

Plan

Last Time

- Linear programming (LP) formulation
 - Problem description
 - Optimization representation
 - Graphical representation

Today

- LP: Continue graphical representation
- Solving linear programs
- Higher dimensions than just 2
- Integer programs

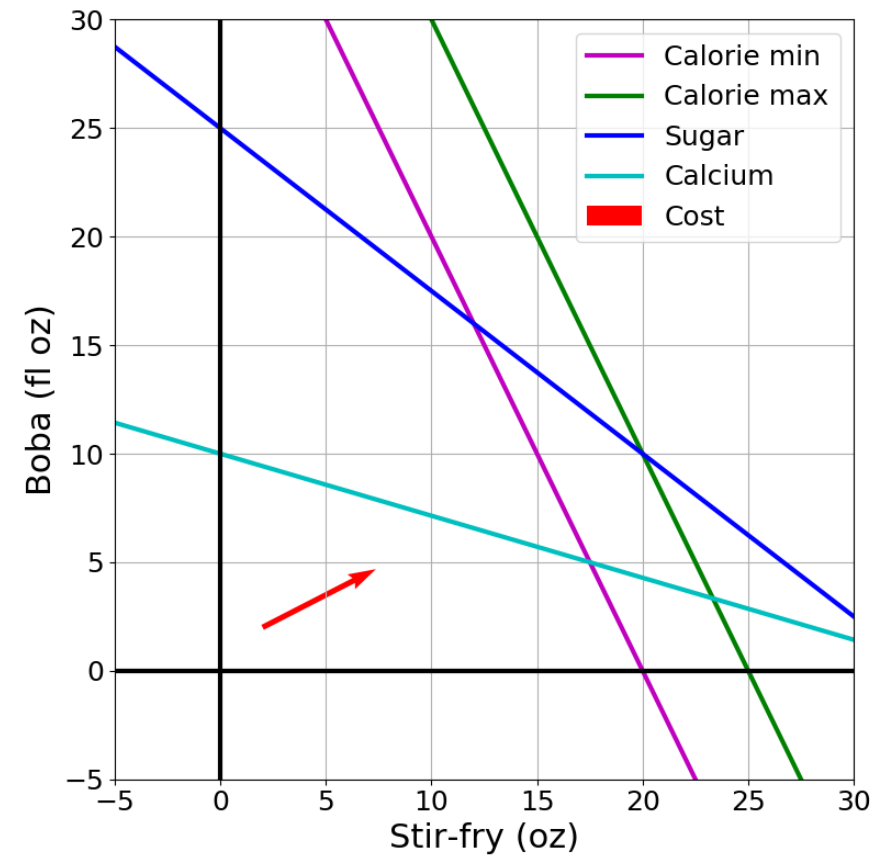
Optimization

Problem
Description

Optimization
Representation

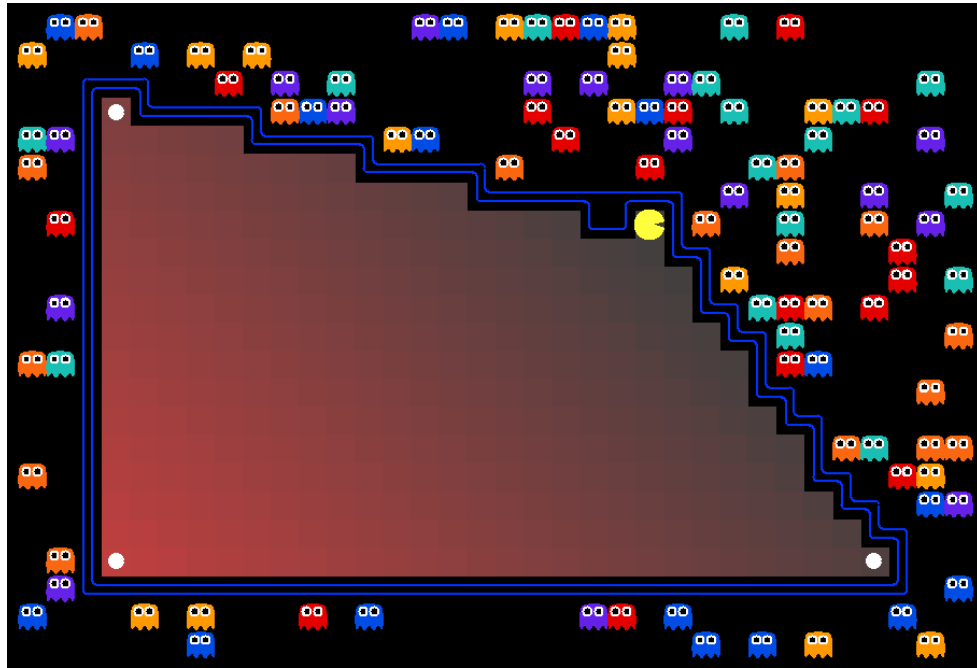
$$\begin{array}{ll}\min_{\mathbf{x}} & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b}\end{array}$$

Graphical Representation



AI: Representation and Problem Solving

Linear and Integer Programming



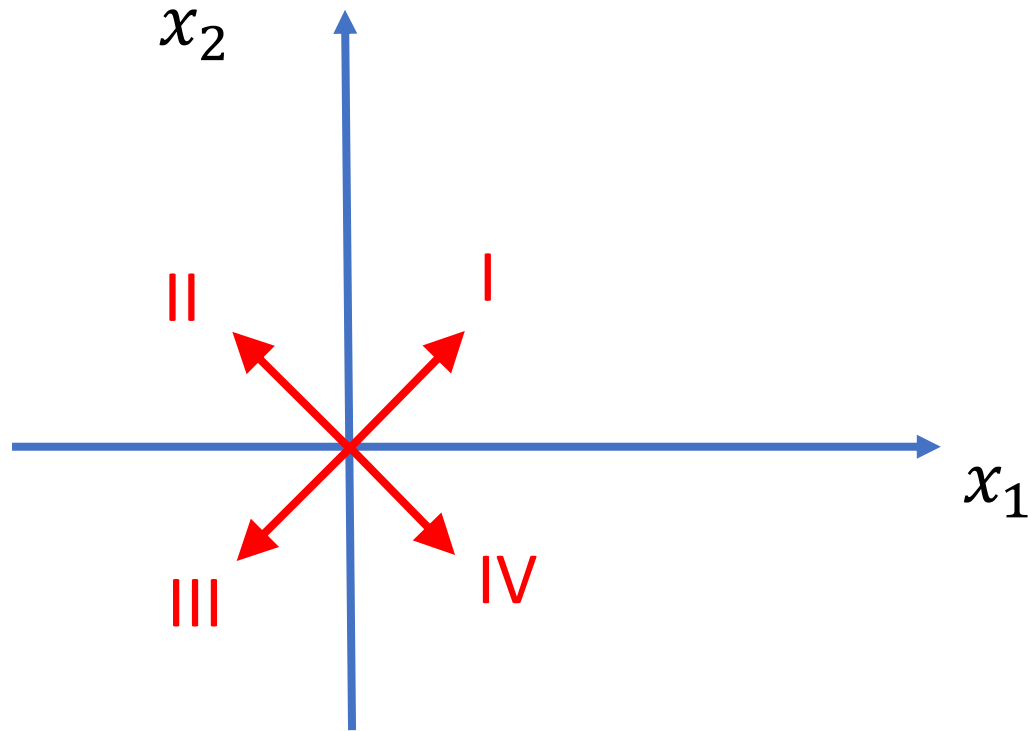
Instructor: Pat Virtue

Slide credits: CMU AI with drawings from <http://ai.berkeley.edu>

Poll 1

Which of these points have cost $\mathbf{c}^\top \mathbf{x} = 0$?

for cost vector: $\mathbf{c} = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$



