## Introduction to Geometry

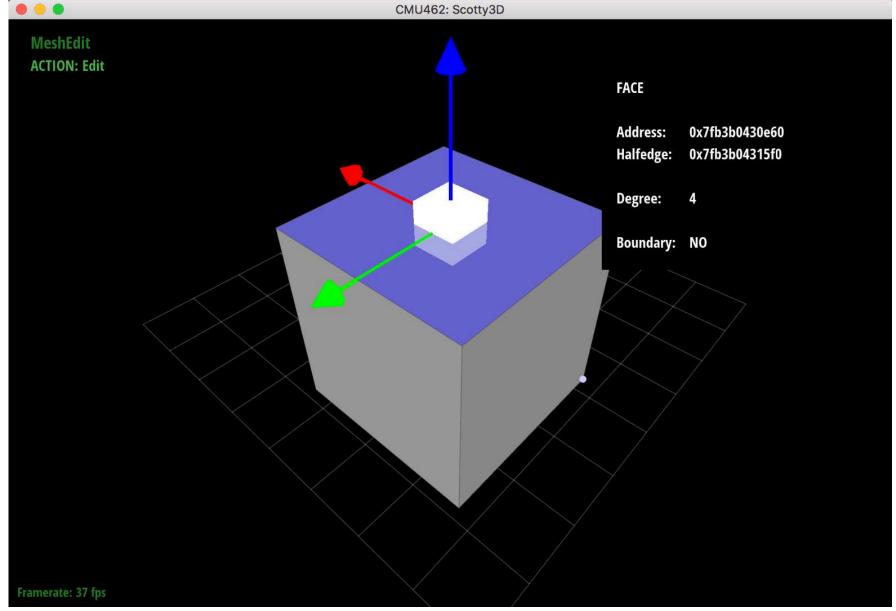
**Computer Graphics CMU 15-462/15-662** 

#### Assignment 2

Start building up "Scotty3D"; first part is 3D modeling



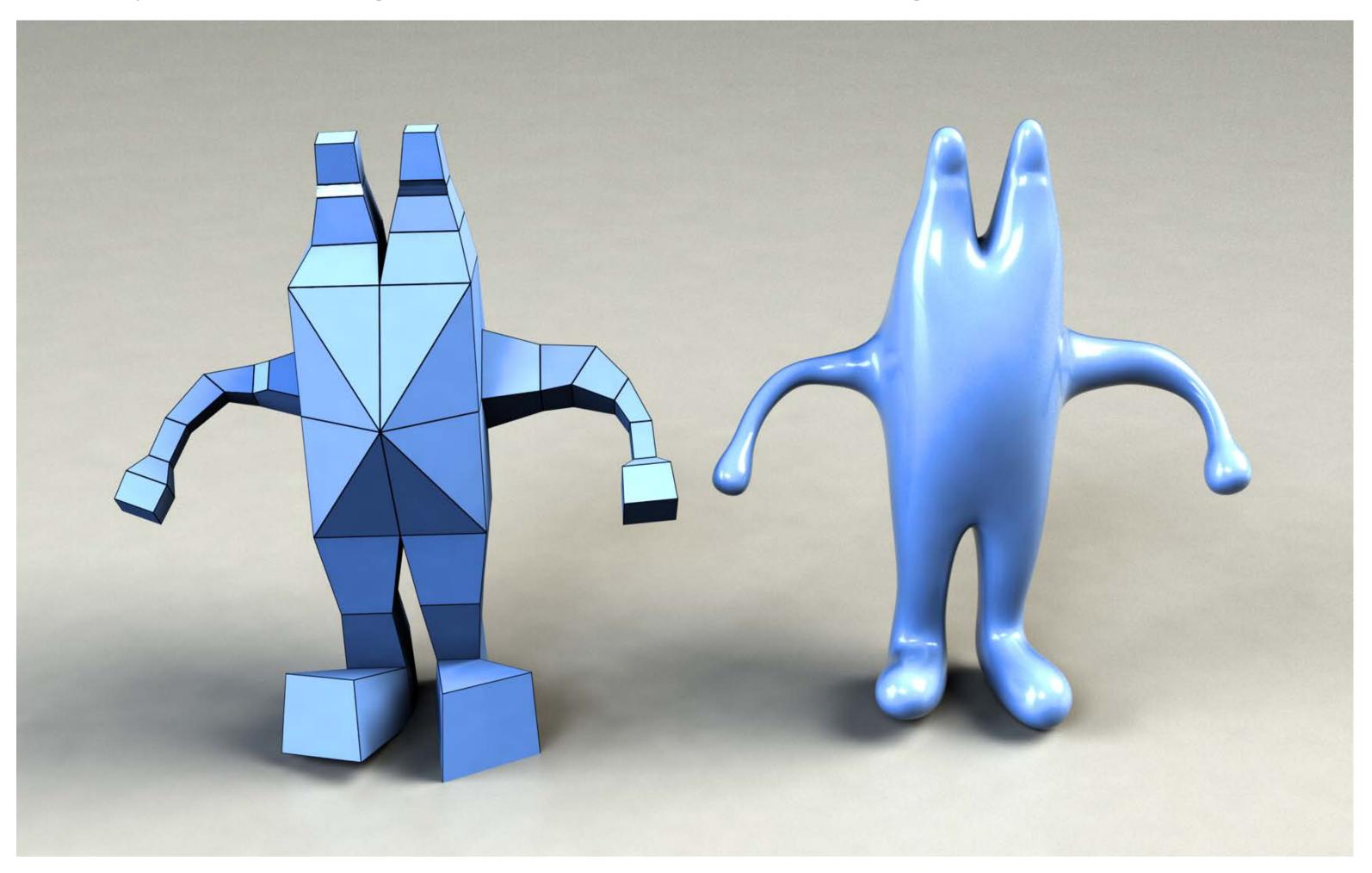




(Start from the cube you described in Lecture 1!)

#### 3D Modeling Competition

■ Don't just make great software... make great art! :-)



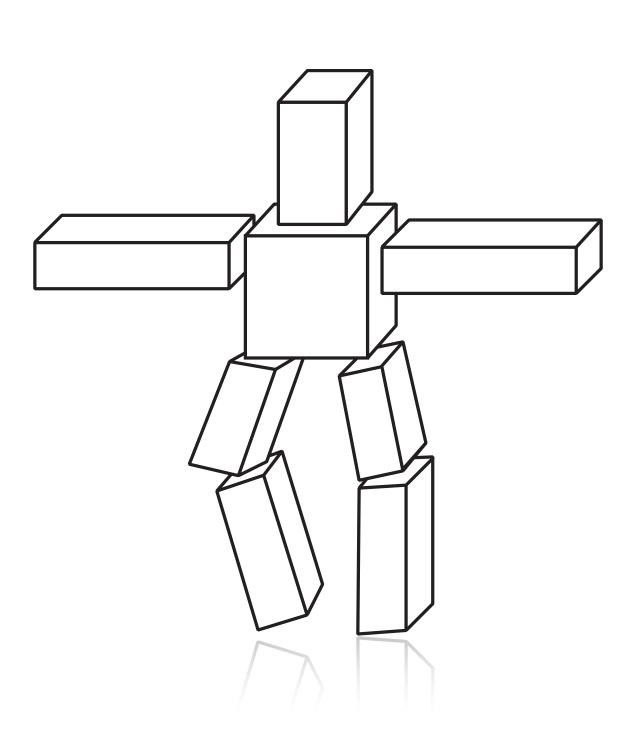
(This mesh was created in Scotty3D in about 5 minutes... you can do much better!)

#### Increasing the complexity of our models

**Transformations** 

Geometry

Materials, lighting, ...







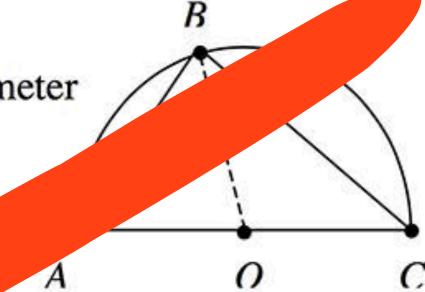
#### Q: What is geometry?

#### A: Geometry is the study of two-column

proofs.

Th. 9.5. Let  $\triangle ABC$  be inscribed in a semicircle with diameter

Then  $\angle ABC$  angle.



Proof:

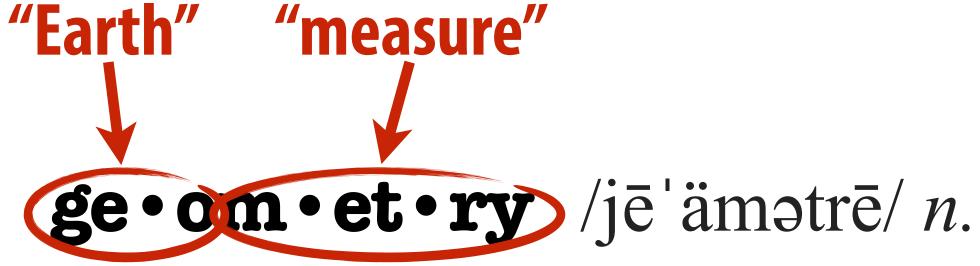
#### Statement

- 1. Draw radius OB. Then  $OB = OC = O_{b}$
- 2.  $m\angle OBC = m\angle BCA$  $m\angle OBA = m\angle BAC$
- 3.  $m\angle ABC = m\angle OBA +$
- 4.  $m\angle ABC + m\angle BC$   $\angle BAC = 180$
- 5.  $m\angle ABC + m\angle OBA = 180$
- 6. 2 mL/ 180
- 7. m = 90
- & ZABC is a right angle

- Given
  - sceles Triangle Theorem
- 3. Ang. Ostulate
- 4. The sum colles of a triangle is 180
- 5. Substitution (Image)
- 6. Substitution (line 3)
- 7. Division Property of Equality
- 8. Definition of Right Angle

#### Ceci n'est pas géométrie.

#### What is geometry?



- 1. The study of shapes, sizes, patterns, and positions.
- 2. The study of spaces where some quantity (lengths, angles, etc.) can be *measured*.



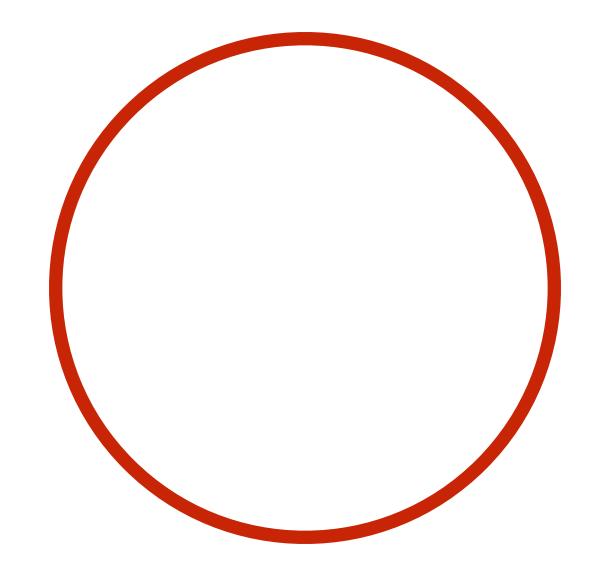
Plato: "...the earth is in appearance like one of those balls which have leather coverings in twelve pieces..."

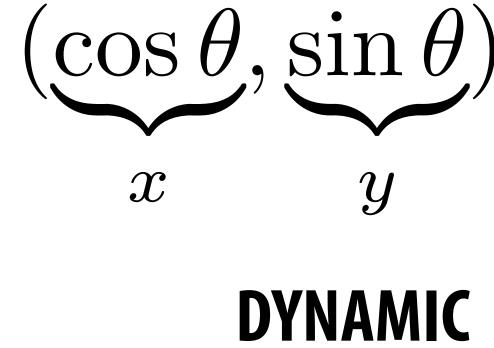
#### How can we describe geometry?

