

PS/OP/Info 92-04  
4.2.1992

## AAC RF SYSTEMS

Copie des transparents  
du cours donné aux techniciens d'opération AAC/LEAR  
le 4.2.1992  
par L. Soby

Distribution

Section OP/AAC/LEAR  
AAS

# AAC RF Systems

## AC H=6:

Debunching of Injected  $\bar{P}$ 's  $\frac{\Delta P}{P} = 6\% \rightarrow 1,5\%$

$$F_{RF} = F_{rev} + 6 = 9.53683 \text{ MHz (FIXED)}$$

$$V_{RF} = 500 V_p \rightarrow 1,2 \text{ MVP } \underline{\underline{2 \text{ gap}^2}}$$

## AC H=1:

a) Bunching of Pre-coded  $\bar{P}$  on Central orbit before transfer to AA

b) Manipulations of Testbeams - Q ( $\downarrow$ ), orbit ( $\downarrow$ )

$$F_{RF} = 1587.2 \text{ kHz} \pm 1.5 \text{ kHz}$$

$$V_{RF} = 1 v_p \text{ to } 3.5 \text{ kv}_p (1 \text{ gap})$$

} GFA's.

## AA H=1:

o) Bucket to Bucket transfer between AA/AC

a) Bunching of Pre-coded  $\bar{P}$ 's

b) Transfer to stack

c) Unstacking of  $\bar{P}$ 's

d) Testbeam manips.

## AAL RF Systems

AA H=1 (cont.) :

$$F_{RF} = 1850 \text{ kHz} \pm 10 \text{ kHz}$$

$$V_{RF} = 5 \text{ Vp to } 14 \text{ kVp (2 gaps)}$$

} GFA

AA H=160 :

~~Controlled blow up of stack prior  
to SPS dump.~~

Not used For Lear transfers

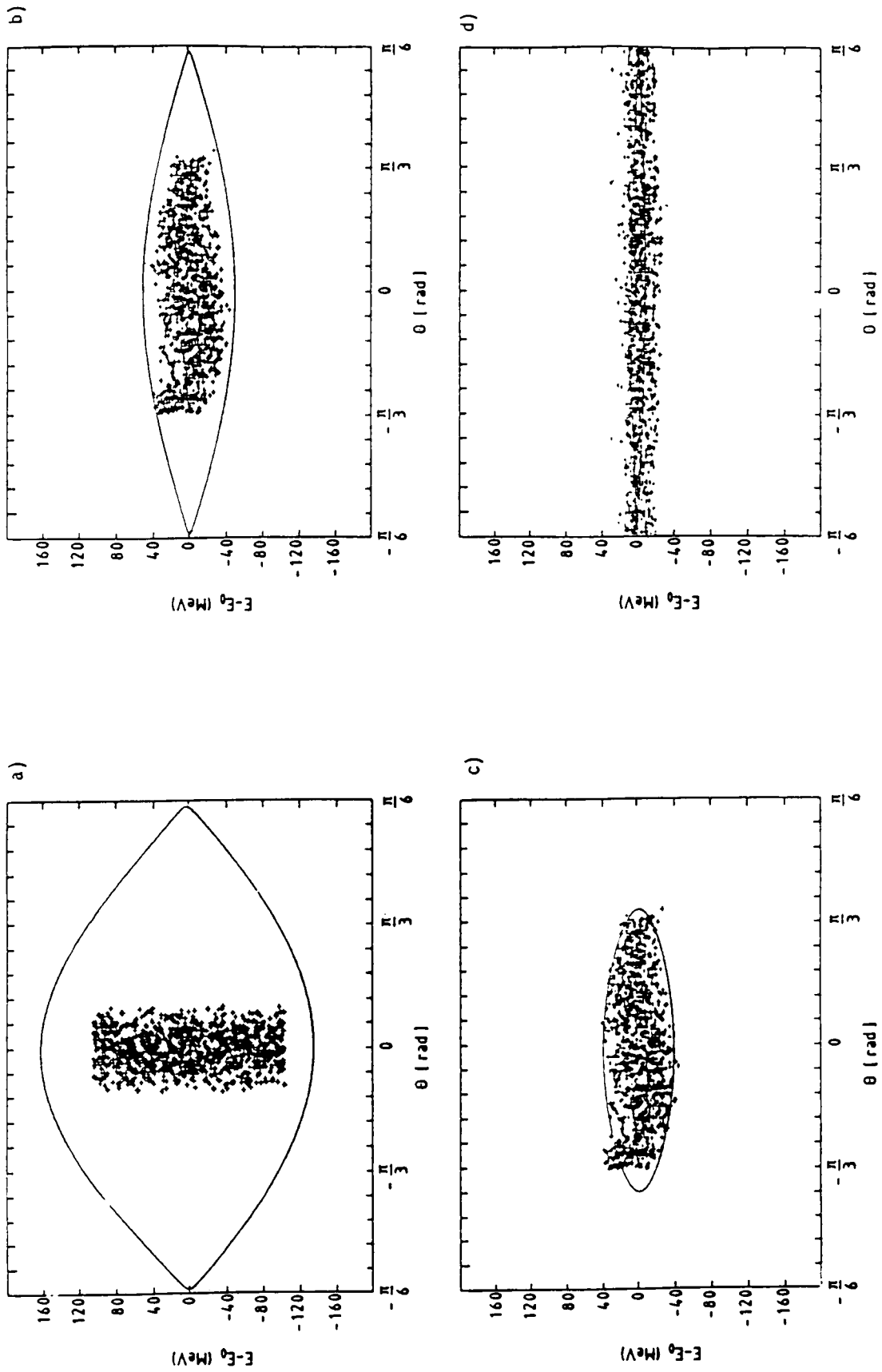


Fig. 13 Debunching in ACO. (a) Initial configuration of the bunch in the longitudinal phase space. (b) After bunch rotation. (c) At the beginning of the adiabatic debunching. (d) After full debunching.

Table 3.2 summarizes the most important rf parameters. Figure 3.2 shows a practical voltage program.

Table 3.2

Voltage, rotation	1.32 MV <sub>p</sub>
Bucket/bunch height	1.41
Harmonic number	6
Frequency	9.537 MHz
Rotation time	60.5 μs
Revolutions during rotation	96
Matching voltage (for initial bunch length of 25 ns)	297 kV <sub>p</sub>
Debunching time	10 ns

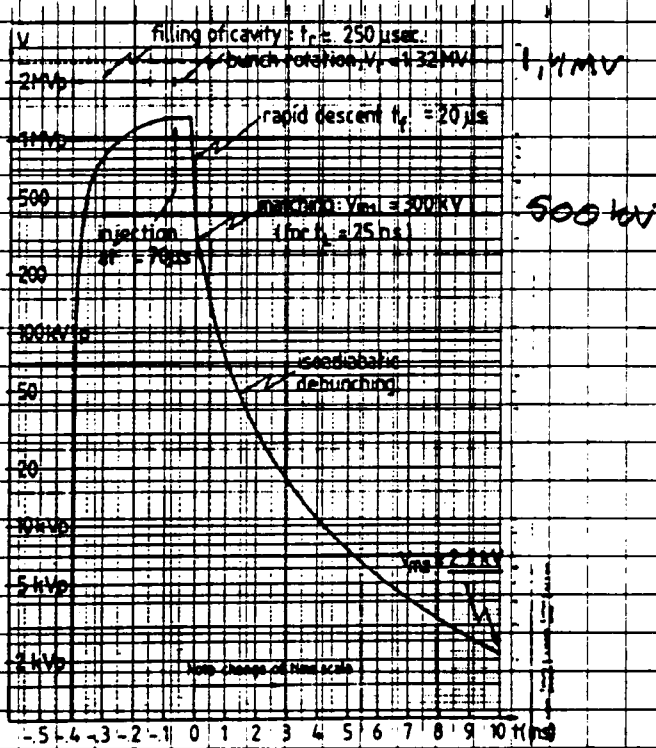


Fig. 3.2 Typical voltage program

### 3.3 Rebunching

To obtain a practically loss and dilution-free transfer of the pre-cooled beam from the AC to the smaller AA while providing reasonable gaps for the AC and AA kickers a rebunching rf system with harmonic number one is provided. This system also serves to manipulate proton test beams to explore the momentum aperture.

AC

\*\*\* FUNCTION NO. 4

\*\*\*00-11-1703:33

HOLD LEVEL	700
MATCH LEVEL	250
FINAL LEVEL	3
DEBUNCHING TIME (MS)	20
ROTATION TIME (105 NS UNITS)	558
ADIABATICITY FACTOR	.15
DISCHARGE TIME (105 NS UNITS)	5000
FROM CX.IKIK-MSW	5000

THE ROTATION TIME AND ADIABATICITY FACTOR ARE CALCULATED  
ASSUMING THAT BOTH CAVITIES ARE WORKING WITH THESE PARAMETERS.  
IF ONLY ONE CAVITY IS USED, BOTH MUST BE MULTIPLIED BY 1.41.

