

Generating Natural Human Motion

Jessica Hodgins

Robotics Institute and Computer Science

jkh@cs.cmu.edu

www.cs.cmu.edu/~jkh

Why Human Motion?

- Computer animation



- Interactive environments

- Physical training

- Robotics



Why Natural?

- Computer animation
- Interactive environments
- Physical training
- Humanoid Robots

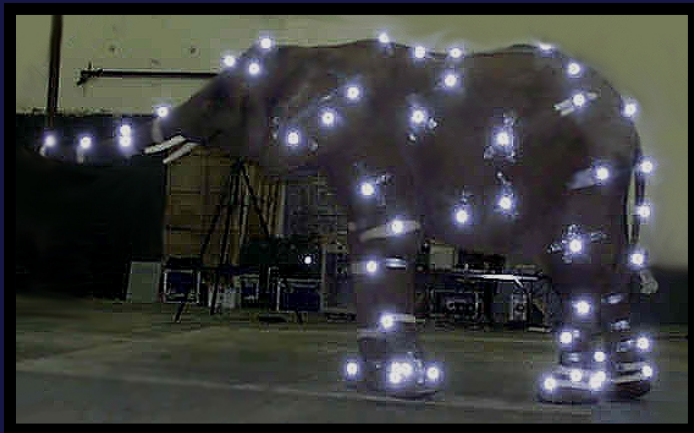


Examples

- Motion Capture
- Simulation
- Optimization
- Robot Control

Motion Capture → Natural?

Motion Capture



Motion Analysis



House of Moves



House of Moves

Human Motion Data

Vicon MX-40 camera system, 12 cameras

120fps at 4Mpixel resolution

4-9mm markers, 40-100+ \Rightarrow joint angles

<http://mocap.cs.cmu.edu>

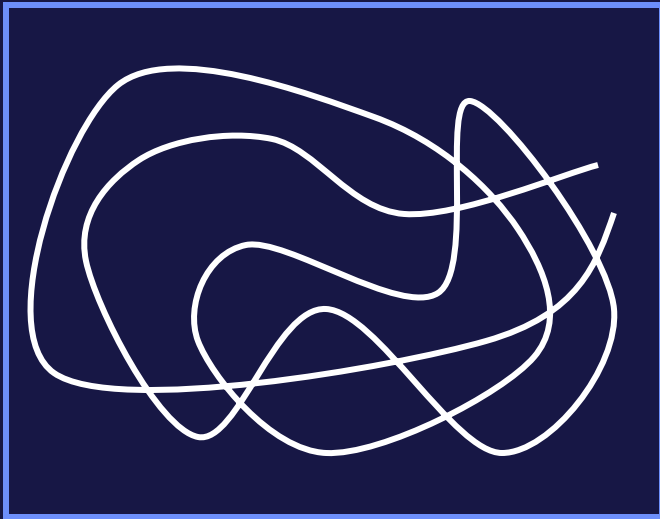


But does it remain natural
through modifications?