Question

Given the cost vector $[c_1, c_2]^T$ where will

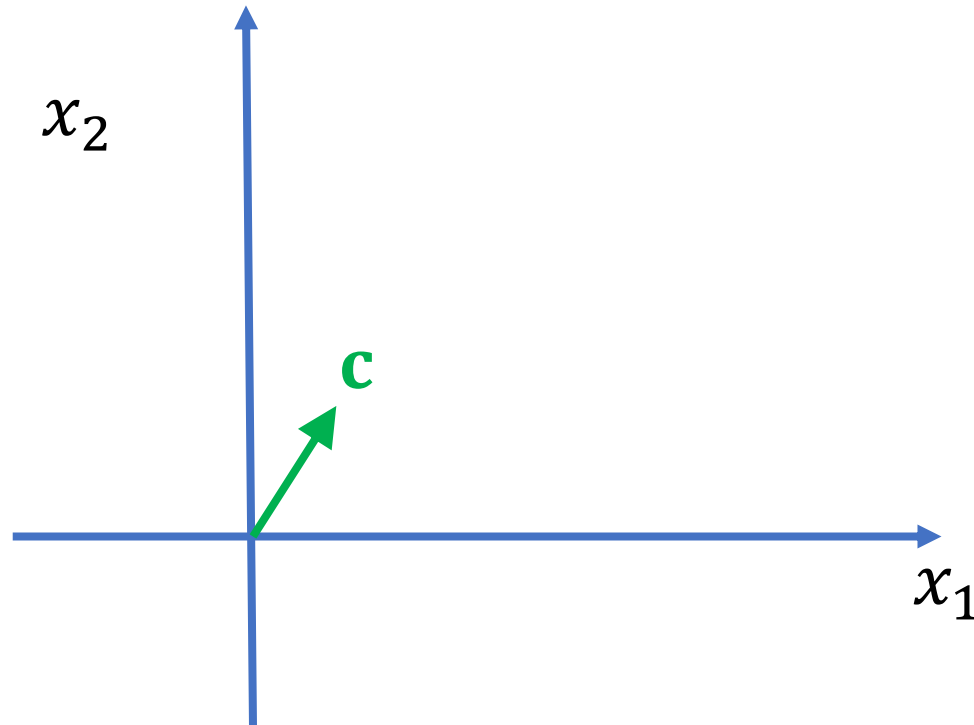
$$\mathbf{c}^T \mathbf{x} = 0 ?$$

$$\mathbf{c}^T \mathbf{x} = 1 ?$$

$$\mathbf{c}^T \mathbf{x} = 2 ?$$

$$\mathbf{c}^T \mathbf{x} = -1 ?$$

$$\mathbf{c}^T \mathbf{x} = -2 ?$$



Cost Contours

Given the cost vector $[c_1, c_2]^T$ where will

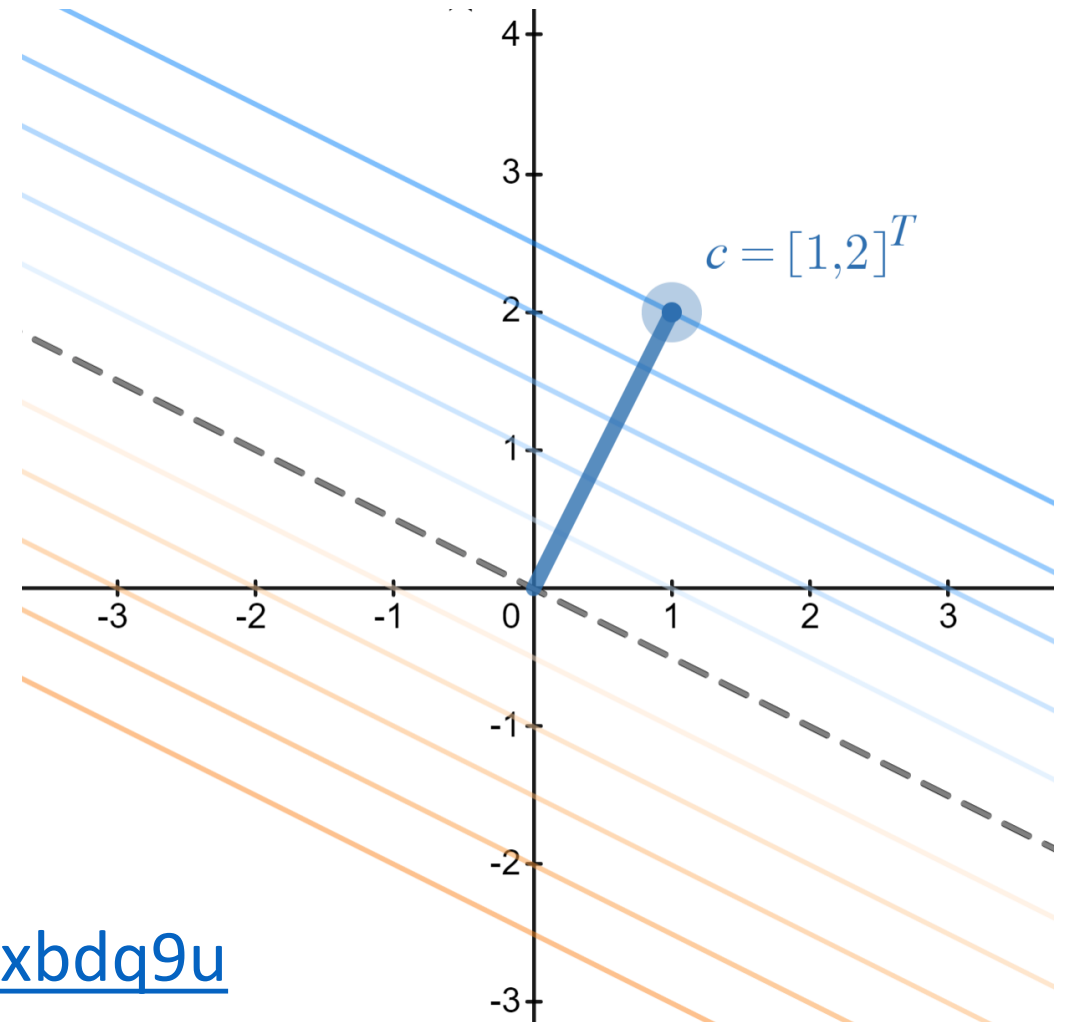
$$\mathbf{c}^T \mathbf{x} = 0 ?$$

$$\mathbf{c}^T \mathbf{x} = 1 ?$$

$$\mathbf{c}^T \mathbf{x} = 2 ?$$

$$\mathbf{c}^T \mathbf{x} = -1 ?$$

$$\mathbf{c}^T \mathbf{x} = -2 ?$$

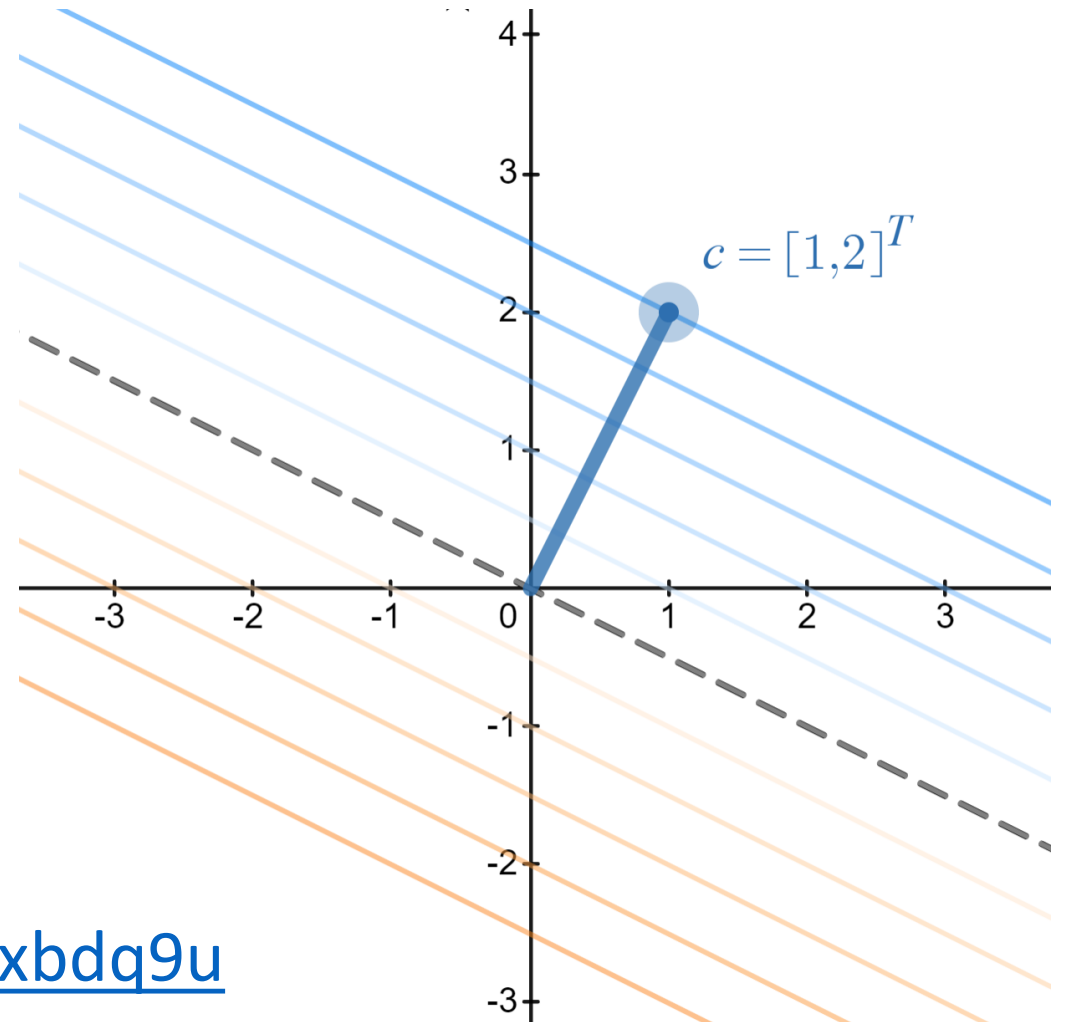


<https://www.desmos.com/calculator/8d9kxbdq9u>

Question

As the magnitude of \mathbf{c} increases, the distance between the contours lines of the objective $\mathbf{c}^T \mathbf{x}$:

- A) Increases
- B) Decreases



<https://www.desmos.com/calculator/8d9kxbdq9u>

Graphics Representation

Geometry / Algebra I Quiz

What shape does this inequality represent?

$$a_1 x_1 + a_2 x_2 \leq b_1$$

Graphics Representation

Geometry / Algebra I Quiz

What shape do these represent?

1. $a_1 x_1 + a_2 x_2 = b_1$

2. $a_1 x_1 + a_2 x_2 \leq b_1$

3.
$$\begin{aligned} a_{1,1} x_1 + a_{1,2} x_2 &\leq b_1 \\ a_{2,1} x_1 + a_{2,2} x_2 &\leq b_2 \\ a_{3,1} x_1 + a_{3,2} x_2 &\leq b_3 \\ a_{4,1} x_1 + a_{4,2} x_2 &\leq b_4 \end{aligned}$$

Feasible region:

All points x that satisfy the constraints

Graphics Representation

Geometry / Algebra I Quiz

What shape do these represent?

1. $a_1 x_1 + a_2 x_2 = b_1$

2. $a_1 x_1 + a_2 x_2 \leq b_1$

3.
$$\begin{aligned} a_{1,1} x_1 + a_{1,2} x_2 &\leq b_1 \\ a_{2,1} x_1 + a_{2,2} x_2 &\leq b_2 \\ a_{3,1} x_1 + a_{3,2} x_2 &\leq b_3 \\ a_{4,1} x_1 + a_{4,2} x_2 &\leq b_4 \end{aligned}$$

Feasible region:

