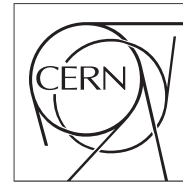


The Compact Muon Solenoid Experiment

Conference Report

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Towards a container-based architecture for CMS data acquisition

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Abstract

The CMS data acquisition (DAQ) is implemented as a service-oriented architecture where DAQ applications, as well as general applications such as monitoring and error reporting, are run as self-contained services. The task of deployment and operation of services is achieved by using several heterogeneous facilities, custom configuration data and scripts in several languages. In this work, we restructure the existing system into a homogeneous, scalable cloud architecture adopting a uniform paradigm, where all applications are orchestrated in a uniform environment with standardized facilities. In this new paradigm DAQ applications are organized as groups of containers and the required software is packaged into container images. Automation of all aspects of coordinating and managing containers is provided by the Kubernetes environment, where a set of physical and virtual machines is unified in a single pool of compute resources. We demonstrate that a container-based cloud architecture provides an across-the-board solution that can be applied for DAQ in CMS. We show strengths and advantages of running DAQ applications in a container infrastructure as compared to a traditional application model.

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Towards a container-based architecture for CMS data acquisition

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The CMS data acquisition (DAQ) is implemented as a service-oriented architecture where DAQ applications, as well as general applications such as monitoring and error reporting, are run as self-contained services. The task of deployment and operation of services is achieved by using several heterogeneous facilities, custom configuration data and scripts in several languages. In this work, we restructure the existing system into a homogeneous, scalable cloud architecture adopting a uniform paradigm, where all applications are orchestrated in a uniform environment with standardized facilities. In this new paradigm DAQ applications are organized as groups of containers and the required software is packaged into container images. Automation of all aspects of coordinating and managing containers is provided by the Kubernetes environment, where a set of physical and virtual machines is unified in a single pool of compute resources. We demonstrate that a container-based cloud architecture provides an across-the-board solution that can be applied for DAQ in CMS. We show strengths and advantages of running DAQ applications in a container infrastructure as compared to a traditional application model.

1 Introduction

The Compact Muon Solenoid (CMS) [1, 2] is one out of four large particle detectors (experiments) at the Large Hadron Collider (LHC) [3] at CERN in Geneva, Switzerland. As a versatile and advanced particle detector, CMS plays an important role in fundamental physics [4].

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It allows to capture and analyze the intricate interactions between particles produced in high-energy collisions within the LHC. The Data Acquisition (DAQ) system is responsible for assembling, filtering, and storing the large influx of data generated by particle collisions within the detector [1]. The CMS DAQ system's main task is to read-out data from the different parts of the detector and assemble them into coherent structures corresponding to one bunch-crossing of the LHC (event building). These tasks require reliable monitoring and error reporting to guarantee the quality of the data collected. The system has been built upon a service-oriented architecture, where applications are encapsulated as self-contained services. This approach has enabled efficient deployment and operation of various applications, albeit using a mix of different tools, configurations, and scripting languages. In this context, two distinct strategies have emerged to manage the life cycle of services. Short-lived services, such as read-out and event building, are managed by a custom infrastructure [5]. On the other hand, long-running, auxiliary services are managed using systemd [6]. The main goal of this work is to transform the existing architecture into a homogeneous, scalable cloud system – a unified environment where all applications are managed uniformly with standardized facilities. In addition to introducing modern technologies, this work intends to demonstrate that a container-based cloud architecture can serve as a comprehensive solution for the CMS DAQ. This is a status report of work in progress since not all the goals have been achieved yet.

2 Motivation

After several years of successful operation of the CMS DAQ system with the initial approach [7], we identified points of improvement to refine the future system. User experience and lessons learned provided the base to reassess the software. To embrace opportunities coming from new technologies, providing an evolutionary framework to cope with the ever changing environment, a full revision of the current design was desirable.

One major concern with the current system lies in the infrastructure lock-in, resulting from the system's reliance on a specific operating system (OS) distribution and libraries. This constraint limits flexibility and the ability to evolve towards alternative software libraries or compilers available in other (more recent) operating system distributions.