#### **IMPLICIT**

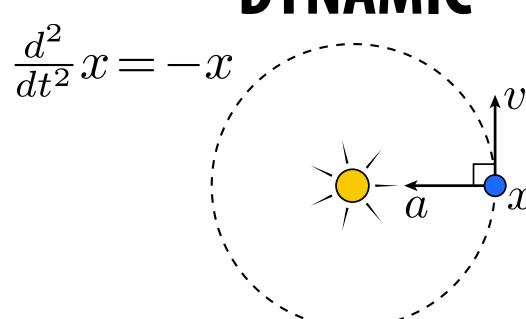
$$x^2 + y^2 = 1$$

#### LINGUISTIC "unit circle"

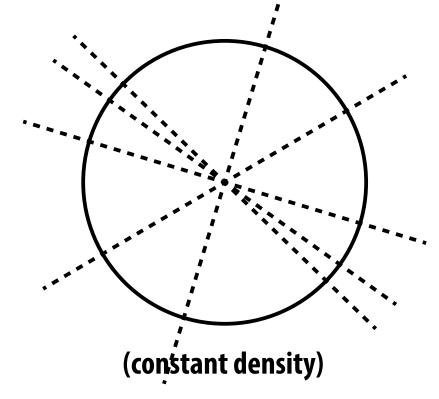




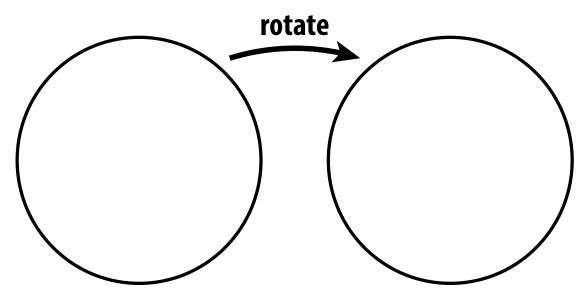
**EXPLICIT** 



#### **TOMOGRAPHIC**



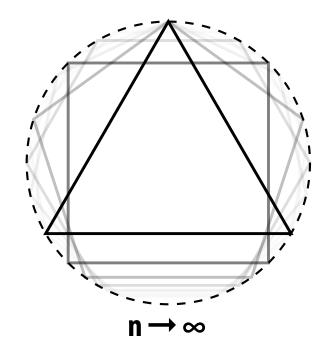
#### **SYMMETRIC**



#### **CURVATURE**

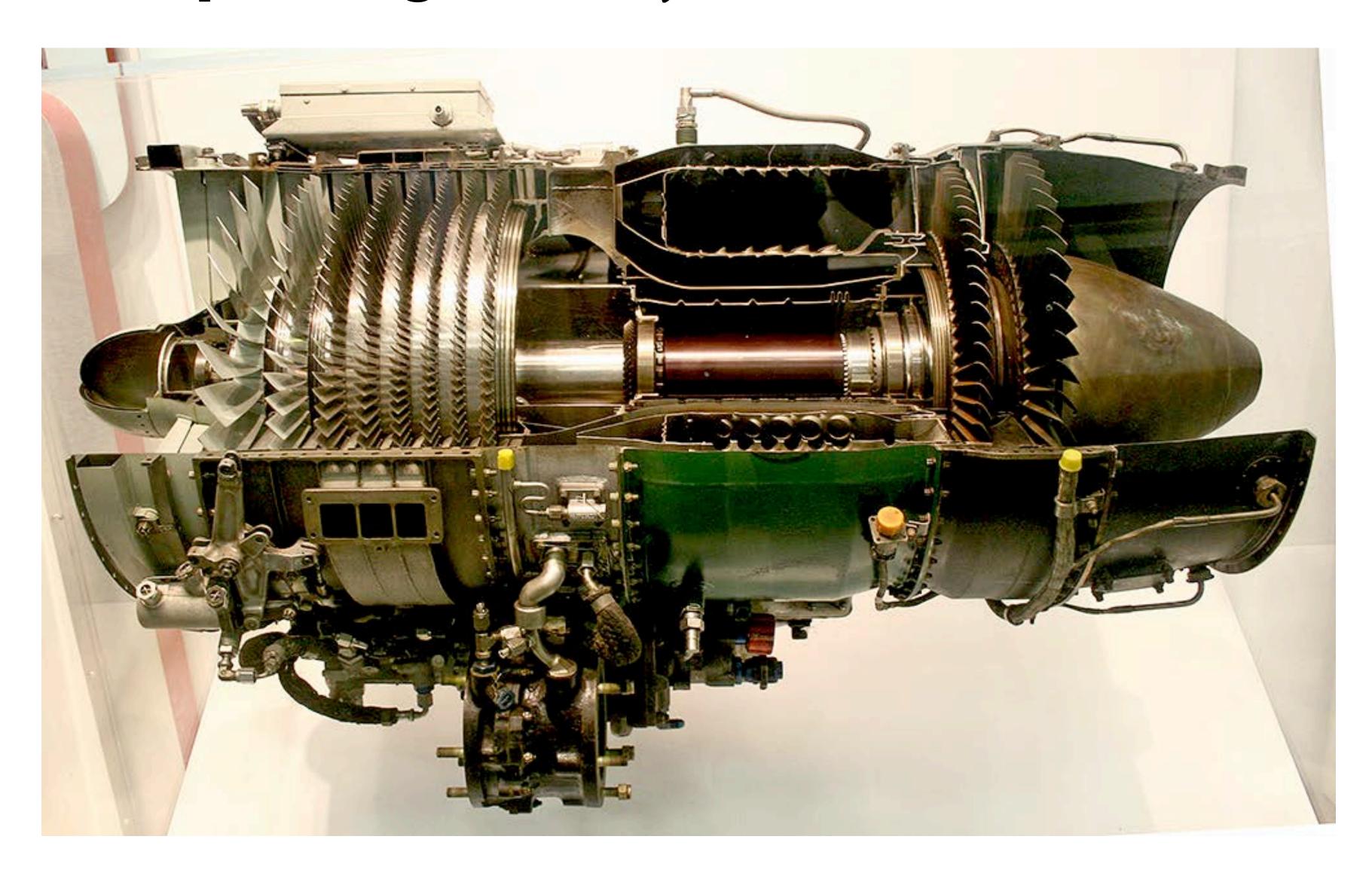
$$\kappa = 1$$

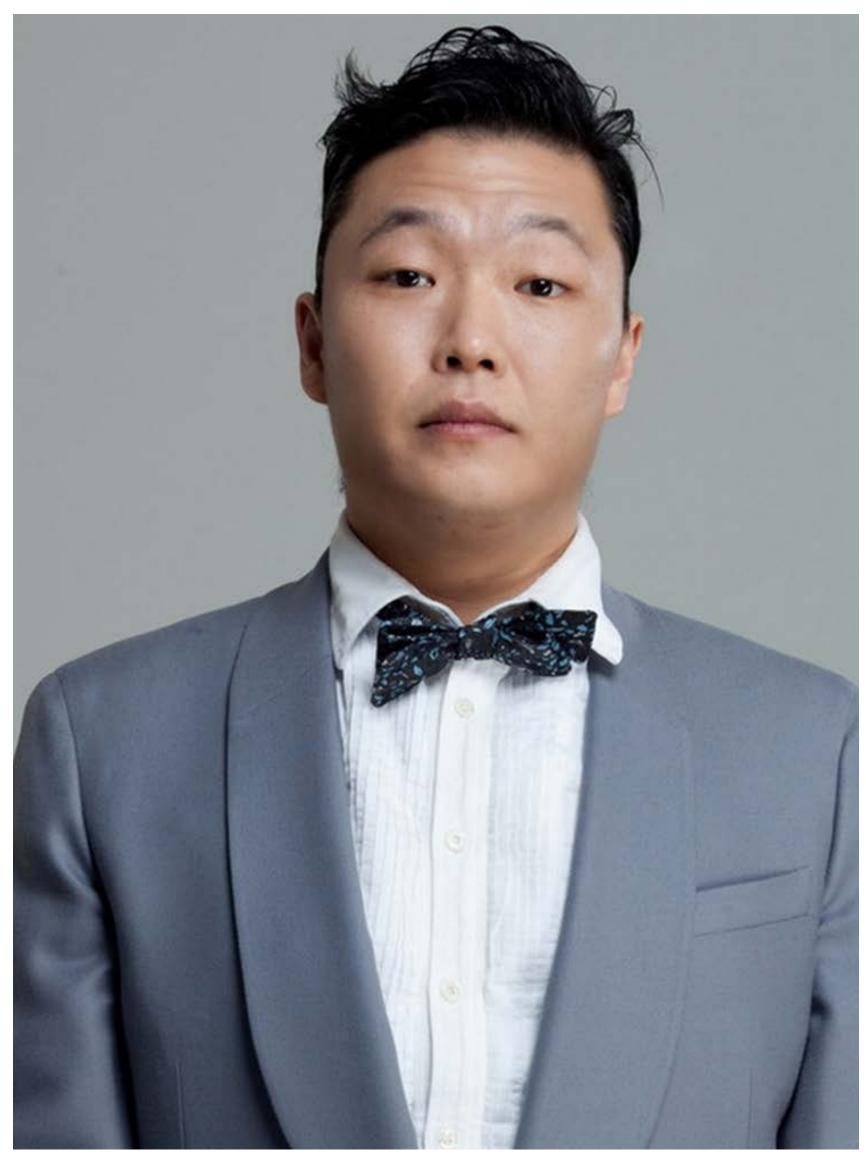
#### **DISCRETE**

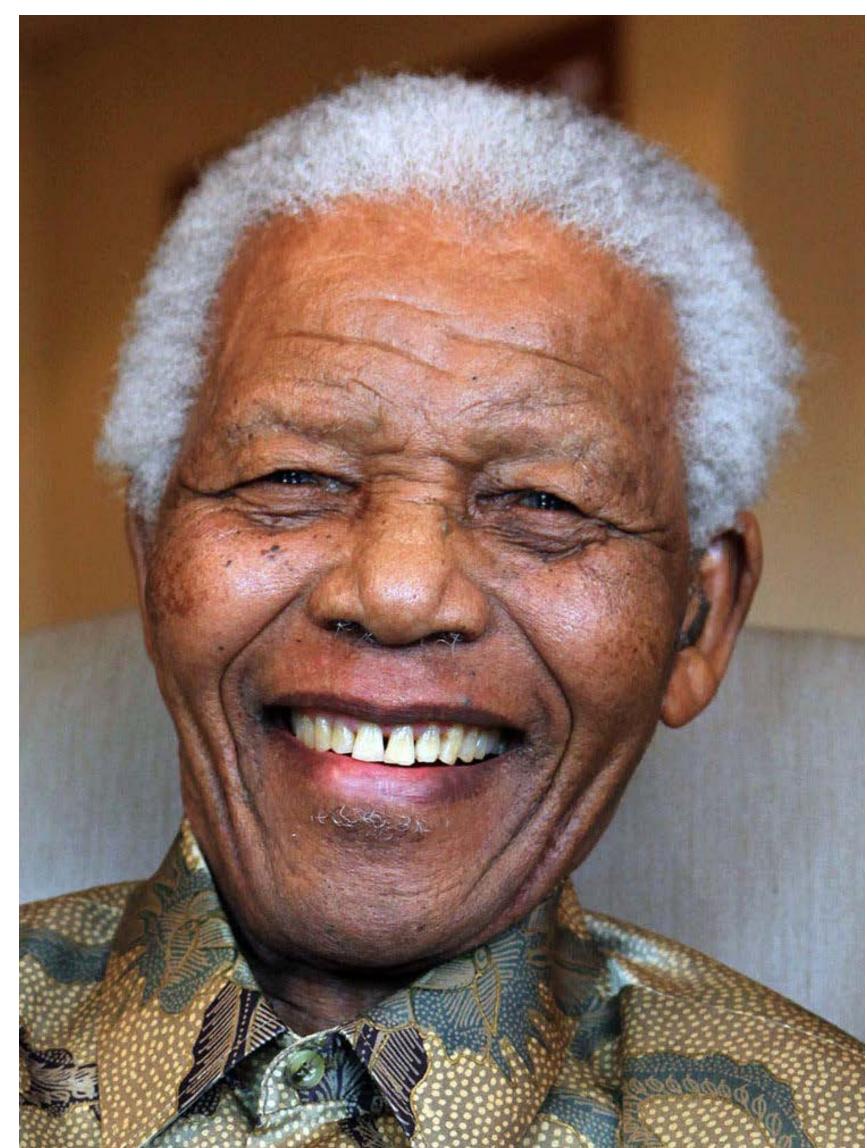


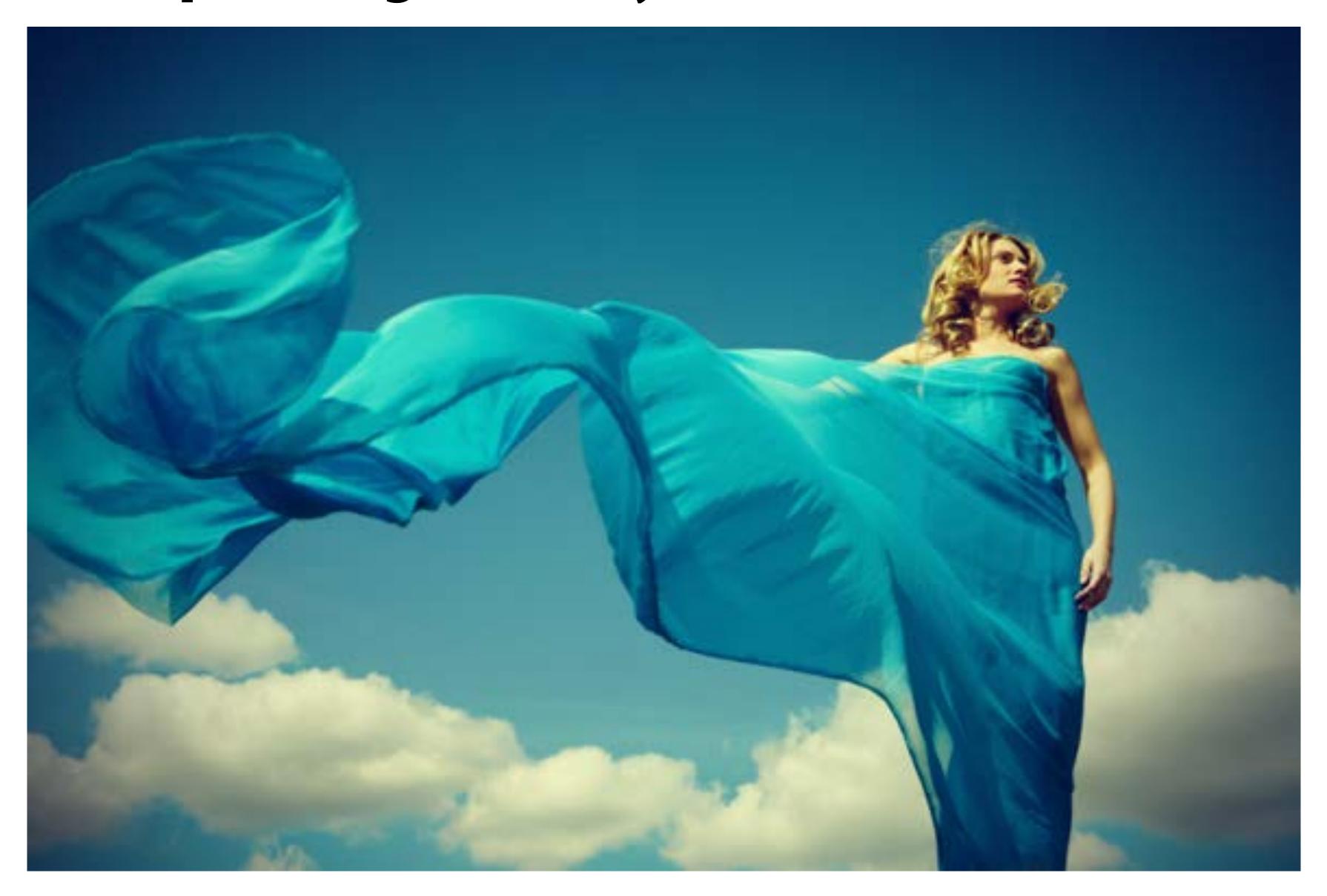
## Given all these options, what's the best way to encode geometry on a computer?



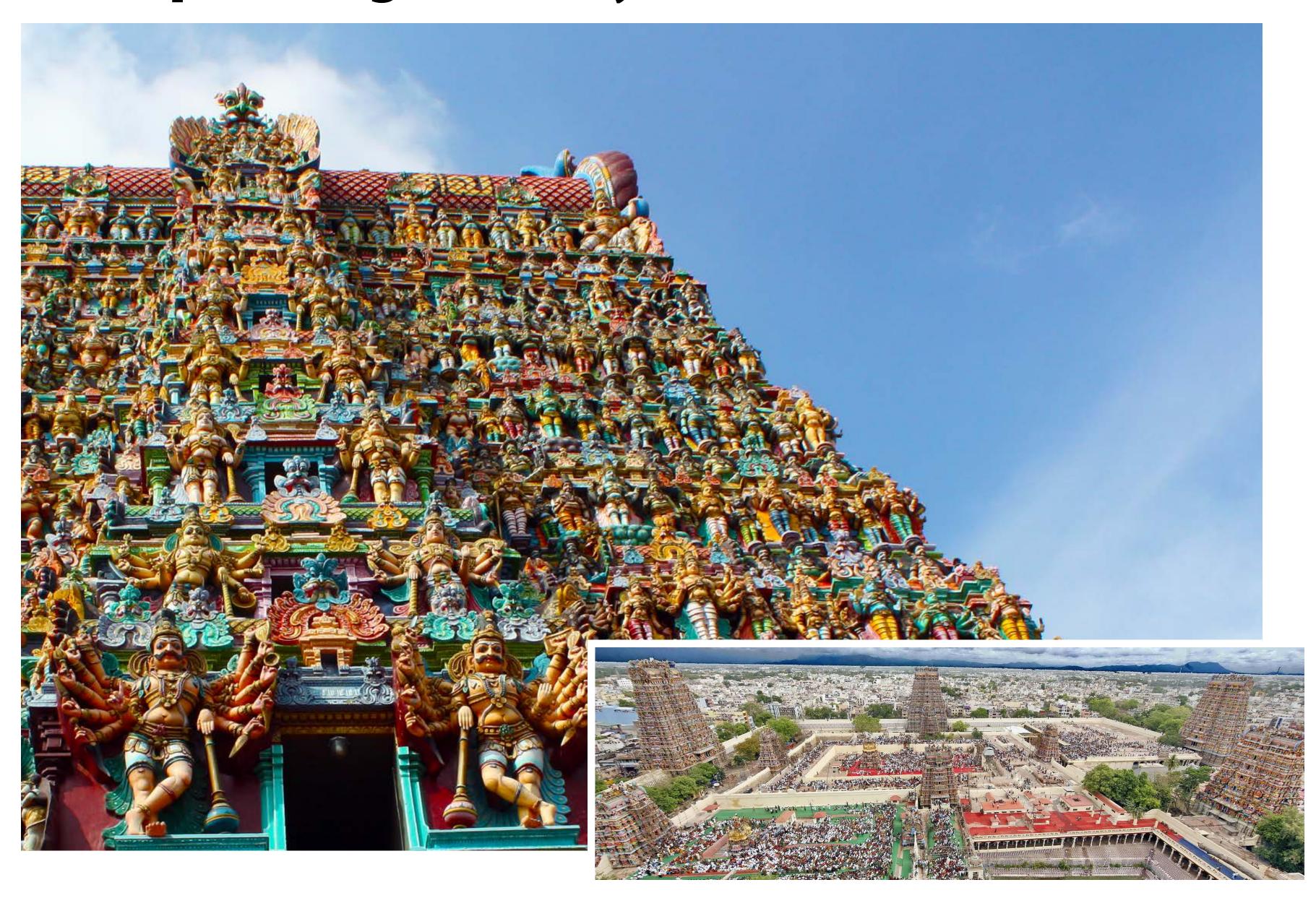




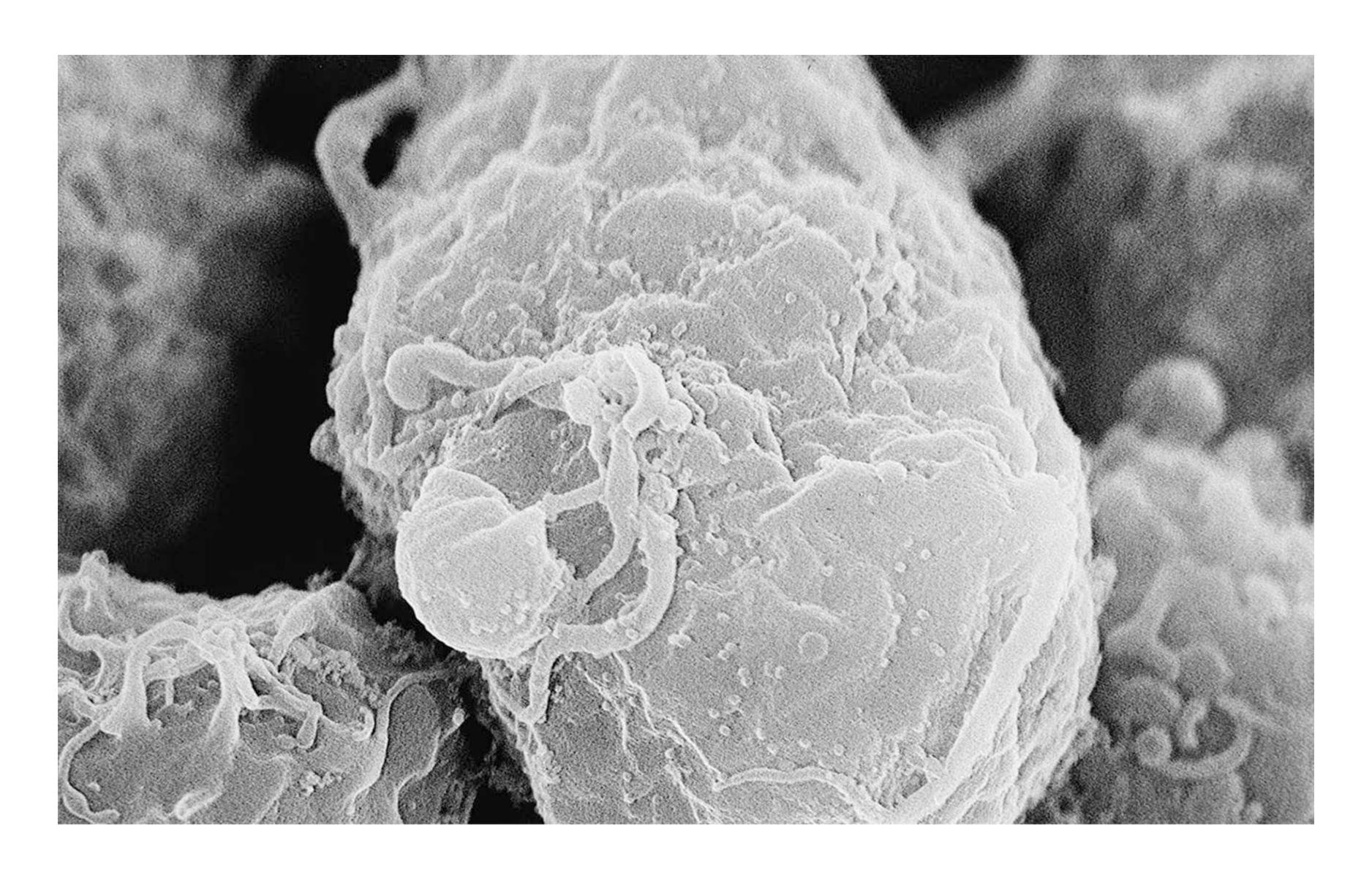












## It's a Jungle Out There!



#### No one "best" choice—geometry is hard!

"I hate meshes.

I cannot believe how hard this is.

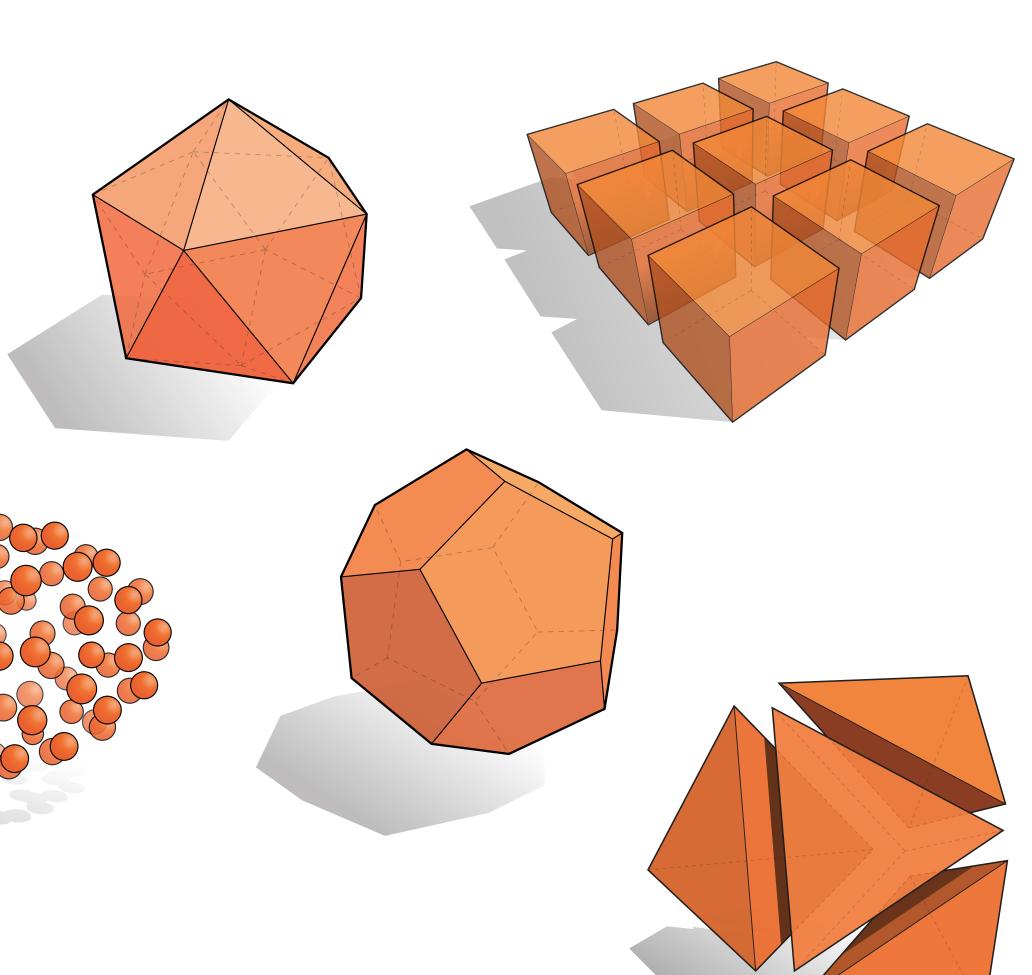
Geometry is hard."