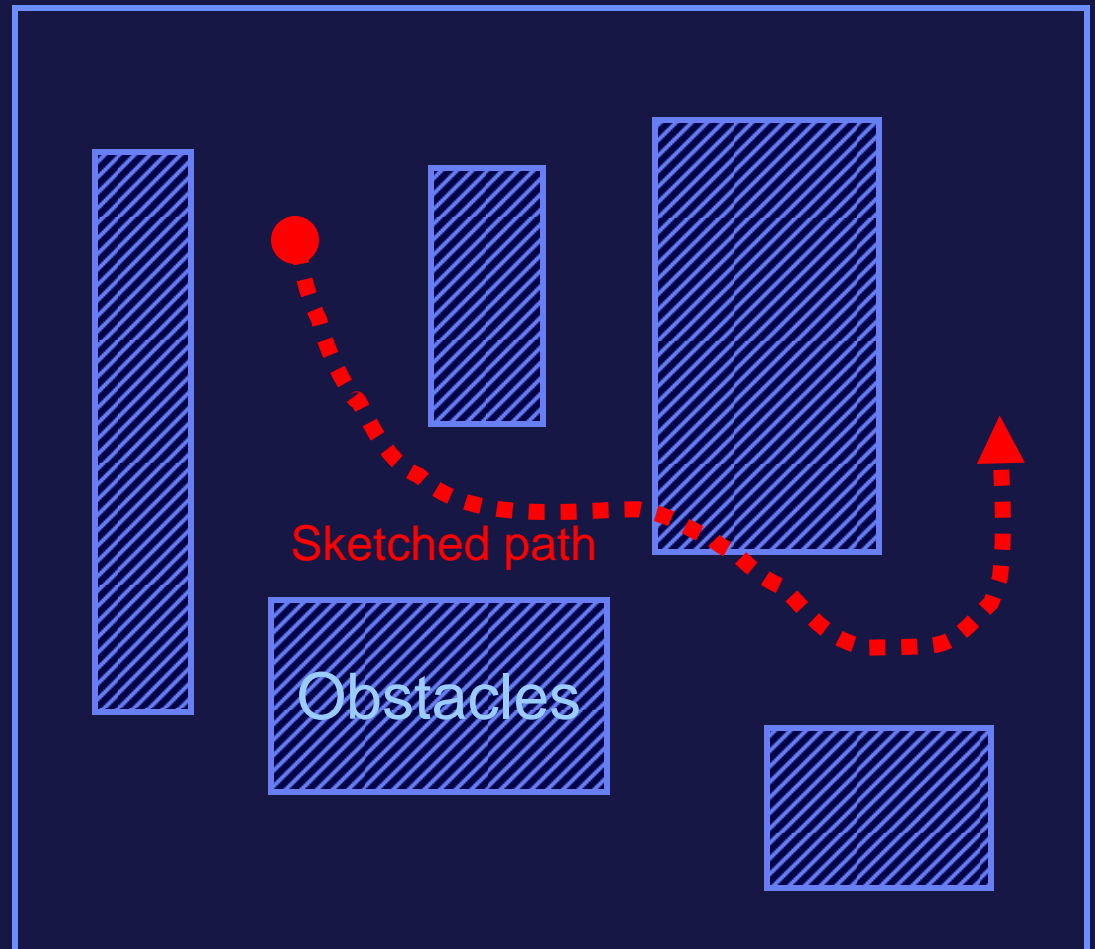
Motion Graphs

Re-sequence

Motion Capture Region

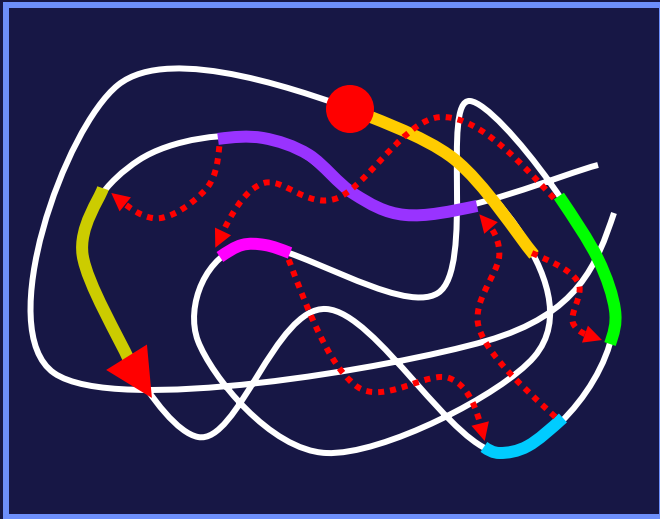


Virtual Environment

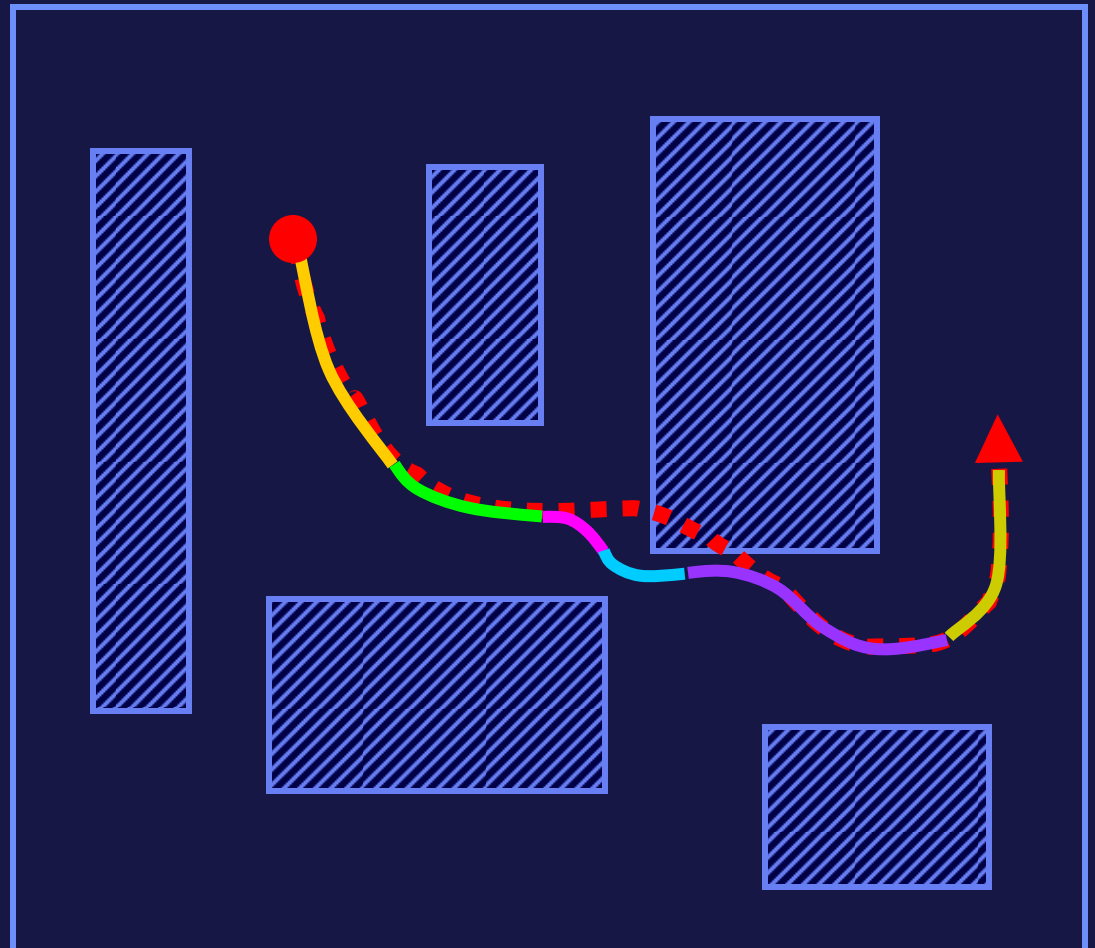


Re-sequence

Motion Capture Region



Virtual Environment

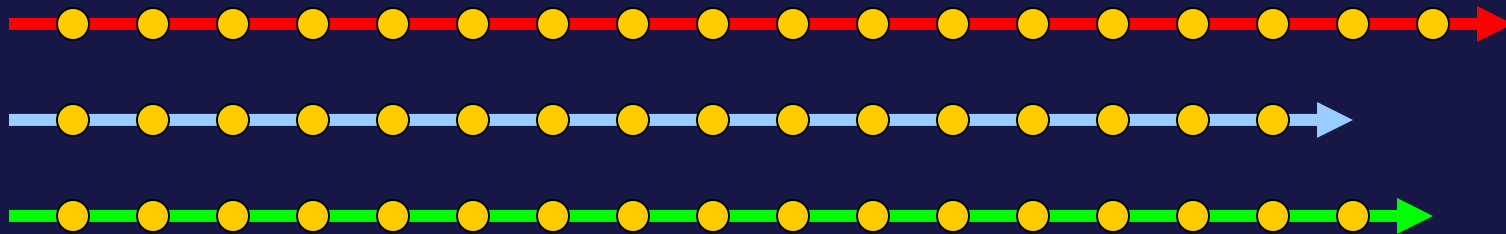


Raw Captured Motion Data

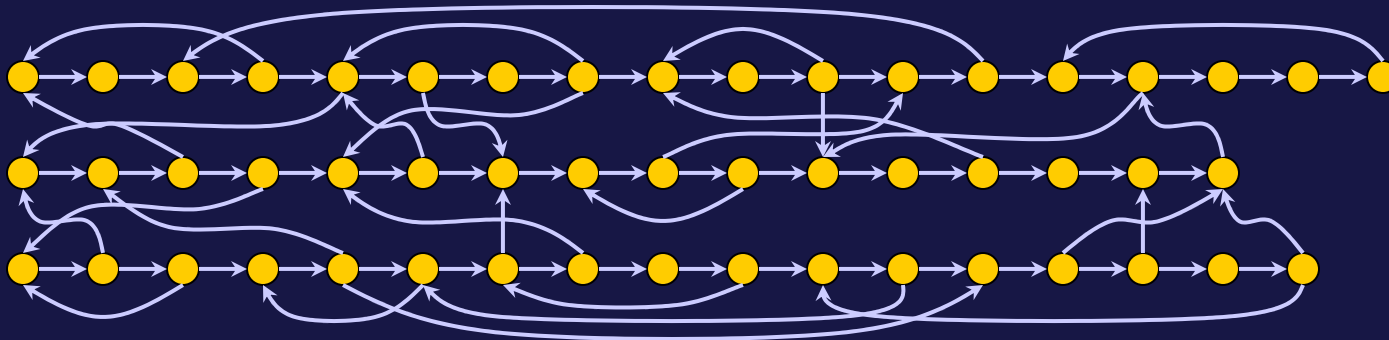
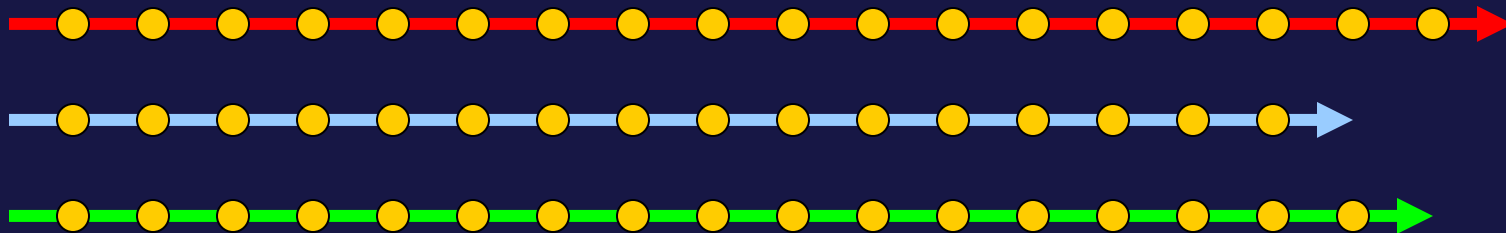


