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Thin n-in-p pixel sensors and the SLID-ICV vertical integration technology for the ATLAS upgrade at the HL-LHC

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Abstract

The R&D activity presented is focused on the development of new modules for the upgrade of the ATLAS pixel system at the High Luminosity LHC (HL-LHC). The performance after irradiation of n-in-p pixel sensors of different active thicknesses is studied, together with an investigation of a novel interconnection technique offered by the Fraunhofer Institute EMFT in Munich, the Solid-Liquid-InterDiffusion (SLID), which is an alternative to the standard solder bump-bonding. The pixel modules are based on thin n-in-p sensors, with an active thickness of 75 μm or 150 μm , produced at the MPI Semiconductor Laboratory (MPI HLL) and on 100 μm thick sensors with active edges, fabricated at VTT, Finland. Hit efficiencies are derived from beam test data for thin devices irradiated up to a fluence of $4 \cdot 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$. For the active edge devices, the charge collection properties of the edge pixels before irradiation is discussed in detail, with respect to the inner ones, using measurements with radioactive sources. Beyond the active edge sensors, an additional ingredient needed to design four side buttable modules is the possibility of moving the wire bonding area from the chip surface facing the sensor to the backside, avoiding the implementation of the cantilever extruding beyond the sensor area. The feasibility of this process is under investigation with the FE-I3 SLID modules, where Inter Chip Vias are etched, employing an EMFT technology, with a cross section of 3 $\mu\text{m} \times 10 \mu\text{m}$, at the positions of the original wire bonding pads.

Keywords:

Pixel detector, ATLAS, HL-LHC, n-in-p, active edges, vertical integration

1. Introduction

Different pixel modules concepts are being developed at the moment in view of the tracker upgrades of the LHC experiments for the Phase II of the High-Luminosity LHC (HL-LHC), in order to cope with the high level of occupancy and radiation damage expected. Detectors with minimal material budget, a larger active area fraction and higher granularity are required, in addition to radiation hardness up to a fluence of $2 \cdot 10^{16} \text{ n}_{\text{eq}}/\text{cm}^2$, as for example in the case of the inner layer of the ATLAS pixel system. In this context thin planar pixel sensors with reduced inactive edges are good candidates to instruments the new trackers, thanks to their reliability, cost-effectiveness and good charge collection properties at high fluences. An R&D towards the development of thin n-in-p pixel modules of different types, partly including sensors with active edges, is presented. They are designed to achieve, in conjunction with 3D vertical integration technologies, four side buttable modules using Inter Chip Vias (ICV), to move the wire bonding area to the chip backside from the present location on the front side facing the sensor. The n-in-p sensor technology is employed in all the productions described. In addition to an easier fabrication, requiring only a single-sided process in comparison to the double-sided n-in-n sensors, it has also been demonstrated that

it achieves the same performance before and after irradiation as the standard n-in-n technology [1, 2, 3]. The homogeneous backside of the n-in-p sensors is also less problematic for the attachment of a handle wafer that is an usual step in the manufacturing of very thin pixel sensors.