BRAC(2,COH1) 178

2506-01-00-0000

	CAV.1 2706	CAV.2 2506		CAV.1 2706	CAV.2 2506
LEVEL 1			MAIN INTERLOCK		
LEVEL 2			AIRFLOW DRIVER		
DETUNED			AIRFLOW FINAL		
HOLD VOLTAGE, KV			WATERFLOW DRIVER		
PHASE, degrees			WATERFLOW FINAL		
			FILAMENT DRIVER		
ON-OFF CONTROL			TEMP. FINAL		
VOLTAGE CONTROL			FILAMENT FINAL		
PHASE CONTROL			WARM-UP FINAL		
SYNTHESIZER			SECURITY		
ISO-AD.DEBUNCH.			CATHODE SWITCH		
TIMING			VACUUM		
			-350V G1 DRIVER		
GAP VOLTAGE			PREDRIVER		
GAP PHASE			+U <sub>3</sub> DRIVER		
			+U <sub>3</sub> FINAL		
			1.5KV DRIVER		
			TUNING		

BRAC(2,COH1) 178 CANAC ERROR (LOOK AT DETAILS BY PROP. CAMERR)

AC

RECENT FILES

ACTIVE FILE SHOWN **INVERTED**

	LAST SAVED	LAST USED
1 STACKING 4.8 S	91-12-03	92-02-04
2 MODE 10 SPECIAL TRANSFER RF.	90-04-11	91-09-27
3 DEBUNCH P'S MODE 3	89-12-27	91-09-27
4 STACKING 4.8 S	90-09-12	91-09-27
5 DEBUNCH, CAPTURE, DEPOSIT	87-11-20	91-09-27
6 BLOW UP - COOL - REBUNCH FOR TRANSFER	87-10-07	87-11-18
7 CAPTURE DEB. P'S FOR XFER TO AA	88-03-28	92-02-04



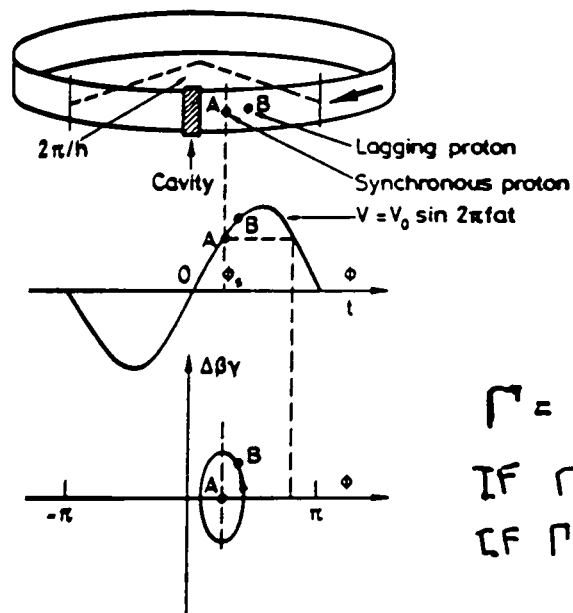
# AC 1 STACKING 4.8 S

SAVED USED  
 31-12-93 32-02-94

NO FREE LOCK

SYNC DISABLED

VALUES AT END OF SEQUENCE											
SEQ	TYPE	dt	t-tini	f	A	eVs	r	W	fs	Hz	VECT
1	IMP	0	0	1588	.2978	0		2		2	1
2	IMP	.056	.056	1588	.2978	0		2		2	2
3	IMP	1.798	1.854	1588	.2978	0		2		2	14
4	IMP	2.39	4.244	1588	.2978	0		2		2	29
5	IMP	.02	4.264	1589.48	.3886	0		2		2	30
6	IMP	.5	4.764	1589.48	9.5	0		1195	50	50	40
7	IMP	.002	4.766	1589.48	9.4998	0		1195	50	50	41
8	IMP	.02	4.786	1588	.2978	0		2		2	42
										max	



$\Gamma = \sin \theta_s$   
 IF  $\Gamma > 0 \Rightarrow$  Acceleration.  
 IF  $\Gamma < 0 \Rightarrow$  DesAcceleration

Fig. 22 Cylindrical coordinate system rotates with beam, demonstrates meaning of RF phase angle in longitudinal phase space

$$\beta = v/c$$

$$Y = E/E_0$$

$$P = (\gamma\beta) E_0$$

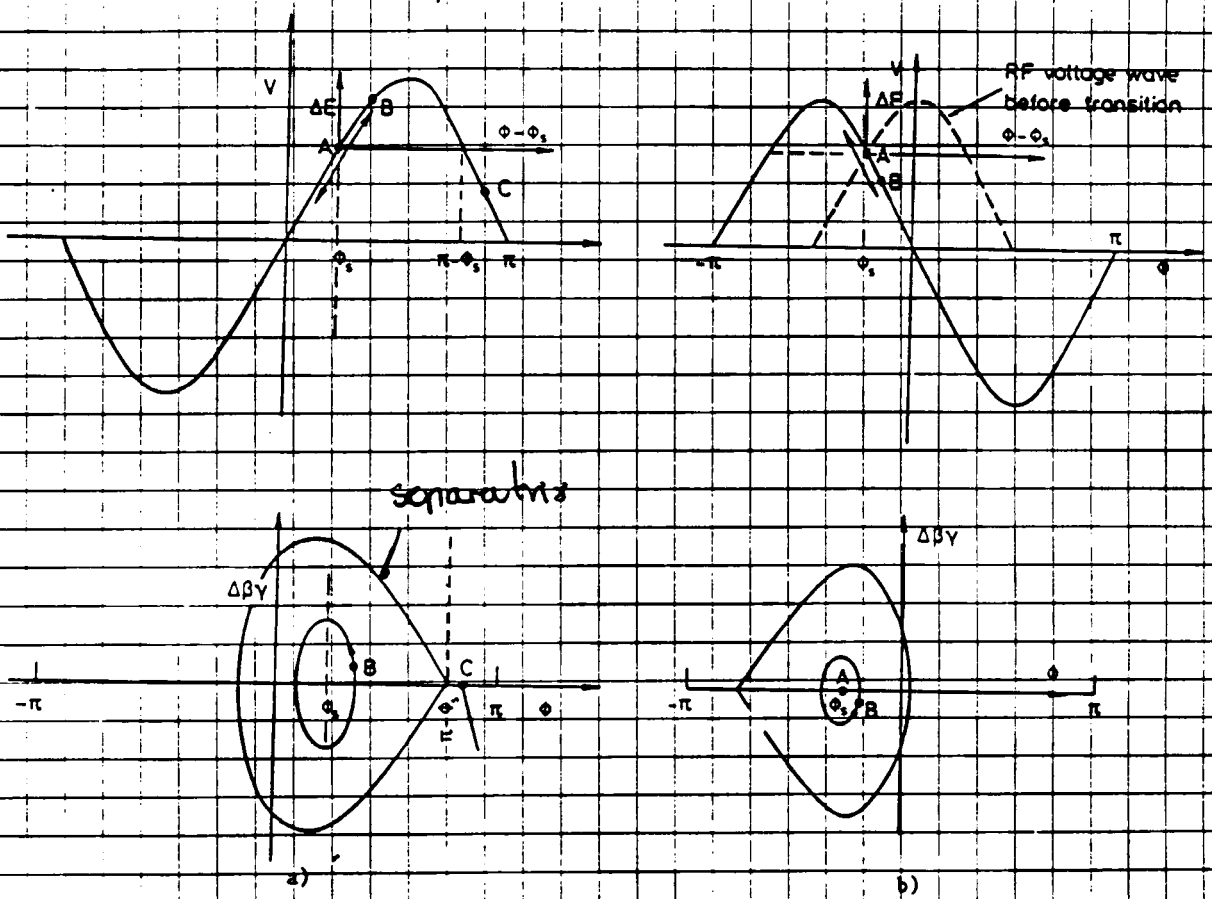


Fig. 23 Phase stability of synchrotron motion below (a) and above (b) transition

$$A_{03} = \frac{|E|E}{h} \frac{h \cdot c V_{RF} \cdot E}{2 \cdot \pi \cdot |\dot{\gamma}|} \quad \text{e.v. sec}$$

$$A_3 = \infty(\Gamma) A_{03}$$

Bucket area:  $(\text{heV})^{1/2} \alpha(\Gamma) (16\gamma/h) (2\pi E|\eta|)^{-1/2}$   
 Bucket (half) height:  $(\text{heV})^{1/2} \gamma(\gamma/h) (\pi E|\eta|)^{-1/2}$   
 Coordinates:  $(\Delta p/m_0 c) - \phi$