with Jehee Lee

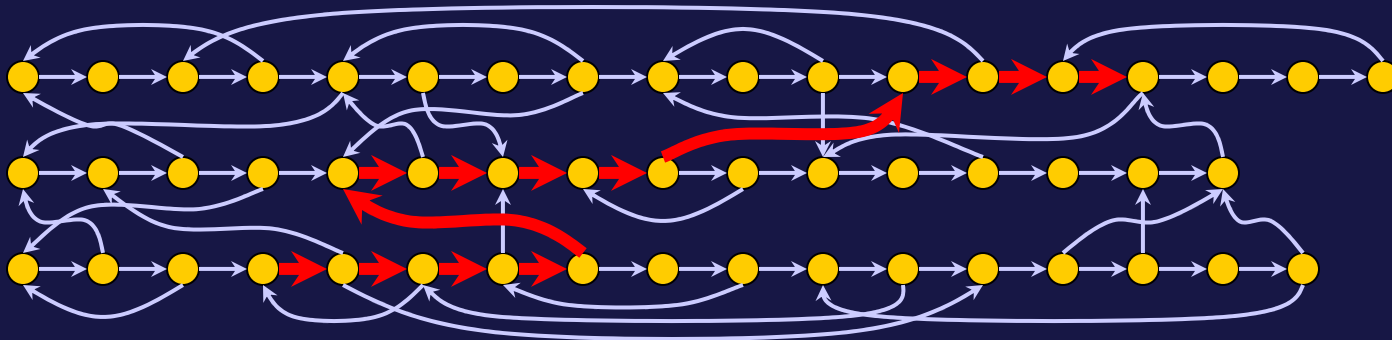
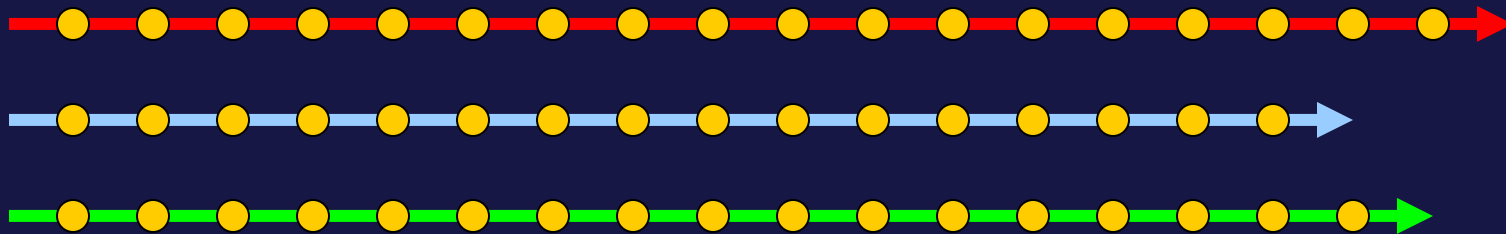
Unstructured Input Data



Connecting Transitions



Search (local) to Find Path





Motion Data for Rough Terrain



Comparison to Real Motion

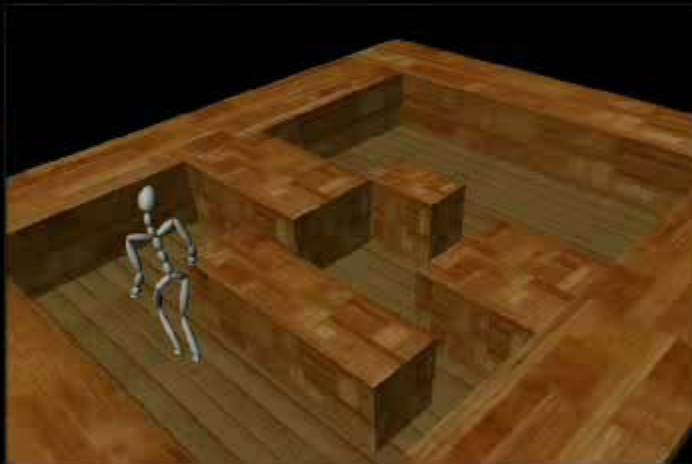


Comparison to Real Motion

Synthesized

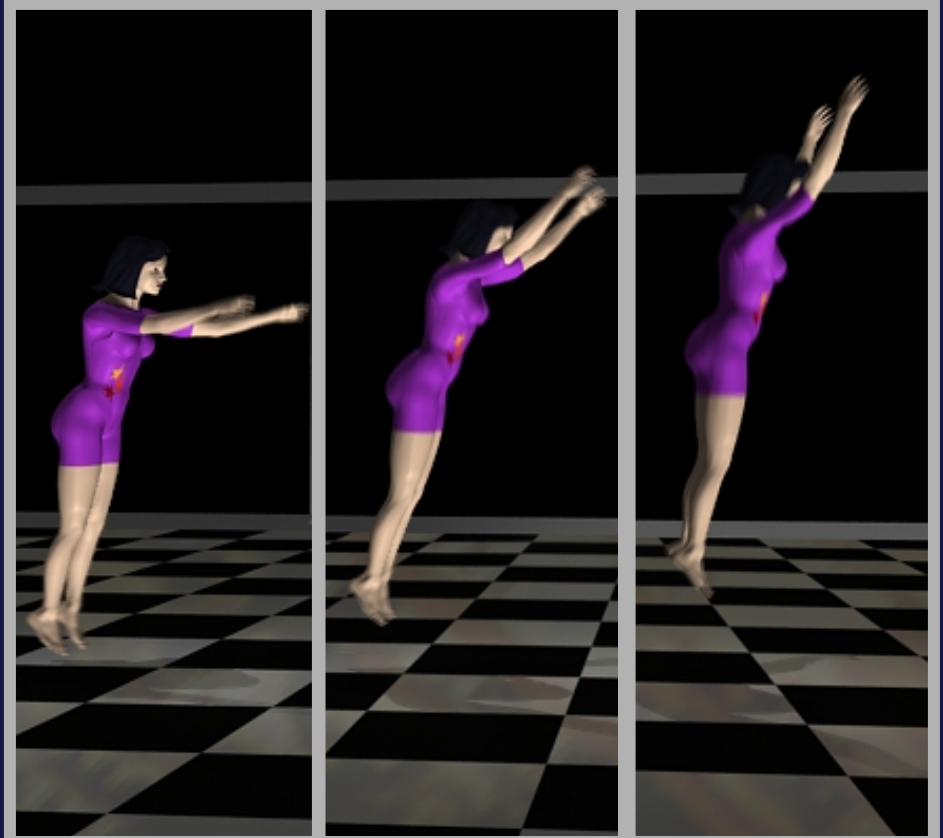
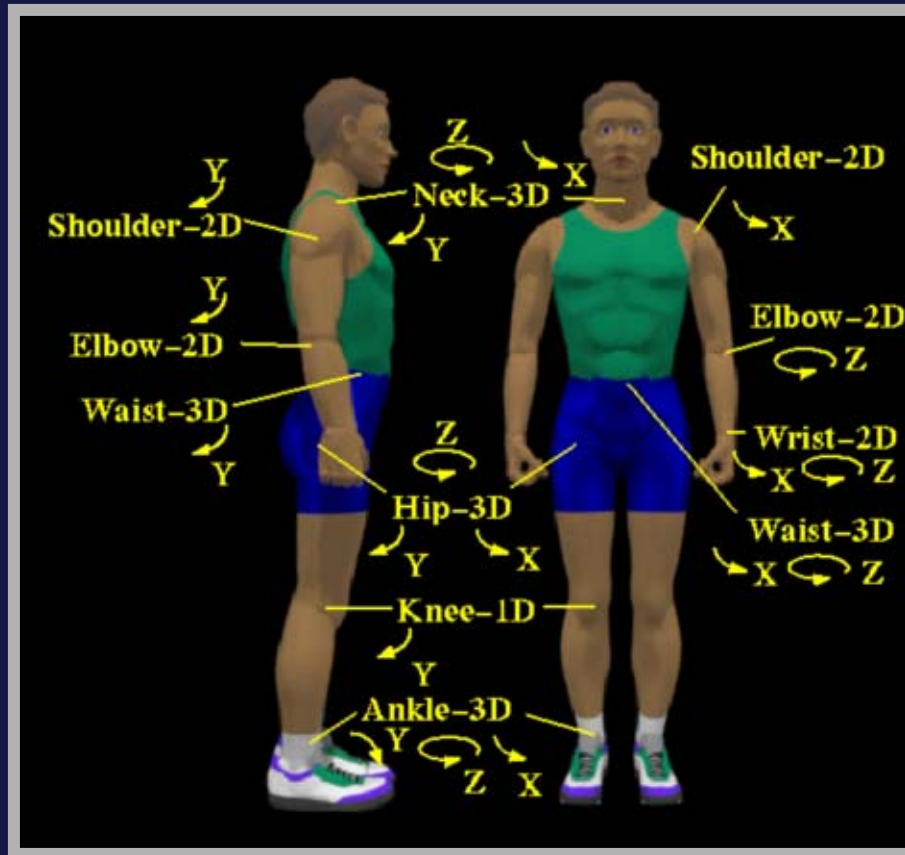


Recorded



Physically Correct \neq Natural

Simulation of Human Motion



Simulation of Human Motion

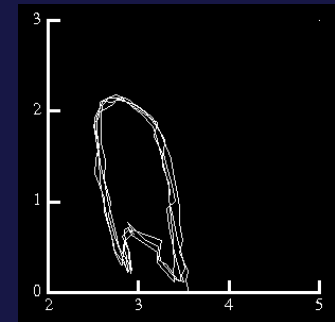
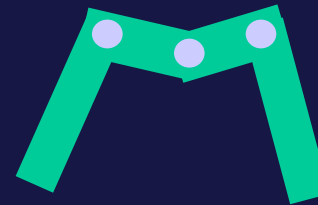
All motion in this animation was
generated using dynamic simulation.