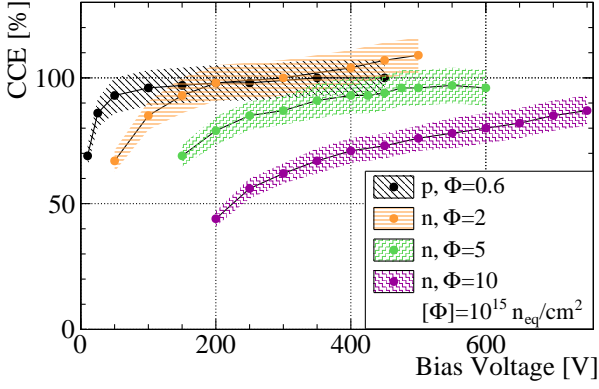
2. Thin pixel sensor productions

2.1. MPI HLL thin pixel productions

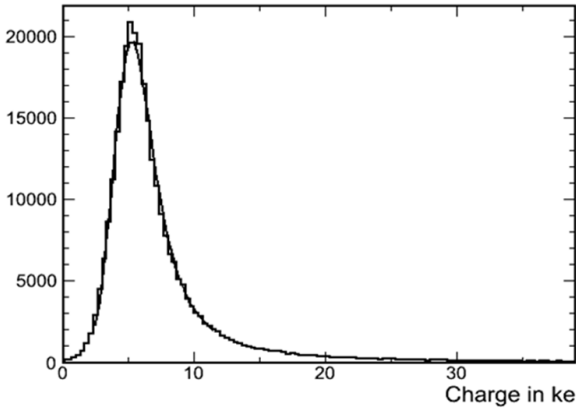
To investigate the properties of thin sensors and to explore their potential for high energy physics applications two successive pixel productions were carried out at MPI HLL, employing a thinning procedure developed at this facility. This technology makes use of a handle wafer to offer mechanical support during the thinning phase of the active wafer and its subsequent processing. The handle wafer can then be removed by using deep anisotropic wet etching with the oxide layer connecting the two wafers acting as etch stopper [4]. The first production contains ATLAS FE-I3 compatible n-in-p sensors with an active thickness of 75 μm and it has been interconnected to the read-out chips via the Solid Liquid Interdiffusion technology (SLID) [5], developed by the Fraunhofer Institute EMFT. This pixel production was extensively described in [6, 7, 8] and has been now further tested up to a fluence of $\Phi = 10^{16} \text{ n}_{\text{eq}}/\text{cm}^2$, by measurements of charge collection efficiency with a ^{90}Sr radioactive source. These were performed, as all the other charge

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collection measurements reported in the following, with the ATLAS USBPix system [9] inside a climate chamber keeping the environmental temperature at 20 °C for not irradiated samples and at -50 °C for irradiated ones.



(a)



(b)

Figure 1: (a) Charge collection efficiency obtained with a ^{90}Sr source for the SLID modules, produced with $75\ \mu\text{m}$ thick sensors. The collected charge is normalized to the values obtained for the same module before irradiation. The colored bands represent the systematic uncertainty of 5% estimated for the normalized charge. (b) Landau distribution of the collected charge for the sample irradiated at $\Phi = 5 \cdot 10^{15}\ \text{n}_{\text{eq}}/\text{cm}^2$, with a bias voltage of 600V.

Fig.1(a) shows the charge collection efficiency (CCE), normalized to the charge collected before irradiation, as a function of the bias voltage, for different received fluences. Also at the maximum fluence of $10^{16}\ \text{n}_{\text{eq}}/\text{cm}^2$, increasing the bias voltage up to 750V, a CCE as high as 90% can be obtained. The Landau distribution of the collected charge at $\Phi = 5 \cdot 10^{15}\ \text{n}_{\text{eq}}/\text{cm}^2$ and a bias voltage of 600V is shown in Fig.1(b). The absolute value of the MPV is of the same size as the pre-irradiation one, that lies for the different SLID modules around (4.5-5) ke, in agreement with the expectation for $75\ \mu\text{m}$ detectors [10]. Even if the charge collection properties of these very thin sensors deteriorate much less than for thick sensors after irradiation, the signal over threshold ratio for the FE-I3 chip is not high enough to operate them with full hit efficiency, given the minimum threshold range around 2500 e achievable with the present ATLAS

read-out chip. The ATLAS FE-I4 chip [11], developed for the IBL project, offers instead the possibility to work at thresholds as low as 1000 e, paving the way to the use thin pixel sensors in the upgraded trackers for Phase II at HL-LHC. The irradiated SLID modules did not present any sign of deterioration of the interconnection, as for example an increase in the number of disconnected channels or of the threshold noise. These findings, even if based on a small statistics of samples, indicate that the SLID interconnection is radiation resistant up to $\Phi = 10^{16}\ \text{n}_{\text{eq}}/\text{cm}^2$.

FE-I4 compatible n-in-p sensors, with an active thickness of $150\ \mu\text{m}$ were obtained with the second production at MPI HLL (indicated as SOI2 in the following) and they were interconnected with solder bump-bonding at the Fraunhofer Institute IZM, Berlin. The bulk material is the same as for the SLID sensors, FZ p-type, with a resistivity of $2\ \text{K}\Omega\text{cm}$. The sensors are characterized by a guard ring scheme containing twelve guard rings resulting in a distance between the last pixel implantation and the sensor edge $d_{\text{edge}}=450\ \mu\text{m}$ (Fig.2).