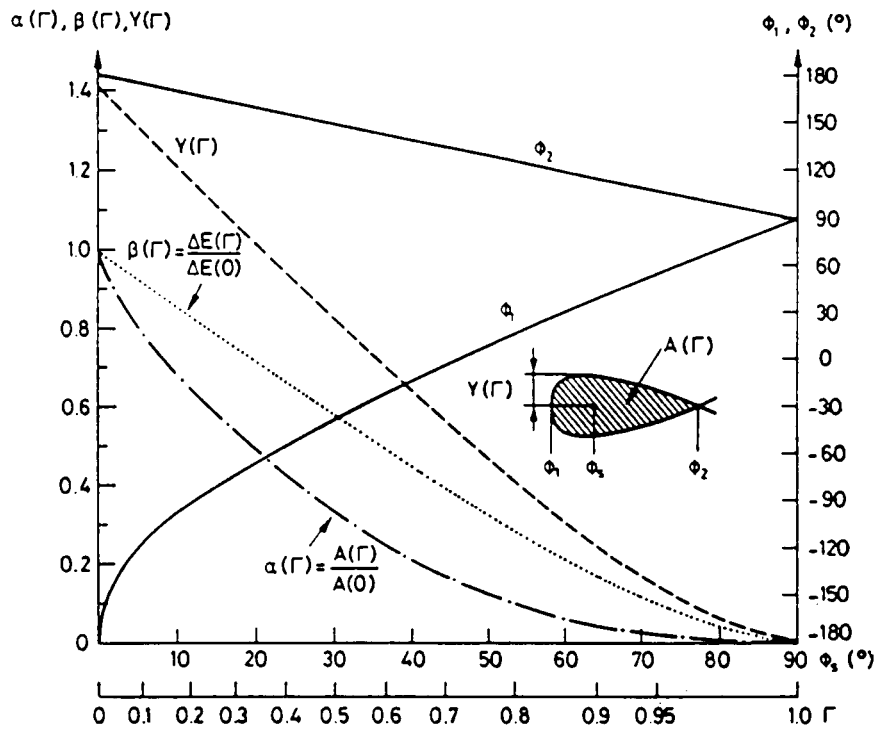
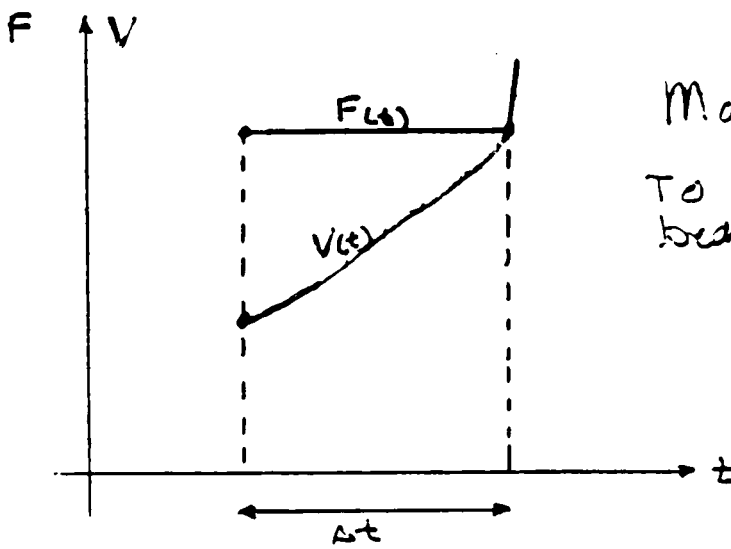
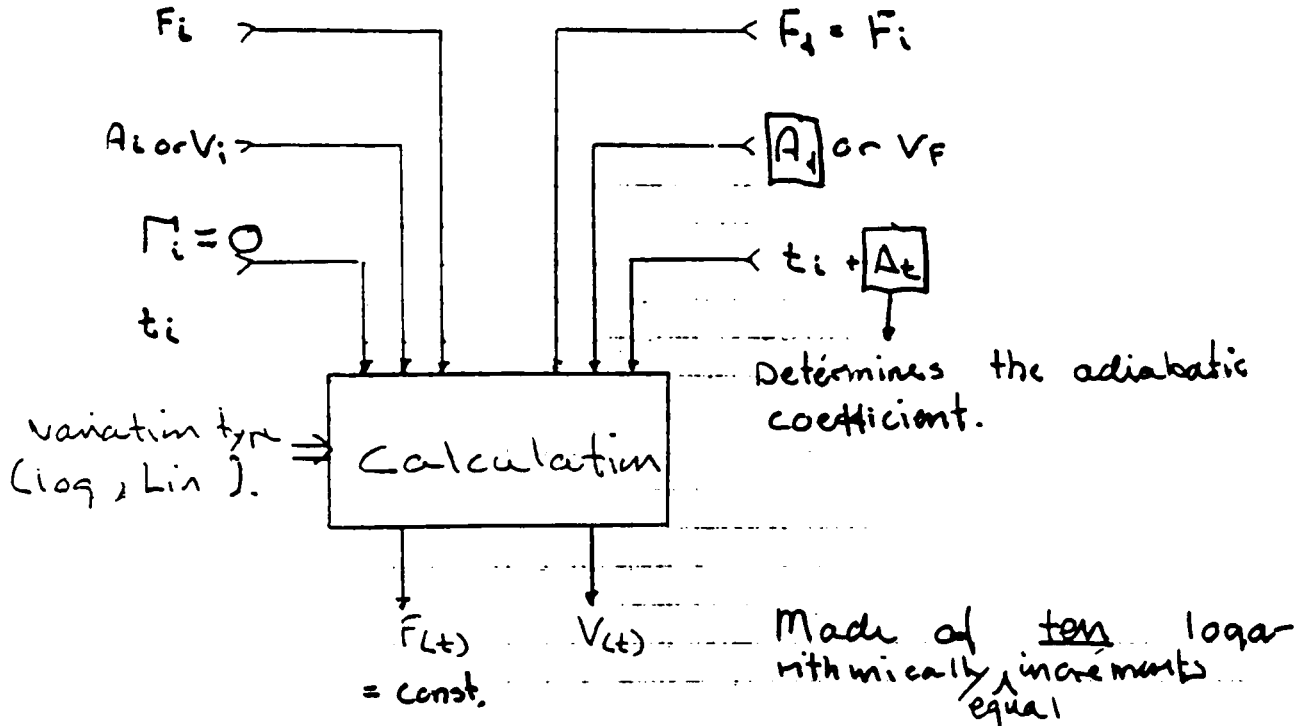


Fig. 27 Normalized bucket area and height (from Ref. 3)

Start values:  
(Init)

Final values



Main purpose:  
To (re)turnish (coasting) beam.

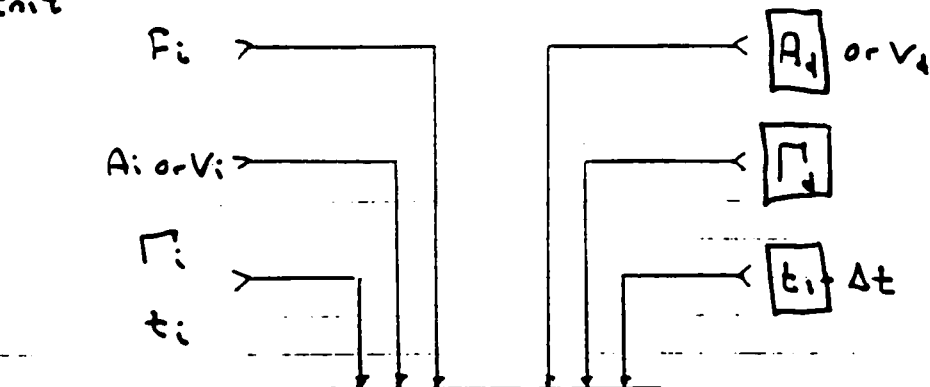
**TRP**

Always adiabatic

Trapping

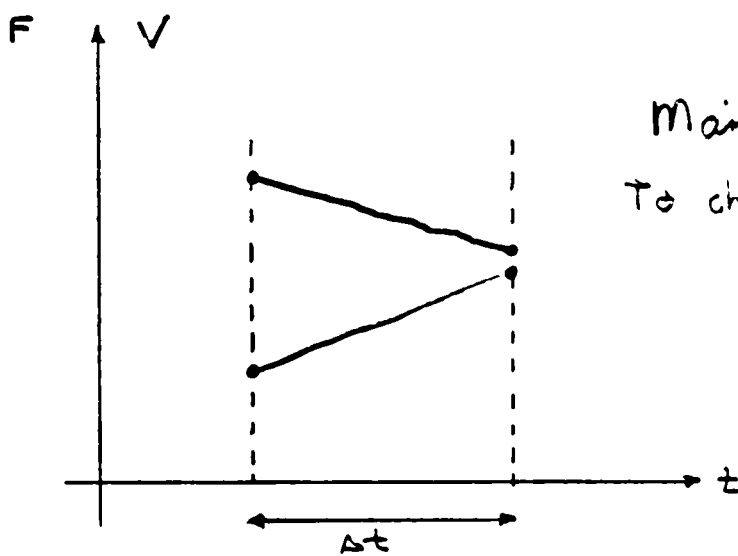
Start values:  
 $t_{init}$

Final values



variation type  $\Rightarrow$  (log, lin).

Consists of 10 vectors equal in time



Main purpose:  
 To change bucket area.