Where do control laws come from?

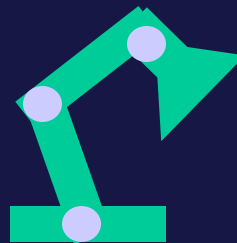
observation



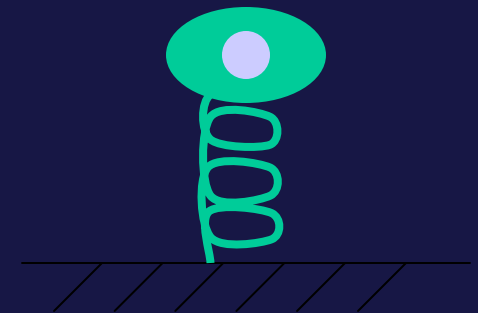
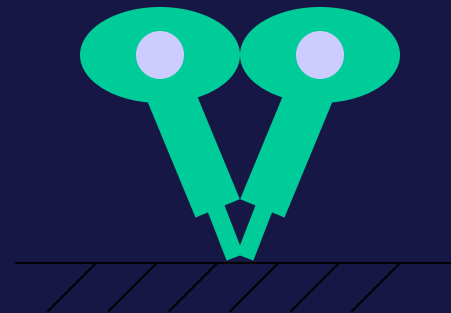
biomechanical literature



optimization

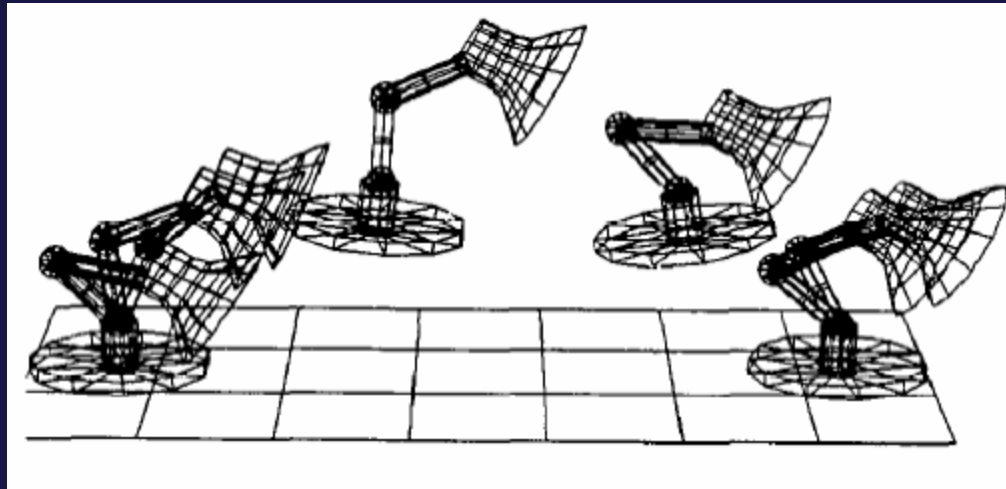
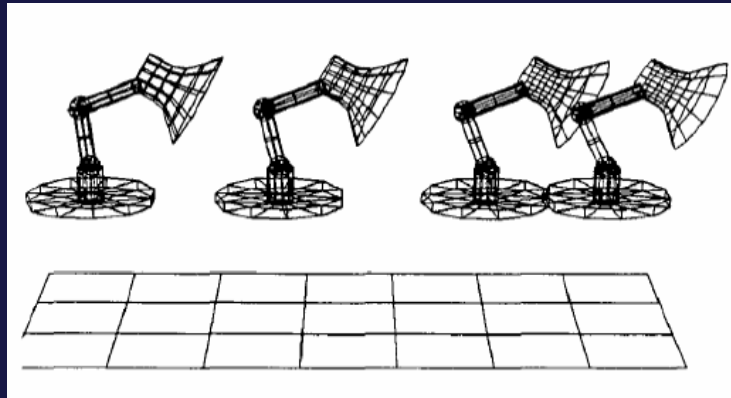


physical intuition

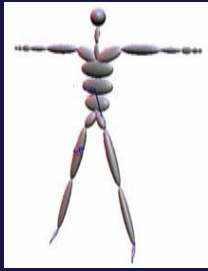


Optimization \neq Natural

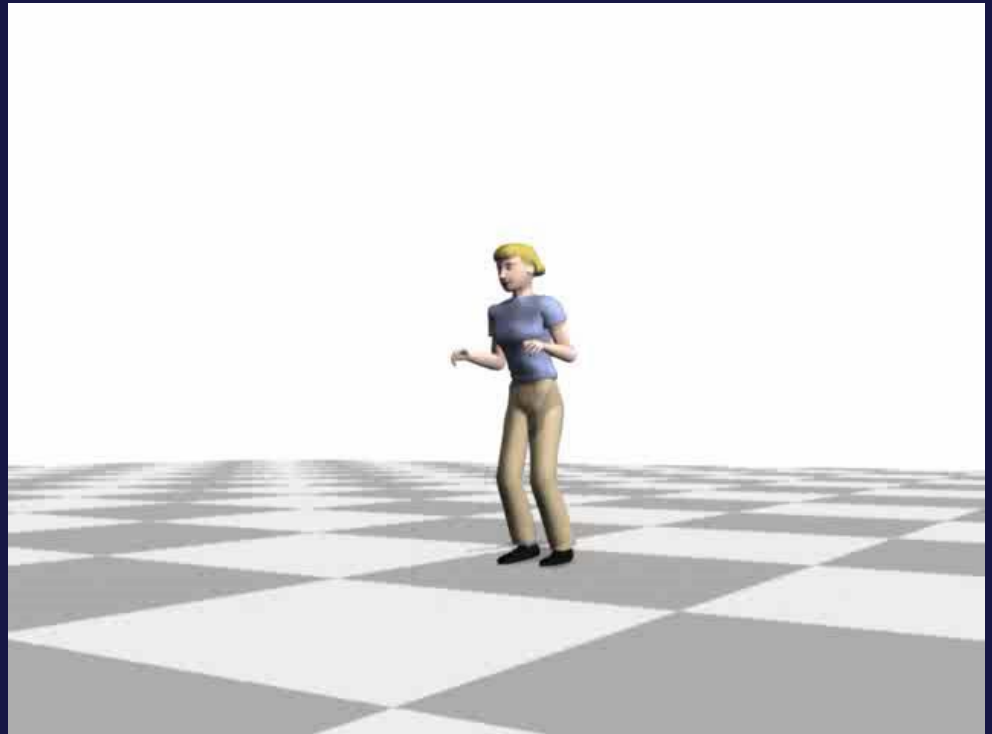
Witkin and Kass SIGGRAPH 1988



But what happens with human characters?