—David Baraff
Senior Research Scientist
Pixar Animation Studios

Slide cribbed from Jeff Erickson. CMU 15-462/662

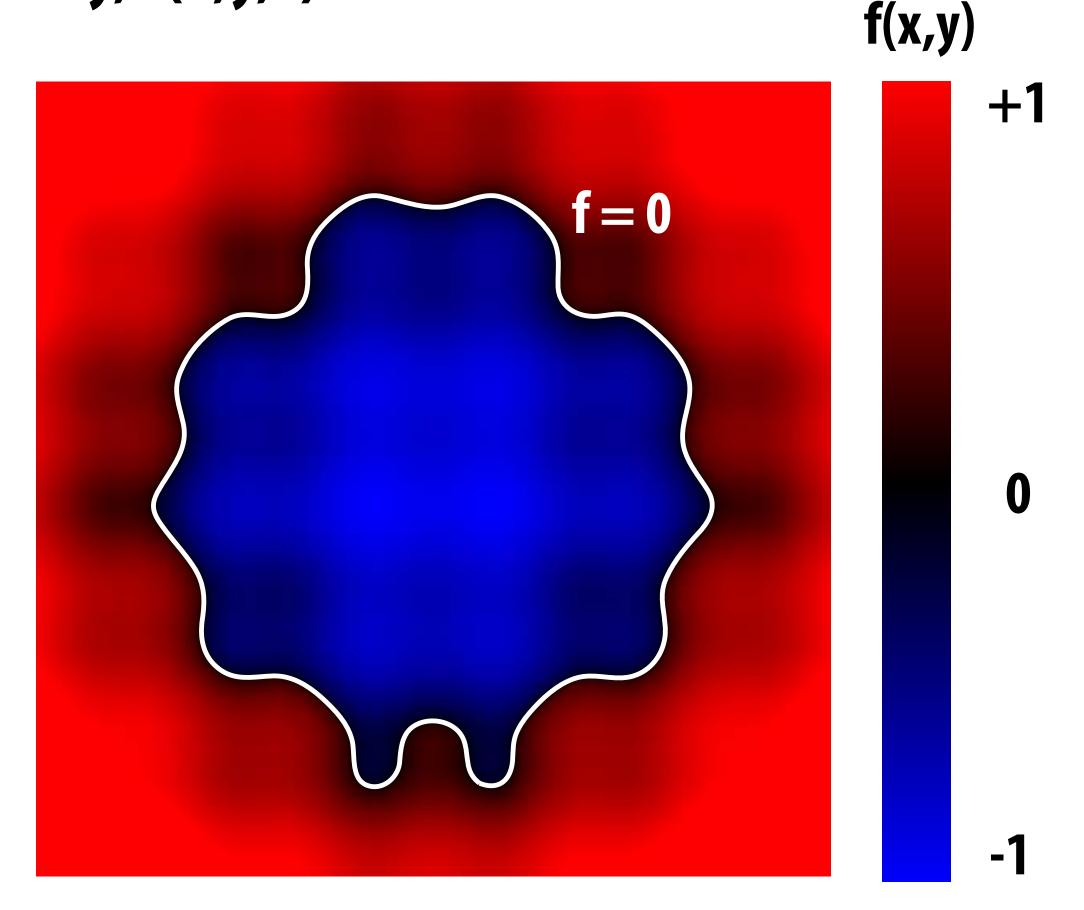
#### Many ways to digitally encode geometry

- EXPLICIT
  - point cloud
  - polygon mesh
  - subdivision, NURBS
  - -
- IMPLICIT
  - level set
  - algebraic surface
  - L-systems
  - -
- Each choice best suited to a different task/type of geometry

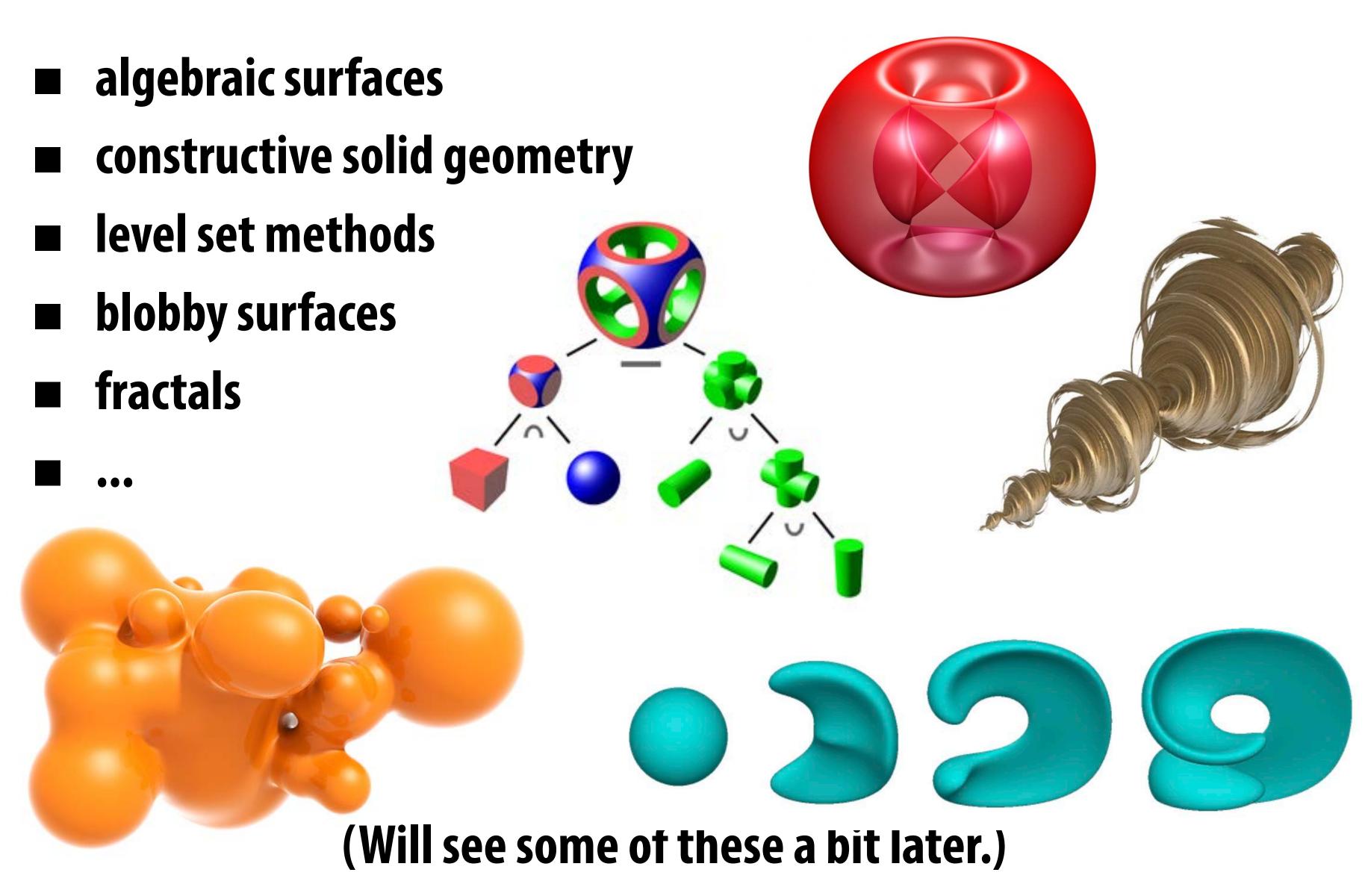


#### "Implicit" Representations of Geometry

- Points aren't known directly, but satisfy some relationship
- E.g., unit sphere is all points such that  $x^2+y^2+z^2=1$
- More generally, f(x,y,z) = 0



#### Many implicit representations in graphics



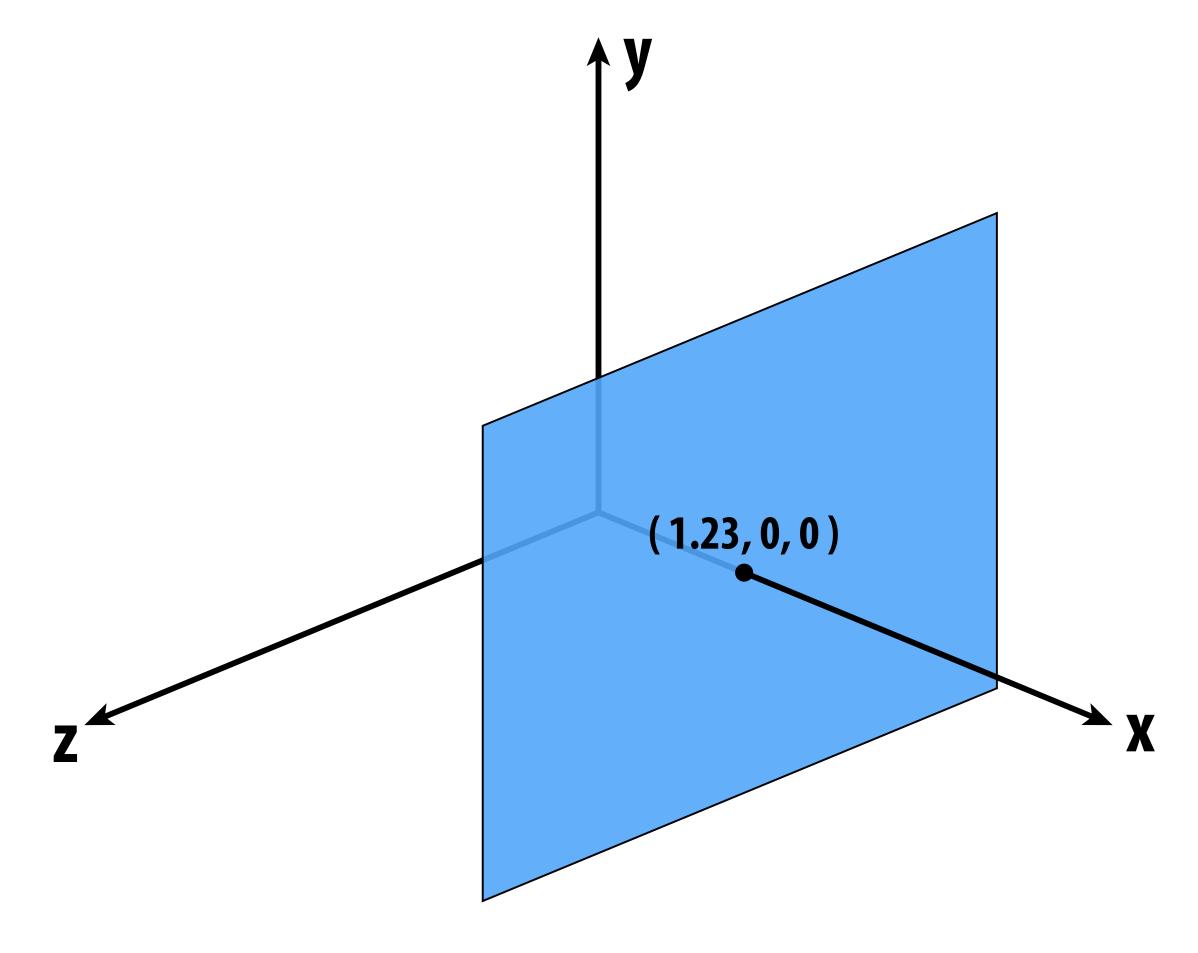
#### But first, let's play a game:

I'm thinking of an implicit surface f(x,y,z)=0.

Find any point on it.

#### Give up?

My function was f(x,y,z) = x - 1.23 (a plane):



Implicit surfaces make some tasks hard (like sampling).

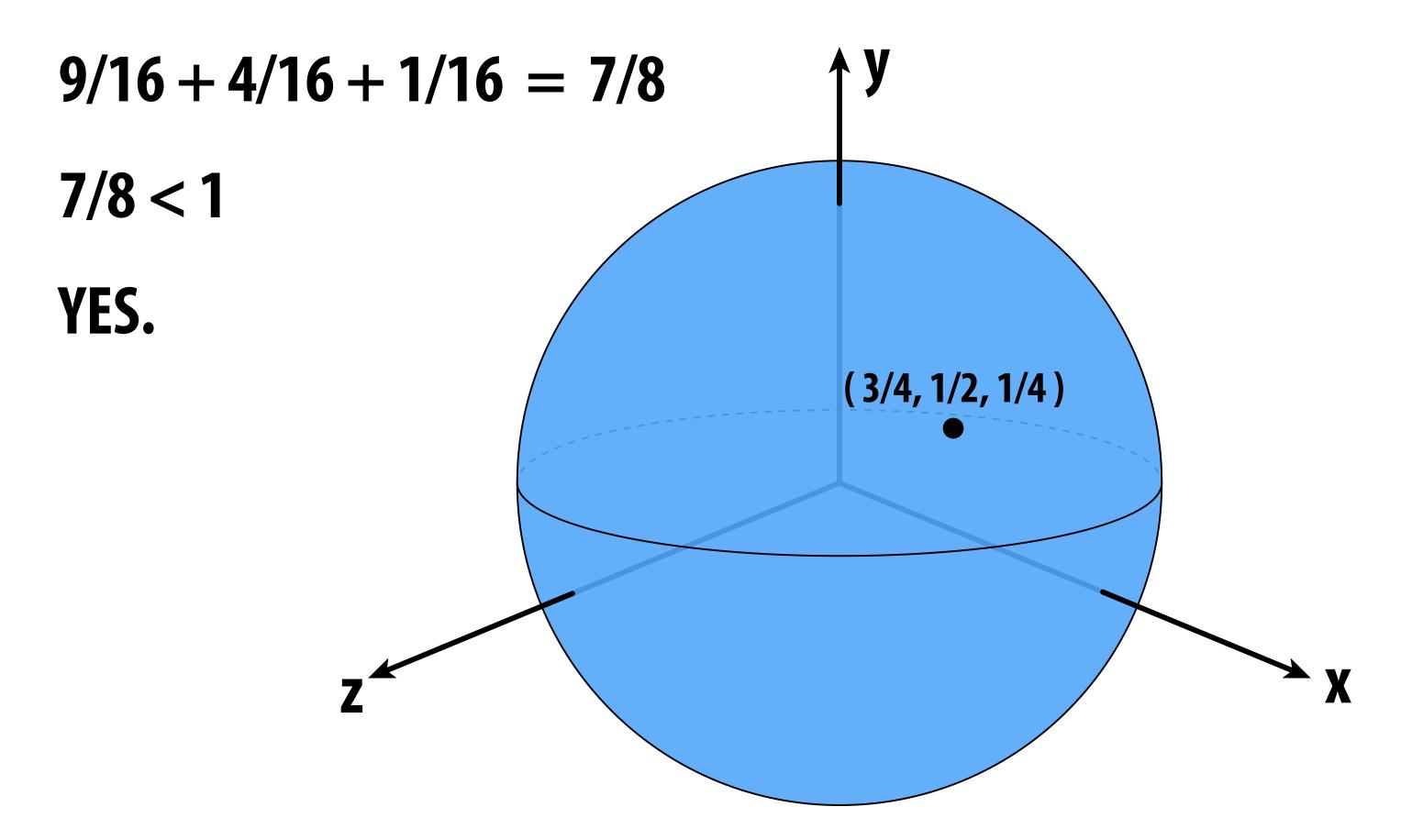
#### Let's play another game.

I have a new surface  $f(x,y,z) = x^2 + y^2 + z^2 - 1$ 

I want to see if a point is inside it.

#### Check if this point is inside the unit sphere

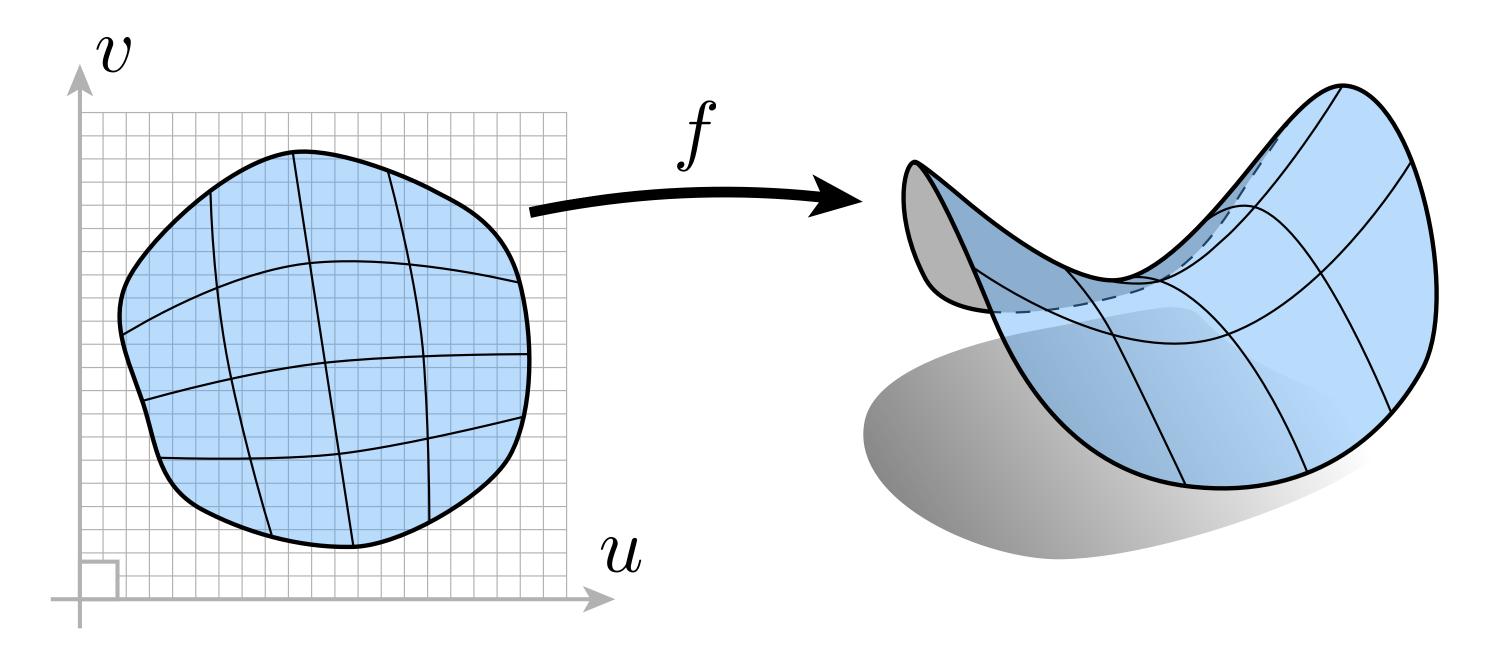
How about the point (3/4, 1/2, 1/4)?



Implicit surfaces make other tasks easy (like inside/outside tests).