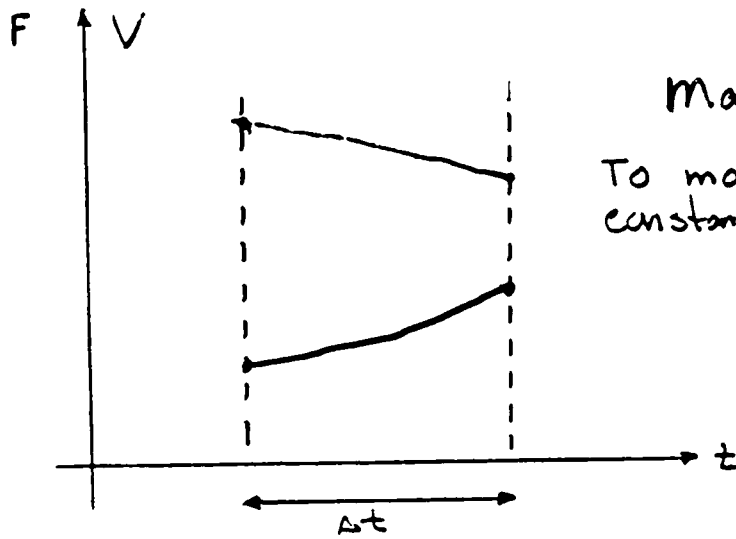
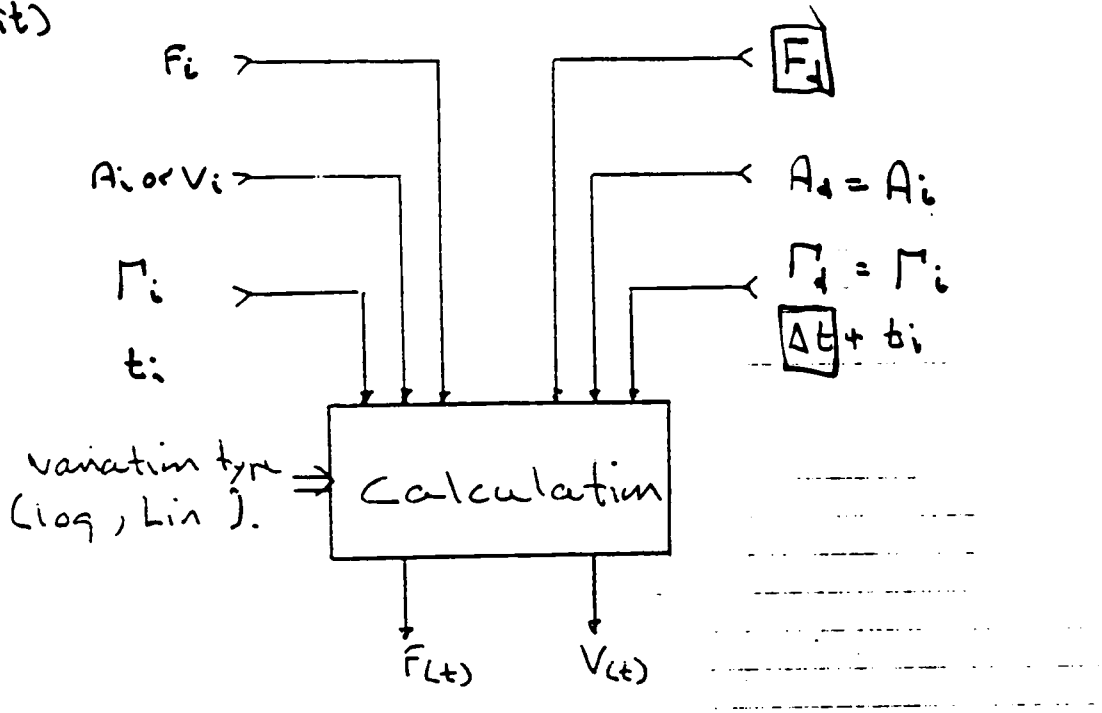
**MAT**

Always Adiabatic

Matching

Start values:  
( $t_i$ )

Final values



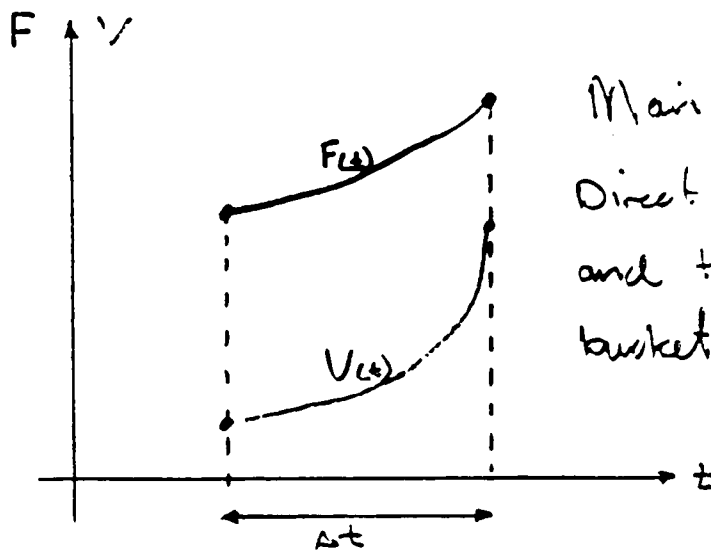
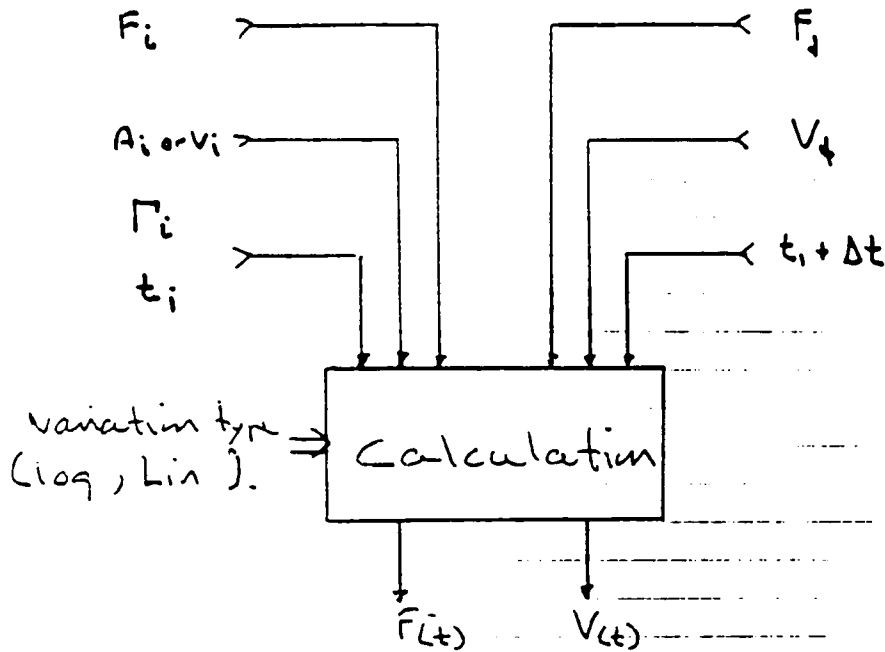
Main Purpose:  
To move the beam with  
constant bucket size.

**MOV**

move

Start values:  
(Initial).

Final values



Main purpose is  
Direct control of \$V\$ and \$F\$  
and to obtain \$M > 1\$ in the  
bucket.