Additionally, the transition from development to deployment proves to be time-consuming, marked by distinctly different environments (e.g., different hostnames) for development, validation, and production stages. This disparity hampers efficiency of the maintenance and development activities, such as bug fixes and new feature introduction. Furthermore, the work required to set up the computing infrastructure for development and validation turns out to be time- and resource-intensive.

The binding of CMS DAQ auxiliary service applications to either physical or virtual machines in the existing system, limits optimal resource utilization, because a safety margin on resources, such as memory and CPU, are required on each individual host.

The process of software update and rollback is often arduous, complicating the system management. It necessitates substantial system administration efforts, diverting resources from more strategic tasks.

A lack of portability due to the configuration binding to physical hostnames, makes changes in computing infrastructure labor-intensive. A minor change in a computing environment might require a full iteration from software reconfiguration to release and deployment (this applies to CMS DAQ auxiliary service applications).

The need for custom (private) scripts for software deployment and operation in test environments, adds supplementary burden on developers and users due to the differences between the two environments.

Finally, two distinct approaches are currently employed to operate and control the life cycle of services. A custom-built infrastructure of Run Control Management System (RCMS) (a web-based, graphical run control system) and Jobcontrol (a service used to start, stop and monitor processes in a distributed environment), working in tandem is used for short-lived application services (e.g., event building and read-out) [8], while for long-running, auxiliary services such as monitoring and error reporting systemd is used [6]. A single uniform approach is desirable to reduce the inherent complexity of the system.

3 Container-based architecture

Containerization transforms the network from being machine-oriented to being application-oriented. As such in container-based approach, DAQ applications are composed as cohesive groups of containers [9–11]. The required software is encapsulated within container images (e.g., Docker images) [9]. The containerization, a hallmark of modern software deployment, carries with it a host of benefits [12]. The orchestration of containers, once a cumbersome task, is streamlined through orchestration systems such as Kubernetes [13, 14], an industry-proven container orchestration platform [15, 16]. Containerization of software and container orchestration allow the use of available computational resources as a unified resource pool while different versions of software, down to the OS distribution specific libraries, can coexist within a single network host. Software changes are prepared at build time, while target machines are not affected by the ongoing modifications. See figure 1 for a graphical depiction of traditional compared to containerized approach.

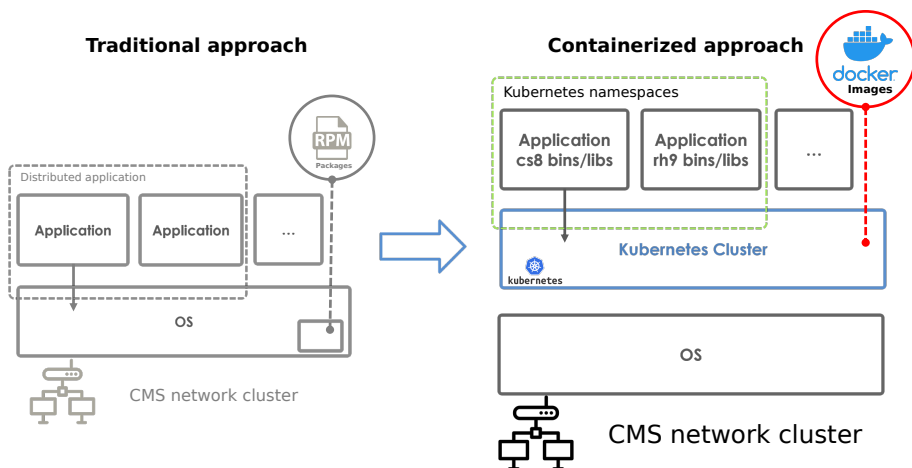


Figure 1. In traditional approach, a physical machine has libraries specific to one OS distribution installed. In containerized approach, OS distribution specific libraries are installed into container images. Containers with libraries from different OS distributions can be used on the same physical machine.

The containerized approach also provides reliability in software validation across both test and production environments, which are managed in the same manner. The construction of container images at build time ensures consistent installation across diverse targets, as container images encapsulate all required application dependencies. In turn, tests in production environment do not cause disruption on the target environment as rollbacks or re-installations are no longer needed.