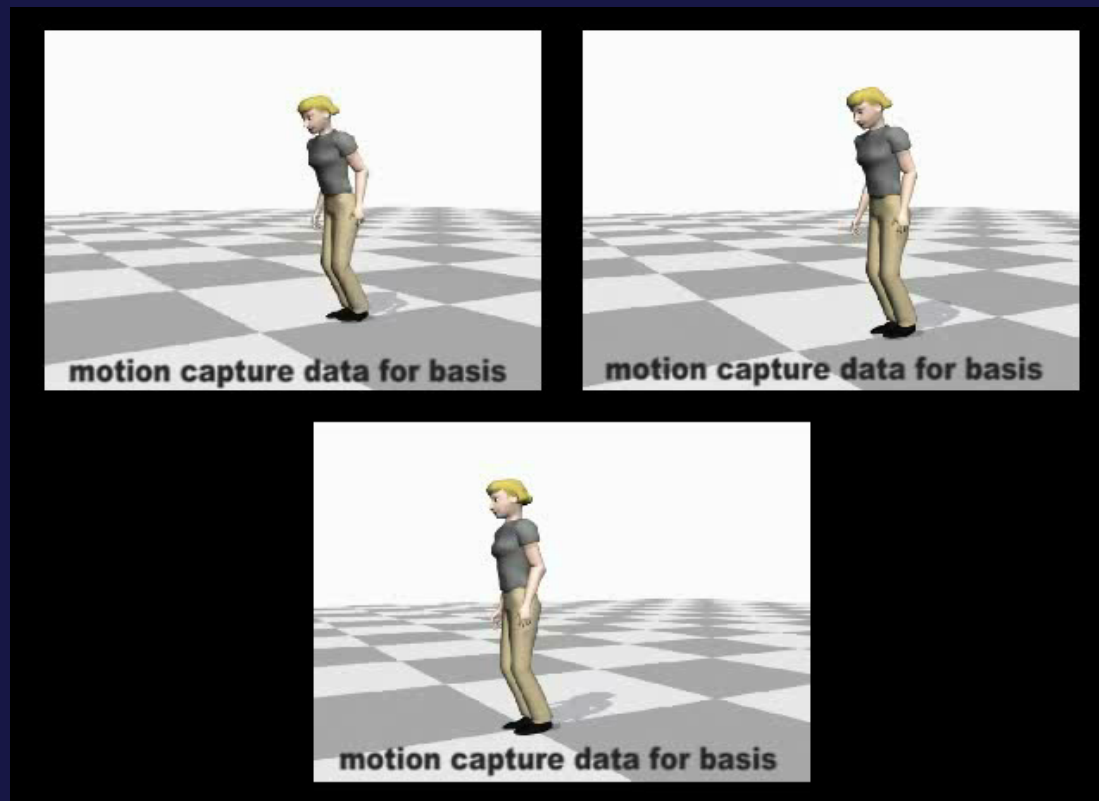
50 to 60 dimensions



Pick few motions with similar behavior

Use principal component analysis to compute low-dimensional space

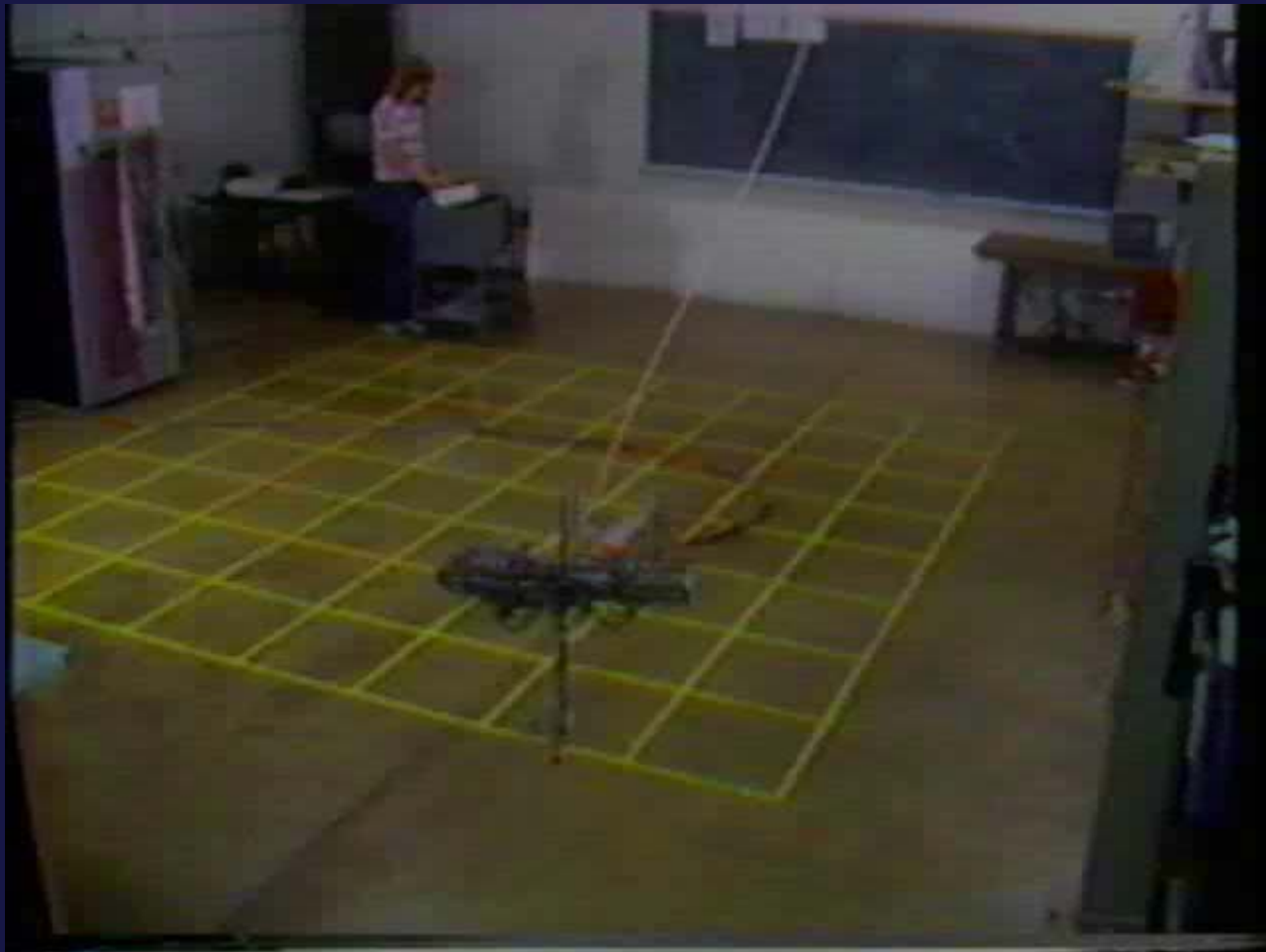
Optimize in low-dimensional space