#### "Explicit" Representations of Geometry

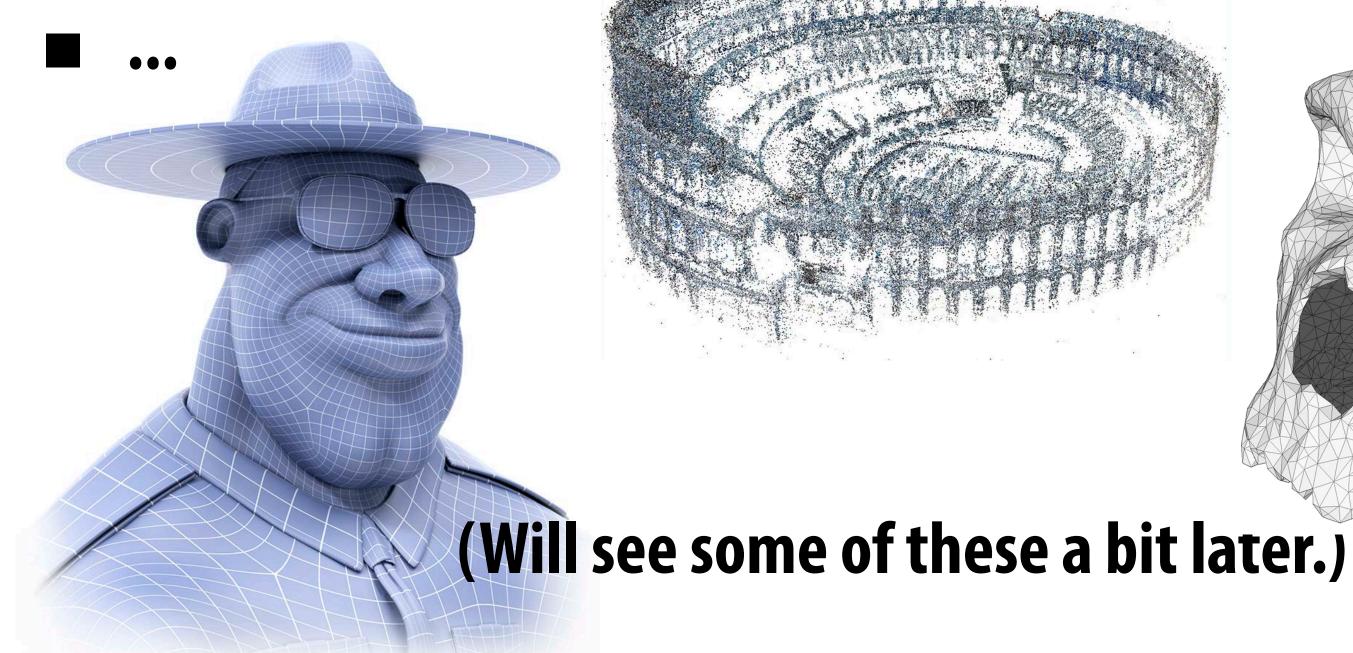
- All points are given directly
- **E.g., points on sphere are**  $(\cos(u)\sin(v),\sin(u)\sin(v),\cos(v)),$  for  $0 < u < 2\pi$  and  $0 < v < \pi$
- More generally:  $f: \mathbb{R}^2 \to \mathbb{R}^3$ ;  $(u,v) \mapsto (x,y,z)$

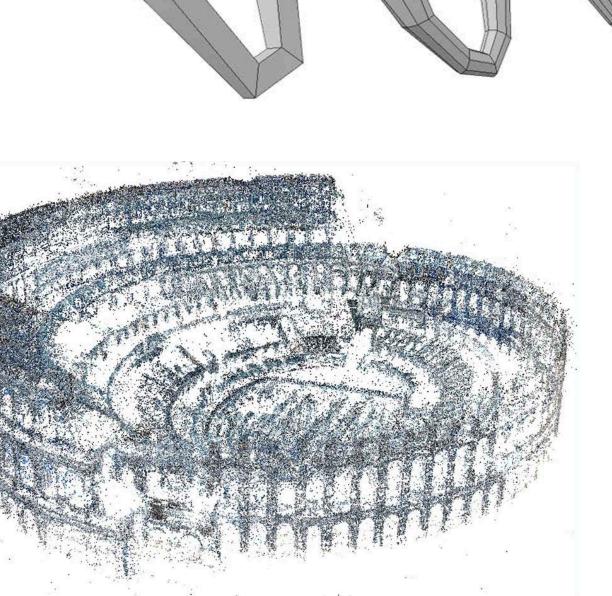


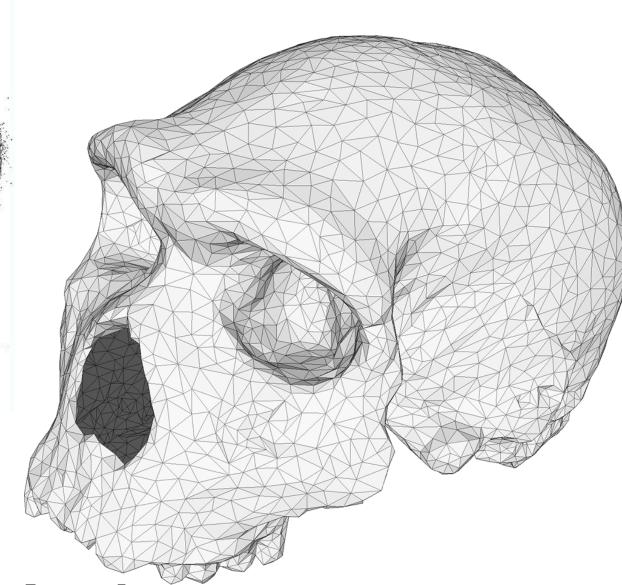
(Might have a bunch of these maps, e.g., one per triangle!)

#### Many explicit representations in graphics

- triangle meshes
- polygon meshes
- subdivision surfaces
- **NURBS**
- point clouds







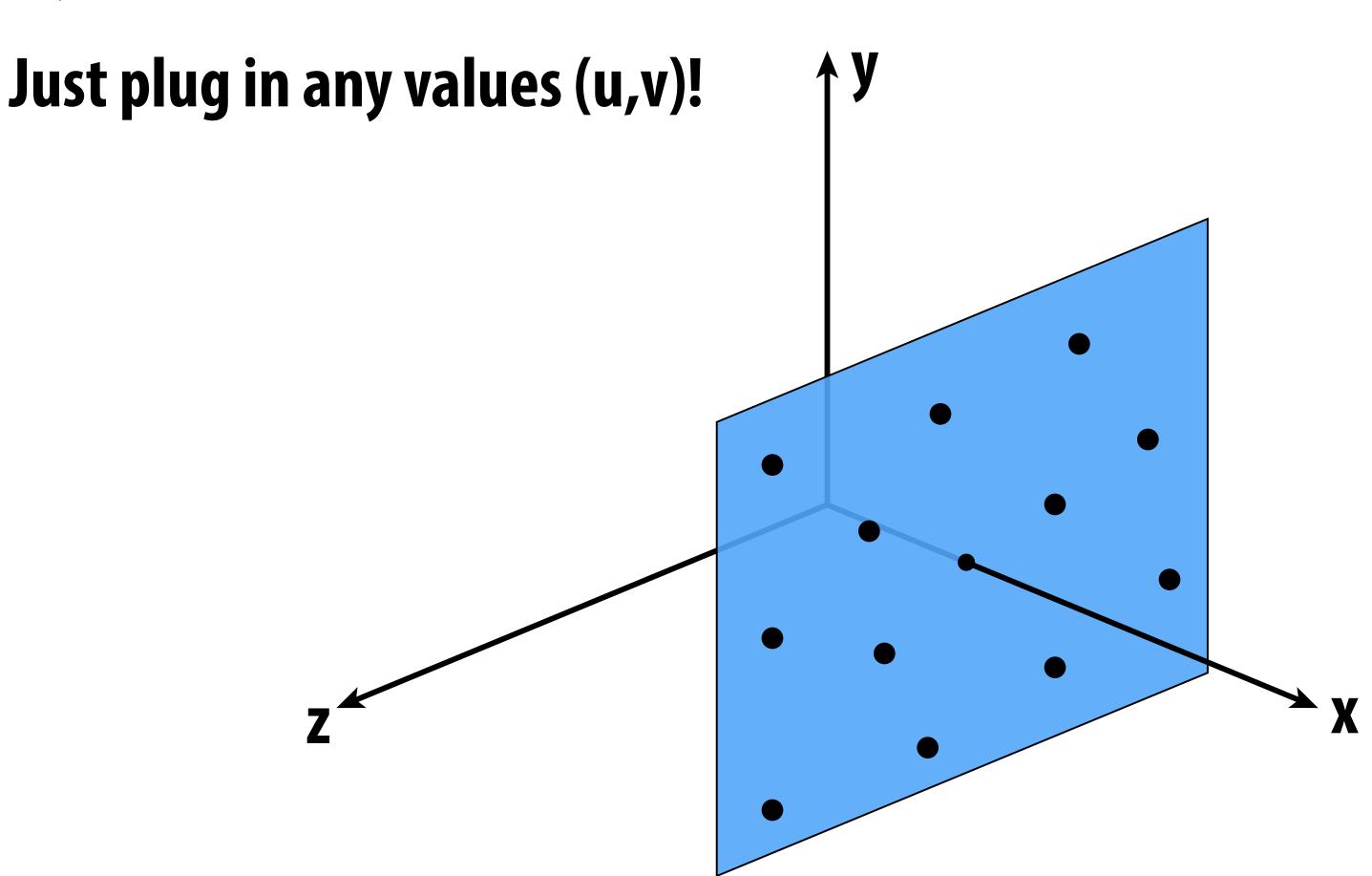
#### But first, let's play a game:

l'Il give you an explicit surface.

You give me some points on it.

#### Sampling an explicit surface

My surface is f(u, v) = (1.23, u, v).



Explicit surfaces make some tasks easy (like sampling).

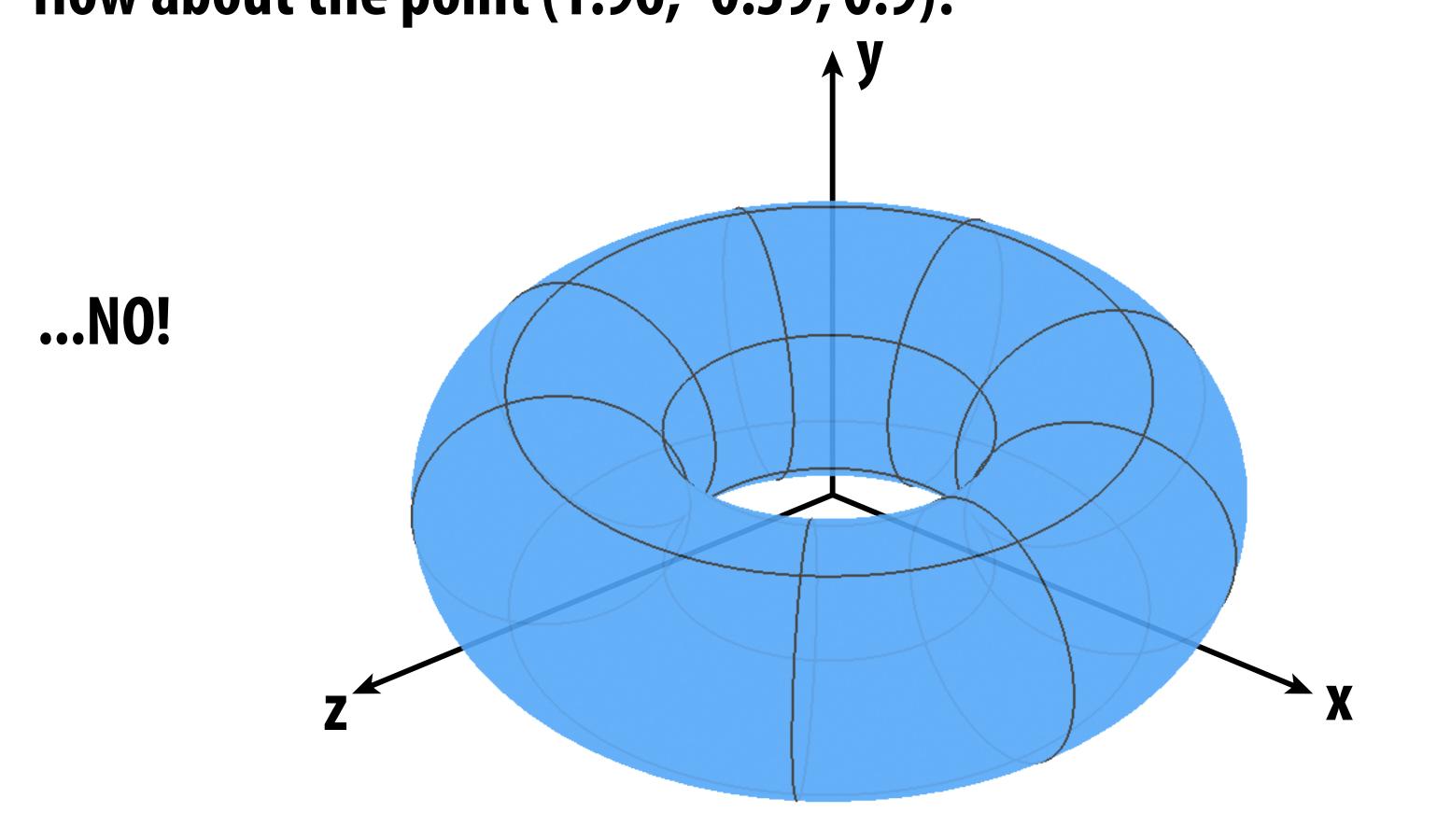
Let's play another game.

I have a new surface f(u,v).

I want to see if a point is inside it.

#### Check if this point is inside the torus

My surface is  $f(u,v) = ((2+\cos u)\cos v, (2+\cos u)\sin v, \sin u)$ How about the point (1.96, -0.39, 0.9)?



Explicit surfaces make other tasks hard (like inside/outside tests).

# CONCLUSION: Some representations work better than others—depends on the task!

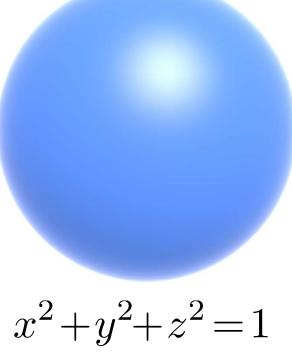
# Different representations will also be better suited to different types of geometry.

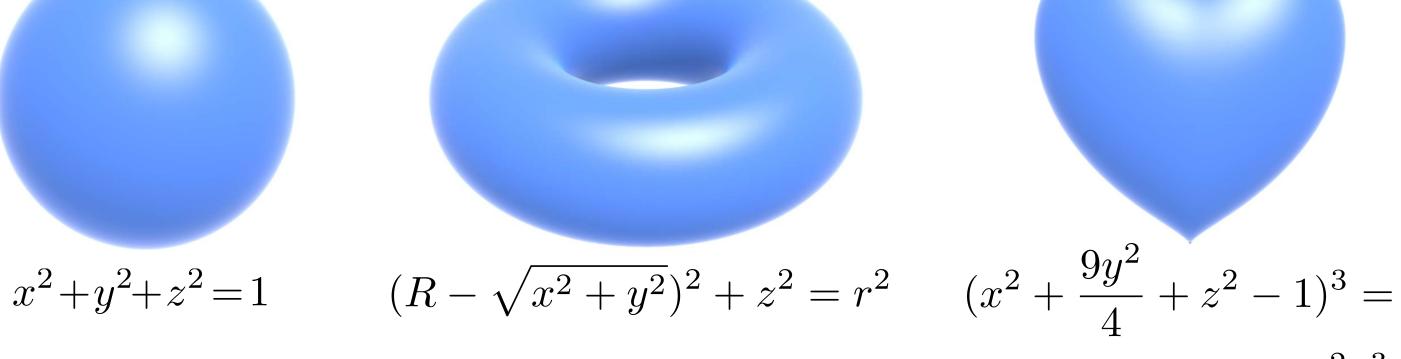
Let's take a look at some common representations used in computer graphics.

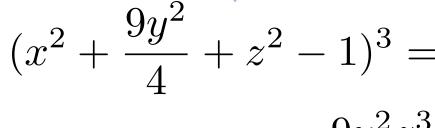
#### Algebraic Surfaces (Implicit)

Surface is zero set of a polynomial in x, y, z ("algebraic variety")

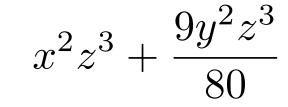
**Examples:** 

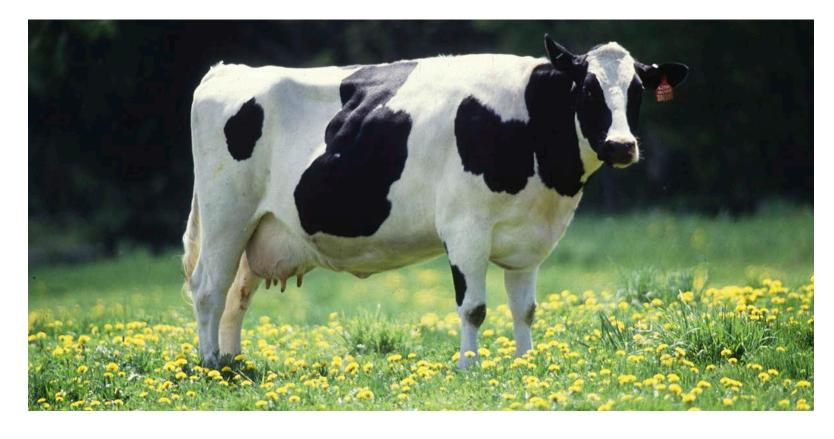






What about more complicated shapes?





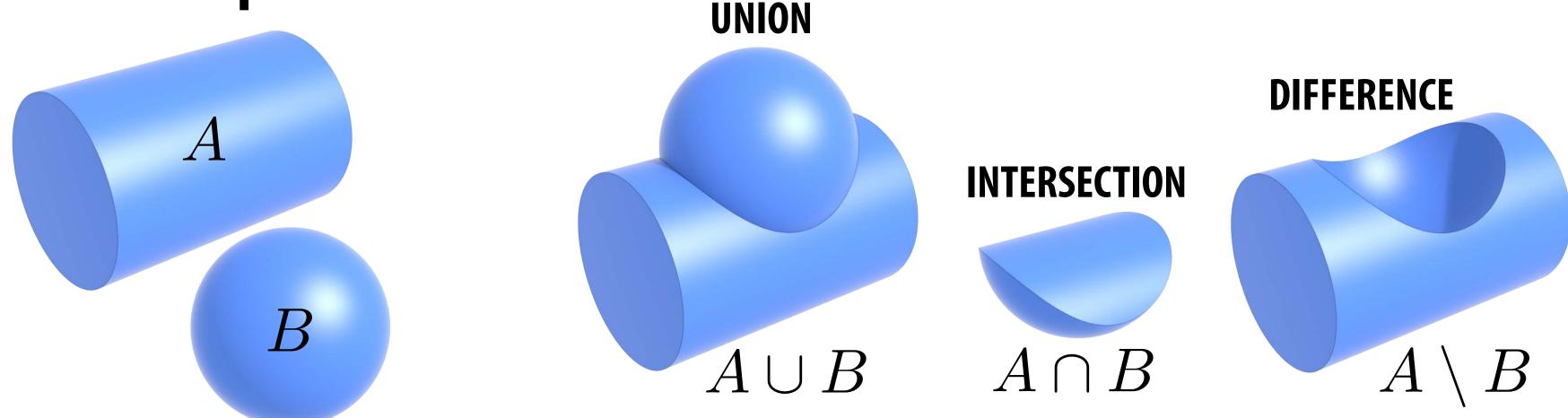


Very hard to come up with polynomials!