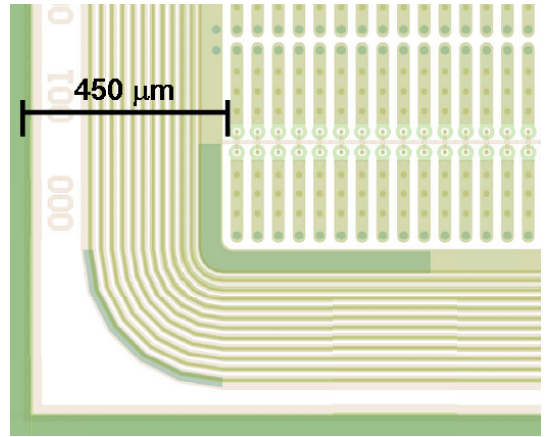


Figure 2: Design of the edge region of the SOI2 pixel sensors, with twelve guard rings and a total distance of $d_{\text{edge}}=450\ \mu\text{m}$ from the last pixel to the dicing line.

For the FE-I4A chip no reliable ToT to charge calibration is available [12], so the charge collection properties of the SOI2 assemblies are mainly based on ToT values, in units of the 25 ns bunch crossing clock, which around the tuning point are linearly proportional to the charge. Figure 3 shows the evolution of the most probable value (MPV) of the measured ToT with the measured bias voltage for a not irradiated SOI2 assembly, obtained during scans with a ^{90}Sr source. Given the tuning of 10 ToT for 15 ke, the saturation value of the charge corresponds to $(12 \pm 2.4)\ \text{ke}$, in agreement with the expectation for a $150\ \mu\text{m}$ thick sensor [10], where a 20% systematic error has been assigned for the FE-I4A calibration uncertainty. The noise of these FE-I4 assemblies before irradiation is around 120 e, even when operating the chips at thresholds down to 800-1000 e (Fig. 4a). The resulting noise occupancy is very low, as shown as a function of the threshold in Fig. 4b. A subsample of the SOI2 modules has undergone an irradiation program, at a fluence of $2 \cdot 10^{15}\ \text{n}_{\text{eq}}/\text{cm}^2$ with 23 MeV protons at the Karlsruhe Institute of Technology (KIT) and at a fluence of $4 \cdot 10^{15}\ \text{n}_{\text{eq}}/\text{cm}^2$ with

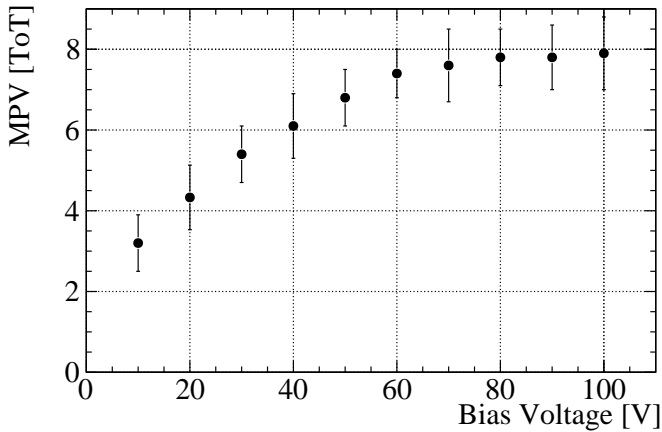
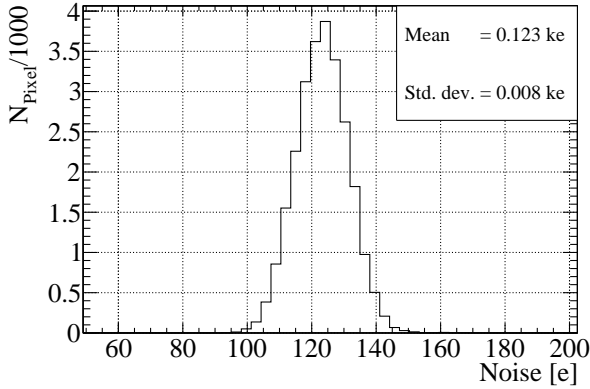
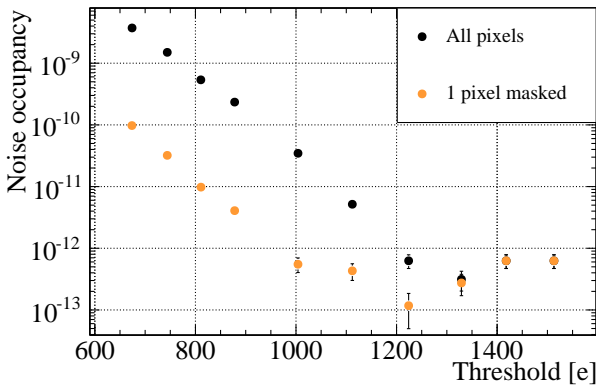