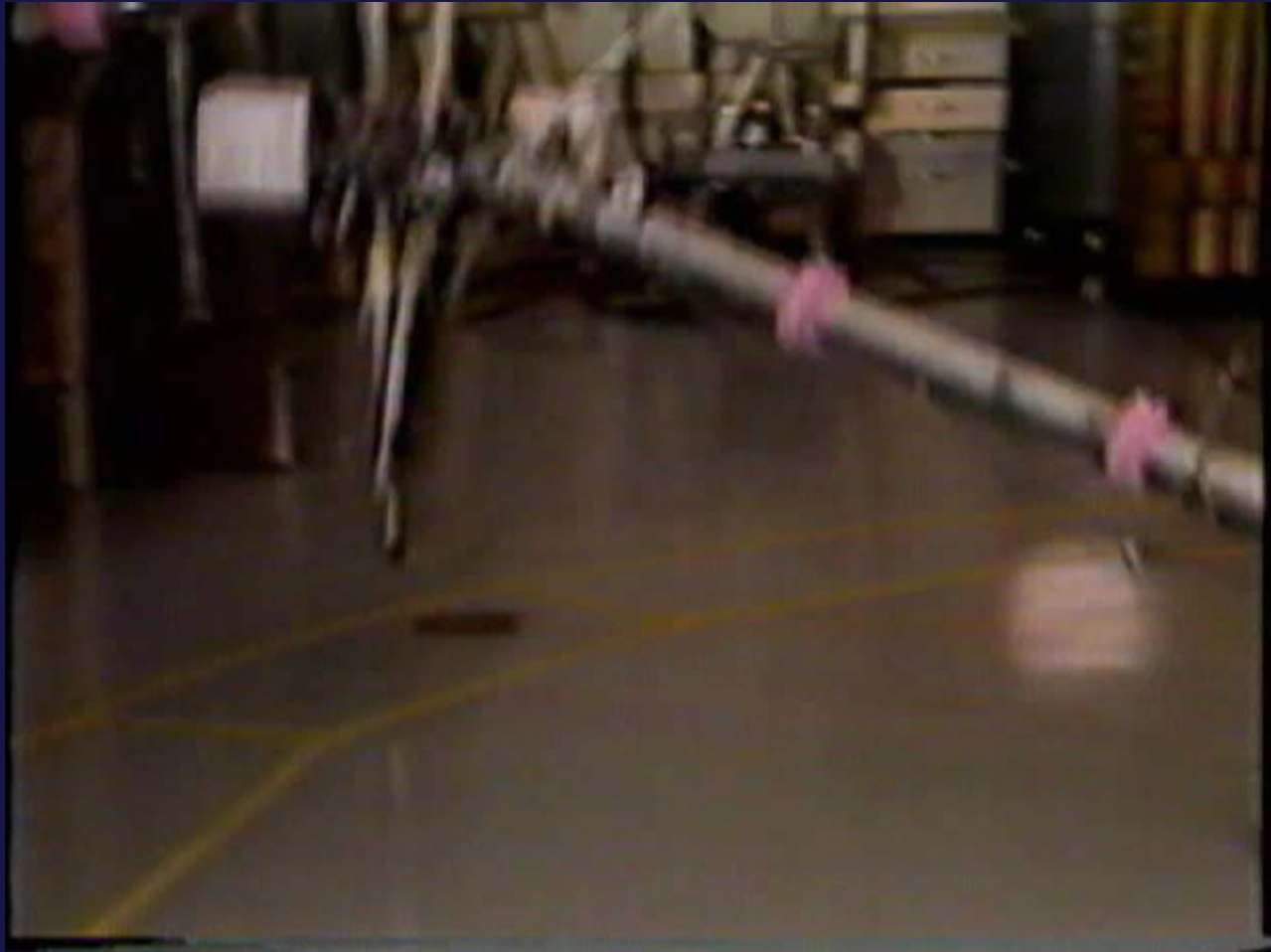
Basis and two generated motions

with Alla Safonova and Nancy Pollard

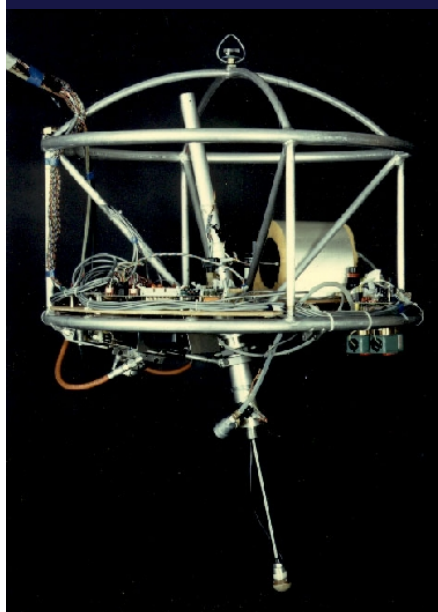
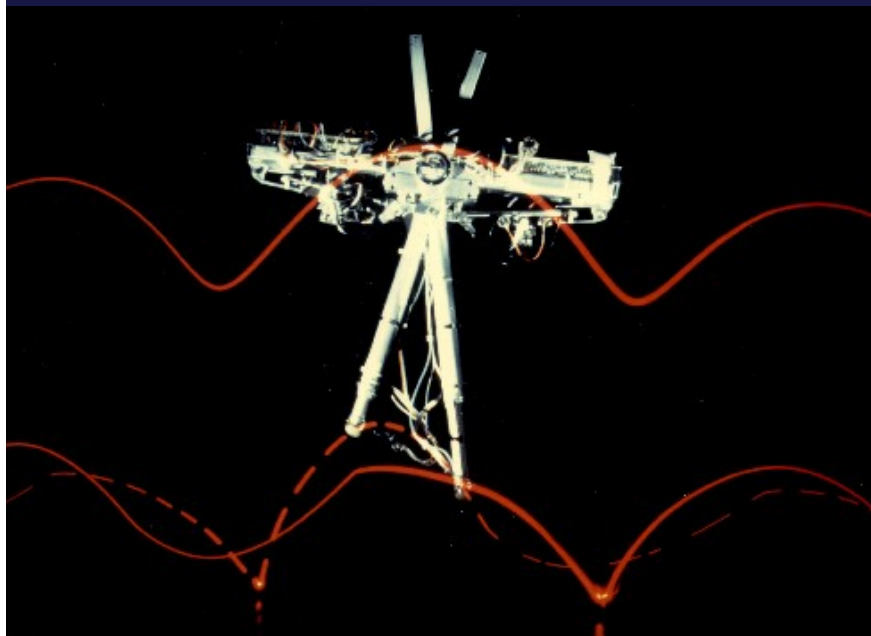
Controlling Robots to be Natural?