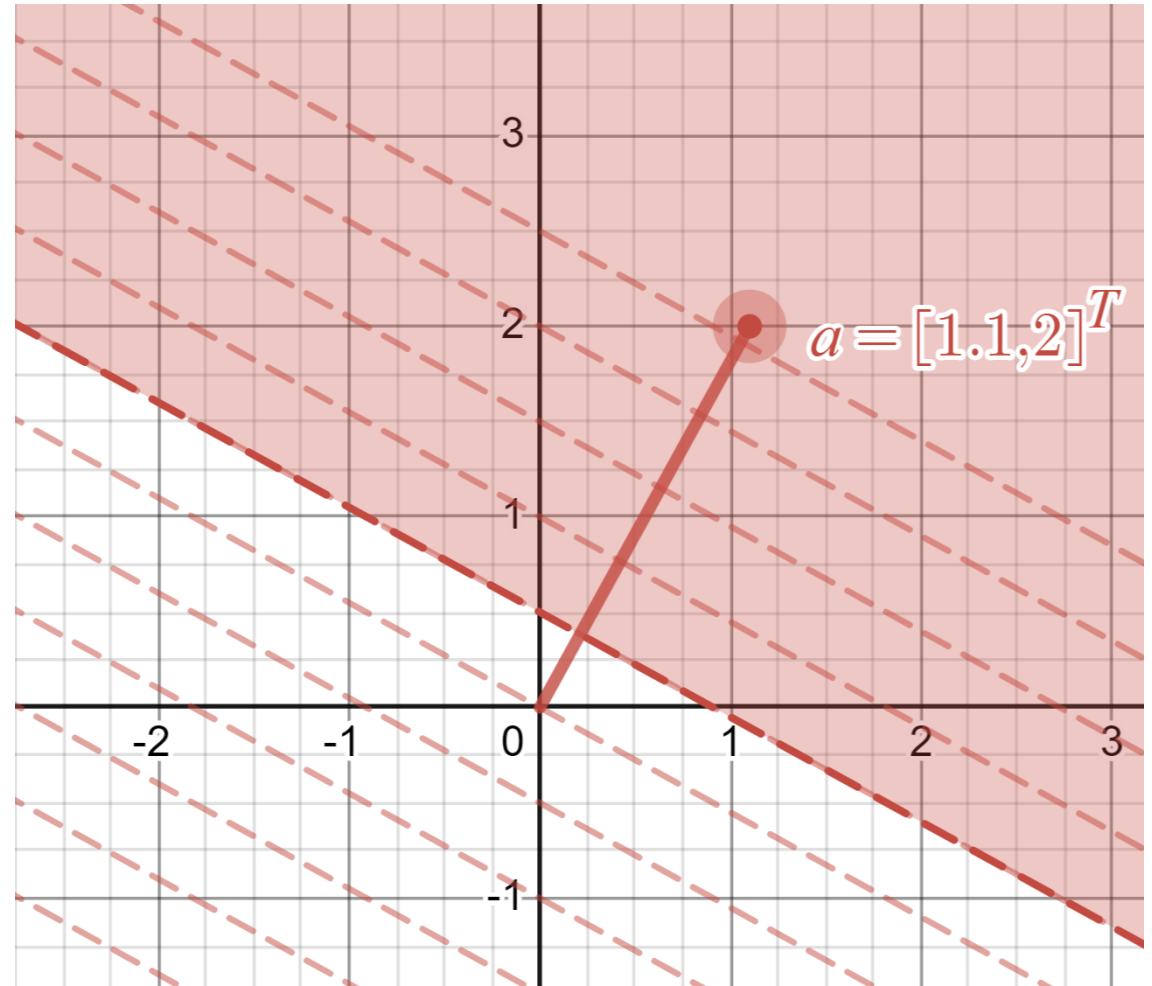
All points x that satisfy the constraints

Graphics Representation

Geometry / Algebra I Quiz

What shape do these represent?

1. $a_1 x_1 + a_2 x_2 = b_1$
2. $a_1 x_1 + a_2 x_2 \leq b_1$
- 3.



<https://www.desmos.com/calculator/lp0rqsb1w6>

Graphics Representation

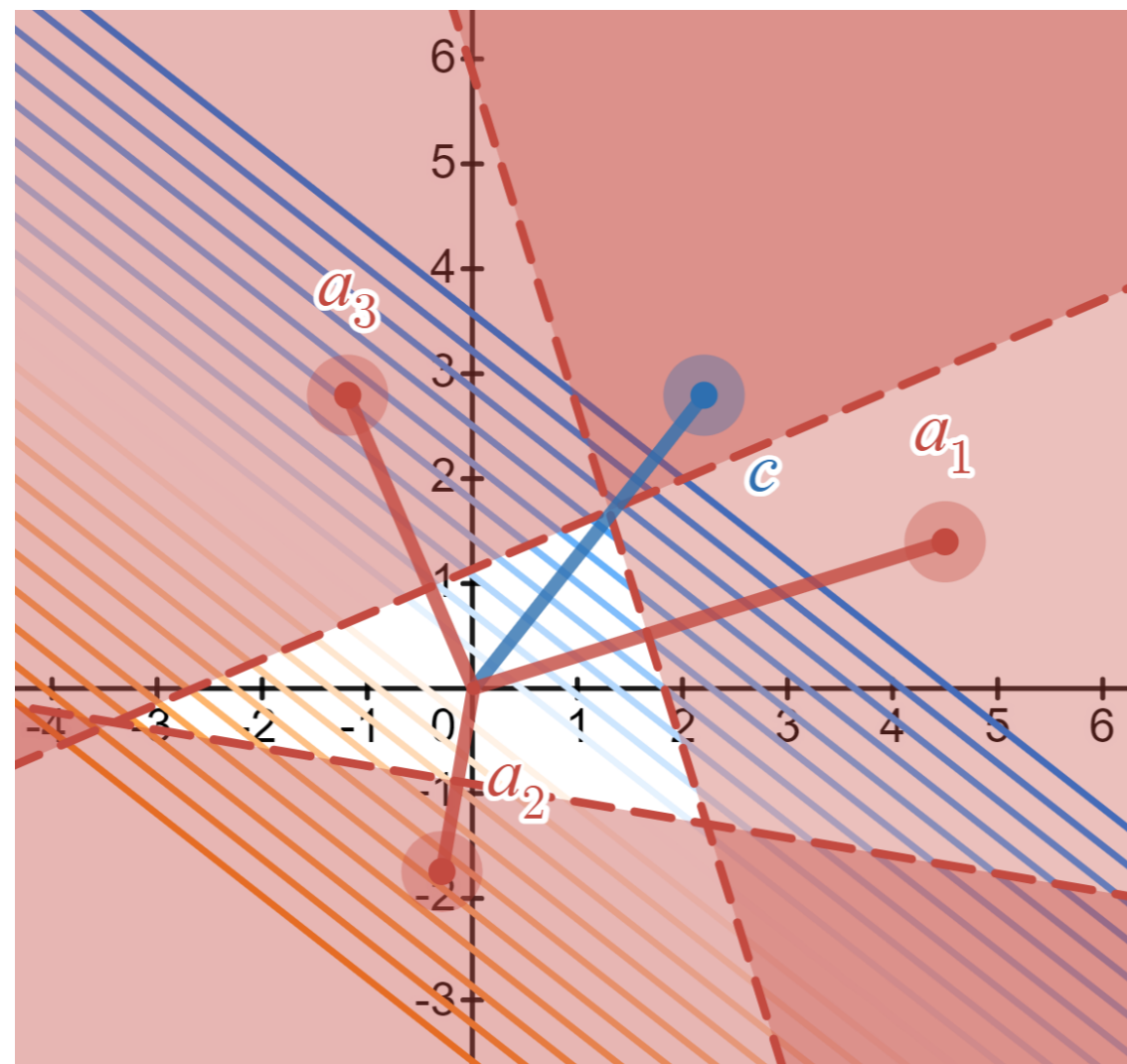
Geometry / Algebra I Quiz

What shape do these represent?

1. $a_1 x_1 + a_2 x_2 = b_1$

2. $a_1 x_1 + a_2 x_2 \leq b_1$

3.
$$\begin{aligned} a_{1,1} x_1 + a_{1,2} x_2 &\leq b_1 \\ a_{2,1} x_1 + a_{2,2} x_2 &\leq b_2 \\ a_{3,1} x_1 + a_{3,2} x_2 &\leq b_3 \\ a_{4,1} x_1 + a_{4,2} x_2 &\leq b_4 \end{aligned}$$



