

Readings:

K&F: 15.1, 15.2, 15.3, 15.4, 15.5

K&F: 7 (overview of inference)

K&F: 8.1, 8.2 (Variable Elimination)

Structure Learning in BNs 3:

(the good, the bad,) and, finally, the ugly

Inference

we now get to use the BNs!!

Graphical Models – 10708

Carlos Guestrin

Carnegie Mellon University

October 6th, 2006

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Bayesian, a decomposable score

$$\log P(D | \mathcal{G}) = \log \int_{\theta_{\mathcal{G}}} P(D | \mathcal{G}, \theta_{\mathcal{G}}) P(\theta_{\mathcal{G}} | \mathcal{G}) d\theta_{\mathcal{G}}$$

■ As with last lecture, assume:

- Local and global parameter independence

■ Also, prior satisfies **parameter modularity**:

- If X_i has same parents in \mathcal{G} and \mathcal{G}' , then parameters have same prior

■ Finally, structure prior $P(\mathcal{G})$ satisfies **structure modularity**

- Product of terms over families $P(\mathcal{G}) \propto \prod P(E(X_i, \text{Par}_i))$
- E.g., $P(\mathcal{G}) \propto c^{|\mathcal{G}|}$

■ Bayesian score decomposes along families!

$$P(\mathcal{G} | D) \propto \sum_i \text{Score Fam}(X_i | \text{Par}_i : D)$$

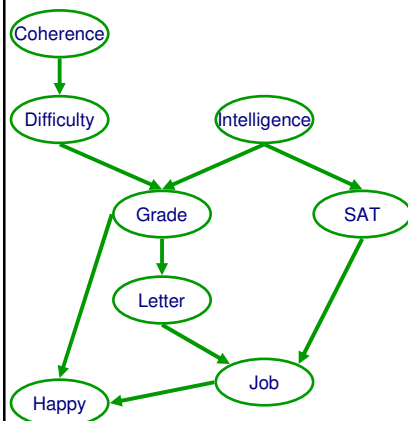
Structure learning for general graphs

- In a tree, a node only has one parent
- **Theorem:**
 - The problem of learning a BN structure with at most d parents is NP-hard for any (fixed) $d \geq 2$
- Most structure learning approaches use heuristics
 - Exploit score decomposition
 - (Quickly) Describe two heuristics that exploit decomposition in different ways

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Understanding score decomposition



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Fixed variable order 1

- Pick a variable order \prec
 - e.g., X_1, \dots, X_n
- X_i can only pick parents in $\{X_1, \dots, X_{i-1}\}$
 - Any subset
 - Acyclicity guaranteed!
- Total score = sum score of each node

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Fixed variable order 2

- Fix max number of parents to k
- For each i in order \prec
 - Pick $\mathbf{Pa}_{X_i} \subseteq \{X_1, \dots, X_{i-1}\}$
 - Exhaustively search through all possible subsets
 - \mathbf{Pa}_{X_i} is maximum $\mathbf{U} \subseteq \{X_1, \dots, X_{i-1}\}$ $\text{FamScore}(X_i | \mathbf{U} : D)$
- Optimal BN for each order!!!
- Greedy search through space of orders:
 - E.g., try switching pairs of variables in order
 - If neighboring vars in order are switch, only need to recompute score for this pair
 - $O(n)$ speed up per iteration
 - Local moves may be worse

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Learn BN structure using local search

Starting from
Chow-Liu tree

Local search,
possible moves:
Only if acyclic!!!

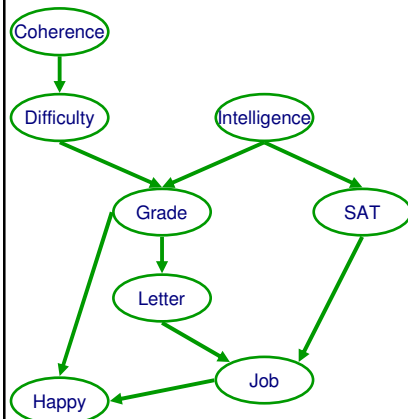
- Add edge
- Delete edge
- Invert edge

**Select using
favorite score**

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Exploit score decomposition in local search



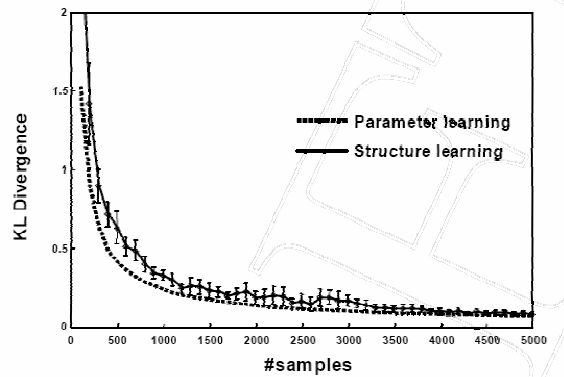
■ Add edge and delete edge:
□ Only rescore one family!