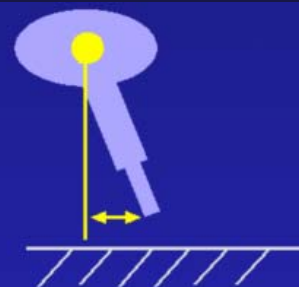
with Jeff Koechling and Marc Raibert



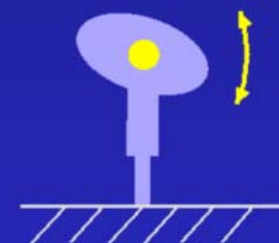
with Marc Raibert



Velocity



Body attitude

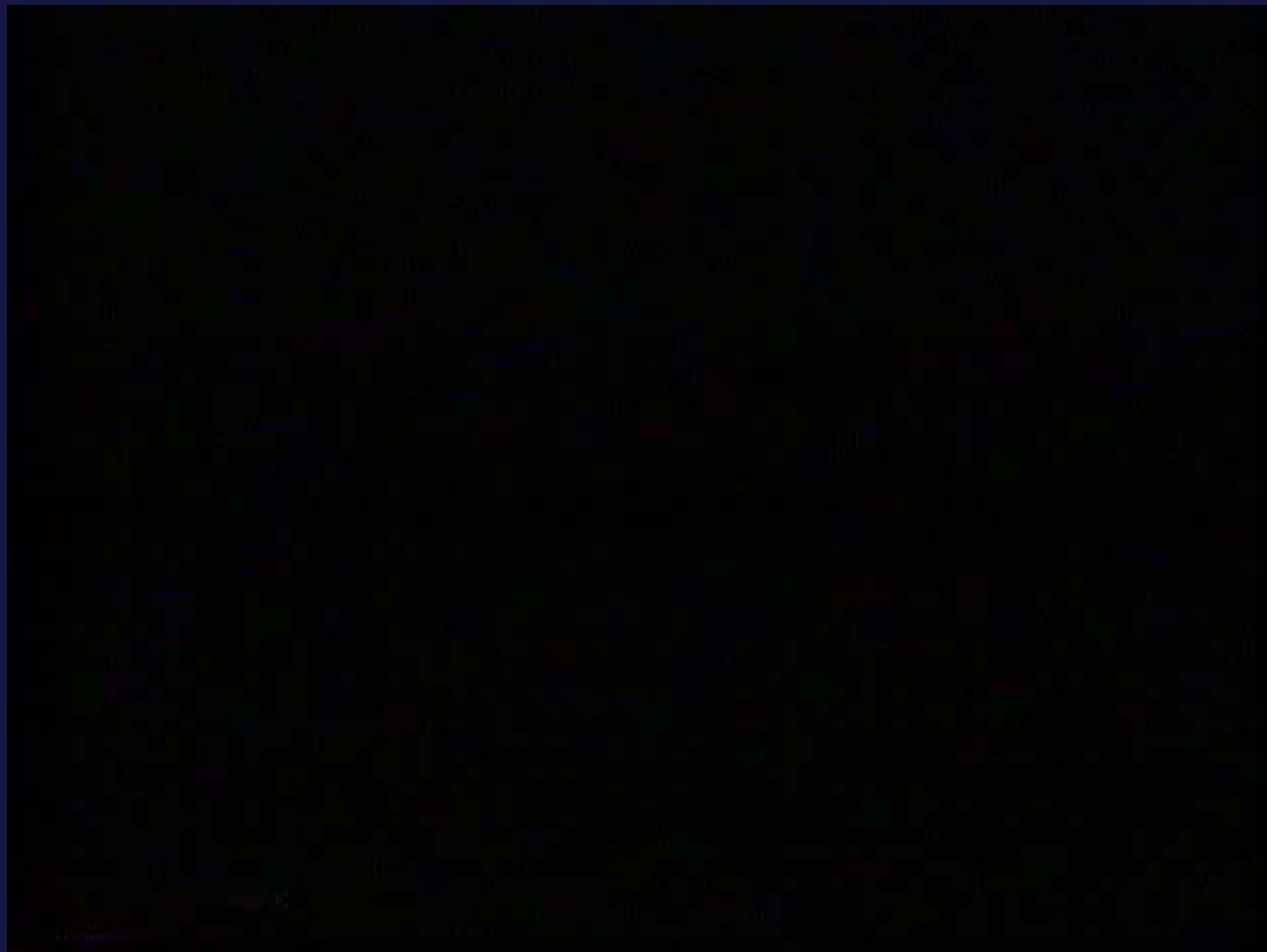


Hopping height





with Marc Raibert



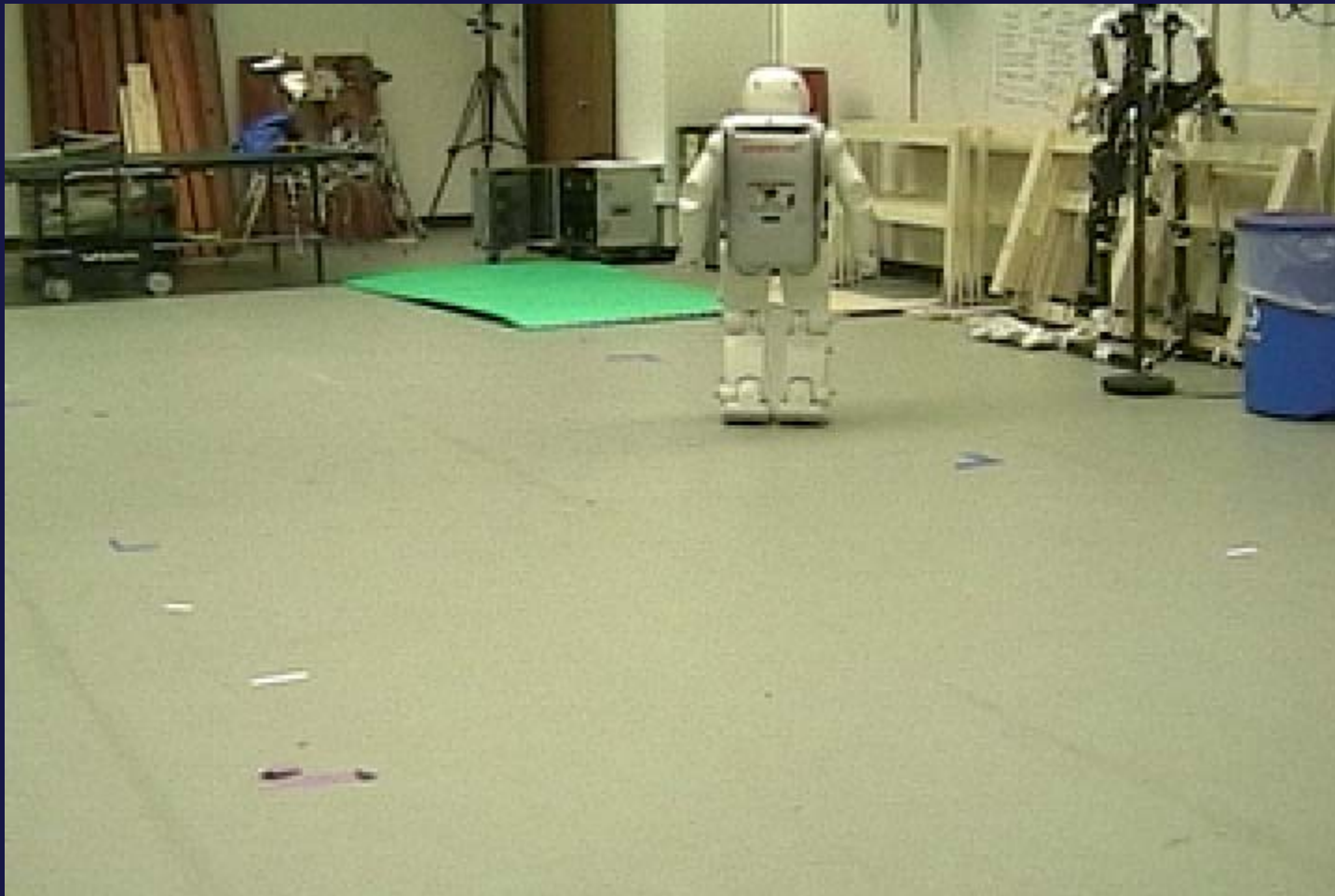
with Marc Raibert

Mimicking people

