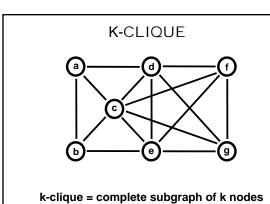
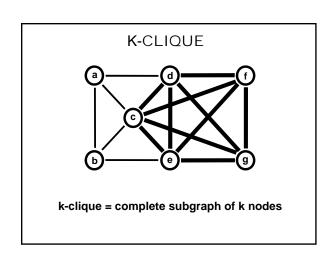
15-453

FORMAL LANGUAGES, AUTOMATA AND COMPUTABILITY NP-COMPLETENESS II

Tuesday April 1



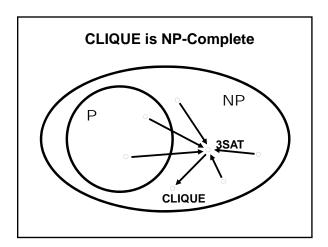


Assume a reasonable encoding of graphs (example: the adjacency matrix is reasonable)

CLIQUE = { (G,k) | G is an undirected graph with a k-clique }

Theorem: CLIQUE is NP-Complete

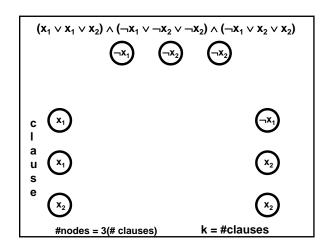
(1) CLIQUE ∈ NP(2) 3SAT ≤_p CLIQUE

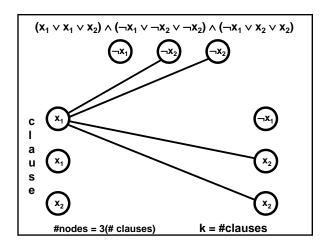


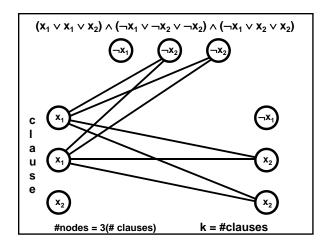
$3\mathsf{SAT} \leq_{\mathsf{P}} \mathbf{CLIQUE}$

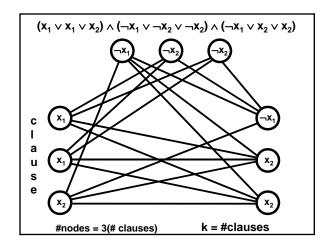
We transform a 3-cnf formula ϕ into (G,k) such that $\phi \in 3SAT \Leftrightarrow (G,k) \in CLIQUE$

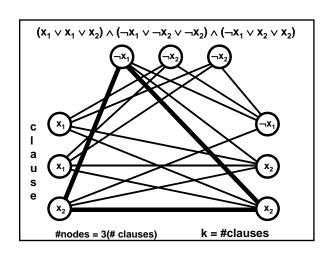
The transformation can be done in time that is polynomial in the length of ϕ











3SAT ≤_P CLIQUE

We transform a 3-cnf formula ϕ into (G,k) such that $\phi \in 3SAT \Leftrightarrow (G,k) \in CLIQUE$

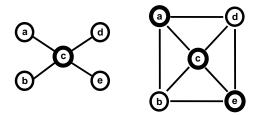
If ϕ has m clauses, we create a graph with m clusters of 3 nodes each, and set k=m Each cluster corresponds to a clause. Each node in a cluster is labeled with a literal from the clause.

We do not connect any nodes in the same cluster We connect nodes in different clusters whenever they are not contradictory

The transformation can be done in time that is polynomial in the length of φ

 $(\mathbf{X}_1 \vee \mathbf{X}_1 \vee \mathbf{X}_1) \wedge (\neg \mathbf{X}_1 \vee \neg \mathbf{X}_1 \vee \mathbf{X}_2) \wedge (\mathbf{X}_2 \vee \mathbf{X}_2 \vee \mathbf{X}_2) \wedge (\neg \mathbf{X}_2 \vee \neg \mathbf{X}_2 \vee \mathbf{X}_1)$

VERTEX COVER



vertex cover = set of nodes that cover all edges

VERTEX-COVER = { (G,k) | G is an undirected graph with a k-node vertex cover }

Theorem: VERTEX-COVER is NP-Complete

- (1) VERTEX-COVER ∈ NP
- (2) 3SAT ≤_p VERTEX-COVER

3SAT ≤_P VERTEX-COVER

We transform a 3-cnf formula ϕ into (G,k) such that $\phi \in 3SAT \Leftrightarrow (G,k) \in VERTEX-COVER$

The transformation can be done in time polynomial in the length of ϕ

 $(x_1 \lor x_1 \lor x_2) \land (\neg x_1 \lor \neg x_2 \lor \neg x_2) \land (\neg x_1 \lor x_2 \lor x_2)$

Variables and negations of variables

 (x_1)







clauses

 (x_1)





 x_1

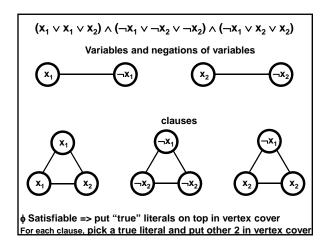


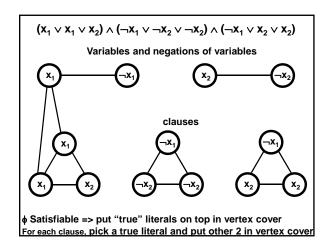


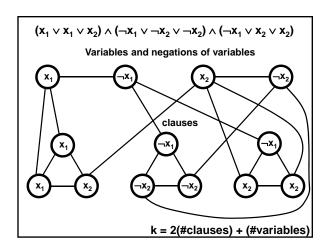


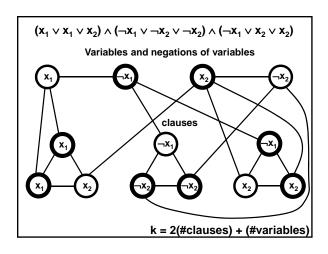




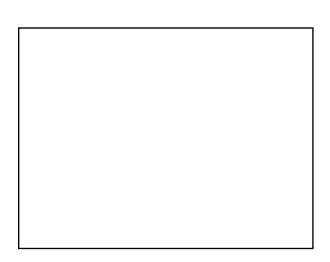


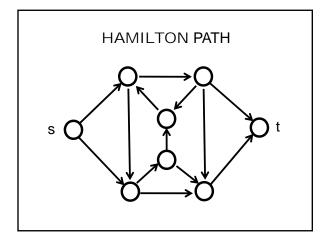






$$(x_{1} \lor x_{1} \lor x_{1}) \land (\neg x_{1} \lor \neg x_{1} \lor x_{2}) \land (x_{2} \lor x_{2} \lor x_{2}) \land (\neg x_{2} \lor \neg x_{2} \lor x_{1})$$





HAMPATH = { (G,s,t) | G is an directed graph with a Hamilton path from s to t}

Theorem: HAMPATH is NP-Complete

- (1) HAMPATH ∈ NP
- (2) 3SAT \leq_P HAMPATH

Proof is in Sipser, Chapter 7.5

$$(\mathbf{x}_1 \lor \mathbf{x}_1 \lor \mathbf{x}_2) \land (\neg \mathbf{x}_1 \lor \neg \mathbf{x}_2 \lor \neg \mathbf{x}_2)$$

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