Figure 3: MPV of collected charge, expressed in ToT units, for a not irradiated SOI2 module, obtained from ^{90}Sr source measurements, as a function of the bias voltage.



(a)



(b)

Figure 4: (a) Threshold noise distribution for a not-irradiated SOI2 module tuned to a threshold of 800 e and a charge calibration of 10 ToT for 15 ke. (b) Noise occupancy per pixel as a function of the threshold.

800 MeV protons at the Los Alamos Neutrons Science Center (LANSC). The collected charge in scans with a ^{90}Sr source for the SOI2 devices after irradiation is compared in Fig.5 to

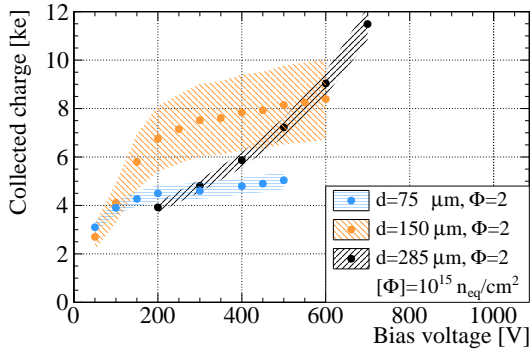
the values obtained for the 75 μm thick sensors and for n-in-p sensors of standard thickness, 285 μm , used as reference. These devices were produced at CiS and interconnected to FE-I3 chips via bump-bonding. Details about their characterization before and after irradiations are reported in [1, 3]. The comparison shows that, at least up to a fluence of $(4 - 5) \cdot 10^{15}$, where data for SOI2 are available, a higher charge may be obtained with these devices of intermediate thickness. Anyhow with increasing fluence the collected charge for different thicknesses tend to equalize, due to the effect of charge trapping, and at $\Phi = 10^{16} \text{n}_{\text{eq}}/\text{cm}^2$ (Fig.5(c)) the 75 μm and 285 μm shows a very comparable performance up to 600V.

The SOI2 modules were further studied in beam tests with 120 GeV pions at CERN-SPS and 5-6 GeV electrons at DESY, using the EUDET telescope for track reconstruction [13]. A summary of the hit efficiency as a function of the applied bias voltages, up to a fluence of $4 \cdot 10^{15} \text{n}_{\text{eq}}/\text{cm}^2$ is given in Fig. 6.

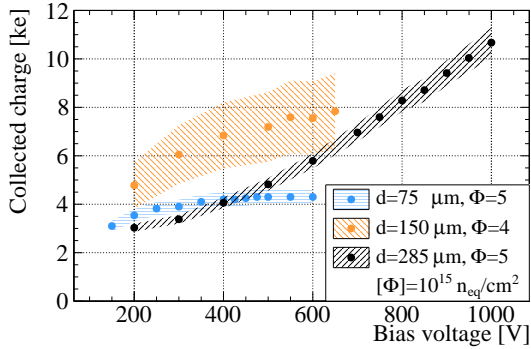
Tracks extrapolated from the telescope are considered as belonging to a specific hit if they are closer than one pixel cell pitch in the long pixel direction and three pixel cell pitches in the short pixel cell direction. These tracks are defined as matched. The hit efficiency is determined as the fraction of matched tracks to a hit in the device and it can be displayed as function of the position in the pixel cell, as predicted by the telescope. Such an efficiency map is shown in Fig.7, together with an image of the pixel cell geometry for the SOI2 modules. The overall efficiencies are $(96.5 \pm 0.3)\%$ at 400V and $(96.9 \pm 0.3)\%$ at 500V, where the errors are due to the systematic uncertainty on the track selection. Lower hit efficiencies are found in the corners and in the region corresponding to the bias rail and to the bias dot, when the beam is perpendicular with respect to the devices, as in this case. For inclined tracks part of the efficiency loss in these areas is recovered because the impinging particles traverse also the central region of the pixel cell, where the electric field is higher. The hit efficiencies in central region of the pixel cell, as indicated in Fig.7, are $(98.7 \pm 0.3)\%$ at 400V and $(98.8 \pm 0.3)\%$ at 500V

