

Readings:

K&F: 15.1, 15.2, 15.3, 15.4, 15.5

# Structure Learning: the good, the bad, the ugly

Graphical Models – 10708

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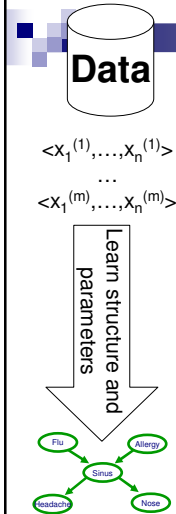
September 29<sup>th</sup>, 2006

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## Where are we with learning BNs?

- Given structure, estimate parameters
  - Maximum likelihood estimation
  - Bayesian learning
- What about learning structure?

# Learning the structure of a BN



## ■ Constraint-based approach

- BN encodes conditional independencies
- Test conditional independencies in data
- Find an I-map

## ■ Score-based approach

- Finding a structure and parameters is a density estimation task
- Evaluate model as we evaluated parameters
  - Maximum likelihood
  - Bayesian
  - etc.

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# Remember: Obtaining a P-map?

- Given the independence assertions that are true for  $P$ 
  - Obtain skeleton
  - Obtain immoralities
- From skeleton and immoralities, obtain every (and any) BN structure from the equivalence class

## ■ Constraint-based approach:

- Use Learn PDAG algorithm
- Key question: **Independence test**

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# Independence tests

- Statistically difficult task!
- Intuitive approach: **Mutual information**

$$I(X_i, X_j) = \sum_{x_i, x_j} P(x_i, x_j) \log \frac{P(x_i, x_j)}{P(x_i)P(x_j)}$$

- Mutual information and independence:
  - $X_i$  and  $X_j$  independent if and only if  $I(X_i, X_j)=0$
- Conditional mutual information:

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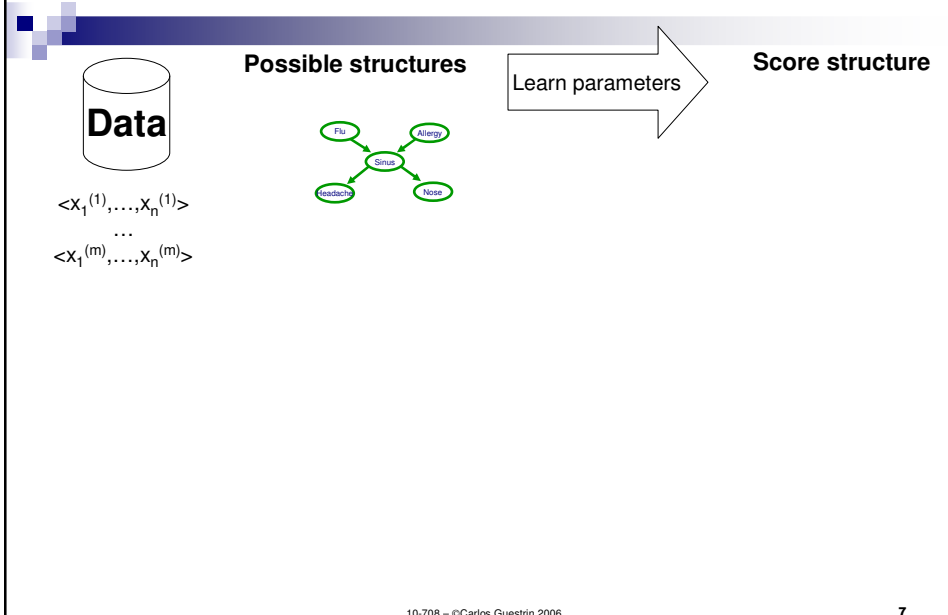
# Independence tests and the constraint based approach

- Using the data  $D$ 
  - Empirical distribution:  $\hat{P}(x_i, x_j) = \frac{\text{Count}(x_i, x_j)}{m}$
  - Mutual information:  $\hat{I}(X_i, X_j) = \sum_{x_i, x_j} \hat{P}(x_i, x_j) \log \frac{\hat{P}(x_i, x_j)}{\hat{P}(x_i)\hat{P}(x_j)}$
  - Similarly for conditional MI
- Use learning PDAG algorithm:
  - When algorithm asks:  $(X \perp Y | \mathbf{U})?$
- Many other types of independence tests
  - See reading...