<https://www.desmos.com/calculator/plp1thgsbh>

Reminder: Cost Contours

Given the cost vector $[c_1, c_2]^T$ where will

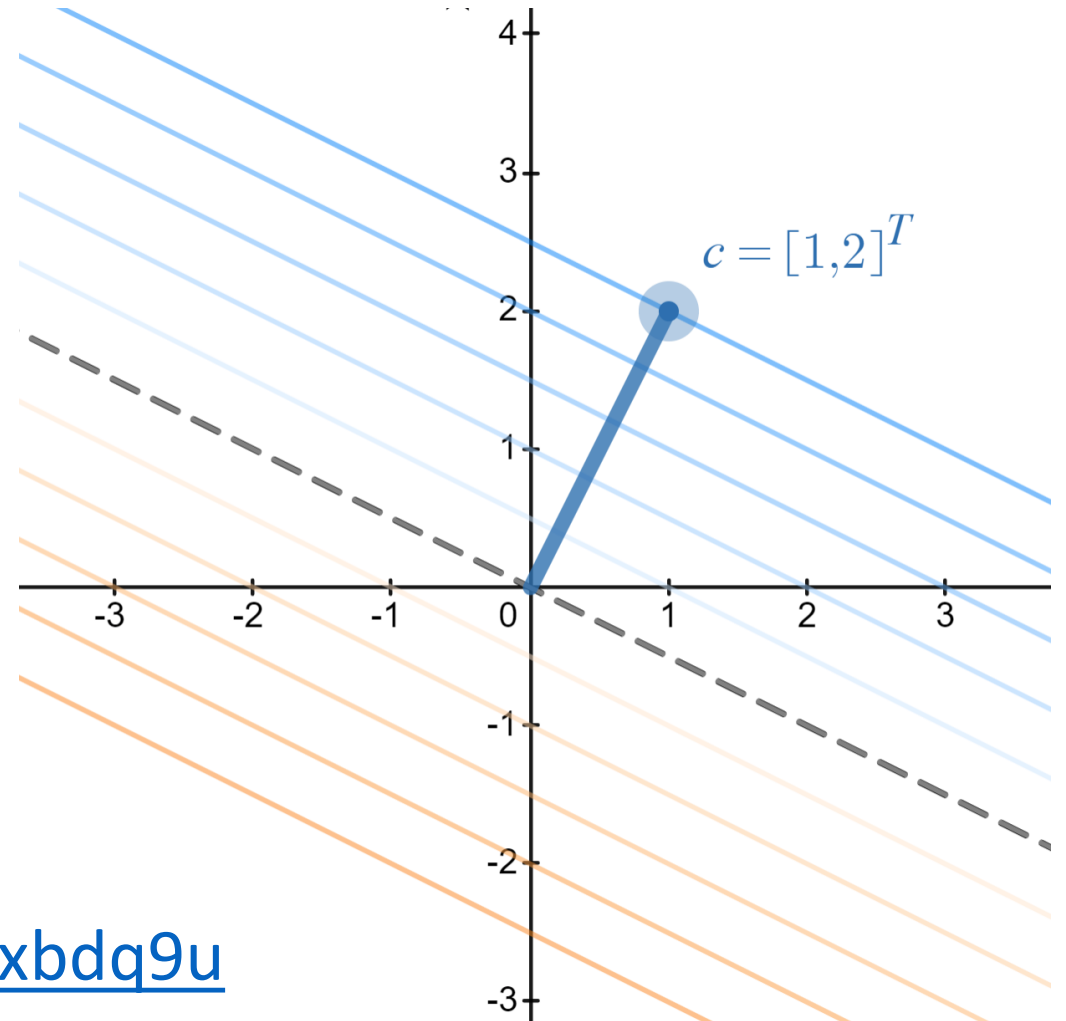
$$\mathbf{c}^T \mathbf{x} = 0 ?$$

$$\mathbf{c}^T \mathbf{x} = 1 ?$$

$$\mathbf{c}^T \mathbf{x} = 2 ?$$

$$\mathbf{c}^T \mathbf{x} = -1 ?$$

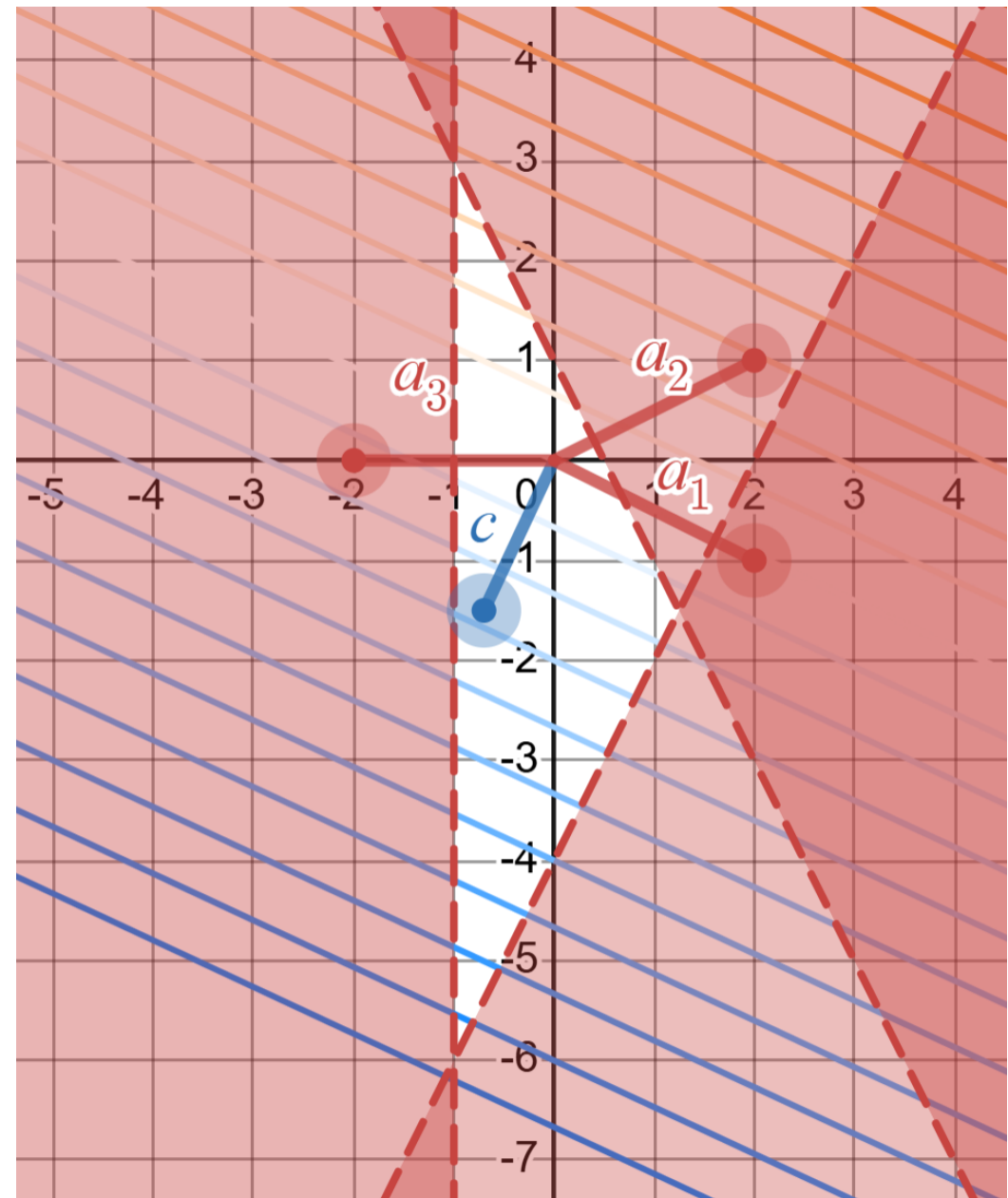
$$\mathbf{c}^T \mathbf{x} = -2 ?$$



<https://www.desmos.com/calculator/8d9kxbdq9u>

Poll 2

What is the solution to this LP?



<https://www.desmos.com/calculator/tnlo7p5plp>

Solving a Linear Program

Inequality form, with no constraints

$$\min_{\mathbf{x}} \quad \mathbf{c}^T \mathbf{x}$$

Solving a Linear Program

Inequality form, with one constraint

$$\begin{array}{ll}\min. & \mathbf{c}^\top \mathbf{x} \\ \text{s.t.} & a_1 x_1 + a_2 x_2 \leq b\end{array}$$

Poll 3

True or False: A minimizing LP with exactly one constraint, will always have a minimum objective at $-\infty$.

$$\begin{array}{ll}\min. & \mathbf{c}^\top \mathbf{x} \\ \text{s.t.} & a_1 x_1 + a_2 x_2 \leq b\end{array}$$

Solving an LP

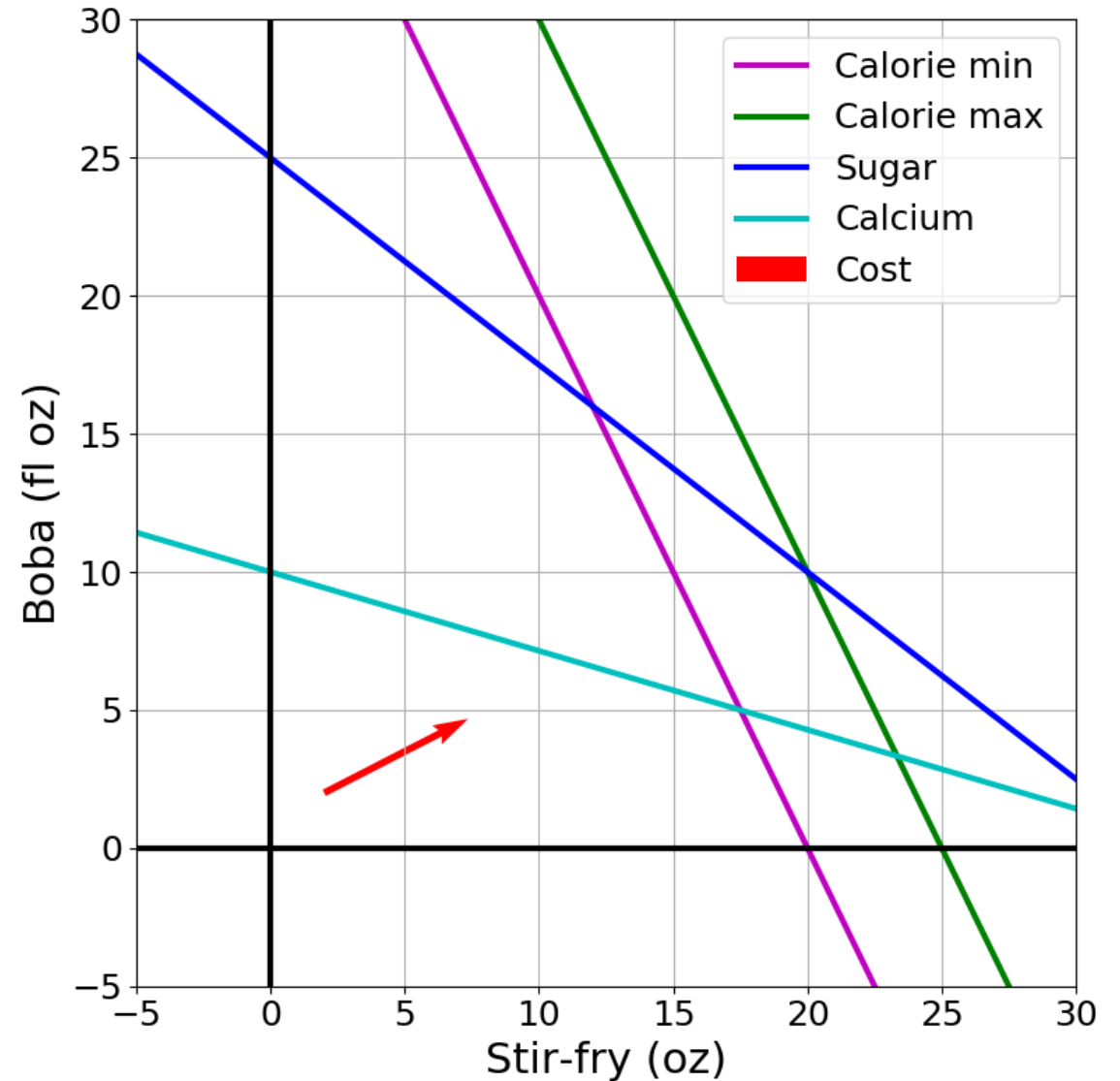
Solutions are at feasible intersections of constraint boundaries!!