■ Reverse edge
□ Rescore only two families

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Some experiments



Alarm network

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Order search versus graph search

- Order search advantages
 - For fixed order, optimal BN – more “global” optimization
 - Space of orders much smaller than space of graphs
- Graph search advantages
 - Not restricted to k parents
 - Especially if exploiting CPD structure, such as CSI
 - Cheaper per iteration
 - Finer moves within a graph

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Bayesian model averaging

- So far, we have selected a single structure
- But, if you are really Bayesian, must average over structures
 - Similar to averaging over parameters
$$\log P(D | \mathcal{G}) = \log \int_{\theta_{\mathcal{G}}} P(D | \mathcal{G}, \theta_{\mathcal{G}}) P(\theta_{\mathcal{G}} | \mathcal{G}) d\theta_{\mathcal{G}}$$
- Inference for structure averaging is very hard!!!
 - Clever tricks in reading

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What you need to know about learning BN structures

- Decomposable scores
 - Data likelihood
 - Information theoretic interpretation
 - Bayesian
 - BIC approximation
- Priors
 - Structure and parameter assumptions
 - BDe if and only if score equivalence
- Best tree (Chow-Liu)
- Best TAN
- Nearly best k-treewidth (in $O(N^{k+1})$)
- Search techniques
 - Search through orders
 - Search through structures
- Bayesian model averaging

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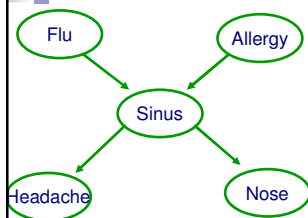
Announcements

- Don't forget project proposals due this Wednesday
- Special recitation on advanced topic:
 - Ajit Singh on Optimal Structure Learning
 - On Monday Oct 9, 5:30-7:00pm in Wean Hall 4615A

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Inference in graphical models: Typical queries 1

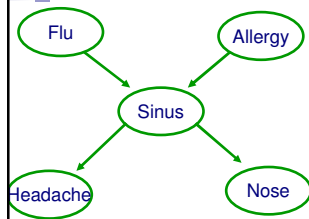


- Conditional probabilities
 - Distribution of some var(s). given evidence

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Inference in graphical models: Typical queries 2 – Maximization



- Most probable explanation (MPE)
 - Most likely assignment to all hidden vars given evidence
- Maximum a posteriori (MAP)
 - Most likely assignment to some var(s) given evidence

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Are MPE and MAP Consistent?



- Most probable explanation (MPE)
 - Most likely assignment to all hidden vars given evidence
- Maximum a posteriori (MAP)
 - Most likely assignment to some var(s) given evidence

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Complexity of conditional probability queries 1

- How hard is it to compute $P(X|\mathbf{E}=\mathbf{e})$?

Reduction – 3-SAT

$$(\bar{X}_1 \vee X_2 \vee X_3) \wedge (\bar{X}_2 \vee X_3 \vee X_4) \wedge \dots$$

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Complexity of conditional probability queries 2

- How hard is it to compute $P(X|\mathbf{E}=\mathbf{e})$?
 - At least NP-hard, but even harder!

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Inference is #P-hard, hopeless?

- Exploit structure!
- Inference is hard in general, but easy for many (real-world relevant) BN structures

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Complexity for other inference questions

- Probabilistic inference
 - general graphs:
 - poly-trees and low tree-width:
- Approximate probabilistic inference
 - Absolute error:
 - Relative error:
- Most probable explanation (MPE)
 - general graphs:
 - poly-trees and low tree-width:
- Maximum a posteriori (MAP)
 - general graphs:
 - poly-trees and low tree-width:

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Inference in BNs hopeless?

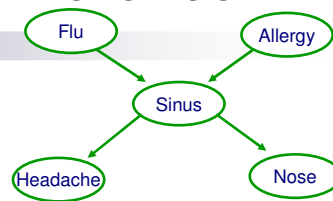
- In general, yes!
 - Even approximate!
- In practice
 - Exploit structure
 - Many effective approximation algorithms (some with guarantees)
- For now, we'll talk about exact inference
 - Approximate inference later this semester

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General probabilistic inference

■ Query: $P(X | e)$



■ Using def. of cond. prob.:

$$P(X | e) = \frac{P(X, e)}{P(e)}$$

■ Normalization:

$$P(X | e) \propto P(X, e)$$

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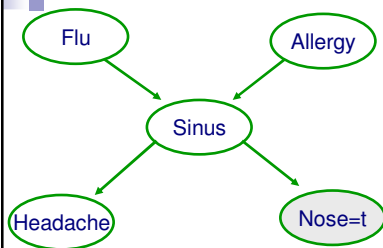
Marginalization



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Probabilistic inference example

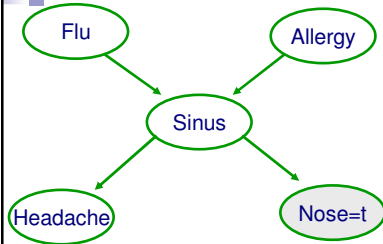


Inference seems exponential in number of variables!