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# Score-based approach



## Information-theoretic interpretation of maximum likelihood

- Given structure, log likelihood of data:

$$\log P(\mathcal{D} \mid \theta_{\mathcal{G}}, \mathcal{G}) = \sum_{j=1}^m \sum_{i=1}^n \log P\left(X_i = x_i^{(j)} \mid \mathbf{Pa}_{X_i} = \mathbf{x}^{(j)}[\mathbf{Pa}_{X_i}]\right)$$



## Information-theoretic interpretation of maximum likelihood 2

- Given structure, log likelihood of data:

$$\log \hat{P}(\mathcal{D} \mid \theta, \mathcal{G}) = m \sum_i \sum_{\mathbf{Pa}_{x_i, \mathcal{G}}} \hat{P}(x_i, \mathbf{Pa}_{x_i, \mathcal{G}}) \log \hat{P}(x_i \mid \mathbf{Pa}_{x_i, \mathcal{G}})$$



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## Decomposable score

- Log data likelihood

$$\log \hat{P}(\mathcal{D} \mid \theta, \mathcal{G}) = m \sum_i \hat{I}(x_i, \mathbf{Pa}_{x_i, \mathcal{G}}) - M \sum_i \hat{H}(X_i)$$

- Decomposable score:

- Decomposes over families in BN (node and its parents)
- Will lead to significant computational efficiency!!!
- $\text{Score}(G : D) = \sum_i \text{FamScore}(X_i \mid \mathbf{Pa}_{X_i} : D)$

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# How many trees are there?

**Nonetheless – Efficient optimal algorithm finds best tree**

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## Scoring a tree 1: I-equivalent trees

$$\log \hat{P}(\mathcal{D} \mid \theta, \mathcal{G}) = M \sum_i \hat{I}(x_i, \text{Pa}_{x_i, \mathcal{G}}) - M \sum_i \hat{H}(X_i)$$

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## Scoring a tree 2: similar trees

$$\log \hat{P}(\mathcal{D} \mid \theta, \mathcal{G}) = M \sum_i \hat{I}(x_i, \text{Pa}_{x_i, \mathcal{G}}) - M \sum_i \hat{H}(X_i)$$

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## Chow-Liu tree learning algorithm 1

- For each pair of variables  $X_i, X_j$

- Compute empirical distribution:

$$\hat{P}(x_i, x_j) = \frac{\text{Count}(x_i, x_j)}{m}$$

- Compute mutual information:

$$\hat{I}(X_i, X_j) = \sum_{x_i, x_j} \hat{P}(x_i, x_j) \log \frac{\hat{P}(x_i, x_j)}{\hat{P}(x_i) \hat{P}(x_j)}$$

- Define a graph

- Nodes  $X_1, \dots, X_n$
- Edge  $(i, j)$  gets weight  $\hat{I}(X_i, X_j)$

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## Chow-Liu tree learning algorithm 2

$$\log \hat{P}(\mathcal{D} \mid \theta, \mathcal{G}) = M \sum_i \hat{I}(x_i, \text{Pa}_{x_i, \mathcal{G}}) - M \sum_i \hat{H}(X_i)$$

### ■ Optimal tree BN

- Compute maximum weight spanning tree
- Directions in BN: pick any node as root, breadth-first-search defines directions

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## Can we extend Chow-Liu 1

### ■ Tree augmented naïve Bayes (TAN)

[Friedman et al. '97]