Algorithms

- Check objective at all feasible intersections

In more detail:

1. Enumerate all intersections
2. Keep only those that are feasible (satisfy *all* inequalities)
3. Return feasible intersection with the lowest objective value



Solving an LP

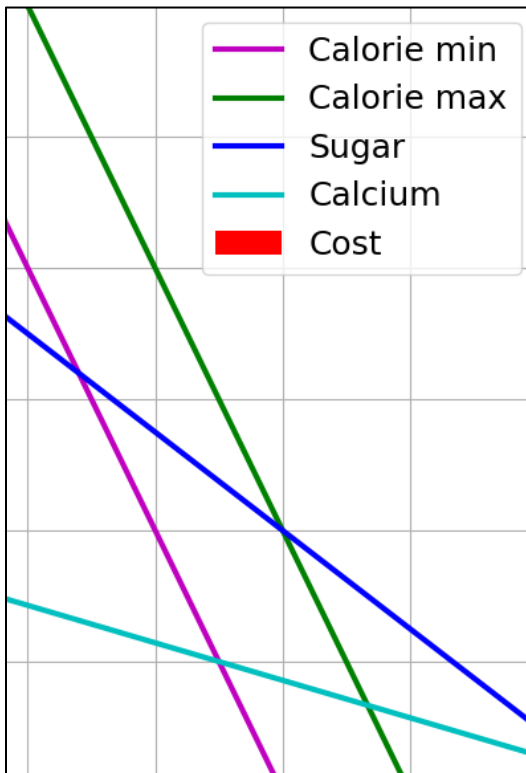
But, how do we find the intersection between boundaries?

$$\begin{array}{ll}\min & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b}\end{array}$$

$$A = \begin{bmatrix} -100 & -50 \\ 100 & 50 \\ 3 & 4 \\ -20 & -70 \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} -2000 \\ 2500 \\ 100 \\ -700 \end{bmatrix}$$

Calorie min
Calorie max
Sugar
Calcium

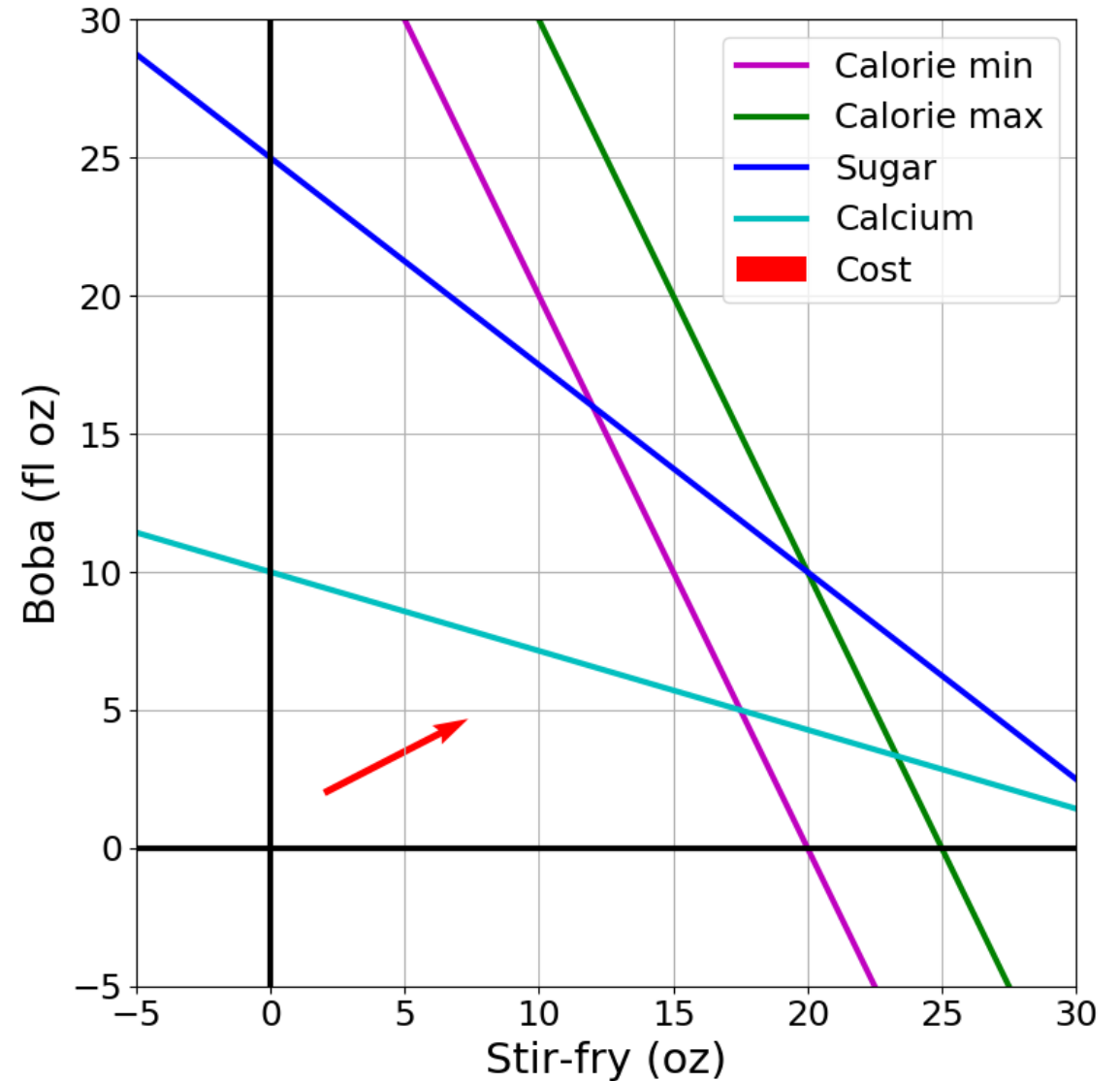


Solving an LP

Solutions are at feasible intersections of constraint boundaries!!

Algorithms

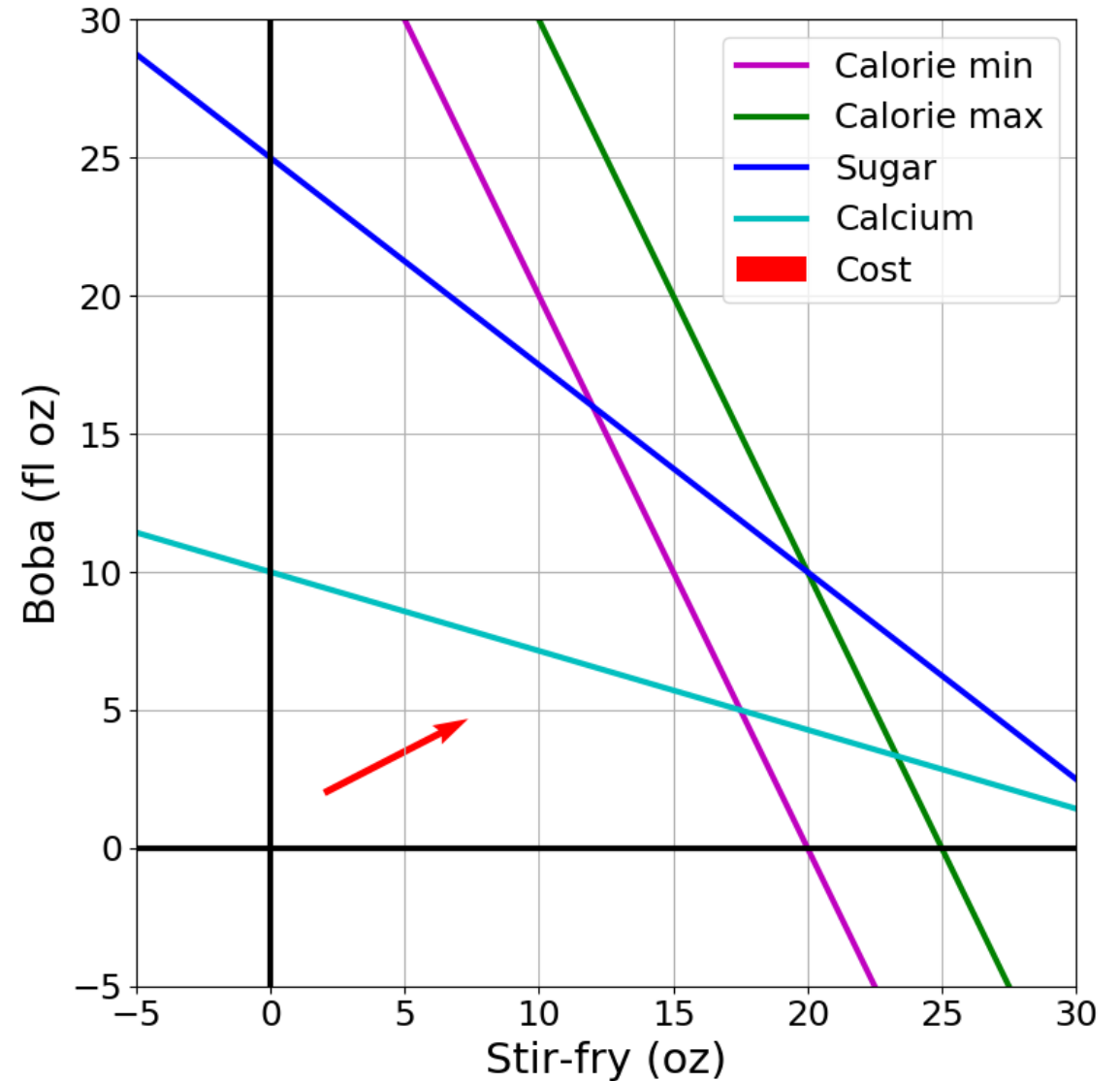
- Check objective at all feasible intersections
- Simplex



Solving an LP

Simplex algorithm

- Start at a feasible intersection (if not trivial, can solve another LP to find one)
- Define successors as “neighbors” of current intersection
 - i.e., remove one row from our square subset of A , and add another row not in the subset; then check feasibility
- Move to any successor with lower objective than current intersection
 - If no such successors, we are done



Greedy local hill-climbing search! ... but always finds *optimal* solution

Solving an LP

Solutions are at feasible intersections
of constraint boundaries!!