#### **Constructive Solid Geometry (Implicit)**

Build more complicated shapes via Boolean operations

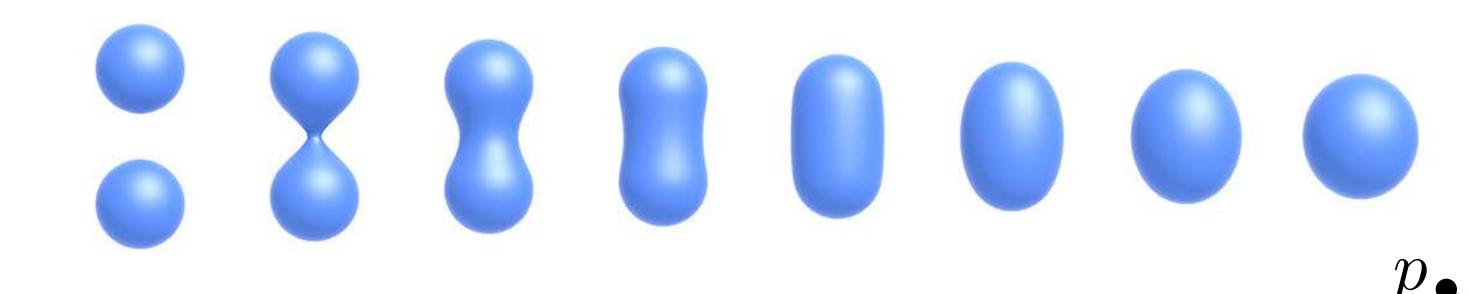
Basic operations:



■ Then chain together expressions:  $(X \cap Y) \setminus (U \cup V \cup W)$ 

#### Blobby Surfaces (Implicit)

Instead of Booleans, gradually blend surfaces together:



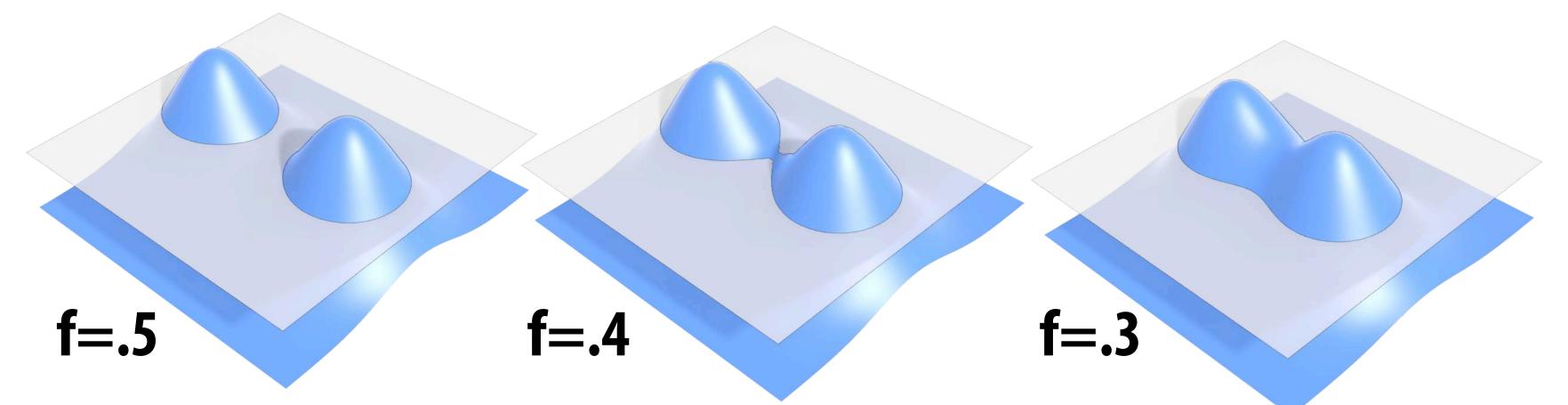
■ Easier to understand in 2D:

$$\phi_p(x) := e^{-|x-p|^2}$$

(Gaussian centered at p)

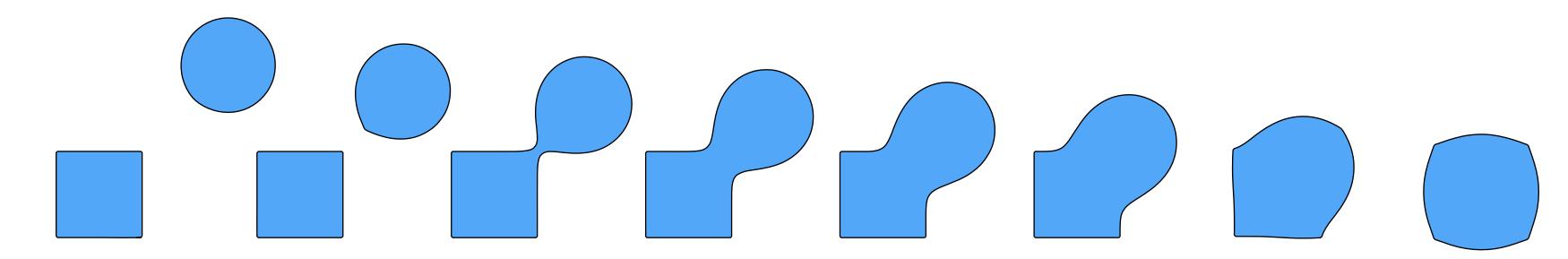
$$f := \phi_p + \phi_q$$

(Sum of Gaussians centered at different points)



# Blending Distance Functions (Implicit)

- A distance function gives distance to closest point on object
- Can blend any two distance functions  $d_1$ ,  $d_2$ :

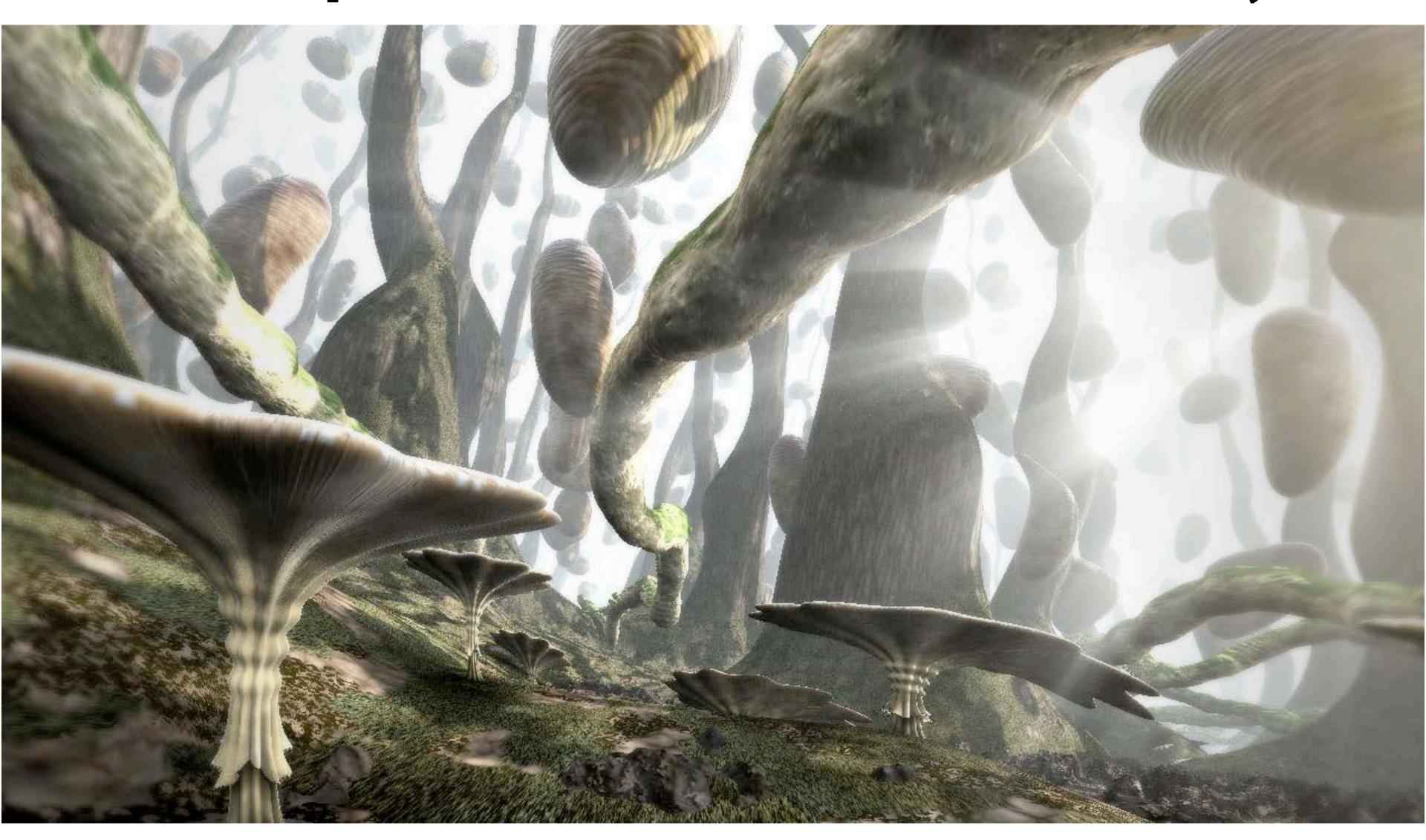


Similar strategy to points, though many possibilities. E.g.,

$$f(x) := e^{d_1(x)^2} + e^{d_2(x)^2} - \frac{1}{2}$$

- Appearance depends on how we combine functions
- $\blacksquare$  Q: How do we implement a Boolean union of d1(x), d2(x)\*?
- **A:** Just take the minimum:  $f(x) := HELP(UL)(x) + \min(d_2(x))$

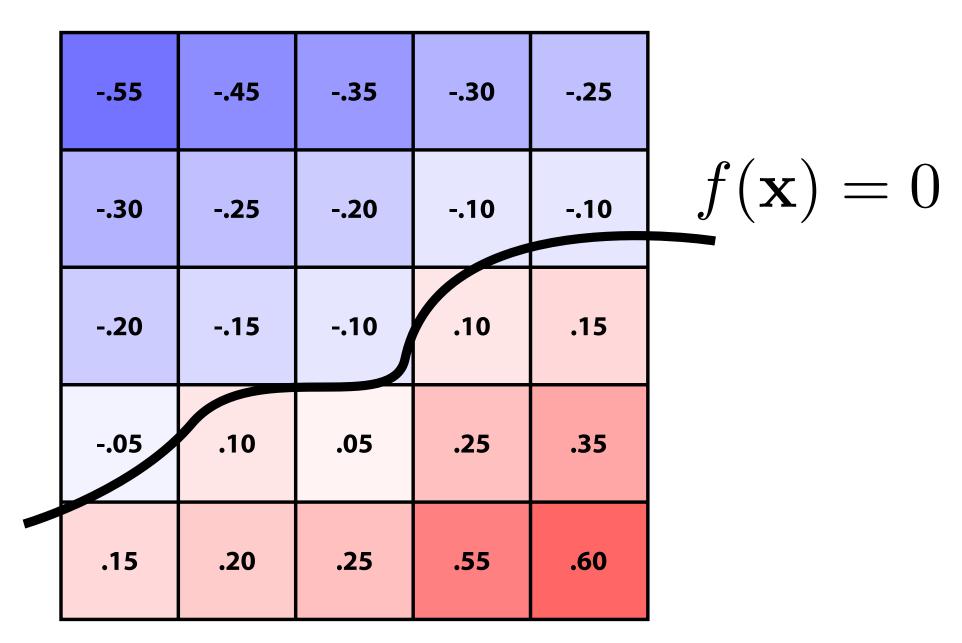
#### Scene of pure distance functions (not easy!)



See <a href="http://iquilezles.org/www/material/nvscene2008/nvscene2008.htm">http://iquilezles.org/www/material/nvscene2008/nvscene2008.htm</a>

#### Level Set Methods (Implicit)

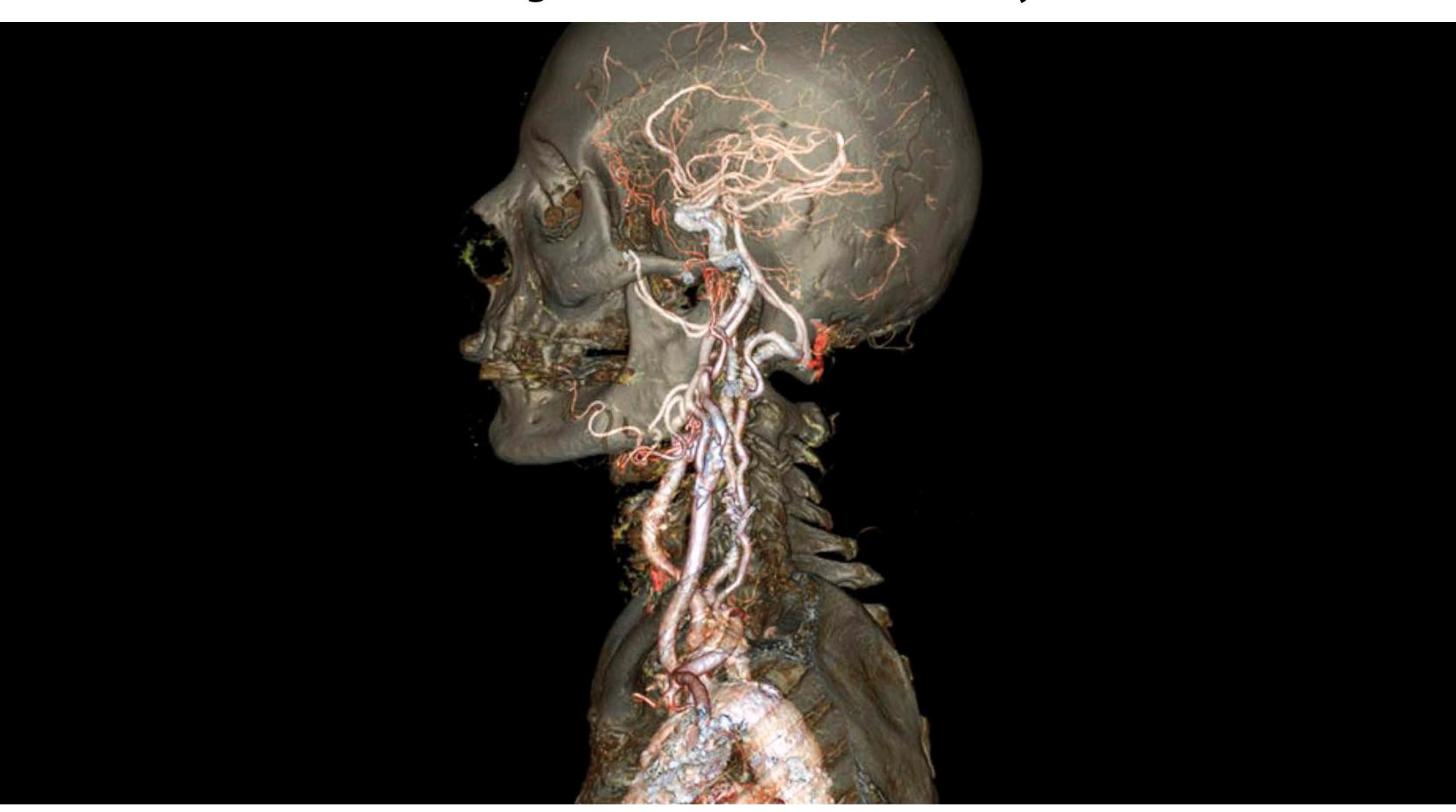
- Implicit surfaces have some nice features (e.g., merging/splitting)
- But, hard to describe complex shapes in closed form
- Alternative: store a grid of values approximating function



- Surface is found where *interpolated* values equal zero
- Provides much more explicit control over shape (like a texture)
- Often demands sophisticated filtering (trilinear, tricubic...)

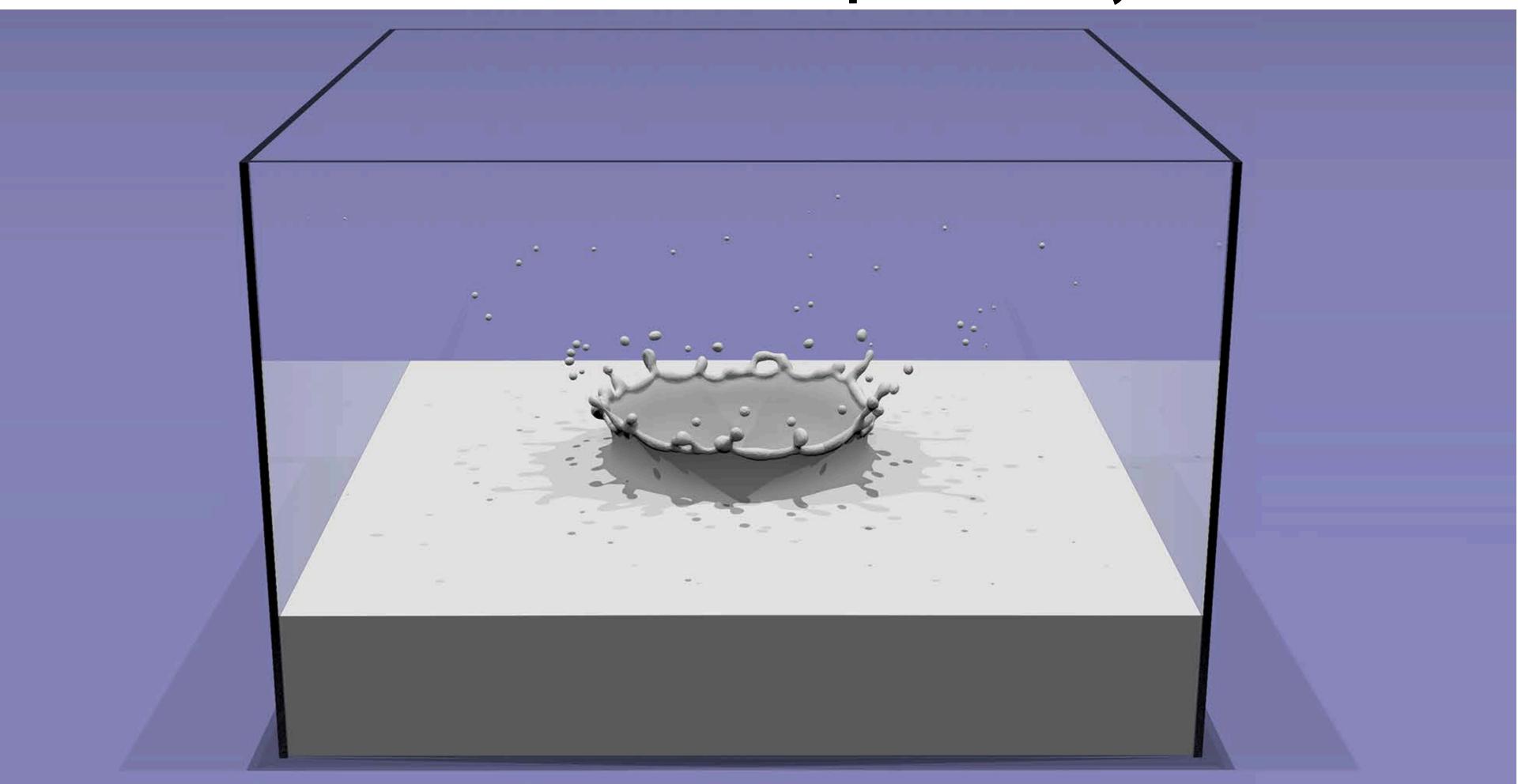
#### Level Sets from Medical Data (CT, MRI, etc.)