- Naïve Bayes model overcounts, because correlation between features not considered
- Same as Chow-Liu, but score edges with:

$$\hat{I}(X_i, X_j \mid C) = \sum_{c, x_i, x_j} \hat{P}(c, x_i, x_j) \log \frac{\hat{P}(x_i, x_j \mid c)}{\hat{P}(x_i \mid c) \hat{P}(x_j \mid c)}$$

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## Can we extend Chow-Liu 2

- (Approximately learning) models with tree-width up to  $k$ 
  - [Narasimhan & Bilmes '04]
  - But,  $O(n^{k+1})\dots$ 
    - and more subtleties

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## What you need to know about learning BN structures so far

- Decomposable scores
  - Maximum likelihood
  - Information theoretic interpretation
- Best tree (Chow-Liu)
- Best TAN
- Nearly best  $k$ -treewidth (in  $O(N^{k+1})$ )

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# Announcements

- Homework 2 out
  - Due Oct. 11th
- Project description out next week

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# Maximum likelihood score overfits!

$$\log \hat{P}(\mathcal{D} \mid \theta, \mathcal{G}) = M \sum_i \hat{I}(x_i, \text{Pa}_{x_i, \mathcal{G}}) - M \sum_i \hat{H}(X_i)$$

- Information never hurts:
- Adding a parent always increases score!!!

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# Bayesian score

- Prior distributions:
  - Over structures
  - Over parameters of a structure
- Posterior over structures given data:

$$\log P(\mathcal{G} \mid D) \propto \log P(\mathcal{G}) + \log \int_{\theta_{\mathcal{G}}} P(D \mid \mathcal{G}, \theta_{\mathcal{G}}) P(\theta_{\mathcal{G}} \mid \mathcal{G}) d\theta_{\mathcal{G}}$$

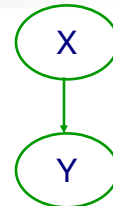
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## Bayesian score and model complexity

$$\log P(D \mid \mathcal{G}) = \log \int_{\theta_{\mathcal{G}}} P(D \mid \mathcal{G}, \theta_{\mathcal{G}}) P(\theta_{\mathcal{G}} \mid \mathcal{G}) d\theta_{\mathcal{G}}$$

True model:



$$P(Y=t|X=t) = 0.5 + \alpha$$


$$P(Y=t|X=f) = 0.5 - \alpha$$

- Structure 1: X and Y independent
  - Score doesn't depend on alpha
- Structure 2:  $X \rightarrow Y$ 
  - Data points split between  $P(Y=t|X=t)$  and  $P(Y=t|X=f)$
  - For fixed M, only worth it for large  $\alpha$ 
    - Because posterior over parameter will be more diffuse with less data

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## Bayesian, a decomposable score



$$\log P(D | \mathcal{G}) = \log \int_{\theta_{\mathcal{G}}} P(D | \mathcal{G}, \theta_{\mathcal{G}}) P(\theta_{\mathcal{G}} | \mathcal{G}) d\theta_{\mathcal{G}}$$

- As with last lecture, assume:
  - Local and global parameter independence
- Also, prior satisfies **parameter modularity**:
  - If  $X_i$  has same parents in  $G$  and  $G'$ , then parameters have same prior
- Finally, structure prior  $P(G)$  satisfies **structure modularity**
  - Product of terms over families
  - E.g.,  $P(G) \propto c^{|G|}$
- Bayesian score decomposes along families!

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## BIC approximation of Bayesian score

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- Bayesian has difficult integrals
  - For Dirichlet prior, can use simple Bayes information criterion (BIC) approximation
    - In the limit, we can forget prior!
    - **Theorem:** for Dirichlet prior, and a BN with  $\text{Dim}(G)$  independent parameters, as  $M \rightarrow \infty$ :
$$\log P(D | \mathcal{G}) = \log P(D | \mathcal{G}, \theta_{\mathcal{G}}) - \frac{\log M}{2} \text{Dim}(\mathcal{G}) + O(1)$$

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## BIC approximation, a decomposable score