2.2. VTT production of active edge pixel sensors

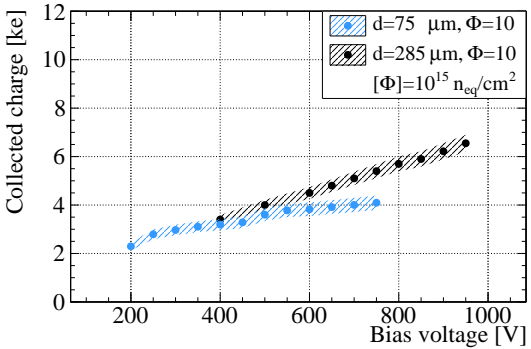
Active edge n-in-p pixel sensors have been fabricated at VTT within a multi project wafer production [14]. The design of the active area of the FE-I3 and FE-I4 devices and the implementation of the p-spray isolation are derived from the MPI HLL productions. The bulk material of the devices discussed in this paper is p-type FZ, with a resistivity of $\rho = 10 \text{ k}\Omega \text{ cm}$. The sensors were thinned to a thickness of 100 μm . The fabrication of thin sensors at VTT exploits, as for the MPI HLL productions, the use of an handle wafer as mechanical support during the grinding phase. The handle wafer is further needed during the etching of the trenches at the sensor borders, a step performed after the electrodes implantation and prior to the final oxidation, implantation activation and Aluminum processing [15]. The trenches are activated with a four-quadrant ion implantation of boron ions, that extends the back-side junction to the vertical edges. The interconnection of the sensors to the FE-I3 and FE-I4 chips has been performed at VTT, with solder bump-bonding. The results shown in the following are relative to three



(a)



(b)



(c)

Figure 5: Comparison of the charge collected with a ^{90}Sr source for irradiated pixel detectors at different thickness and received fluences: (a) results relative to $\Phi = 2 \cdot 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$, (b) $\Phi = (4-5) \cdot 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$ and (c) $\Phi = 10^{16} \text{ n}_{\text{eq}}/\text{cm}^2$. The colored bands are representative of the systematic uncertainties associated to the measurements: 7.3%, 5.2 %, 20% for the SLID sensors, 285 μm thick sensors and the SOI2 sensors respectively. The larger systematic error estimated for the SOI2 modules is due to the lack of a reliable charge calibration for the FE-I4A chips.

different implementations of the edge regions. The first one, meant to serve as a reference, incorporates eleven guard rings, with the same structure as in the SOI2 production, as well as a bias ring, and it has $d_{\text{edge}}=460 \mu\text{m}$. The second design is characterized by only a floating guard ring and a bias ring, connected to the pixel punch-through structures, allowing for the testability before interconnection and the grounding of each individual pixel, even in the case of missing bumps, after interconnection.

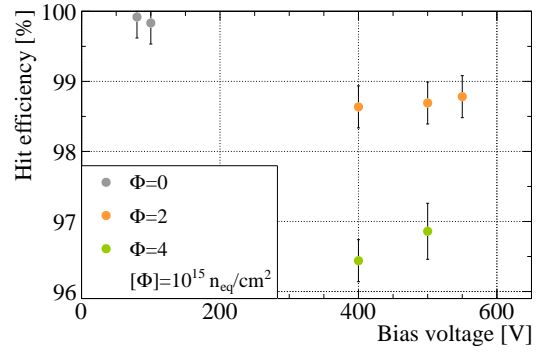
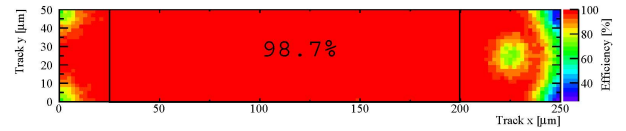