Level sets encode, e.g., constant tissue density



# Level Sets in Physical Simulation

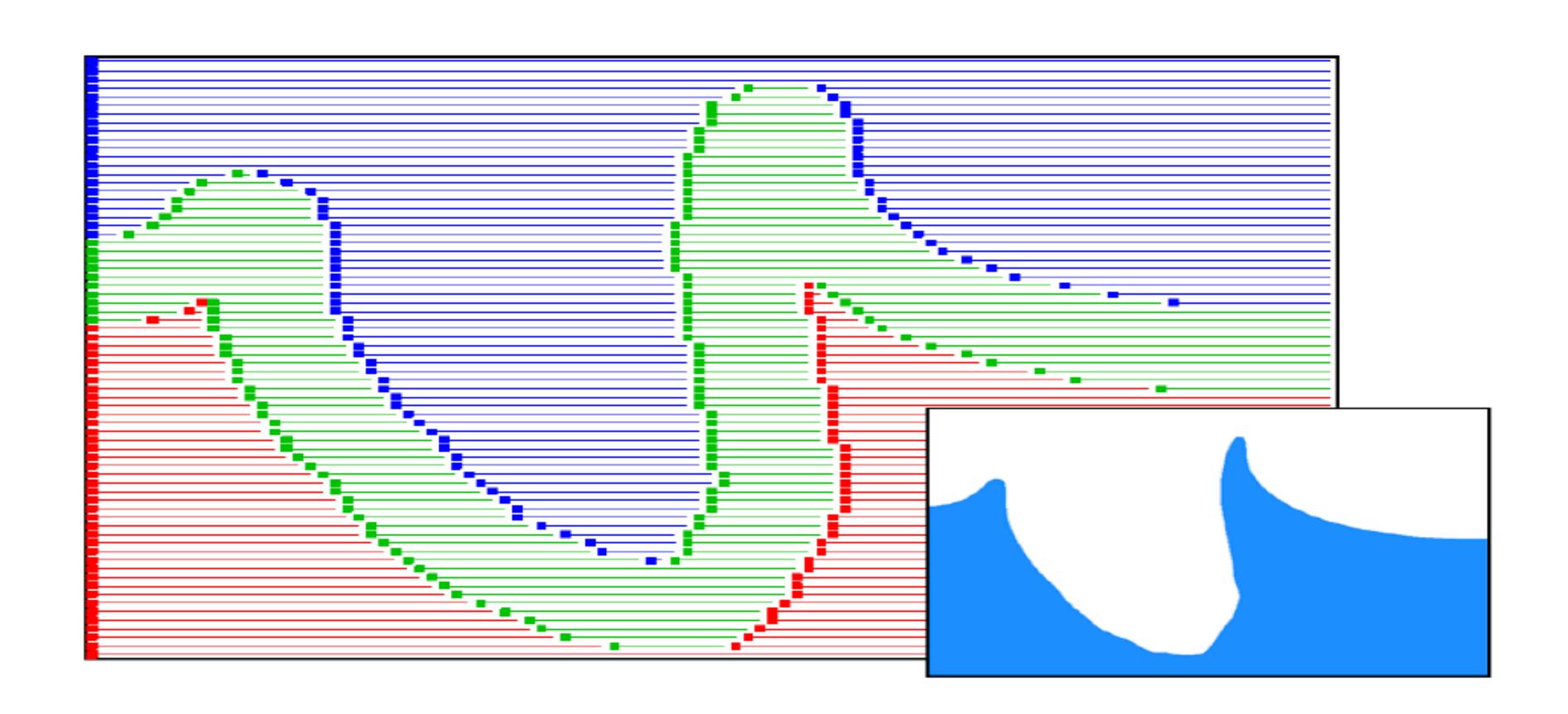
Level set encodes distance to air-liquid boundary



See <a href="http://physbam.stanford.edu">http://physbam.stanford.edu</a>

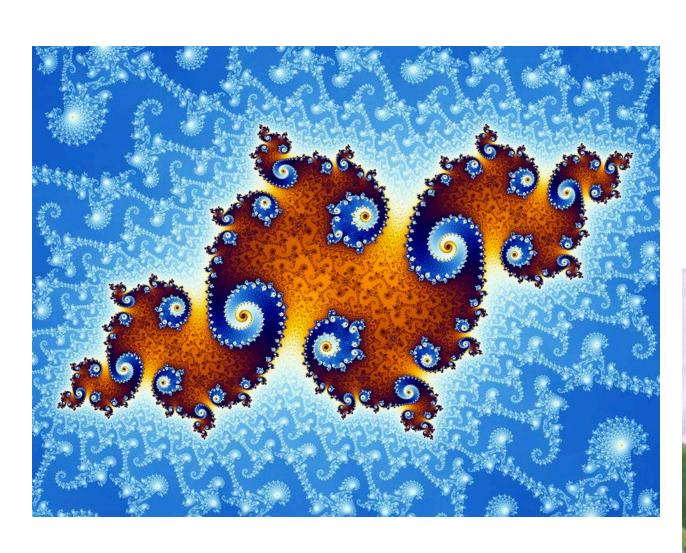
## Level Set Storage

- Drawback: storage for 2D surface is now O(n³)
- Can reduce cost by storing only a narrow band around surface:



#### Fractals (Implicit)

- No precise definition; exhibit self-similarity, detail at all scales
- New "language" for describing natural phenomena
- Hard to control shape!

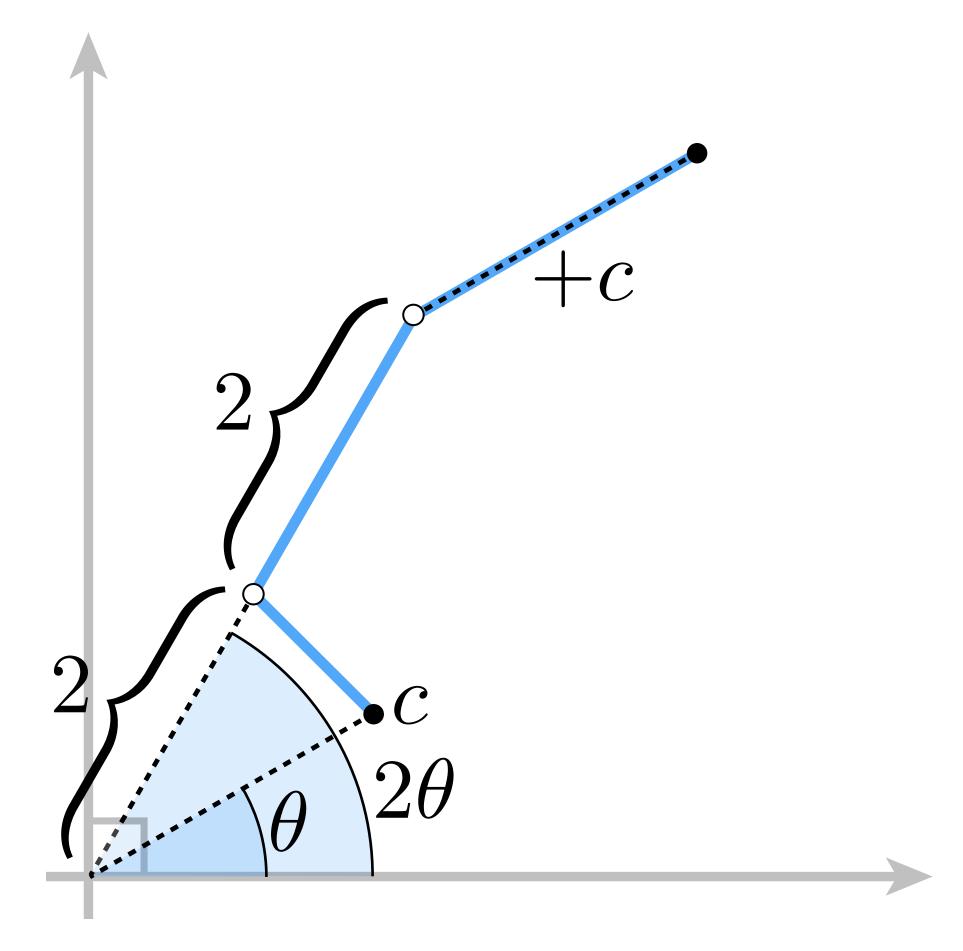






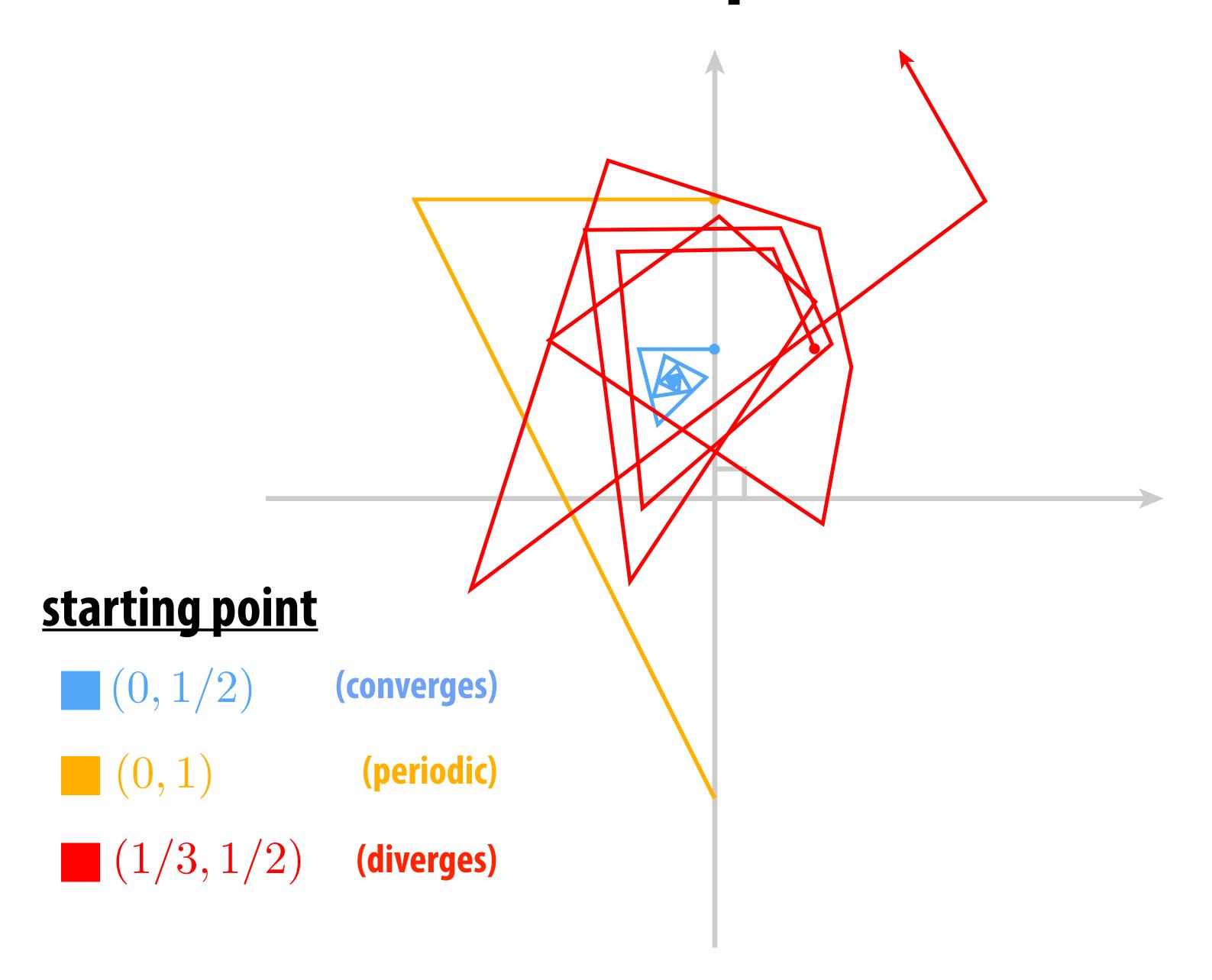
#### Mandelbrot Set - Definition

- For each point c in the plane:
  - double the angle
  - square the magnitude
  - add the original point c
  - repeat
- Complex version:
  - Replace z with  $z^2+c$
  - repeat

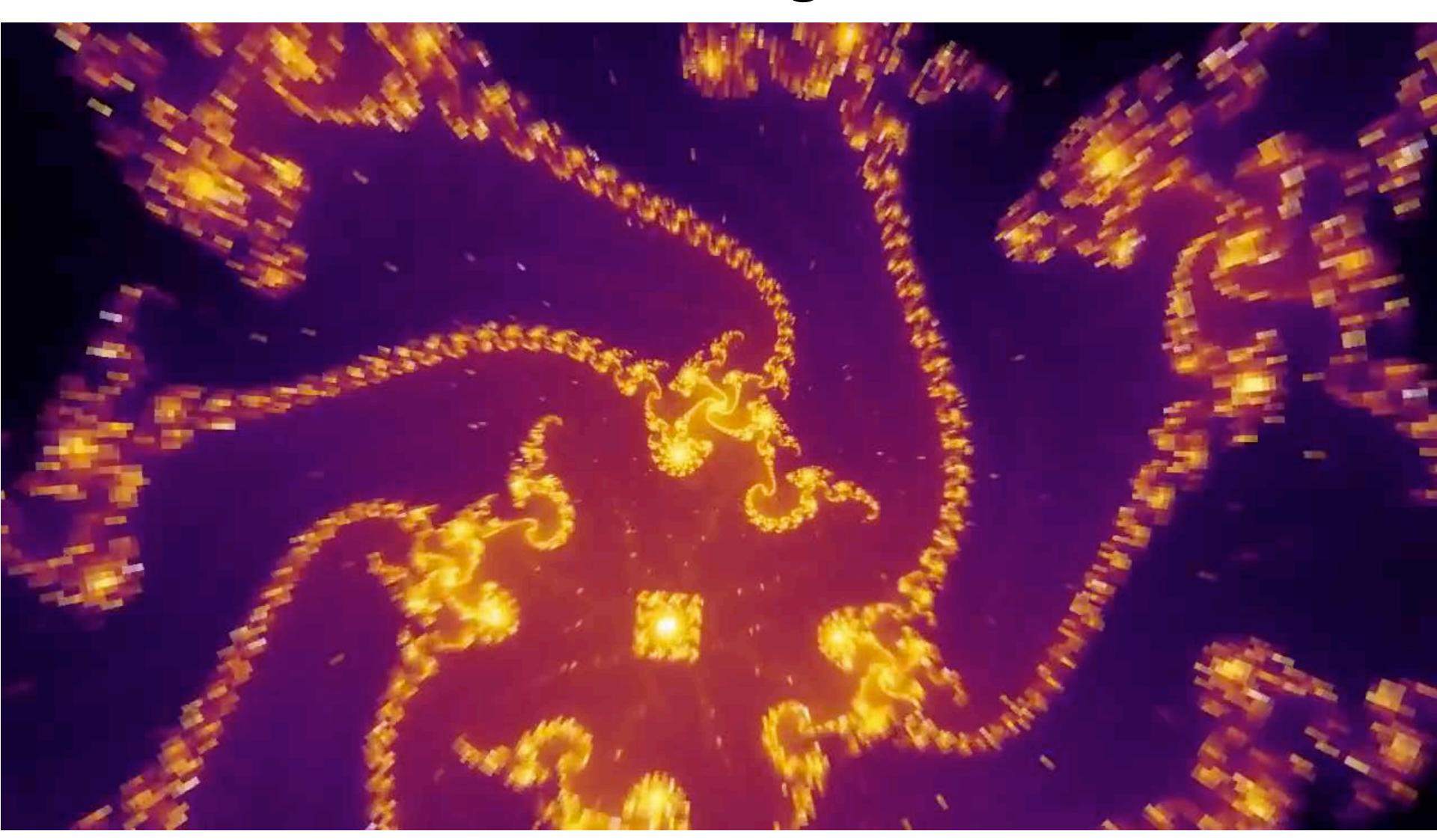


If magnitude remains bounded (never goes to  $\infty$ ), it's in the Mandelbrot set.

#### Mandelbrot Set - Examples



## Mandelbrot Set - Zooming In



(Colored according to how quickly each point diverges/converges.)

#### Iterated Function Systems



Scott Draves (CMU Alumnus) - see <a href="http://electricsheep.org">http://electricsheep.org</a>

#### Implicit Representations - Pros & Cons

#### ■ Pros:

- description can be very compact (e.g., a polynomial)
- easy to determine if a point is in our shape (just plug it in!)
- other queries may also be easy (e.g., distance to surface)
- for simple shapes, exact description/no sampling error
- easy to handle changes in topology (e.g., fluid)

#### Cons:

- expensive to find all points in the shape (e.g., for drawing)
- very difficult to model complex shapes

# What about explicit representations?

## Point Cloud (Explicit)

Easiest representation: list of points (x,y,z)

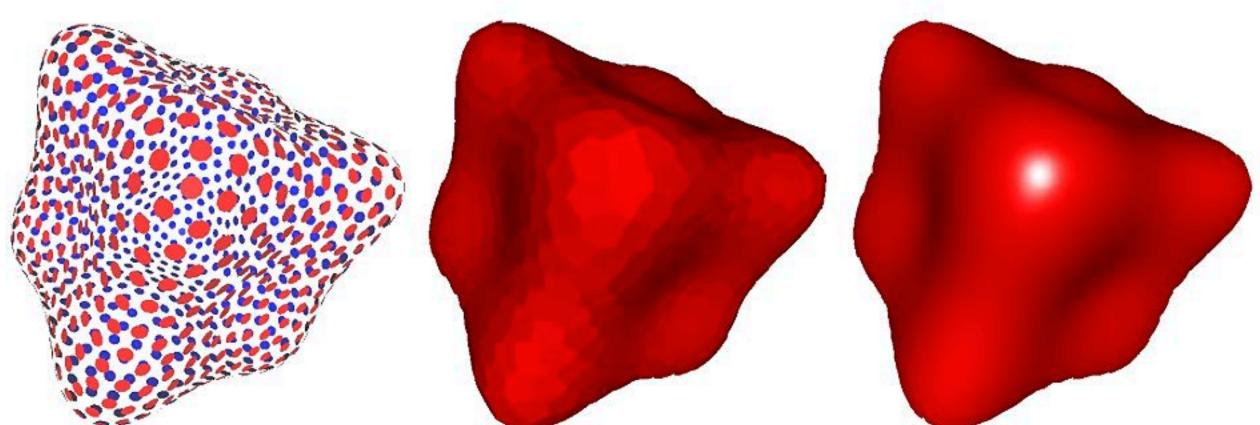
Often augmented with normals

Easily represent any kind of geometry

Useful for LARGE datasets (>>1 point/pixel)

Hard to interpolate undersampled regions

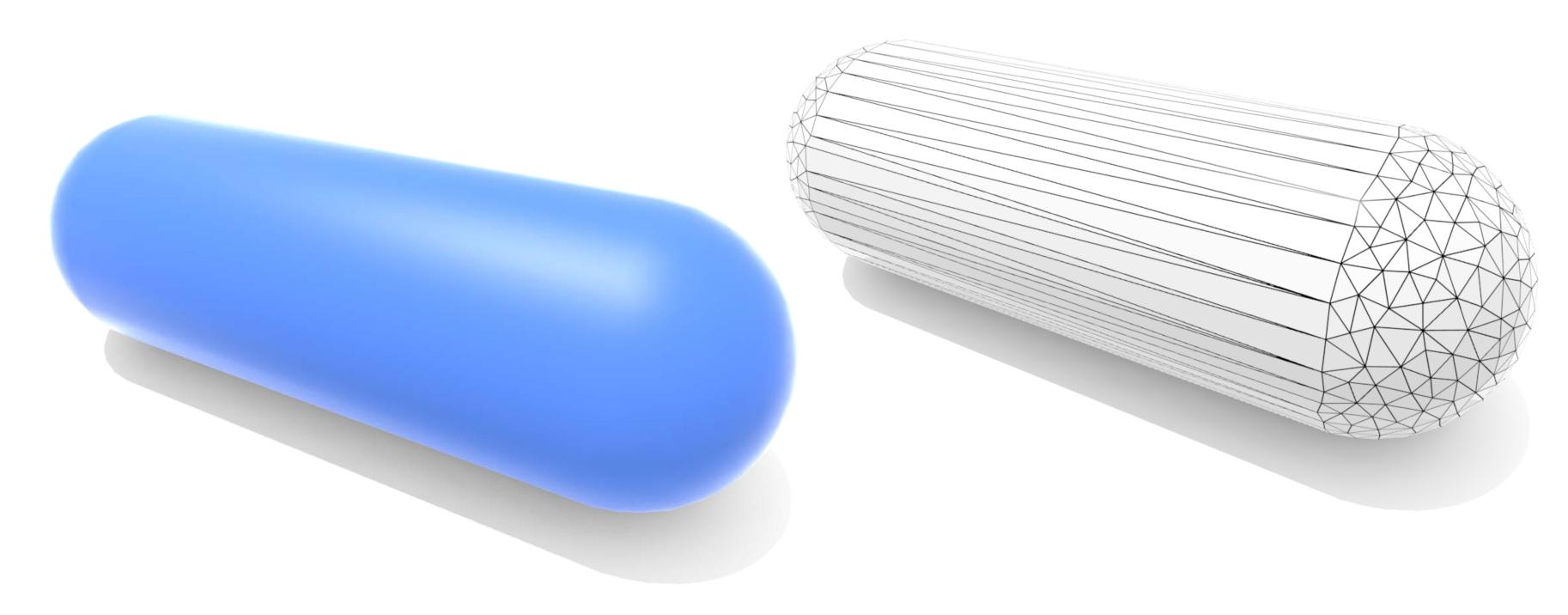
■ Hard to do processing / simulation / ...