Algorithms

- Check objective at all feasible intersections
- Simplex
- Interior Point

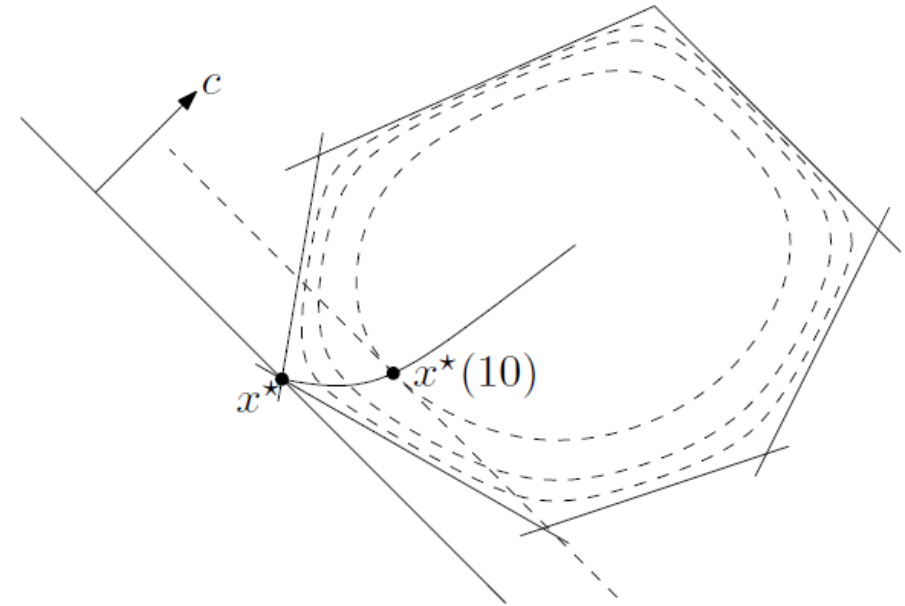


Figure 11.2 from Boyd and Vandenberghe, *Convex Optimization*

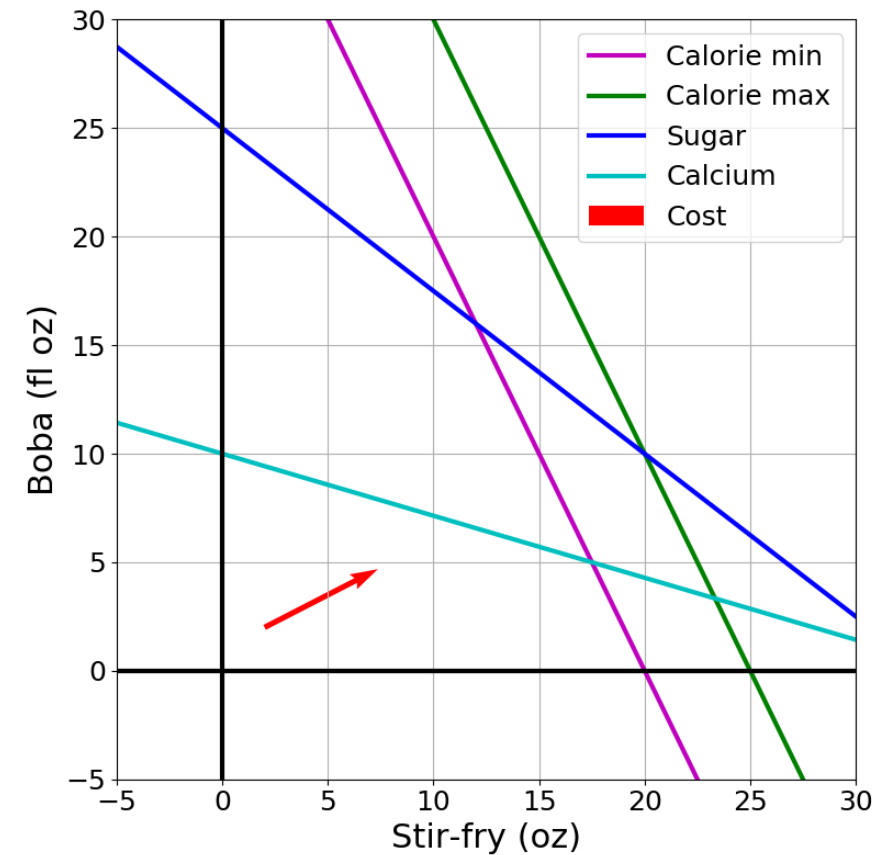
What about higher dimensions?

Problem Description

Optimization Representation

$$\begin{array}{ll}\min_{\mathbf{x}} & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b}\end{array}$$

Graphical Representation



“Marty, you’re not thinking fourth-dimensionally”



<https://www.youtube.com/watch?v=CUcNM7OsdY>

Shapes in higher dimensions

How do these linear shapes extend to 3-D, N-D?

$$a_1 x_1 + a_2 x_2 = b_1$$

$$a_1 x_1 + a_2 x_2 \leq b_1$$

$$a_{1,1} x_1 + a_{1,2} x_2 \leq b_1$$

$$a_{2,1} x_1 + a_{2,2} x_2 \leq b_2$$

$$a_{3,1} x_1 + a_{3,2} x_2 \leq b_3$$

$$a_{4,1} x_1 + a_{4,2} x_2 \leq b_4$$

What are intersections in higher dimensions?

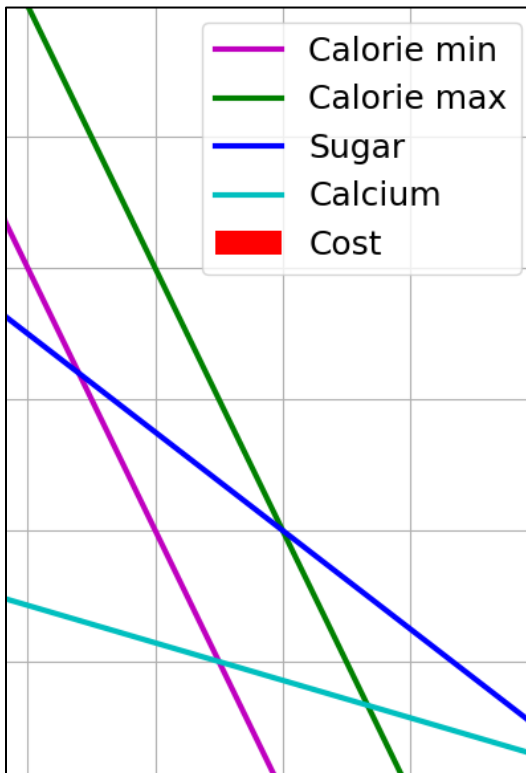
How do these linear shapes extend to 3-D, N-D?

$$\begin{array}{ll} \min & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \end{array}$$

$$A = \begin{bmatrix} -100 & -50 \\ 100 & 50 \\ 3 & 4 \\ -20 & -70 \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} -2000 \\ 2500 \\ 100 \\ -700 \end{bmatrix}$$

Calorie min
Calorie max
Sugar
Calcium



How do we find intersections in higher dimensions?

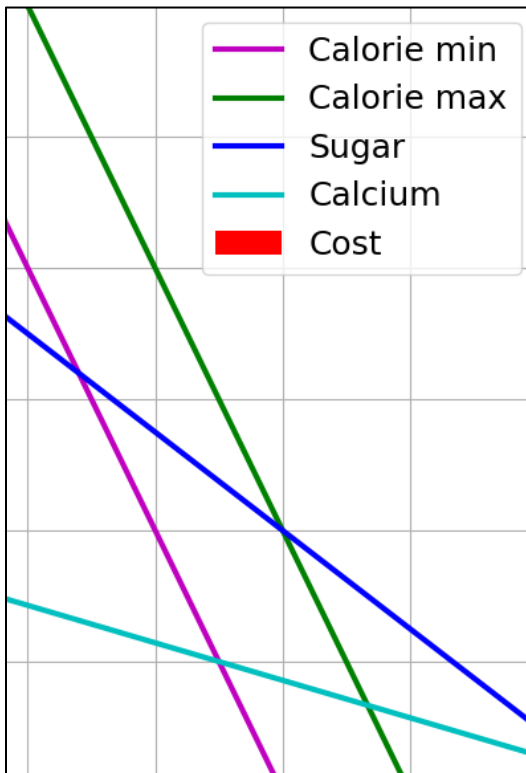
Still looking at subsets of A matrix

$$\begin{array}{ll} \min & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \end{array}$$

$$A = \begin{bmatrix} -100 & -50 \\ 100 & 50 \\ 3 & 4 \\ -20 & -70 \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} -2000 \\ 2500 \\ 100 \\ -700 \end{bmatrix}$$

Calorie min
Calorie max
Sugar
Calcium



Integer Programming

Linear Programming

We are trying healthy by finding the optimal amount of food to purchase.

We can choose the amount of **stir-fry** (ounce) and **boba** (fluid ounces).

Healthy Squad Goals

- $2000 \leq \text{Calories} \leq 2500$
- $\text{Sugar} \leq 100 \text{ g}$
- $\text{Calcium} \geq 700 \text{ mg}$

Food	Cost	Calories	Sugar	Calcium
Stir-fry (per oz)	1	100	3	20
Boba (per fl oz)	0.5	50	4	70

What is the cheapest way to stay “healthy” with this menu?

How much **stir-fry** (ounce) and **boba** (fluid ounces) should we buy?

Linear Programming → Integer Programming

We are trying healthy by finding the optimal amount of food to purchase.

We can choose the amount of stir-fry (bowls) and boba (glasses).

Healthy Squad Goals

- $2000 \leq \text{Calories} \leq 2500$
- $\text{Sugar} \leq 100 \text{ g}$
- $\text{Calcium} \geq 700 \text{ mg}$

Food	Cost	Calories	Sugar	Calcium
Stir-fry (per bowl)	1	100	3	20
Boba (per glass)	0.5	50	4	70

What is the cheapest way to stay “healthy” with this menu?

How much stir-fry (ounce) and boba (fluid ounces) should we buy?

Linear Programming vs Integer Programming

Linear objective with linear constraints, but now with additional constraint that all values in \mathbf{x} must be integers

$$\begin{array}{ll} \min_{\mathbf{x}} & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \end{array}$$

$$\begin{array}{ll} \min_{\mathbf{x}} & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \in \mathbb{Z}^N \end{array}$$

We could also do:

- Even more constrained: Binary Integer Programming
- A hybrid: Mixed Integer Linear Programming

Notation Alert!