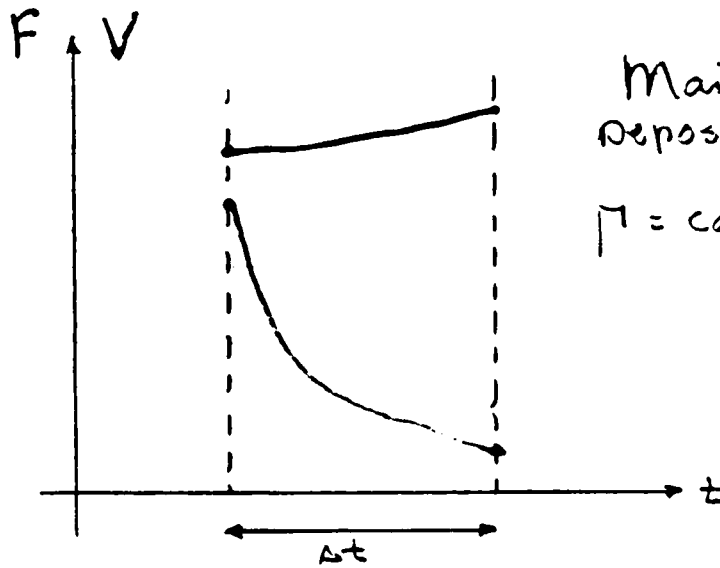
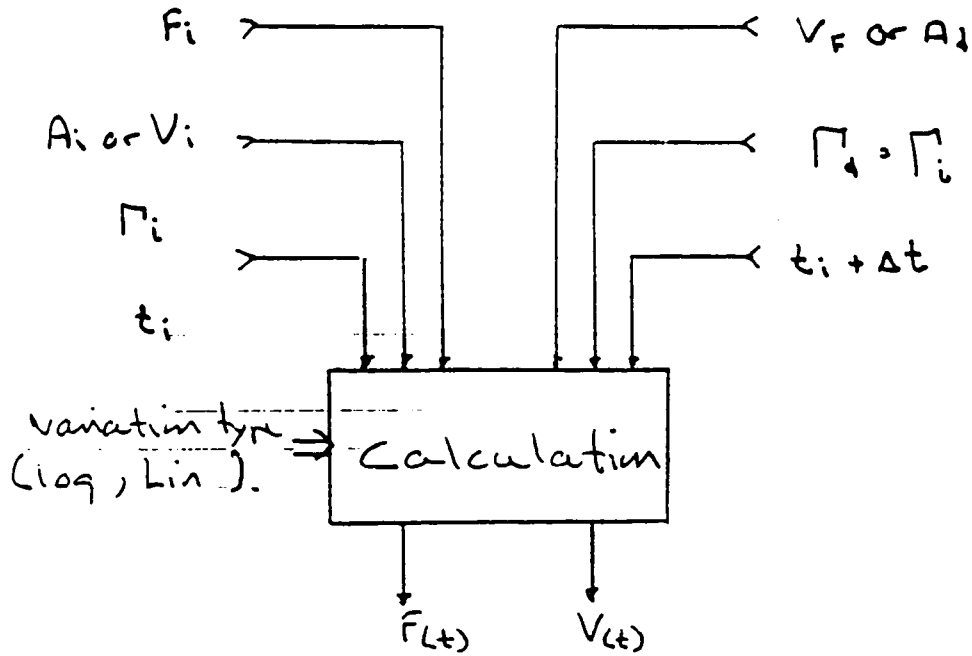
**DHS**

Direct Hardware Sand



Start values:  
(Init)

Final values



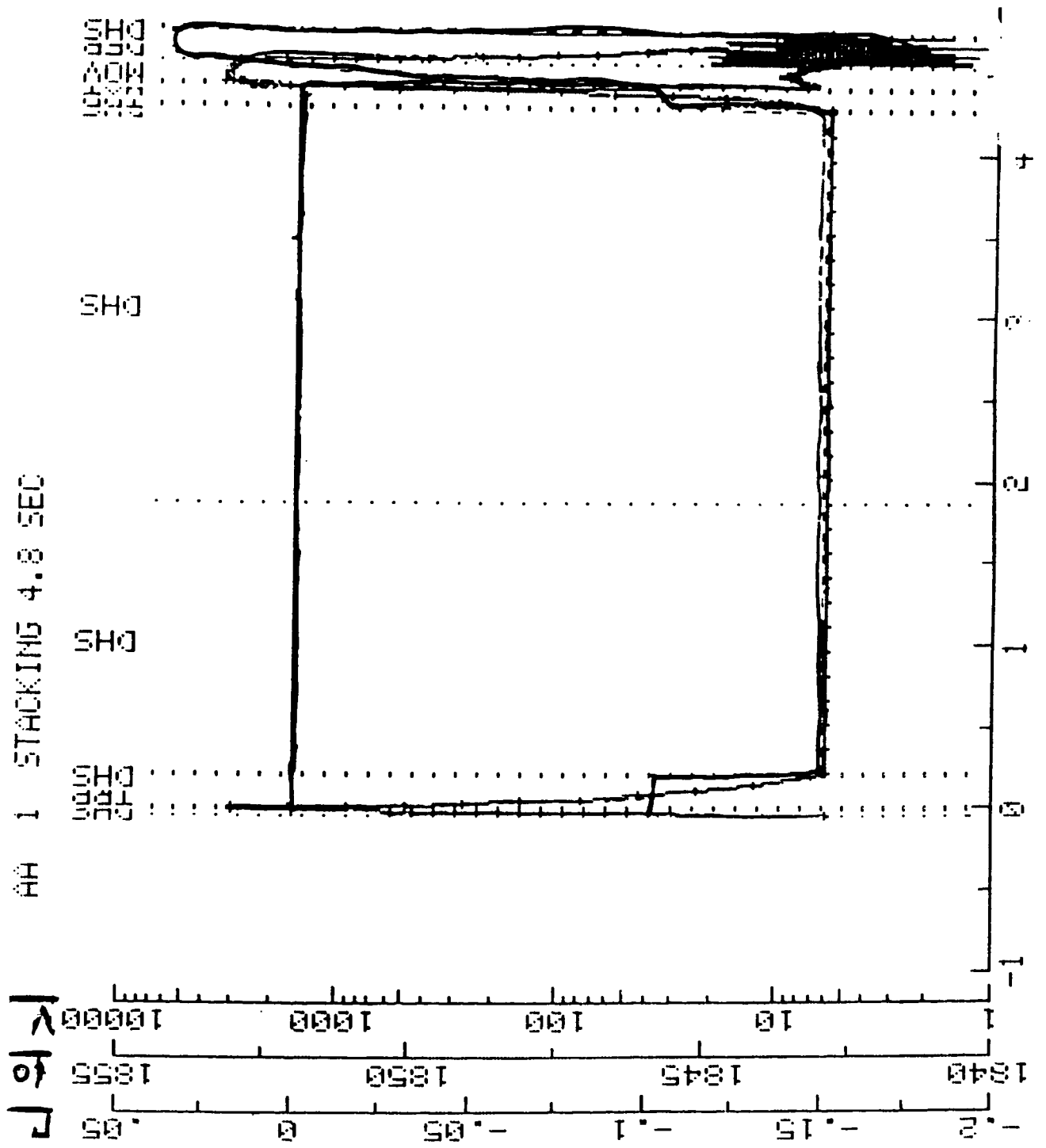
Main Purpose:  
Deposit of  $\bar{\pi}$  in stack and  
 $\pi = \text{const}$ ,  $A$  or  $V$  decreases

**DEP**  
Deposit

# AA 1 STACKING 4.8 SEC

t-tini f  
 PHASE LOCK ON 0 1845.86 SAVED USED  
 PHASE LOCK OFF .02 1845.86 91-12-03 92-02-04  
 SYNC ENABLED

VALUES AT END OF SEQUENCE											
SEQ	TYPE	Δt	t-tini	f	A	eV3	Γ	V	f <sub>s</sub>	HZ	VECT
1	INI	0	-.04	1845.86		.2316	0	6	10		1
2	DHS	.03	-.01	1845.86		7.3246	0	6000	331		2
3	DHS	.02	.01	1845.86		7.3246	0	6000	331		3
4	TRP	.2	.21	1845.86		.25	0	6	11		13
5	DHS	.009	.216	1843		.2332	0	6	10		14
6	DHS	1.66	1.878	1843		.2332	0	6	10		25
7	DHS	2.4	4.278	1843		.2332	0	6	10		41
8	DHS	.02	4.298	1845.86		.2316	0	6	10		42
9	TRP	.1	4.398	1845.86		4	0	1789	181		52
10	NAT	1	4.421	1846.4		4		3406	249		62
11	NOV	.141	4.563	1853.8		4		2969	217		69
12	DEF	.186	4.749	1854.2		.2		7	10		82
13	DHS	.009	4.758	1845.86		.2316	0	6	10		83



# Adiabatic Trapping of unbunched Beam

$$dA/A = dv_c dt/T_s$$

$$dv_c \approx \ll 1 \quad ; \quad T_s = \frac{1}{\dot{\phi}}$$

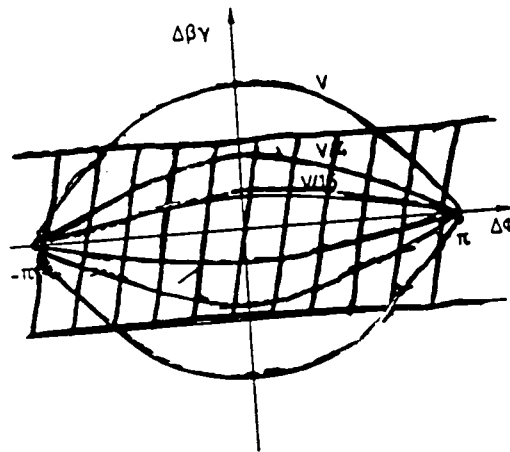


Fig. 24 Adiabatic trapping of coasting beam in growing stationary bucket

95% of the coasting beam.  
will be with 4 evs.