# Polygon Mesh (Explicit)

- Store vertices *and* polygons (most often triangles or quads)
- Easier to do processing/simulation, adaptive sampling
- More complicated data structures
- Perhaps most common representation in graphics



(Much more about polygon meshes in upcoming lectures!)

# Triangle Mesh (Explicit)

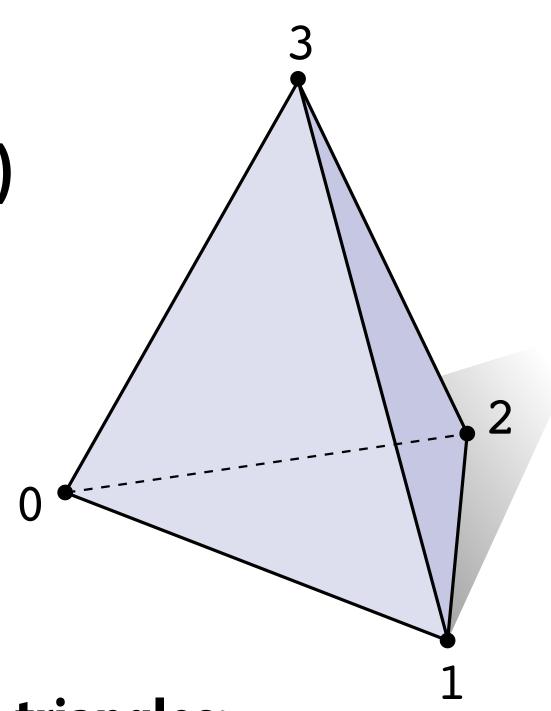
- Store vertices as triples of coordinates (x,y,z)
- Store triangles as triples of indices (i,j,k)
- **■** E.g., tetrahedron:

#### **VERTICES**

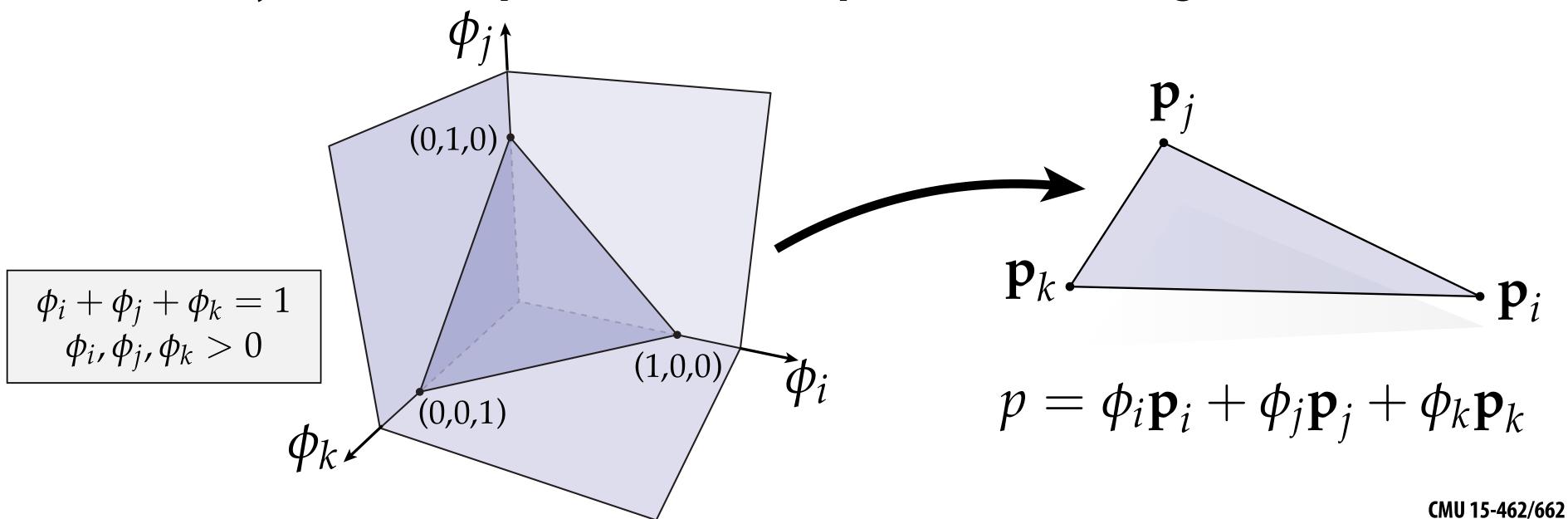
**TRIANGLES** 

	x	Y	Z
0:	-1	-1	-1
1:	1	-1	1
2:	1	1	-1
3:	-1	1	1

i	j	k
0	2	1
0	3	2
3	0	1
3	1	2



Use barycentric interpolation to define points inside triangles:

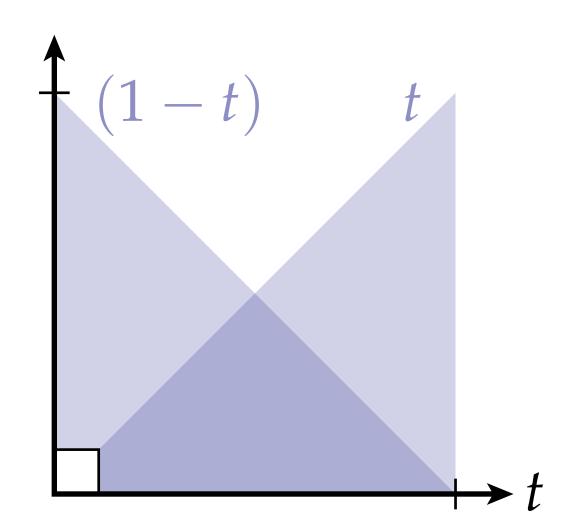


#### Recall: Linear Interpolation (1D)

Interpolate vertex positions using linear interpolation; in 1D:

$$\hat{f}(t) = (1 - t)f_i + tf_j$$

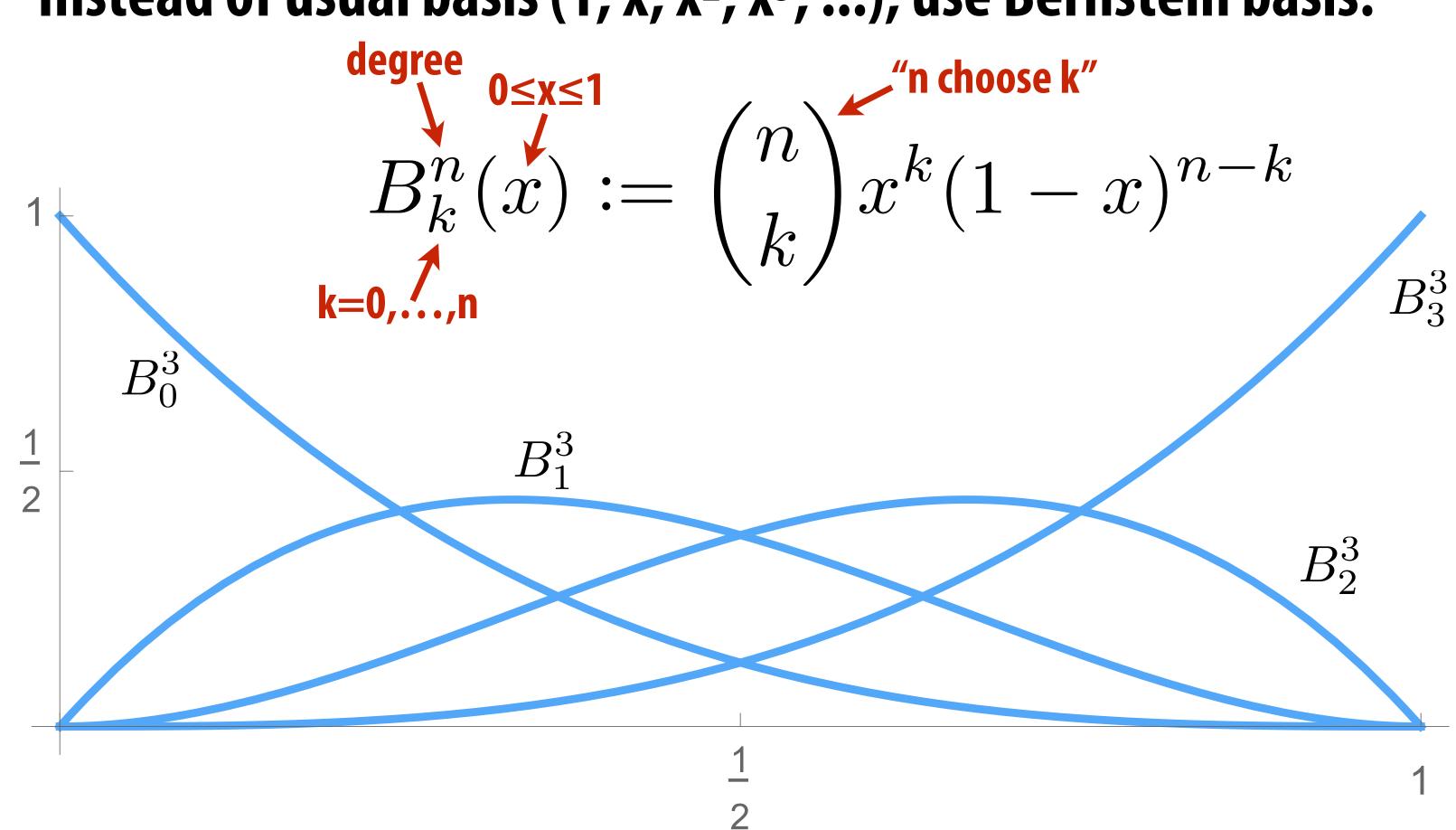
Can think of this as a linear combination of two functions:



- As we move closer to t=0, we approach the value of f at  $x_i$
- As we move closer to t=1, we approach the value of f at  $x_j$

#### Bernstein Basis

- Why limit ourselves to just linear interpolation?
- More flexibility by using higher-order polynomials
- Instead of usual basis  $(1, x, x^2, x^3, ...)$ , use Bernstein basis:



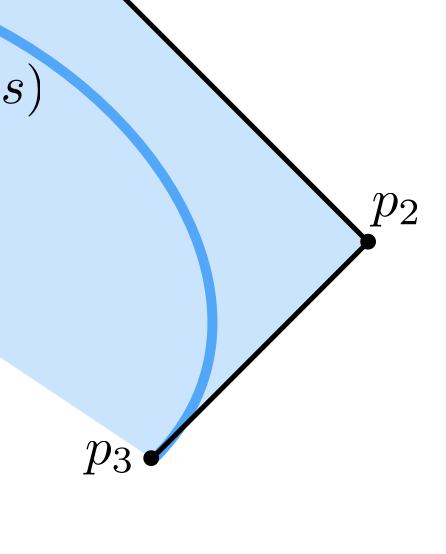
## Bézier Curves (Explicit)

■ A Bézier curve is a curve expressed in the Bernstein basis:

 $p_0$ 

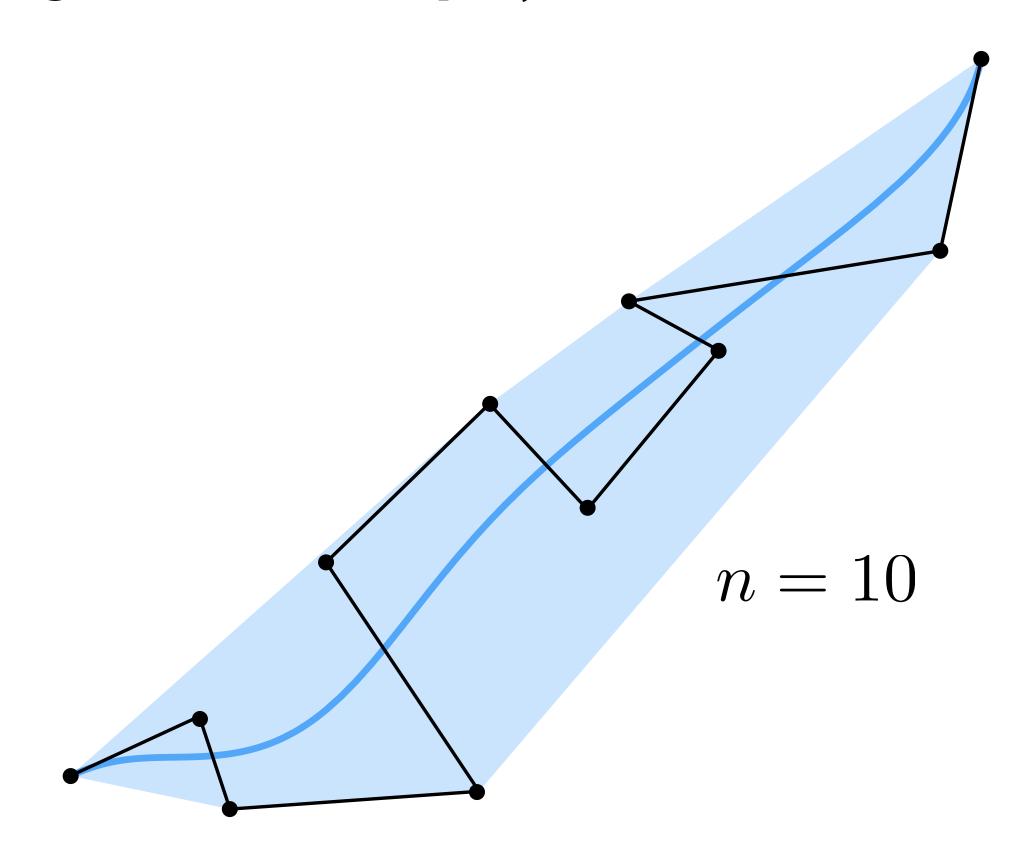
$$\gamma(s) := \sum_{k=0}^{n} B_{n,k}(s) p_k$$
 control points 
$$p_1$$

- For n=1, just get a line segment!
- For n=3, get "cubic Bézier":
- Important features:
  - 1. interpolates endpoints
  - 2. tangent to end segments
  - 3. contained in convex hull (nice for rasterization)



## Just keep going...?

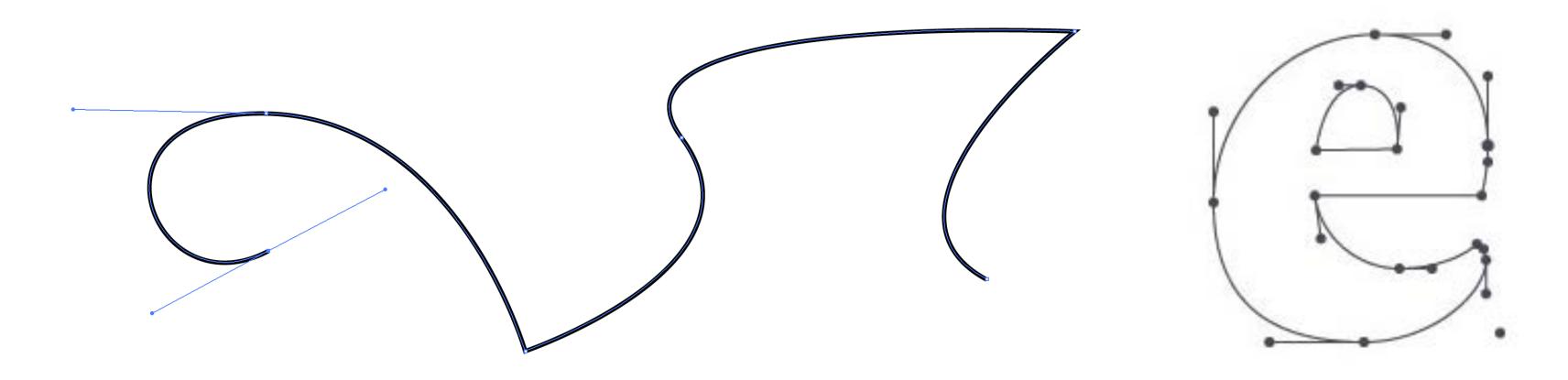
- What if we want an even more interesting curve?
- High-degree Bernstein polynomials don't interpolate well:



Very hard to control!

## Piecewise Bézier Curves (Explicit)

- Alternative idea: piece together many Bézier curves
- Widely-used technique (Illustrator, fonts, SVG, etc.)

