phi_{c,m,t/2}$  is true and  $\phi_{m,d,t/2}$  is true"

We let  $\phi = \phi_{c_{start}, c_{accept}, h}$ , where  $h = 2^{e s(n)}$  for a

constant e chosen so that M has less than  $2^{e s(n)}$  possible configurations on an input of length n Here  $s(n) = n^k$ 

### **HIGH-LEVEL IDEA:**

Encode the Algorithm of Savitch's Theorem with a Quantified Boolean Formula

If M uses n<sup>k</sup> space,
then the QBF φ will have size O(n<sup>2k</sup>)

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We let  $\phi = \phi_{c_{start}}$ ,  $c_{accept}$ , h, where  $h = 2^{e s(n)}$  for a

constant e chosen so that M has less than  $2^{e \, s(n)}$  possible configurations on an input of length n Here  $s(n) = n^k$ 

To construct  $\phi_{c,d,t}$  use ideas of Cook-Levin plus Savitch:

Each cell in a configuration is associated with variables representing possible tape symbols and states.

Each config has n<sup>k</sup> cells so and is encoded by O(n<sup>k</sup>) variables.

If t = 0 or 1, we can easily construct  $\phi_{c,d,t}$ :

 $\phi_{c,d,t}$  = "c equals d" OR "d follows from c in a single step of M"

How do we express "c equals d"?
Write a Boolean formula saying that each of
the variables representing c is equal to the
corresponding one in d

"d follows from c in a single step of M"? Use 2 x 3 windows as in the Cook-Levin theorem, and write a CNF formula If t > 1, we construct  $\phi_{c,d,t}$  recursively:

$$\begin{split} \varphi_{c,d,t} &= \exists m \ \big[ \varphi_{c,m,t/2} \land \varphi_{m,d,t/2} \ \big] \\ &\exists x_1 \, \exists x_2 \dots \exists x_L \quad L = O(n^k) \end{split}$$

But how long is this formula?

Every level of the recursion cuts t in half but roughly doubles the size of the formula (so back to length O(t)

So, we modify the formula to be:

$$\phi_{c,d,t} = \exists m \forall a,b[ [(a,b)=(c,m) \lor (a,b)=(m,d)]$$
  
=> [  $\phi_{a,b,t/2}$  ] ]

This folds the 2 recursive sub-formulas into 1

$$\phi_{c,d,t} = \exists m \forall a,b[ [(a,b)=(c,m) \lor (a,b)=(m,d)] =>[ \phi_{a,b,t/2} ] ]$$

Set 
$$\phi = \phi_{c_{start}, c_{accept}, h}$$
 where  $h = 2^{d s(n)}$ 

- Each recursive step adds a portion that is linear in the size of the configurations, so has size O(s(n))
  - Number of levels of recursion is log h = O(s(n))
    - Hence, the size of φ is O(s(n)²)

PSPACE is often called the class of games

Formalizations of many popular games are PSPACE-Complete

# THE FORMULA GAME (FG)

...is played between two players, E and A Given a fully quantified Boolean formula  $\exists y \forall x [(x \lor y) \land (\neg x \lor \neg y)]$ 

E chooses values for variables quantified by ∃
A chooses values for variables quantified by ∀
Start at the leftmost quantifier
E wins if the resulting formula is true
A wins otherwise

$$\forall x \exists y [ (x \lor y) \land (\neg x \lor \neg y) ]$$
  
 $\exists x \exists y [ x \lor \neg y ]$ 

FG = {  $\phi$  | Player E has a winning strategy in  $\phi$  }

Theorem: FG is PSPACE-Complete

Proof:

FG = TQBF

# **GEOGRAPHY**

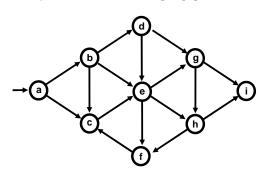
Two players take turns naming cities from anywhere in the world

Each city chosen must begin with the same letter that the previous city ended with

Cities cannot be repeated

 $\mbox{Austin} \rightarrow \mbox{Nashua} \rightarrow \mbox{Albany} \rightarrow \mbox{York}$  Whoever cannot name any more cities loses

GENERALIZED GEOGRAPHY



GG = { (G, b) | Player 1 has a winning strategy for generalized geography played on graph G starting at node b }

Theorem: GG is PSPACE-Complete

## $GG \in PSPACE$

WANT: Machine M that accepts (G,b)

⇔ Player 1 has a winning strategy on (G, b)

M(G, b): If b has no outgoing edges, reject.

- 1. Remove node b and all edges touching it to get to a new graph G<sub>1</sub>
- 2. For each of the nodes  $b_1, b_2, ..., b_k$  that b originally pointed at, recursively call  $M(G_1, b_i)$ 
  - 3. If all of these accept, Player 2 has a winning strategy, so *reject*.

    Otherwise, *accept*.

## GG IS PSPACE-HARD

We show that FG ≤<sub>p</sub> GG

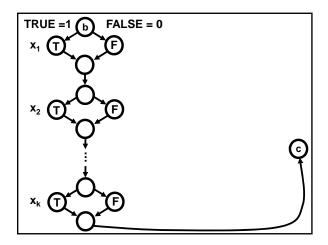
We convert a formula ∮ into (G, b) such that:

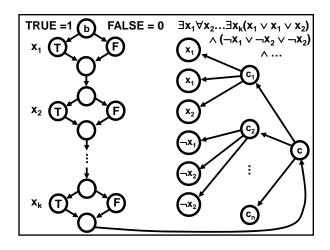
Player E has winning strategy in φ if and only if Player 1 has winning strategy in (G, b)

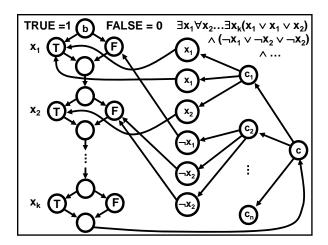
For simplicity we assume  $\phi$  is of the form:

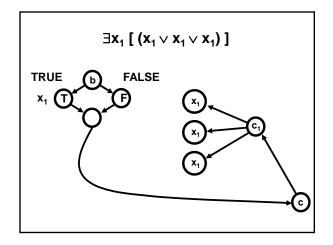
$$\phi = \exists x_1 \forall x_2 \exists x_3 ... \exists x_k [\psi]$$

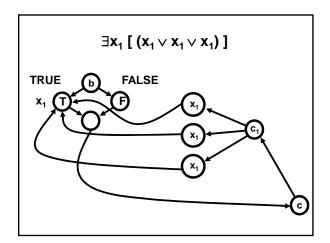
where  $\psi$  is in cnf. (Quantifiers alternate, and the last move is E's)











GG = { (G, b) | Player 1 has a winning strategy for generalized geography played on graph G starting at node b }

Theorem: GG is PSPACE-Complete

### Question:

Is Chess a PSPACE complete problem?

No, because determining whether a player has a winning strategy takes CONSTANT time and space (OK, the constant is large...)

But n x n GO, Chess and Checkers can be shown to be PSPACE-hard

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Read Chapter 10.2 of the book for next time