AA

SELECT FILE

ACTIVE FILE SHOWN **INVERTED**

1 STACKING 4.8 SEC

**2 SPS UNSTACKING FUNCTION**

3 PROTON STACKER, MODE 7, 1854.9, 6 SHOTS

4 BRING PBARS TO CENTRAL ORBIT

5 EMERGENCY RESTACK

6 PROTON STACKER MODE 2

7 XFER AND DEB. RF - P'S OR PBARS FROM AC

8 FAST PROTON STACKER - MODE 10.

9 TRANSFER RF, MODE 3 OR 4 (DO NOT CHANGE)

10 TRANSFER RF, MODE 3 OR 4 W. LONG. BLOW-UP

11 FAST ION UNSTACKING

12 STACKING 4.8 SEC, 2 eVs

13 PROTON STACKER, MODE 7, 1854.7, 2 SHOTS

14 PROTON STACKER, MODE 7, 1854.8, 4 SHOTS

LAST SAVED	LAST USED
91-12-03	91-12-19
<b>91-12-20</b>	<b>92-01-31</b>
91-03-26	91-03-27
90-11-09	90-11-09
91-06-01	91-06-01
89-11-14	90-02-26
90-06-22	91-12-12
90-04-10	90-09-26
91-03-16	92-01-29
90-09-11	90-09-26
90-05-02	90-09-26
90-05-09	91-05-10
90-04-11	90-09-26
90-04-11	91-03-27

AA = SEE UNSTACKING FUNCTION

PHASE LOCK ON                    t-tinj                    f                    SAVED                    USED  
    -1.873                    1854.64                    91-12-20                    91-12-20  
 PHASE LOCK OFF                  -1.4                    1845.73  
 SYNC DISABLED

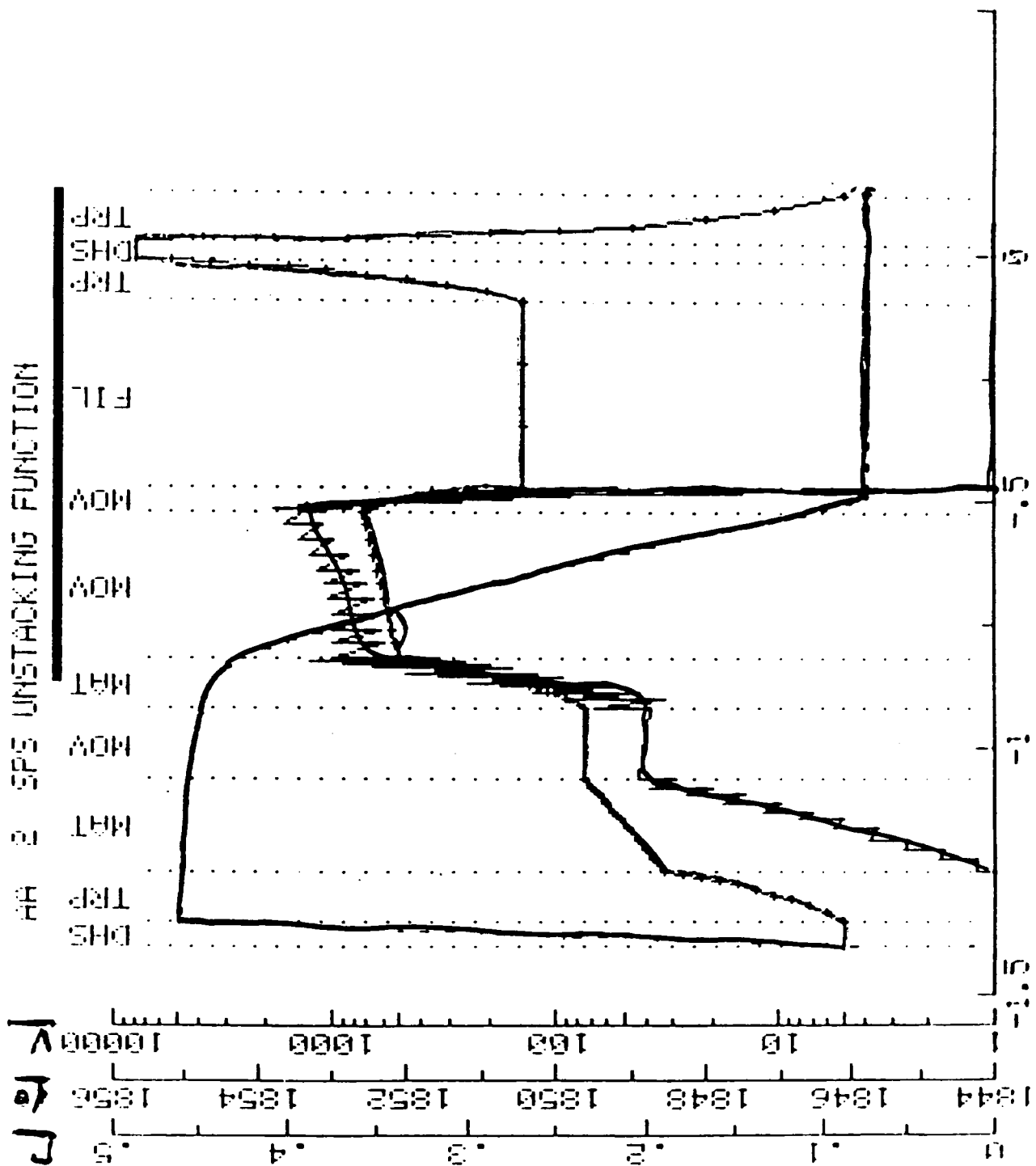
VALUES AT END OF SEQUENCE											
SEQ	TYPE	dt	t-tinj	f	A	ave	-	W	fs	HZ	VECT
1	INI	0	-1.4	1845.73	.2115	0		5	9		1
2	DHS	.05	-1.35	1855.04	.2362	0		5	9		2
3	TRP	.1	-1.25	1855.04	.6	0		32	31		12
4	MAT	1	-1.064	1854.95	.6		.2	74	32		22
5	MOV	.146	-.917	1854.74	.6		.2	75	33		23
6	MAT	1	-.820	1854.21	1.1		.36	513	36		33
7	MOV	.296	-.523	1846.5	1.1		.4	728	111		43
8	MOV	.045	-.478	1845.73	1.1		.005	140	50		53
9	FIL	.378	-.1	1845.73	0	0		140	50		55
10	TRP	.08	-.02	1845.73	8.4607	0		7996	333		66
11	DHS	.04	.32	1845.73	8.4625	0		8000	333		67
12	TRP	.1	.12	1845.73	.2116	0		5	9		77