In summary, containerization of software compounded by container orchestration addresses all the points of concern identified in section 2 at least to some extent.

4 Pilot project

4.1 Goals

The transition of the DAQ system from a traditional approach to a container-based architecture is being carried out through a pilot project with the following goals:

- Rework DAQ system elements in a cloud approach based on Kubernetes patterns;
- Adopt a full software life cycle for the new environment, focusing on the development, delivery, deployment and operation;
- Resolve issues concerning building and maintenance of the Kubernetes cluster and hardware resources;
- Determine implications on the current system administration environment;
- Implement a fully functional DAQ column from back-end electronics, collecting data from the detector front-ends, to High Level Trigger (HLT), including run control and monitoring.

The scope of the pilot project applies to all dimensions of expertise within the CMS DAQ system:

- Operation;
- Development;
- Release;
- Deployment;
- System administration;
- Networking;
- Security;
- Integration.

The aforementioned goals can be achieved through the implementation of the following study modules:

1. Performance and scalability;
2. Hardware access and binding (VME bus, PCI bus, remote direct memory access (RDMA), FEROL [17], etc.);
3. System fine-tuning (driver interrupts, non-uniform memory access (NUMA) settings, etc.);
4. User access (Graphical User Interface (GUI), Command Line Interface (CLI), Dashboards, API, etc.);
5. Networking (configuration, fine-tuning TCP/IP, RDMA over Converged Ethernet (RoCE), etc.);
6. Control and monitoring;
7. Configuration;

8. Additional technologies and their integration (Elasticsearch, Opensearch, Oracle, WinCC Open Architecture (WinCC OA), etc.);
9. Scalable event builder prototype;
10. Startup measurements.

4.2 Current achievements

At the time of writing of this paper, the following work has already been performed.

- A thorough exploration of user access options, which involved GUIs, CLIs, Dashboards, and the Kubernetes API (study module 4);
- The CMS DAQ is utilizing high bandwidth RDMA devices [18–21], thus, an effort was dedicated to investigation and prototyping with RDMA-based device access (RoCE) in Kubernetes. Prototypes were able to successfully communicate through RDMA devices (study modules 2 and 5);
- Various Kubernetes cluster networking approaches were evaluated. Prototypes with several Container Network Interface (CNI) plugins such as flannel, Calico, and ipvlan [22] were built (study module 5);
- Different software configuration techniques within pods, including custom scripting in Python language as well as Helm [23] scripting were prototyped (study module 7);
- In the realm of monitoring, the deployment and testing of Elasticsearch and Opensearch within the Kubernetes cluster were carried out to assess their viability for monitoring functionalities (study modules 6 and 8);
- Multiple event building prototypes were designed and implemented to operate within a Kubernetes cluster (study modules 1, 3, 6 and 9);
- Measurements of startup time (study modules 1 and 10). More details are available in section 4.3.

4.3 Measurements

In the DAQ system, minimizing the periods of system downtime is of utmost importance. Since there are situations where system reconfiguration or restart is necessary, this leads to a requirement to minimize the startup time, and the current DAQ system is optimized for fast startup [5] (by startup we mean the full restart of the system). Thus it is imperative for the new design to also perform well in this regard. In this work we performed measurements of system startup time. We considered the overall startup time to be the time interval from the moment right before starting installation of necessary Kubernetes objects using Helm tool until all the pods are ready to perform their function. Each pod running a single application, had to connect with every other application in the Kubernetes cluster via RDMA semantics. This interconnectivity is a typical requirement for an event building application. In addition, we measured the time needed for intermediate steps during startup in order to determine which steps are the most time consuming.