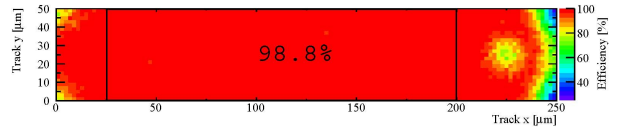
Figure 6: Hit efficiency of the SOI2 modules, as a function of the applied bias voltage, for different fluences, as obtained in beam tests with the EUDET telescope with 120 GeV pions at CERN-SPS and 5-6 GeV electrons at DESY.



(a)



(b)



(c)

Figure 7: (a) Design of the pixel cell for the SOI2 sensors, with a pitch of $50 \mu\text{m} \times 250 \mu\text{m}$. (b) Hit efficiency map for a SOI2 module irradiated at $\Phi = 4 \cdot 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$ and biased at 400V and 500 V(c). The numbers indicated in the square are the hit efficiency for the central region, excluding the corners and the bias dot.

In this case $d_{\text{edge}}=125 \mu\text{m}$ (Fig.8(a)). The most aggressive design with active edges, implemented only for FE-I3 sensors, foresees one floating guard ring and $d_{\text{edge}}=50 \mu\text{m}$ (Fig.8(b)). Since a bias ring structure is not present, also the bias rails and the punch-through structures have been omitted.

Fig.9 shows the IV curves of not irradiated FE-I3 and FE-I4 modules, with breakdown voltages of the order of (110-120)V and leakage currents well below $10 \text{ nA}/\text{cm}^2$ over all the voltage range.

Measurements of charge collection have been performed with these modules after tuning of the FE-I3 samples to a threshold of 1800 e and of the FE-I4 sample to a threshold of 1000 e. Typical values of the threshold noise are measured to be around 190 e for the FE-I3 assemblies and 180 e for the FE-I4 assemblies. The MPV of the collected charge with a ^{90}Sr source, as shown in Fig.10, is normalized to the MPV at 50V, to equilibrate the different absolute scales, due to the offset of the unknown calibration capacitance. A residual systematic un-

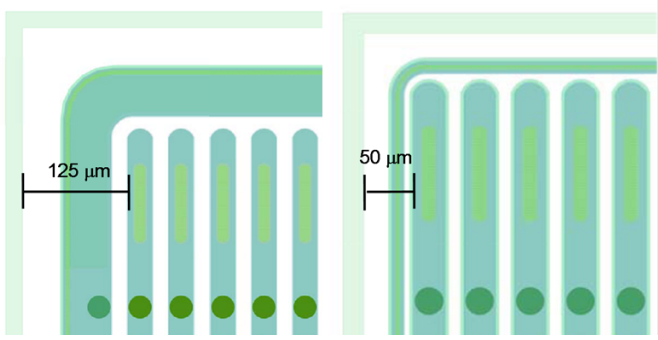


Figure 8: Edge design for VTT sensors with (a) bias ring and guard ring with $d_{edge}=125\ \mu\text{m}$, implemented in FE-I3 and FE-I4 modules; (b) only a guard ring with $d_{edge}=50\ \mu\text{m}$, implemented in FE-I3 modules.

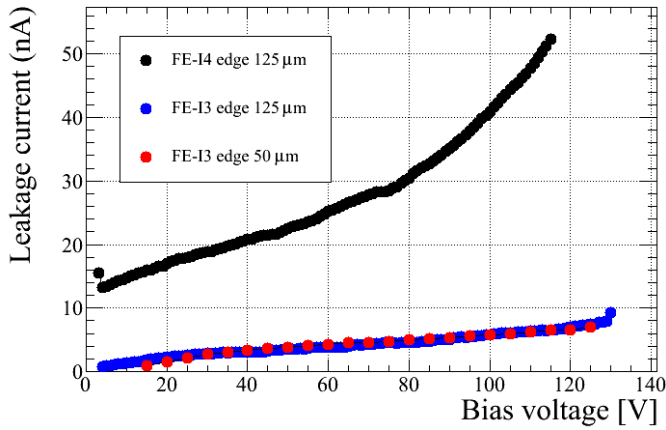


Figure 9: IV curves for not irradiated FE-I3 and FE-I4 VTT modules, with breakdown voltages in the range 110-120V.