- BIC:  $\text{Score}_{\text{BIC}}(\mathcal{G} : D) = \log P(D \mid \mathcal{G}, \theta_{\mathcal{G}}) - \frac{\log M}{2} \text{Dim}(\mathcal{G})$

- Using information theoretic formulation:

$$\text{Score}_{\text{BIC}}(\mathcal{G} : D) = M \sum_i \hat{I}(x_i, \mathbf{Pa}_{x_i, \mathcal{G}}) - M \sum_i \hat{H}(X_i) - \frac{\log M}{2} \sum_i \text{Dim}(P(X_i \mid \mathbf{Pa}_{x_i, \mathcal{G}}))$$

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## Consistency of BIC and Bayesian scores

**Consistency is limiting behavior, says nothing about finite sample size!!!**

- A scoring function is **consistent** if, for true model  $G^*$ , as  $M \rightarrow \infty$ , with probability 1
  - $G^*$  maximizes the score
  - All structures **not I-equivalent** to  $G^*$  have strictly lower score
- **Theorem:** BIC score is consistent
- **Corollary:** the Bayesian score is consistent
- What about maximum likelihood score?

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## Priors for general graphs

- For finite datasets, prior is important!
- Prior over structure satisfying prior modularity
- What about prior over parameters, how do we represent it?
  - *K2 prior*: fix an  $\alpha$ ,  $P(\theta_{X_i|Pa_{X_i}}) = \text{Dirichlet}(\alpha, \dots, \alpha)$
  - K2 is “inconsistent”

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## BDe prior

- Remember that Dirichlet parameters analogous to “fictitious samples”
- Pick a fictitious sample size  $m'$
- For each possible family, define a prior distribution  $P(X_i, Pa_{X_i})$ 
  - Represent with a BN
  - Usually independent (product of marginals)
- **BDe prior**:
- Has “consistency property”:

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## Score equivalence

- If  $G$  and  $G'$  are I-equivalent then they have same score
- **Theorem 1:** Maximum likelihood score and BIC score satisfy score equivalence
- **Theorem 2:**
  - If  $P(G)$  assigns same prior to I-equivalent structures (e.g., edge counting)
  - and parameter prior is dirichlet
  - then **Bayesian score satisfies score equivalence** *if and only if* prior over parameters represented as a **BDe prior**!!!!!!

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## Chow-Liu for Bayesian score

- Edge weight  $w_{X_j \rightarrow X_i}$  is advantage of adding  $X_j$  as parent for  $X_i$
- Now have a directed graph, need directed spanning forest
  - Note that adding an edge can hurt Bayesian score – choose forest not tree
  - But, if score satisfies score equivalence, then  $w_{X_j \rightarrow X_i} = w_{X_i \rightarrow X_j}$  !
  - Simple maximum spanning forest algorithm works

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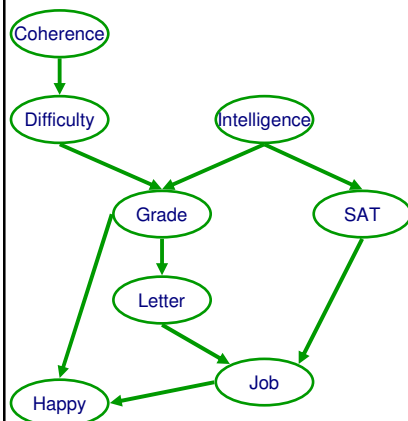
# Structure learning for general graphs

- In a tree, a node only has one parent
- **Theorem:**
  - The problem of learning a BN structure with at most  $d$  parents is **NP-hard for any (fixed)  $d \geq 2$**
- Most structure learning approaches use heuristics
  - Exploit score decomposition
  - (Quickly) Describe two heuristics that exploit decomposition in different ways

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# Understanding score decomposition



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## Fixed variable order 1

- Pick a variable order  $\prec$ 
  - e.g.,  $X_1, \dots, X_n$
- $X_i$  can only pick parents in  $\{X_1, \dots, X_{i-1}\}$ 
  - Any subset
  - Acyclicity guaranteed!
- Total score = sum score of each node