The measurements were performed on a Kubernetes cluster with 106 physical nodes (these machines were used for event building task by CMS DAQ during LHC Run 2). Each node was running a single pod. Required container images were pulled on each node before performing measurements. Each measurement was performed five times and the mean value of the startup times was calculated. After each measurement, all the pods and all

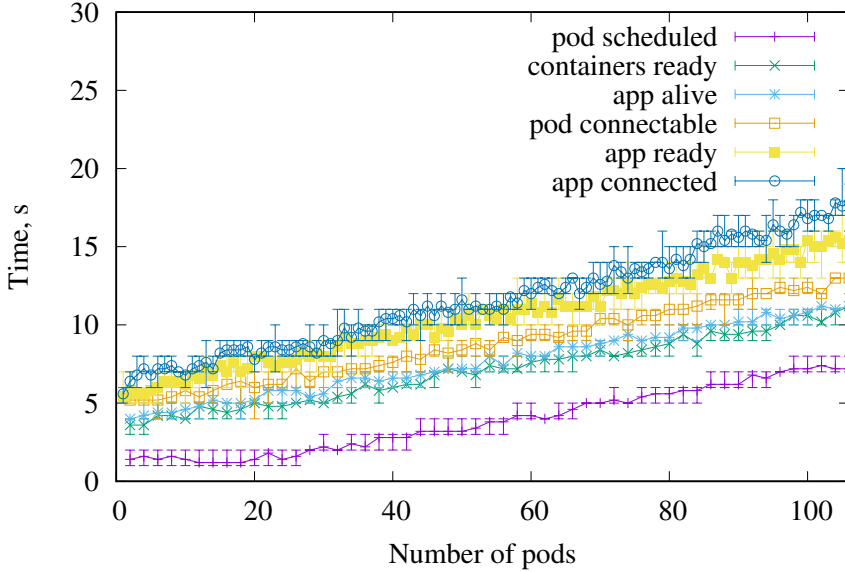


Figure 2. Startup time measurements. Points in the plot signify mean values, while bars signify maximum and minimum values measured.

other measurement-related Kubernetes objects (e.g., services, configmaps, namespace) were deleted before performing a new measurement.

The intermediate startup steps measured were the following: "pod scheduled" – all pods are scheduled to run on required nodes, "containers ready" – all containers are created, applications are being started, "app alive" – the time needed to start a simplified application without the requirement for interconnection, "pod connectable" – all DNS names required by an application are resolved to IP addresses, "app ready" – application with full configuration is successfully started, "app connected" - all required network connections specific to an application to fulfill its function and inter-operate are established. The measurement results are shown in figure 2.

We can see that the startup time does not grow drastically with the increase in number of pods used in the experiment. The mean values of the different cumulative components of startup time with the maximum number of pods (106) were the following: "pod scheduled" - 7.2 s, "containers ready" - 11.2 s, "app alive" - 11.2 s, "pod connectable" - 13 s, "app ready" - 15.4 s and "app connected" - 17.8 s. For Kubernetes, it takes 7.2 s to schedule pods on all 106 nodes available in the cluster and it takes another 4 s to bring containers to the ready state. In order to speedup the transition to the "pod connectable" state, we optimized the DNS names resolution by using a custom script interrogating Kubernetes API. We can see that after containers are ready it takes 1.8 s in each pod to resolve DNS names required to access every other pod. After pods are connectable our test application starts on each single pod in 2.4 s and it takes an additional 2.4 s for all applications to connect to each other in the cluster.

The estimated number of CMS DAQ event builder nodes in Phase 2 is 200 [24], while our measurements were performed on 106 nodes, also different hardware will be used in Phase 2. Therefore additional measurements are needed to get conclusive results. However, 35 s was considered an acceptable startup time for CMS DAQ during LHC Run 1 [5] and it is possible

that our measured 17.8 s for 106 nodes would translate into a comparable value with 35 s, with the required number of nodes and the new hardware.

5 Conclusion and future work

Encouraging results were achieved so far. Containerization was shown to be an appealing technology for DAQ applications as a replacement for a bare metal infrastructure. Containerization and orchestration solve most of the limitations experienced by running with a traditional infrastructure. The approach fits well with distributed inter-communicating applications such as the event builder. No limitations of the approach were discovered during the investigation of predefined objectives. Future work concerns unresolved study modules, finalization of a working DAQ column from back-end electronics to HLT, repeating startup measurements on the actual machines and network infrastructure that will be used by CMS DAQ in Phase 2, whenever these resources will become available, and finally measuring the performance of the actual event building in the real Phase 2 system.

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