Integer Programming: Graphical Representation

Just add a grid of integer points onto our LP representation

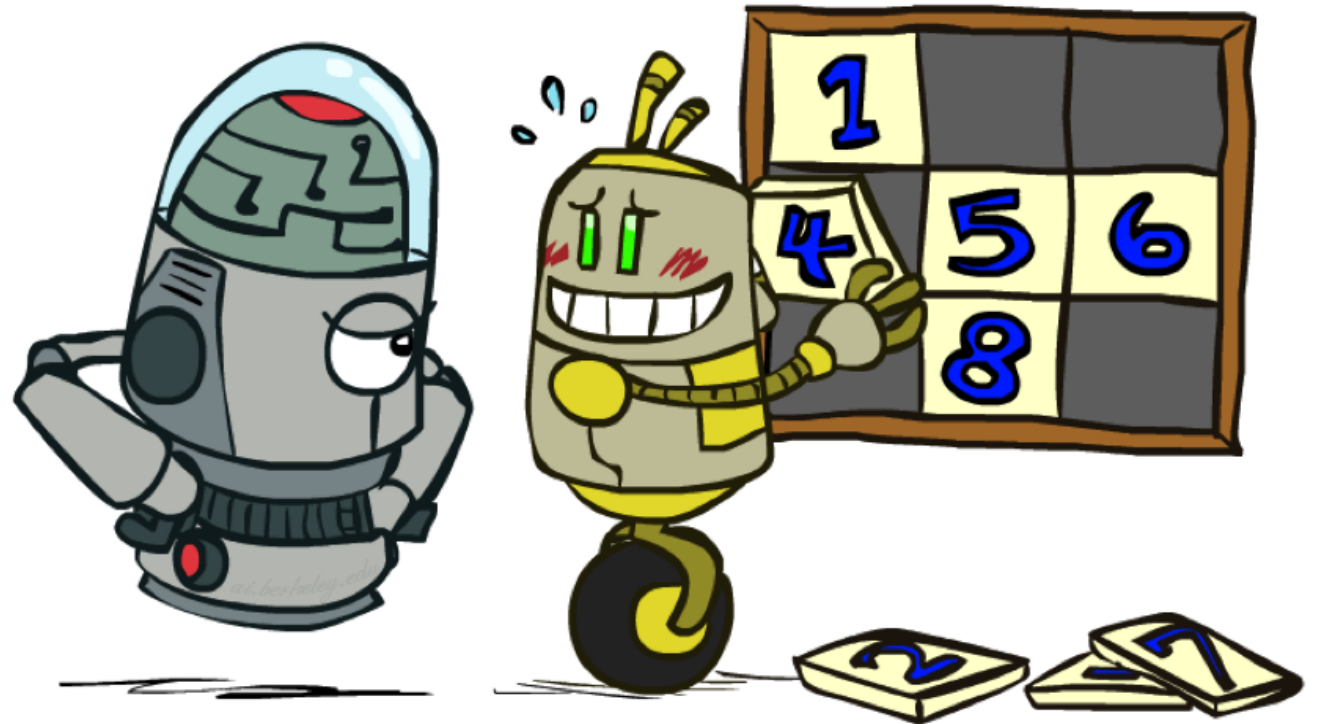
$$\begin{array}{ll}\min. & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \in \mathbb{Z}^N\end{array}$$

Relaxation

Relax IP to LP by dropping integer constraints

$$\begin{array}{ll}\min. & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \\ & \cancel{\mathbf{x} \in \mathbb{Z}^N}\end{array}$$

Remember heuristics?



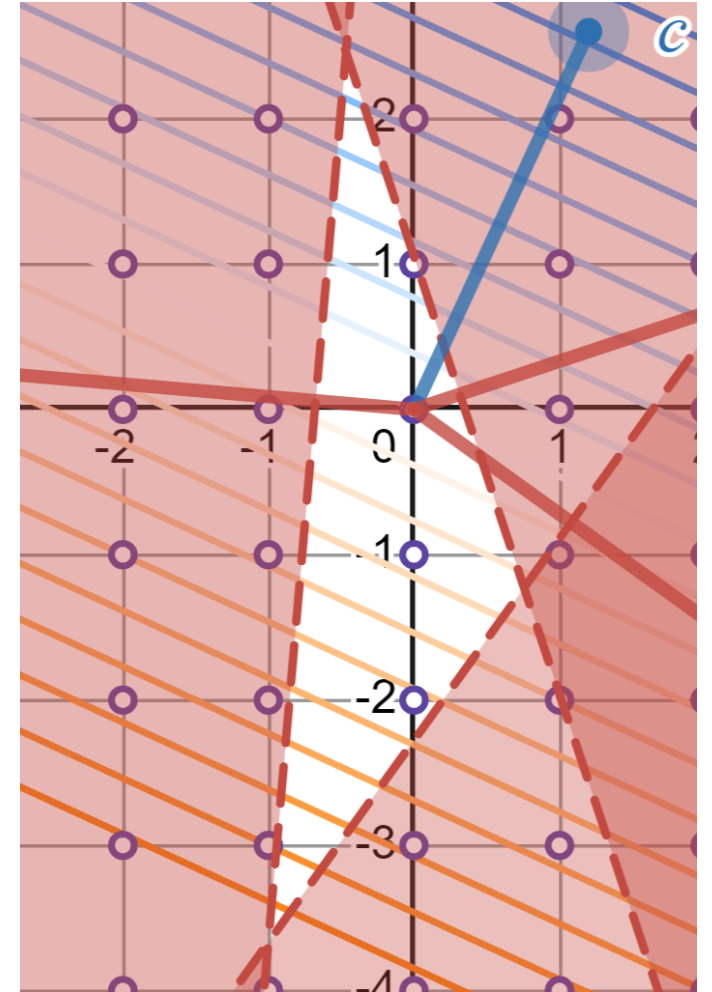
Notation Alert

Let y represent the objective value (total cost), $y = \mathbf{c}^\top \mathbf{x}$

Pay attention to argmin. vs just min.

$$\begin{array}{ll} x_{IP}^* = \underset{\mathbf{x}}{\operatorname{argmin.}} & \mathbf{c}^\top \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \in \mathbb{Z}^N \end{array}$$

$$\begin{array}{ll} y_{IP}^* = \underset{\mathbf{x}}{\min.} & \mathbf{c}^\top \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \in \mathbb{Z}^N \end{array}$$



Poll 4:

Let y_{IP}^* be the optimal objective of an integer program P .

Let \mathbf{x}_{IP}^* be an optimal point of an integer program P .

Let y_{LP}^* be the optimal objective of the LP-relaxed version of P .

Let \mathbf{x}_{LP}^* be an optimal point of the LP-relaxed version of P .

Assume that P is a minimization problem.

Which of the following are true?

A) $\mathbf{x}_{IP}^* = \mathbf{x}_{LP}^*$

B) $y_{IP}^* \leq y_{LP}^*$

C) $y_{IP}^* \geq y_{LP}^*$

$$\begin{array}{ll} y_{IP}^* = \min_{\mathbf{x}} & \mathbf{c}^\top \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \in \mathbb{Z}^N \end{array}$$

$$\begin{array}{ll} y_{LP}^* = \min_{\mathbf{x}} & \mathbf{c}^\top \mathbf{x} \\ \text{s.t.} & A\mathbf{x} \leq \mathbf{b} \end{array}$$

Poll 5:

True/False: It is sufficient to consider the integer points around the corresponding LP solution?

Solving an IP

Branch and Bound algorithm

Core steps:

Use LP solver to find \mathbf{x}_{LP}^*

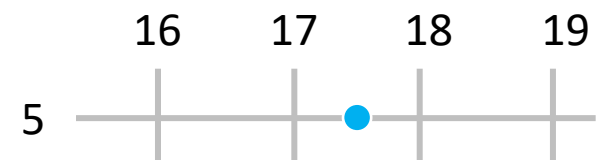
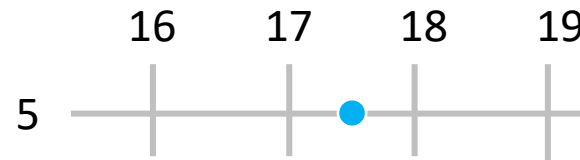
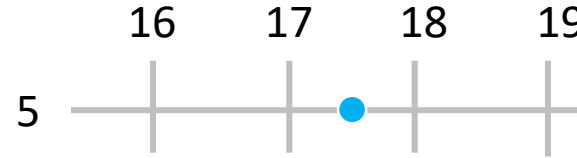
If \mathbf{x}_{LP}^* is all integer valued,
return solution

Otherwise:

Create two branches

Left branch: Added constraint $x_i \leq \text{floor}(x_i)$

Right branch: Added constraint $x_i \geq \text{ceil}(x_i)$



Solving an IP

Branch and Bound algorithm

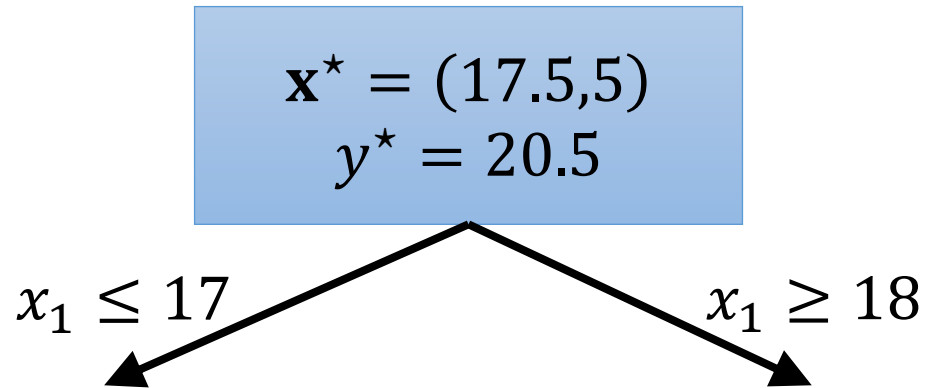
1. Push LP solution of problem into priority queue,
ordered by objective value of LP solution
2. Repeat:
 - If queue is empty, return IP is infeasible
 - Pop candidate solution \mathbf{x}_{LP}^* from priority queue ()
 - If \mathbf{x}_{LP}^* is all integer valued, we are done; return solution
 - Otherwise, select a coordinate x_i that is not integer valued, and add two additional LPs to the priority queue:

Left branch: Added constraint $x_i \leq \text{floor}(x_i)$

Right branch: Added constraint $x_i \geq \text{ceil}(x_i)$

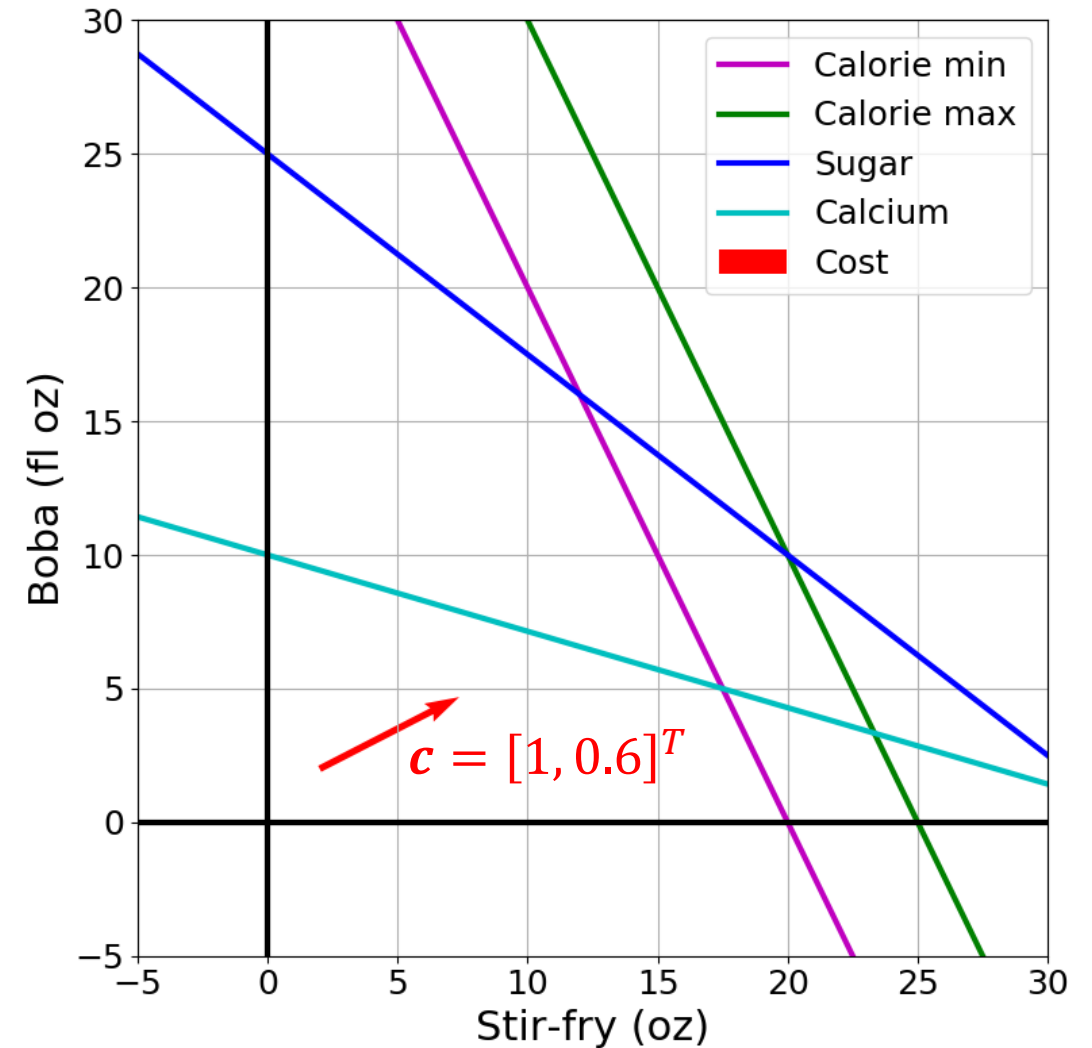
Note: Only add LPs to the queue if they are feasible

Branch and Bound Example

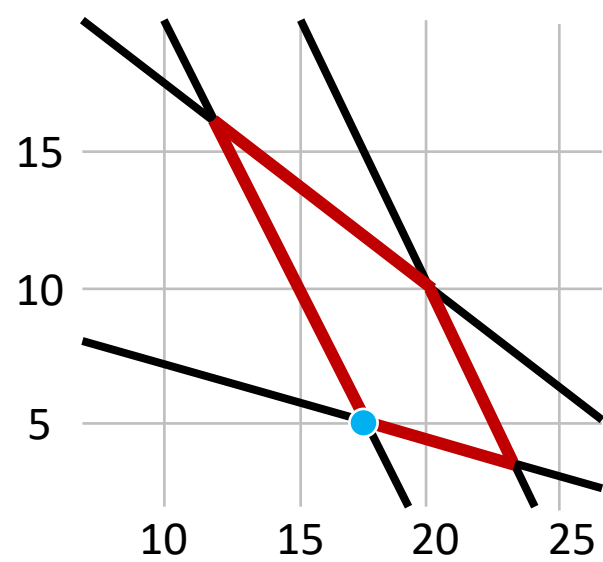


Priority Queue:

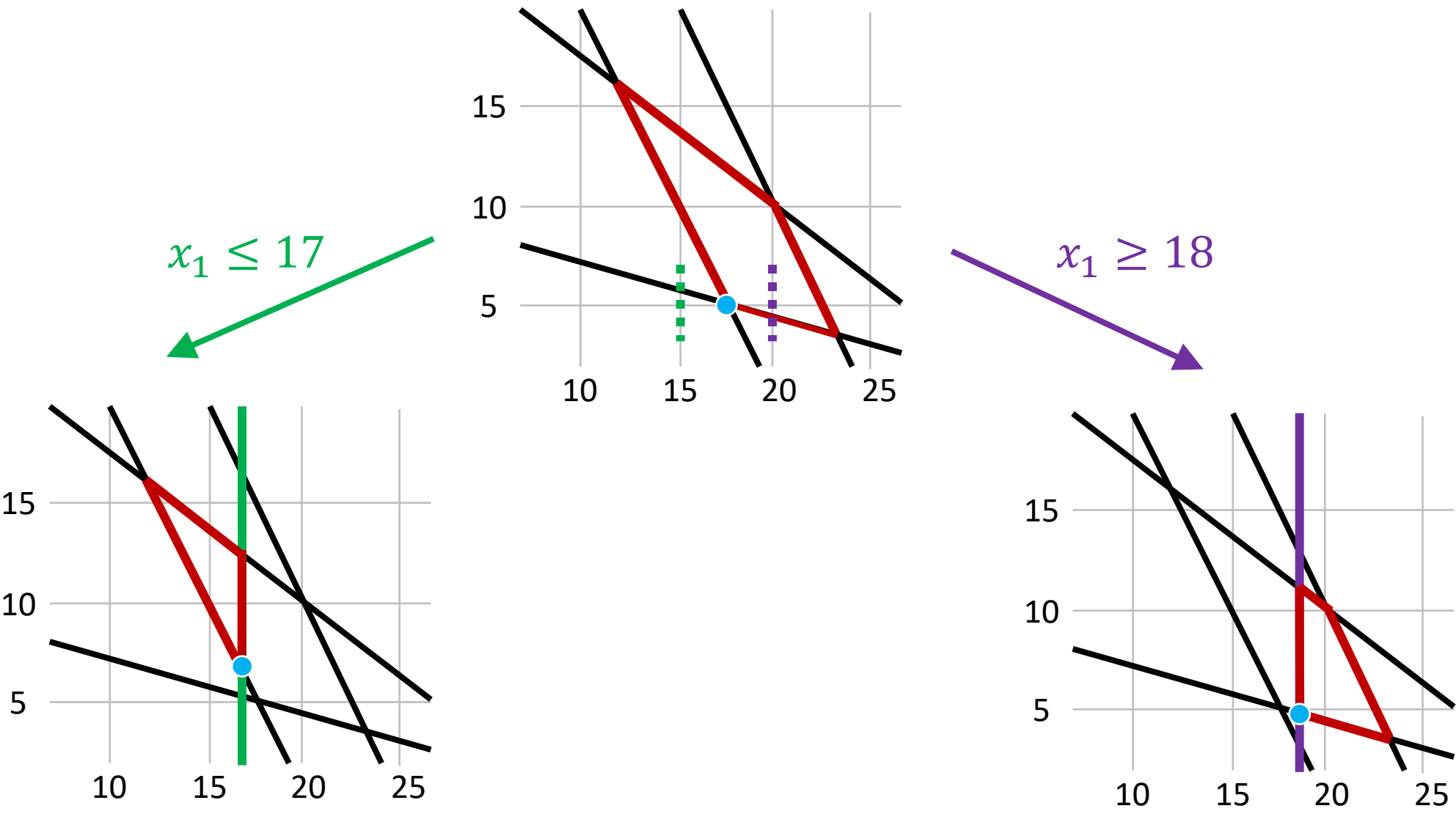
1. $\mathbf{x}^* = (17.5, 5), y^* = 20.5$



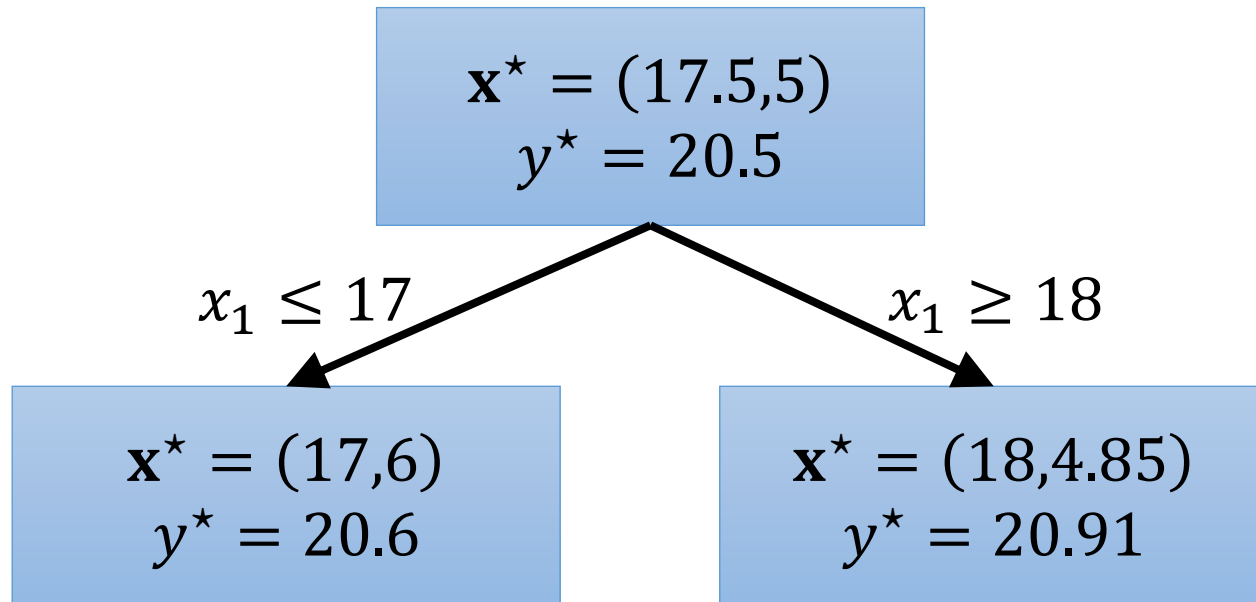
Branch and Bound Example



Branch and Bound Example



Branch and Bound Example



Priority Queue:

1. $\mathbf{x}^* = (17, 6)$, $y^* = 20.6$
2. $\mathbf{x}^* = (18, 4.85)$, $y^* = 20.91$