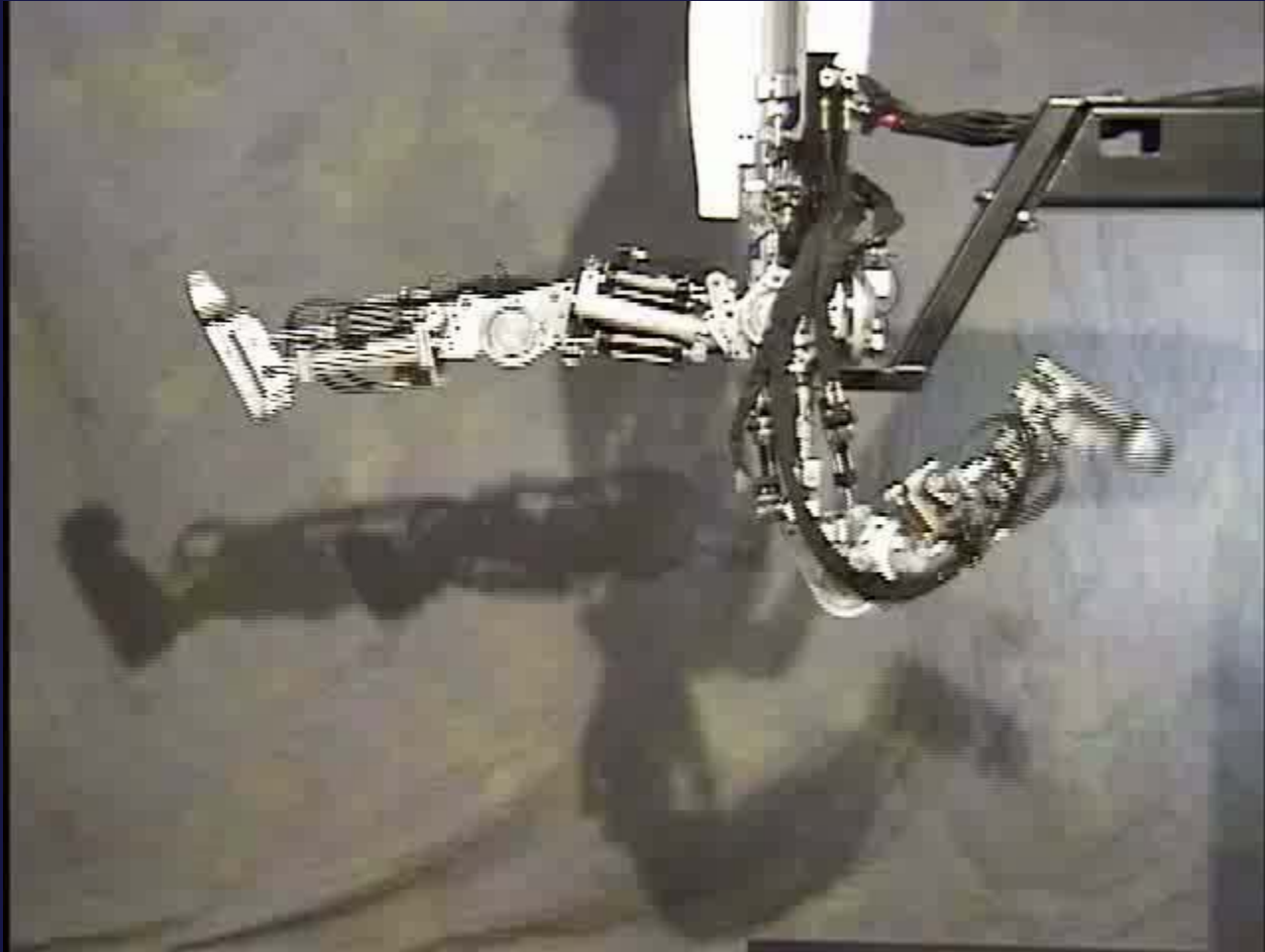


with Alla Safonova and Nancy Pollard

ASIMO



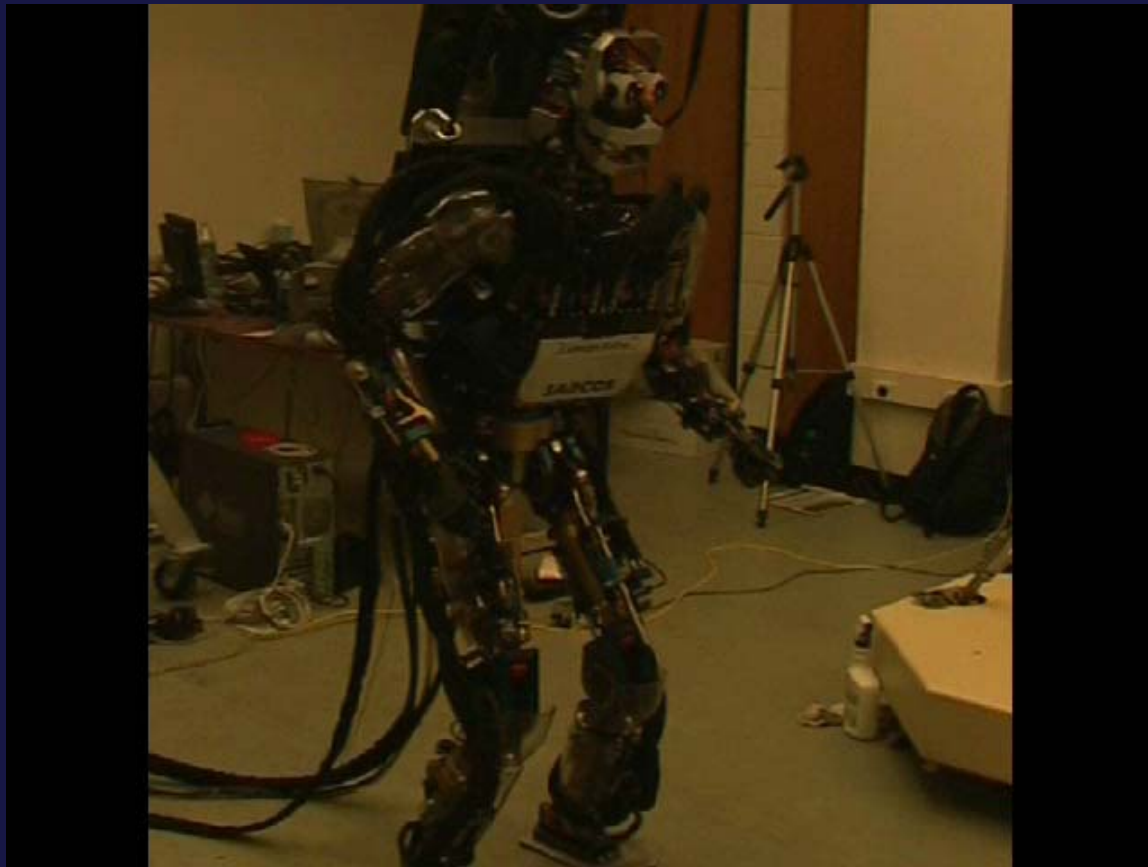
Sarcos Humanoid



Sarcos Humanoid: Pushes

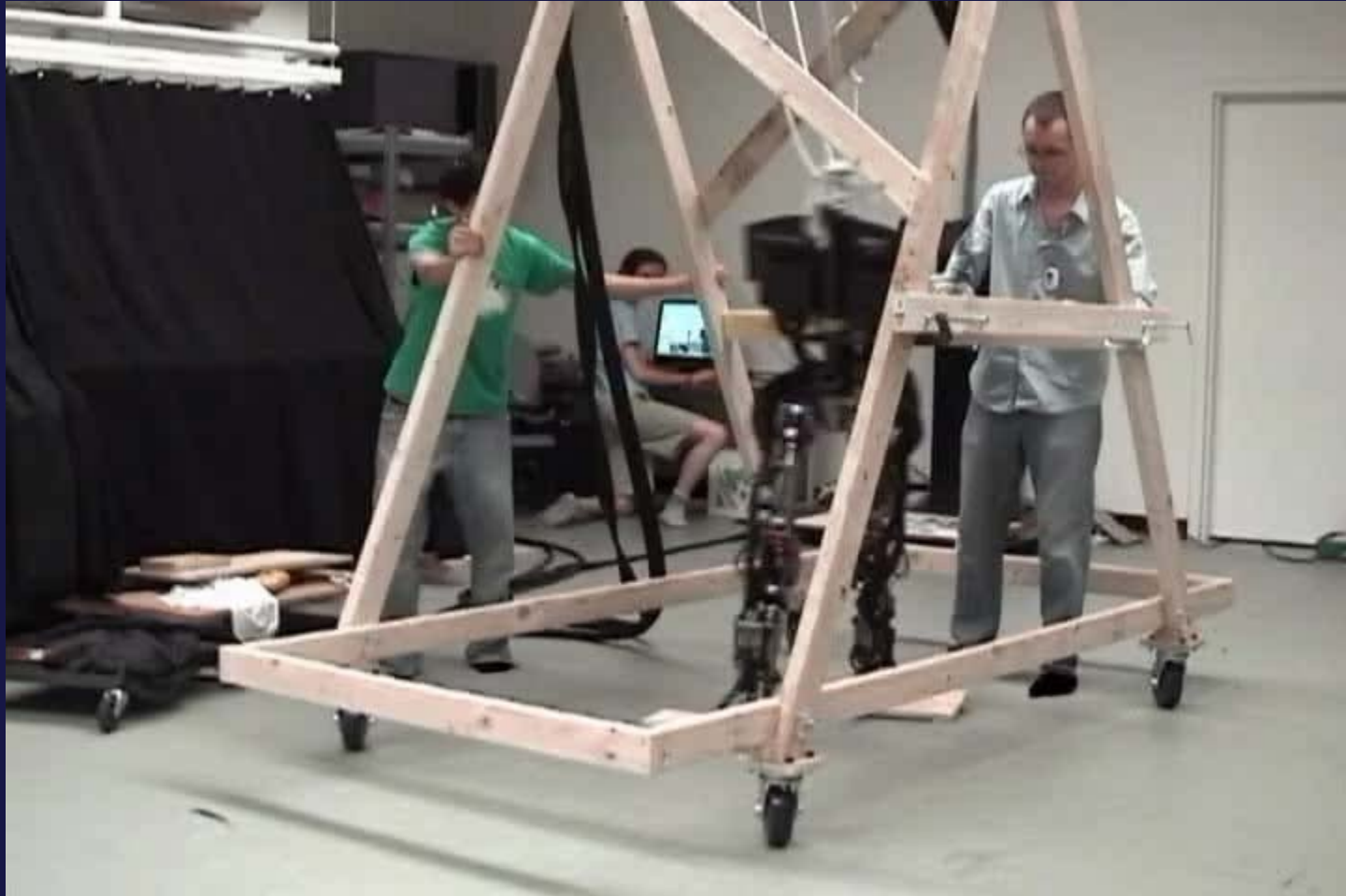


Sarcos Humanoid: Human Data



Stuart Anderson

Sarcos Humanoid



with Stuart Anderson and others

Sarcos Humanoid