AA

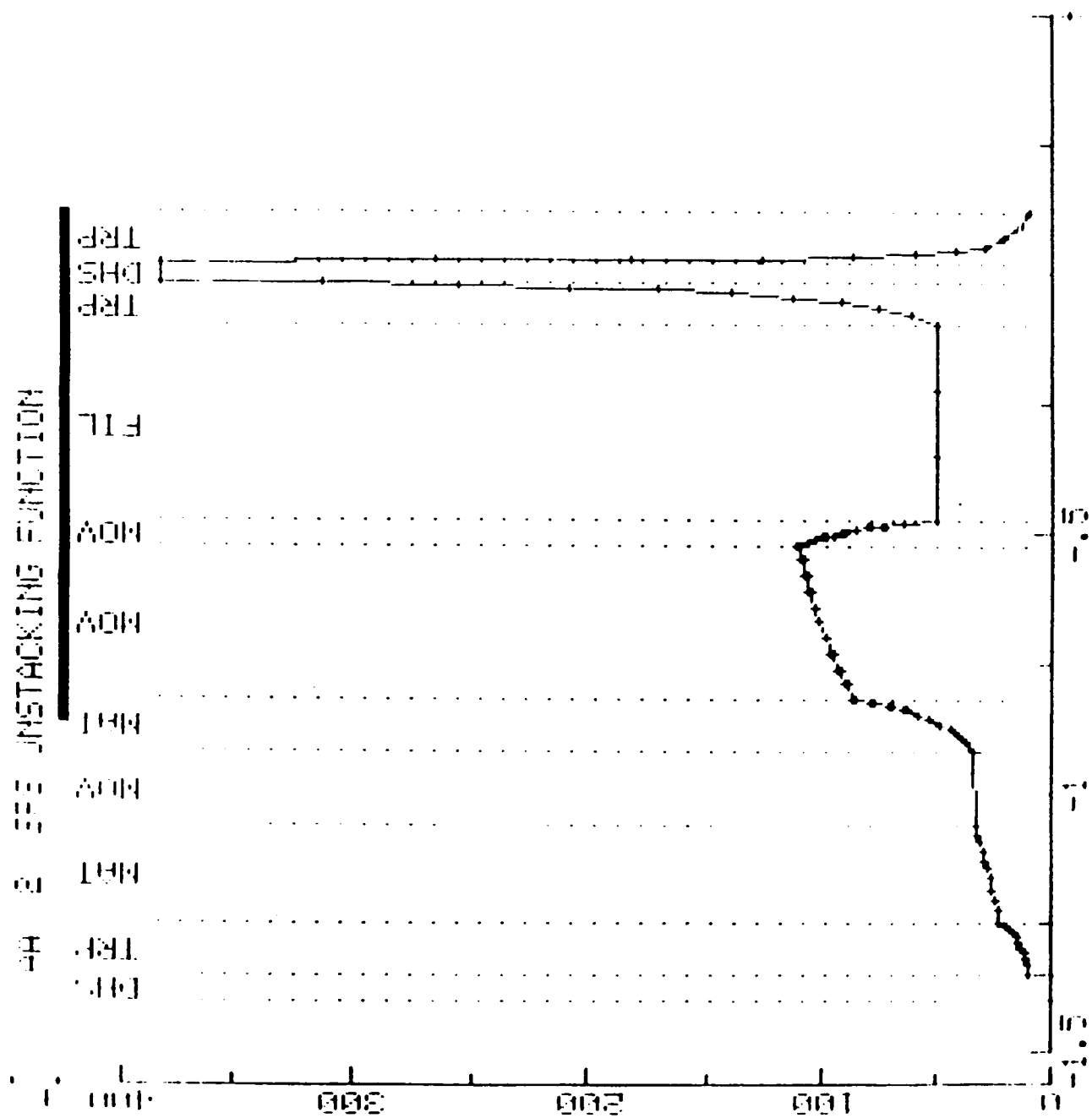
2 LEAR UNSTACKING FUNCTION

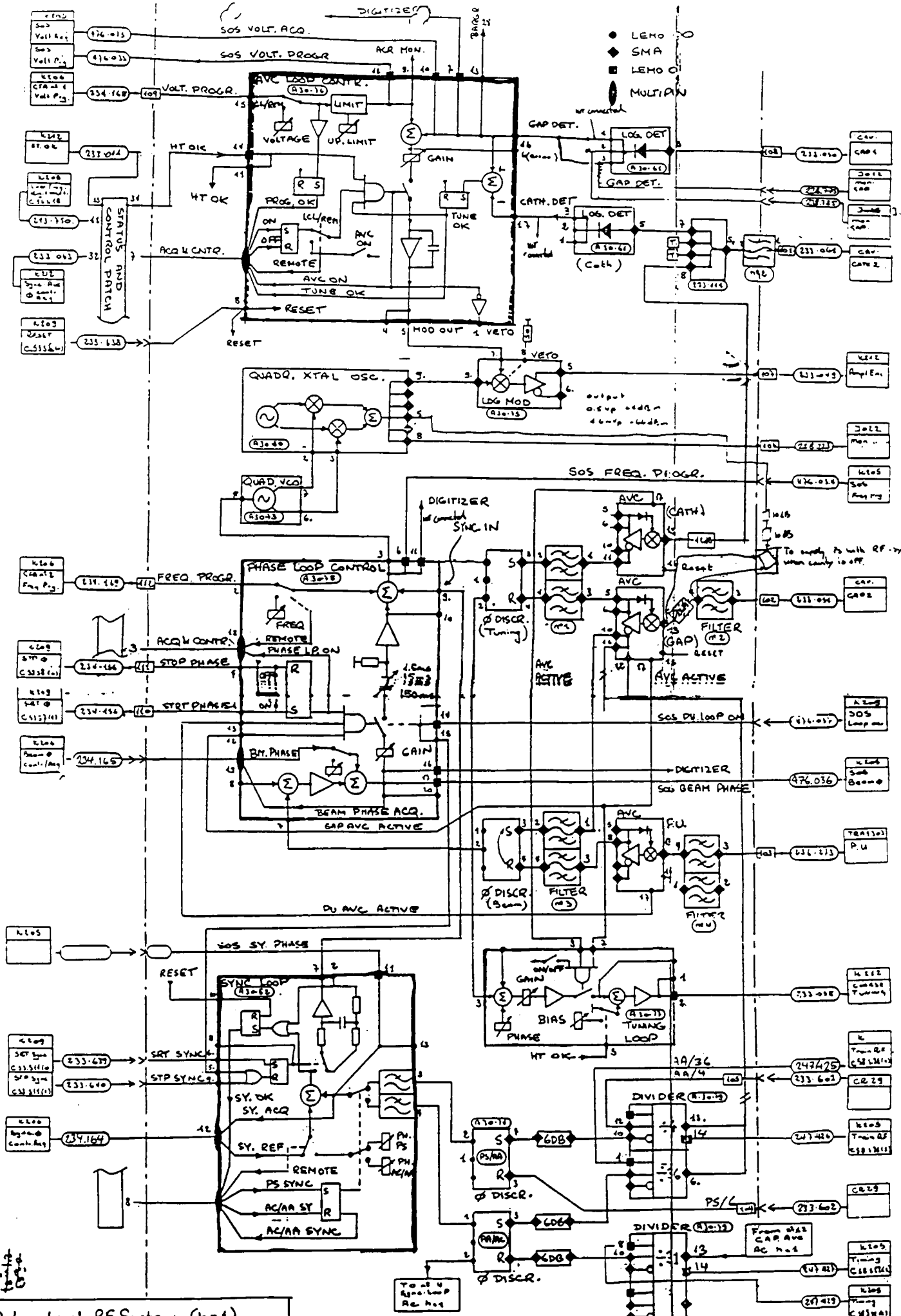
t-tinj f  
 PHASE LOCK ON -1.486 1852 SAVED USED  
 PHASE LOCK OFF -2.29 1845.9 89-12-22 89-12-22  
 SYNC DISABLED

VALUES AT END OF SEQUENCE									
SEQ	TYPE	Δt	t-tinj	f	A eV/s	Γ	W	f <sub>s</sub> Hz	VECT
1	INI	0	-2.29	1845.9	.2114	0	5	9	1
2	DHS	.05	-2.24	1855.06	.2364	0	5	8	2
3	TRP	.15	-2.09	1855.06	.5	0	22	18	12
4	MAT	.15	-1.899	1854.88	.1047	.745	53	23	19
5	DEP	.219	-1.679	1854	.1047	.745	56	24	33
6	MAT	1	-1.533	1852.75	.2	.745	222	50	43
7	MAT	1	-1.454	1851.43	1.1	.34	539	95	53
8	MOV	.231	-1.223	1846.5	1.1	.34	554	98	57
9	MOV	.054	-1.168	1845.9	1.1	.005	140	50	67
10	FIL	1.068	-.1	1845.9	0	0	140	50	74
11	TRP	.08	-.02	1845.9	8.463	0	8012	383	84
12	DHS	.04	.02	1845.9	8.4564	0	8000	383	85
13	TRP	.1	.12	1845.9	.2116	0	5	9	95









AA Low Level RF System (4-1)  
Block Diagram

## Synchronisation Between AA/AC

$$\frac{F_{AA}}{F_{AC}} = \frac{1846.1 \text{ kHz}}{1589.5 \text{ kHz}} = 1.16143$$

$$\frac{36}{31} = 1.16129 \quad \text{OR} \quad F_{AA} = \frac{36}{31} \times 1589.5 = 1845.9$$

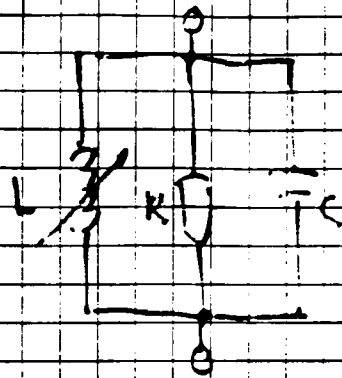
$\frac{F_{AC}}{31} = 51.2742 \text{ kHz} \Rightarrow$  The 2 RF systems  
are in phase every 19.5  $\mu$ s

## Synchronisation between AA/PS

$$\frac{F_{PS}}{6} = 461.456 \text{ kHz}$$

$$\frac{F_{AA}}{4} = \frac{1845.855}{4} = 461.466 \text{ kHz}$$

## Cavity



$$F_{RES} = \frac{1}{\sqrt{LC}}$$

$$Z_{RES} = R$$

$$Q = \frac{R_P}{X_{RES}} \Rightarrow R_P = X_{RES} \cdot Q$$

For AA H=1 And AC H=1 the cavity is tuned into resonance by biasing 2 Ferrites located inside the cavity, with  $\approx 50$  Amps and thereby change the total inductance.