certainty on the charge ratio is estimated to be 5%. The saturation of the charge collection is visible around 10V, in agreement with the value expected from the bulk resistivity, but also at bias voltages as low as 5V, more of 90% of the charge is still collected. A more detailed analysis of the edge pixel efficiency has been performed, comparing the Landau distributions of these cells to the ones obtained with the full device. The results are shown in Fig.11, where only very small deviations are found between the two sets of curves, both for the FE-I3 devices with $d_{edge}=50\ \mu\text{m}$ and the FE-I4 devices with $d_{edge}=125\ \mu\text{m}$. The different binning in the two figures is due to the different ToT resolution for the two generations of chips, 8 bits for the FE-I3 and 4 bits for the FE-I4. The performance of the edge pixels in terms of hit efficiency will be further investigated in the near future with beam tests of these devices.

3. Vertical Integration Technology

A second step in the R&D activity with the modules interconnected with SLID is the etching of Inter Chip Vias in the FE-I3 chips with the Via Last approach, performed at the Fraun-

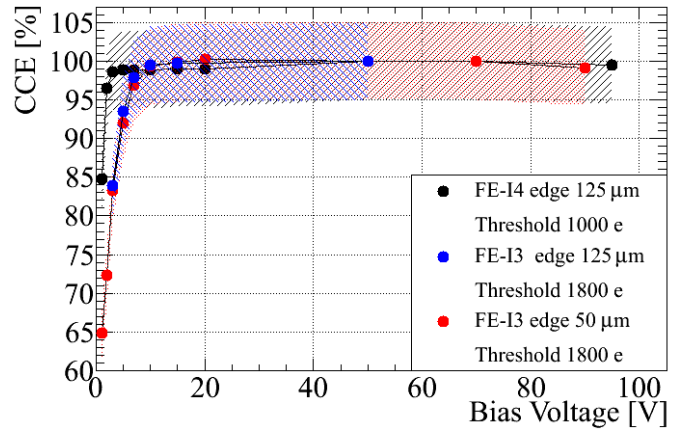
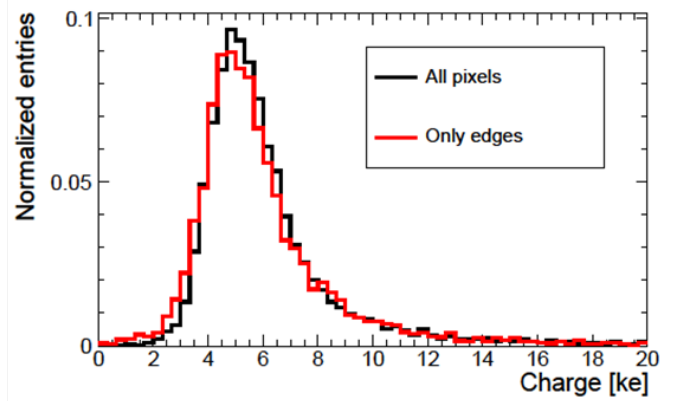
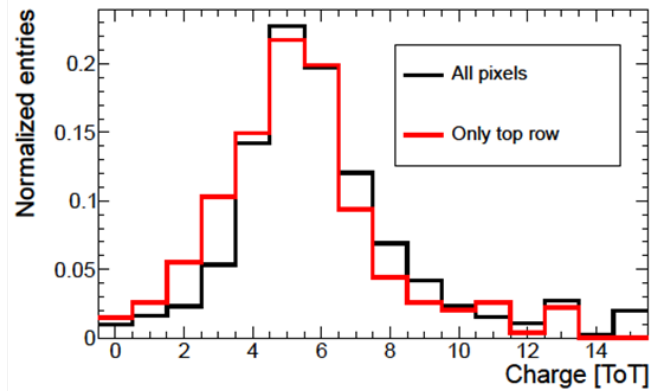


Figure 10: Collected charge of VTT FE-I3 and FE-I4 modules before irradiation determined with a ^{90}Sr source, normalized to the MPV at 50V. A systematic uncertainty of 5% is estimated for the normalized values.