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## Fixed variable order 2

- Fix max number of parents to  $k$
- For each  $i$  in order  $\prec$ 
  - Pick  $\mathbf{Pa}_{X_i} \subseteq \{X_1, \dots, X_{i-1}\}$ 
    - Exhaustively search through all possible subsets
    - $\mathbf{Pa}_{X_i}$  is maximum  $\mathbf{U} \subseteq \{X_1, \dots, X_{i-1}\} \text{ FamScore}(X_i | \mathbf{U} : D)$
- Optimal BN for each order!!!
- Greedy search through space of orders:
  - E.g., try switching pairs of variables in order
  - If neighboring vars in order are switch, only need to recompute score for this pair
    - $O(n)$  speed up per iteration
    - Local moves may be worse

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## Learn BN structure using local search

Starting from  
Chow-Liu tree

**Local search,**  
possible moves:  
**Only if acyclic!!!**

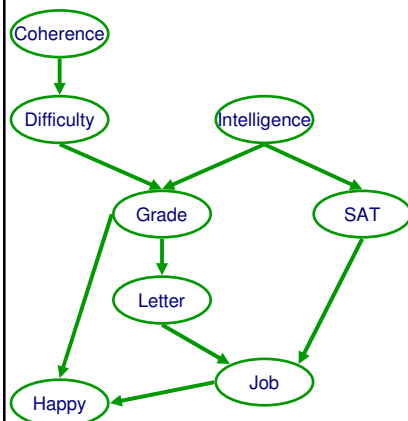
- Add edge
- Delete edge
- Invert edge

**Select using  
favorite score**

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## Exploit score decomposition in local search



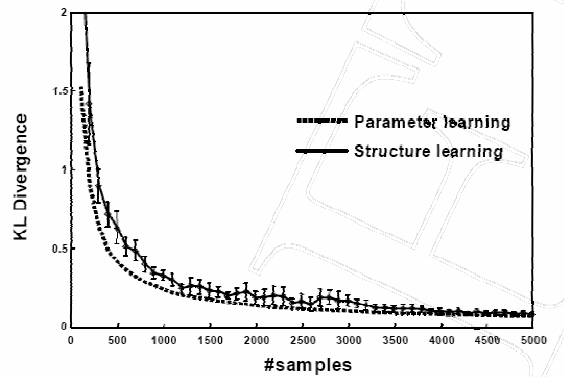
■ Add edge and delete edge:  
□ Only rescore one family!

■ Reverse edge  
□ Rescore only two families

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## Some experiments



Alarm network

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## Order search versus graph search

- Order search advantages
  - For fixed order, optimal BN – more “global” optimization
  - Space of orders much smaller than space of graphs
- Graph search advantages
  - Not restricted to  $k$  parents
    - Especially if exploiting CPD structure, such as CSI
  - Cheaper per iteration
  - Finer moves within a graph

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## Bayesian model averaging

- So far, we have selected a single structure
- But, if you are really Bayesian, must average over structures
  - Similar to averaging over parameters
$$\log P(D | \mathcal{G}) = \log \int_{\theta_{\mathcal{G}}} P(D | \mathcal{G}, \theta_{\mathcal{G}}) P(\theta_{\mathcal{G}} | \mathcal{G}) d\theta_{\mathcal{G}}$$
- Inference for structure averaging is very hard!!!
  - Clever tricks in reading

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## What you need to know about learning BN structures

- Decomposable scores
  - Data likelihood
  - Information theoretic interpretation
  - Bayesian
  - BIC approximation
- Priors
  - Structure and parameter assumptions
  - BDe if and only if score equivalence
- Best tree (Chow-Liu)
- Best TAN
- Nearly best k-treewidth (in  $O(N^{k+1})$ )
- Search techniques
  - Search through orders
  - Search through structures
- Bayesian model averaging

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