To avoid longitudinal instabilities, and allow for maximum power transfer to the cavity, the cavity must be in resonance <sup>low shunt impedance</sup>

For tuning the H=6 cavity a BS Trim capacitor is used

BEAM PHASE, SYNC PHASE + FREQUENCY

1990-02-20-13:30:49

	BEAM PHASE OFFSET, deg	NOTE	SYNC PHASE OFFSET, deg	NOTE	FREQ. kHz	NOTE
H#8, CAY.#1			+60	1	9536.868	1
AG H#6, CAY.#2			-45	1		
H#1, FROM HA	31	1	-13.7	1,2	1582.472	1,4
H#1, FROM PS	9	1		3	1599.414	1,5
FROM AC	-35	1	30	1,2,3	1845.845	1,7
FROM PS-LOOP	-80	1	61.3	1,2	1845.76	1,6
FROM PS-DIR.	-95	1	-175.0	1,2	1845.76	1,6
PBAR EJECTN.					1845.897	1,2

NOTES 1. SET BY THIS PROGRAM

2. SET BY RELEVANT COHERENT OSCILLATION PROGRAM

3. NO SYNCHRONISATION PROVIDED

4. BUNCH ROTATION FREQUENCY DIVIDED BY 6

5. INFLUENCED BY ENERGY LOSS IN AIR ETC.

6. PS REVOLUTION FREQUENCY \*4

7. BUNCH ROTATION FREQUENCY \*6/31

8. FOR PROTONS; 28 DEGREES LESS FOR ANTI-PROTONS

PHASE OFFSETS ARE SENT TO HARDWARE BY THE MODE PROGRAM (OR

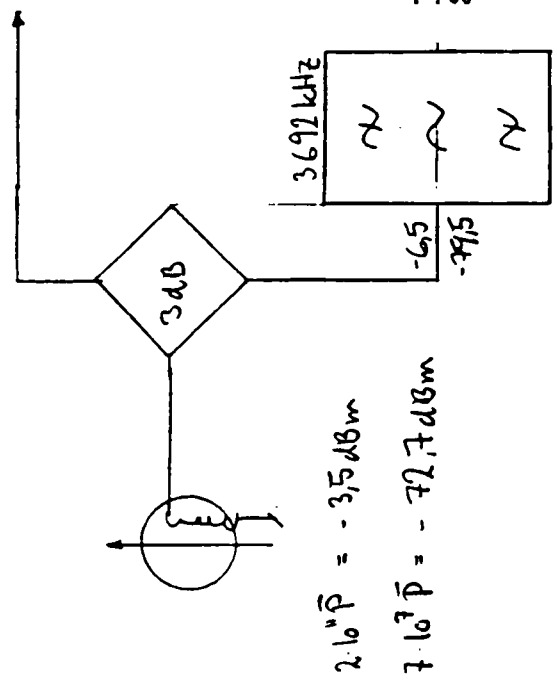
WHEN SET BY THIS PROGRAM, PROVIDED THE MODE IS CORRECT)

FREQUENCY VALUES ARE USED BY RF FUNCTION DEFINING PROGRAMS (H#1)

12/10/2015

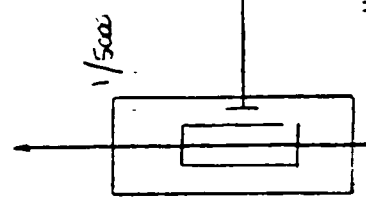
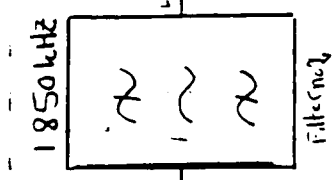
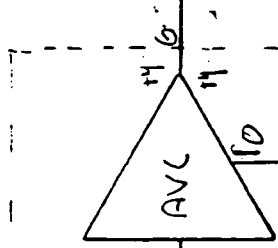
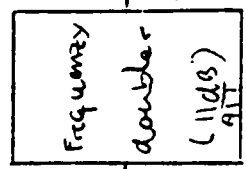
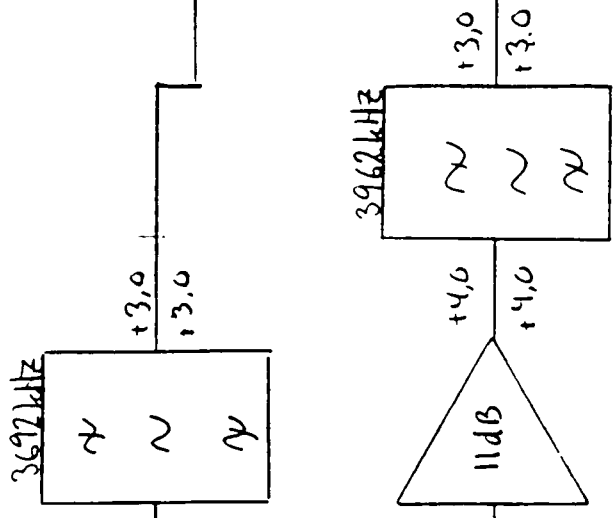
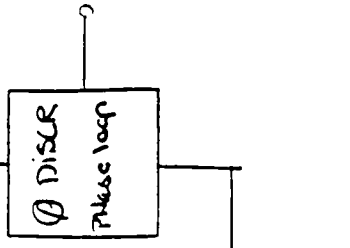
Existing system

1 Harmonic



$$2.10^6 \bar{P} = -35 \text{ dBm}$$

$$7.10^7 \bar{P} = -72.7 \text{ dBm}$$

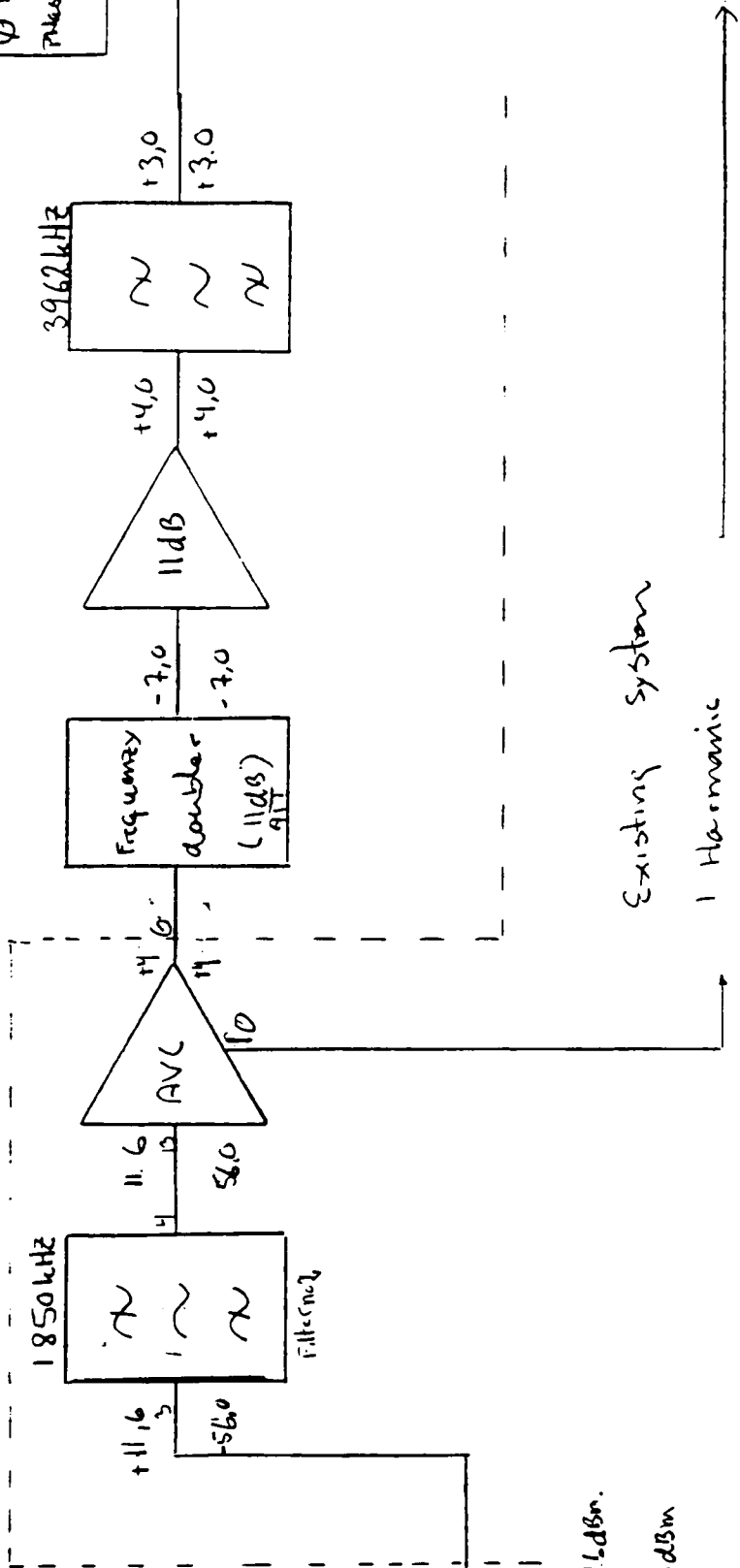


$$14 \text{ kVp} = 111.5 \text{ dBm}$$

$$\text{Sup} = -56 \text{ dBm}$$

Existing system

1 Harmonic



RF HARDWARE CONTROL (HF1, RA)

LEVEL 1  
 LEVEL 2  
 PHASE LOOP  
 AWC  
 SYNC  
 VOLT. PROGR.  
 TUNE  
 SYNC

AMPLIFIER EN1  
 COARSE TUNING  
 DOORS CAVITY  
 WATER COOLING FERRITES  
 VACUUM

FINAL  
 STAGE

WATER COOLING  
 AIR COOLING  
 FILAMENT 1  
 FILAMENT DELAY  
 FILAMENT 2  
 ANODE VOLTAGE  
 GRID 1 VOLTAGE  
 GRID 2 VOLTAGE

DRIVER

EL55 VOLTAGE  
 FILAMENTS  
 CATHODE VOLTAGE  
 GRID 2 VOLTAGE