(a)



(b)

Figure 11: Comparison of the Landau distributions of all (black) and edge pixels (red) for the FE-I3 VTT module with $d_{edge}=50\ \mu\text{m}$ (a) and for the VTT FE-I4 module with $d_{edge}=125\ \mu\text{m}$.

hofer Institute EMFT, to allow for the extraction of signal and services across the chip to the backside. In a 3D compliant de-

sign of the pixel electronics, Inter Chip Vias could eventually avoid the need for the cantilever area where the wire bonding pads are presently located. The via cross-section has been optimized with etching trials in a FE-I3 wafer to be $3 \times 10 \mu\text{m}^2$, and the initial depth to $60 \mu\text{m}$. After the isolation of the vias with Chemical Vapour Deposition (CVD) of silicon dioxide and the metalization with tungsten filling, the chip wafer front side is passivated and bonded to a handle wafer. The FE-I3 wafer has then to be thinned to $50 \mu\text{m}$ to expose vias and finally new wire bonding pads are applied on the backside, connected to the ICVs with a redistribution layer on the backside. The via preparation has started on the FE-I3 wafer with the etching of the dielectrics below the aluminum layer of the original wire bonding pads (Fig.12).

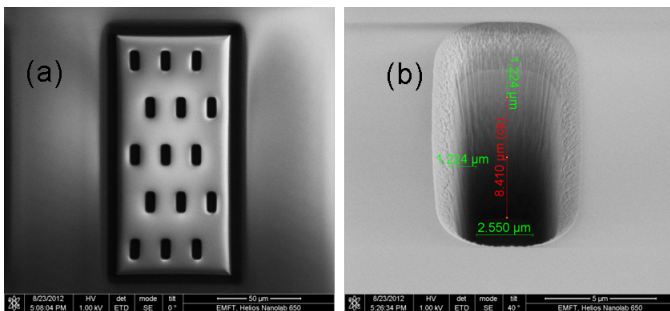


Figure 12: EMFT courtesy (a) View of the wire bonding pad of the FE-I3 chip with the ICVs. Several of them are placed on the same pad for redundancy. A trench surrounds the ICVs to provide further isolation from the silicon bulk. (b) Zoom in of the ICV after the etching of the dielectric layers beneath the top aluminum layer. In red the depth of the etching is indicated, while in green the lateral dimensions are given. $2.550 \mu\text{m}$ is the width of the ICV at the bottom of the stack of the first dielectric layers.

4. Conclusions

The characterization of pixel modules composed with thin n-in-p sensors, with a thickness range from $75 \mu\text{m}$ to $150 \mu\text{m}$, interconnected to the ATLAS FE-I3 and FE-I4 read-out chips has been presented. The charge collected after irradiation is compared for different fluences to that obtained with n-in-p pixel assemblies of standard thickness. In the range of fluence from 2 to $4 \cdot 10^{15} \text{n}_{\text{eq}}/\text{cm}^2$ higher charge may be obtained with the SOI2 devices of $150 \mu\text{m}$ thickness. Anyhow, with increasing fluence, the collected charge for different thicknesses tend to equalize, due to the effect of charge trapping, and at $\Phi = 10^{16} \text{n}_{\text{eq}}/\text{cm}^2$ the $75 \mu\text{m}$ and $285 \mu\text{m}$ thick sensors show a very comparable performance up to a bias voltage of 600V . Active edge pixel sensors were fabricated at VTT and they have been studied before irradiation with a ^{90}Sr source to compare the behaviour of the edge and the internal pixels. Negligible differences have been observed in terms of charge collection but further analysis with beam tests are needed to determine the tracking performance of these devices and the effective inactive edge that can be reached with them. Finally, to obtain four side buttable modules, vertical integration technologies are investigated. In particular Inter Chip Vias are being prepared at the moment on

FE-I3 chips, to allow for the extraction of signal and services across the chip to the backside. In a 3D compliant chip design Inter Chip Vias could eventually avoid the need for the cantilever area, where the wire bonding pads are presently located, and this would lead, in conjunction with active edge sensors, to pixel modules with no or very reduced inactive edges.

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