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Fast probabilistic inference example – Variable elimination

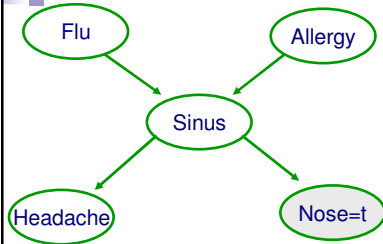


(Potential for) Exponential reduction in computation!

Understanding variable elimination – Exploiting distributivity



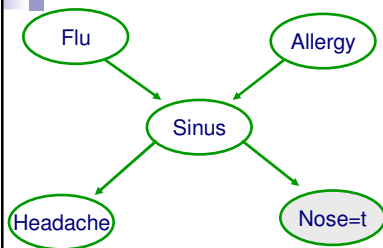
Understanding variable elimination – Order can make a HUGE difference



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Understanding variable elimination – Intermediate results

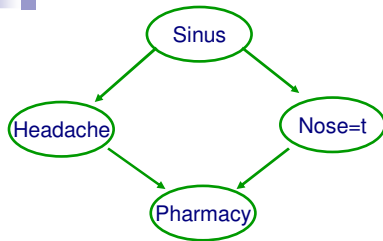


Intermediate results are probability distributions

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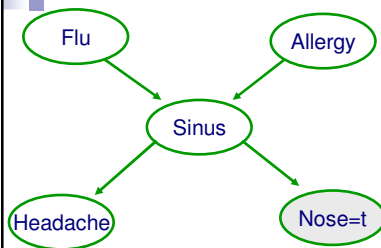
Understanding variable elimination – Another example



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Pruning irrelevant variables



Prune all non-ancestors of query variables
More generally: Prune all nodes not on active trail between evidence and query vars

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Variable elimination algorithm

- Given a BN and a query $P(X|e) \propto P(X,e)$
- Instantiate evidence \mathbf{e}
- Prune non-active vars for $\{X, \mathbf{e}\}$
- Choose an ordering on variables, e.g., X_1, \dots, X_n
- Initial *factors* $\{f_1, \dots, f_n\}$: $f_i = P(X_i | \mathbf{Pa}_{X_i})$ (CPT for X_i)
- For $i = 1$ to n , If $X_i \notin \{X, \mathbf{E}\}$
 - Collect factors f_1, \dots, f_k that include X_i
 - Generate a new factor by eliminating X_i from these factors

IMPORTANT!!!

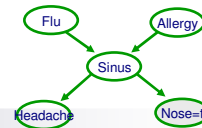
$$g = \sum_{X_i} \prod_{j=1}^k f_j$$

- Variable X_i has been eliminated!
- Normalize $P(X, \mathbf{e})$ to obtain $P(X|\mathbf{e})$

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Operations on factors



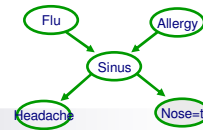
$$g = \sum_{X_i} \prod_{j=1}^k f_j$$

Multiplication:

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Operations on factors



$$g = \sum_{X_i} \prod_{j=1}^k f_j$$

Marginalization:

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Complexity of VE – First analysis

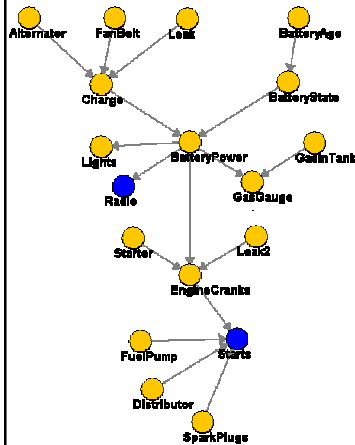
- Number of multiplications:

- Number of additions:

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Complexity of variable elimination – (Poly)-tree graphs



Variable elimination order:

Start from “leaves” inwards:

- Start from skeleton!
- Choose a “root”, any node
- Find topological order for root
- Eliminate variables in reverse order

Linear in CPT sizes!!! (versus exponential)

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What you need to know about inference thus far

- Types of queries
 - probabilistic inference
 - most probable explanation (MPE)
 - maximum a posteriori (MAP)
 - MPE and MAP are truly different (don't give the same answer)
- Hardness of inference
 - Exact and approximate inference are NP-hard
 - MPE is NP-complete
 - MAP is much harder (NPP-complete)
- Variable elimination algorithm
 - Eliminate a variable:
 - Combine factors that include this var into single factor
 - Marginalize var from new factor
 - Efficient algorithm (“only” exponential in induced-width, not number of variables)
 - If you hear: “Exact inference only efficient in tree graphical models”
 - You say: “No!!! Any graph with low induced width”
 - And then you say: “And even some with very large induced-width” (next week with context-specific independence)
- Elimination order is important!
 - NP-complete problem
 - Many good heuristics

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