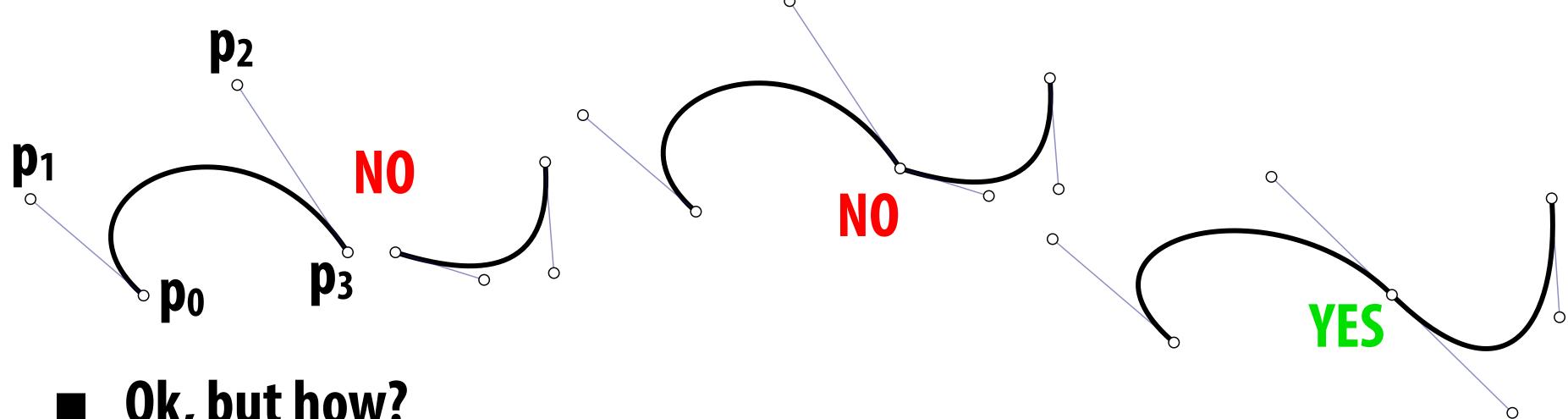


**■** Formally, piecewise Bézier curve:

piecewise Bézier 
$$\gamma(u) := \gamma_i \left(\frac{u-u_i}{u_{i+1}-u_i}\right), \qquad u_i \leq u < u_{i+1}$$
 single Bézier

## Bézier Curves — tangent continuity

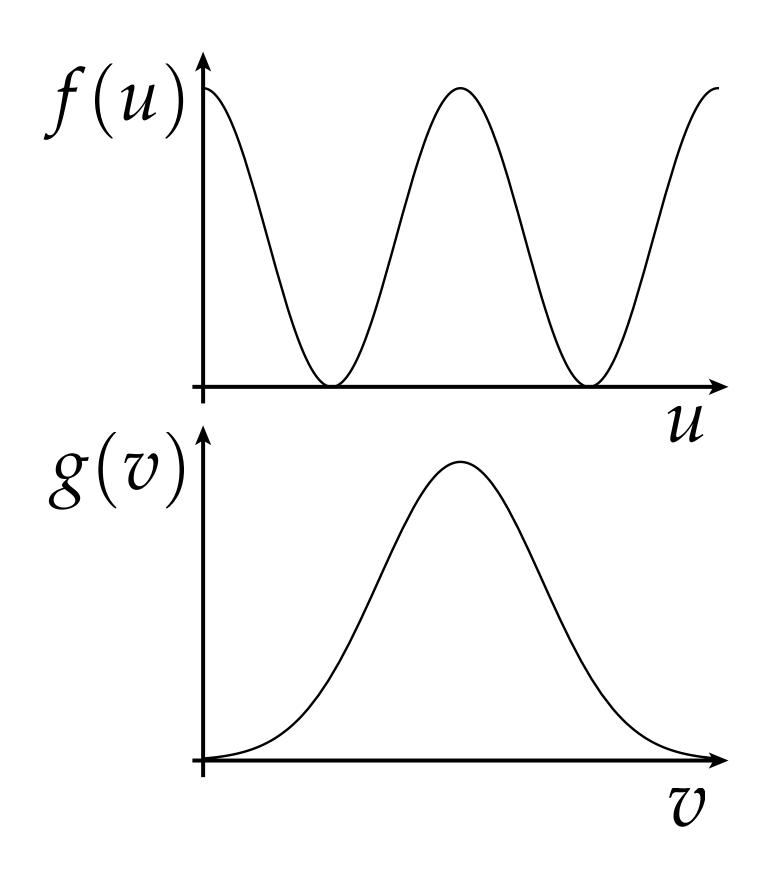
To get "seamless" curves, need *points* and *tangents* to line up:

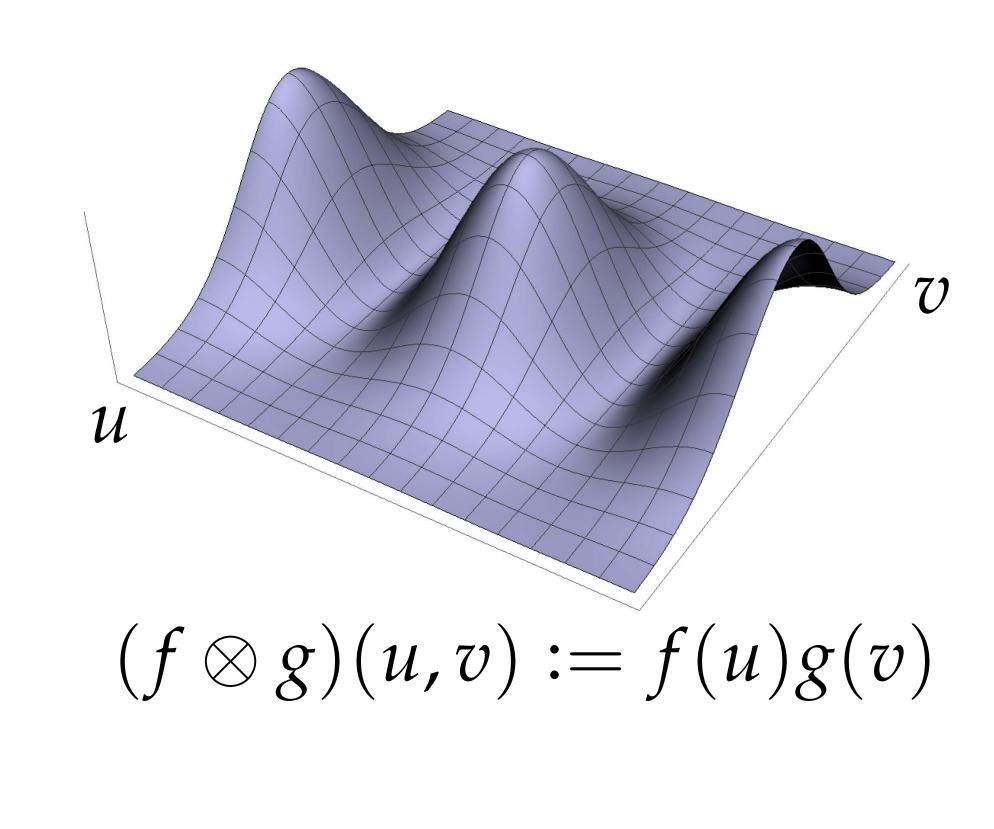


- Ok, but how?
- Each curve is cubic:  $u^3p_0 + 3u^2(1-u)p_1 + 3u(1-u)^2p_2 + (1-u)^3p_3$
- Want endpoints of each segment to meet
- Want tangents at endpoints to meet
- Q: How many constraints vs. degrees of freedom?
- Q: Could you do this with *quadratic* Bézier? *Linear* Bézier?

#### **Tensor Product**

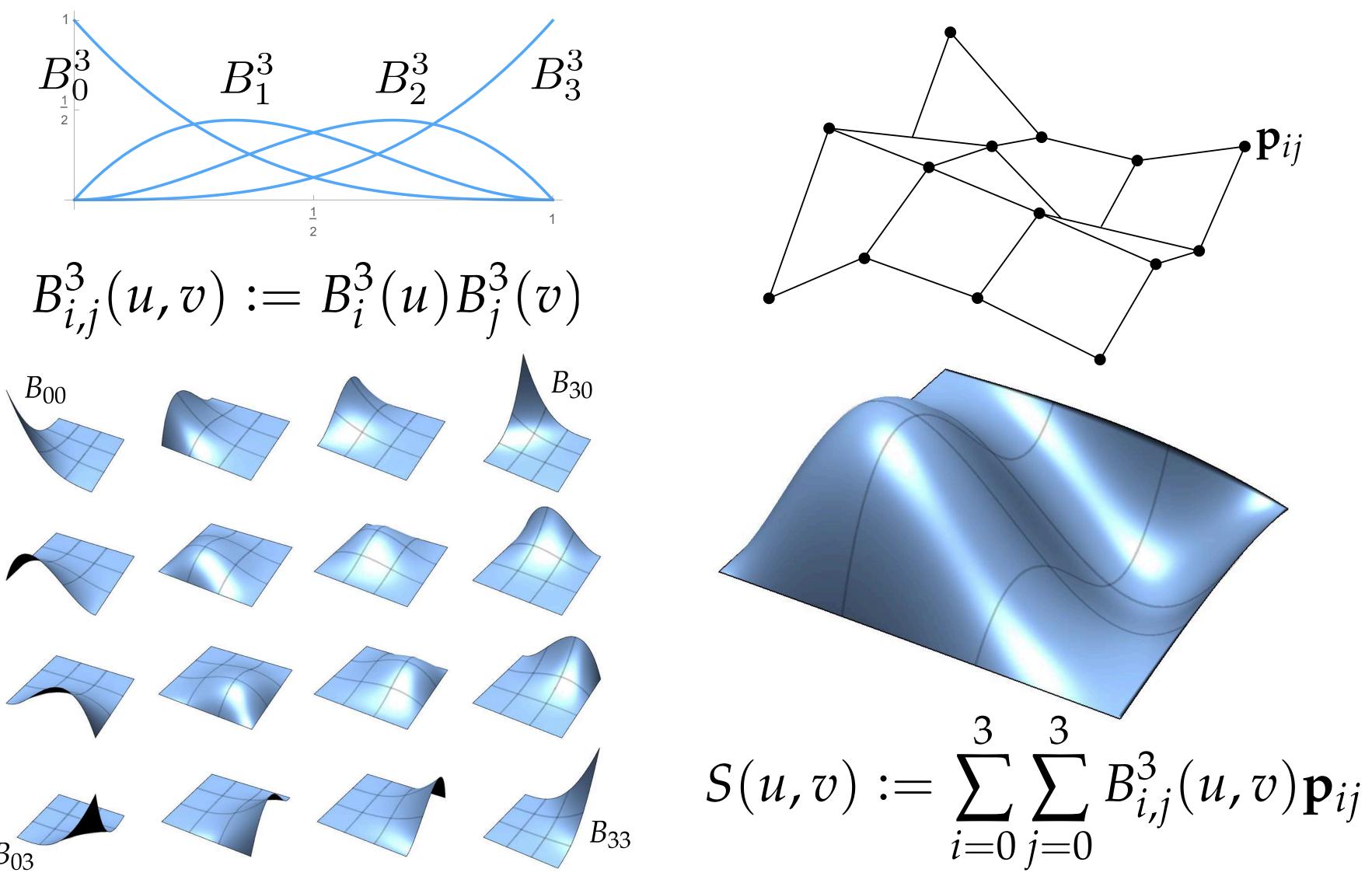
- Can use a pair of curves to get a surface
- Value at any point (u,v) given by product of a curve f at u and a curve g at v (sometimes called the "tensor product"):





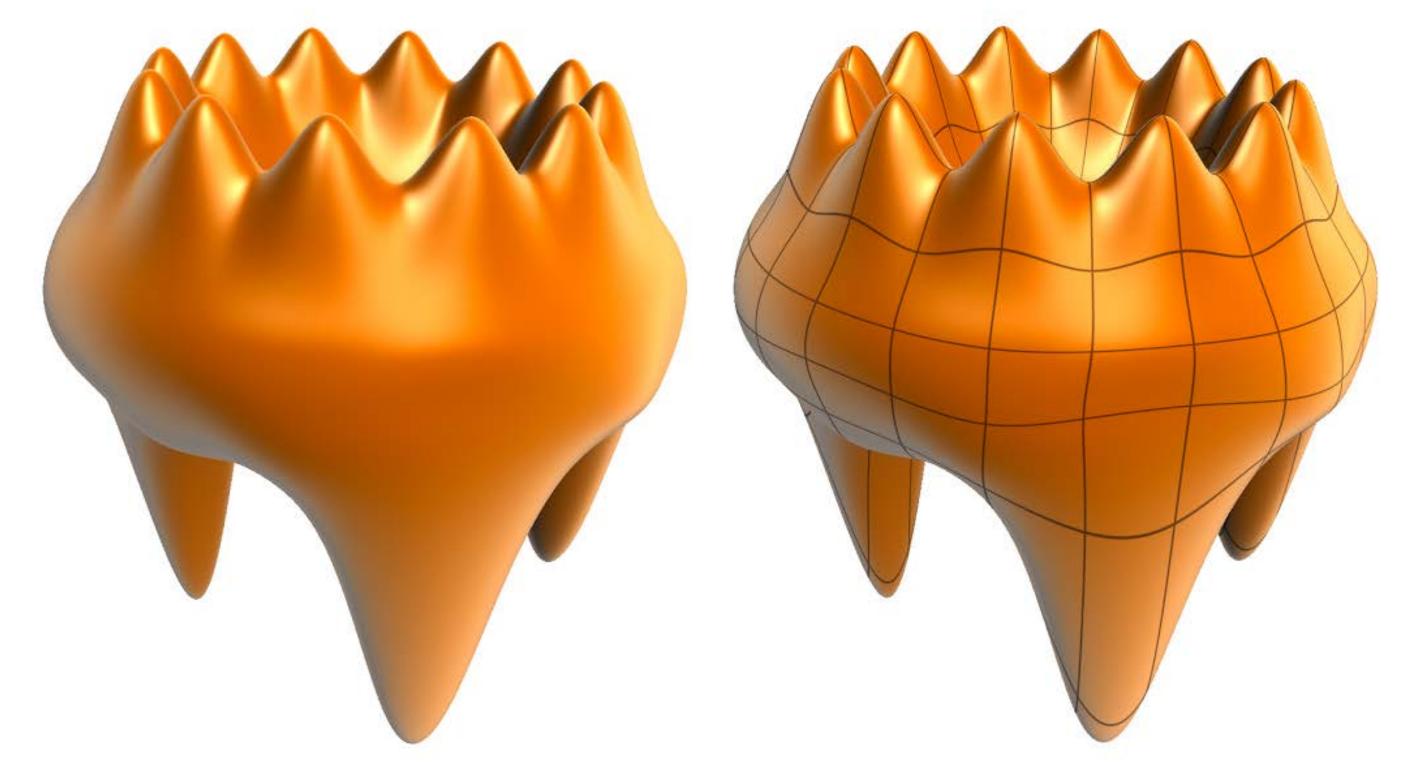
#### Bézier Patches

#### ■ Bézier patch is sum of (tensor) products of Bernstein bases



#### Bézier Surface

Just as we connected Bézier curves, can connect Bézier patches to get a surface:



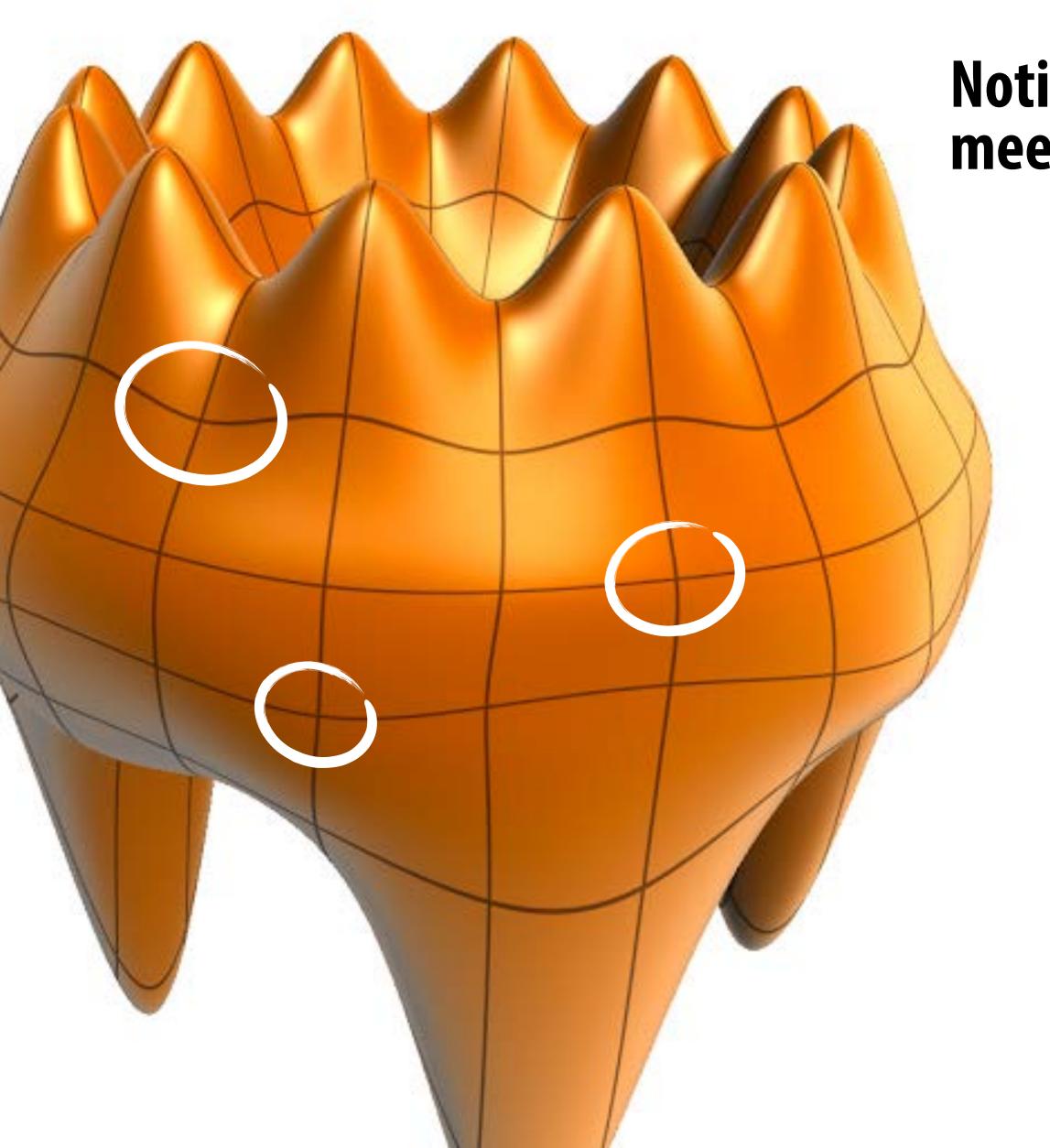
Very easy to draw: just dice each patch into regular (u,v) grid!

Q: Can we always get tangent continuity?

(Think: how many constraints? How many degrees of freedom?)

# Notice anything fishy about the last picture?

#### Bézier Patches are Too Simple



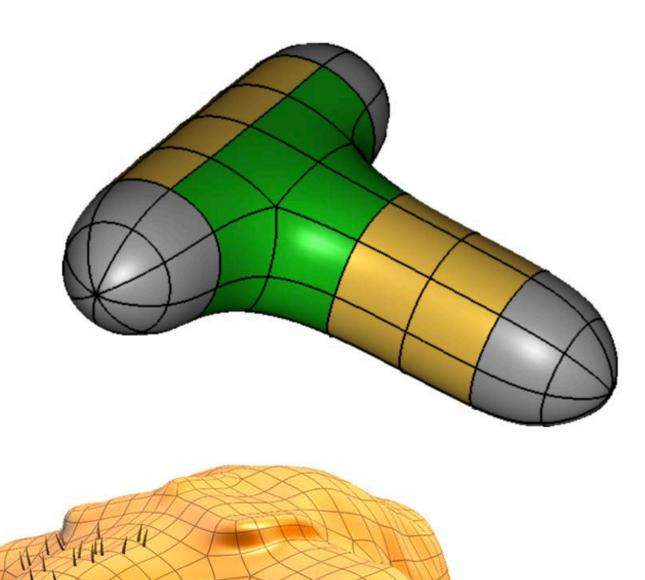
Notice that exactly four patches meet around *every* vertex!

In practice, far too constrained.

To make interesting shapes (with good continuity), we need patches that allow more interesting connectivity...

## Spline patch schemes

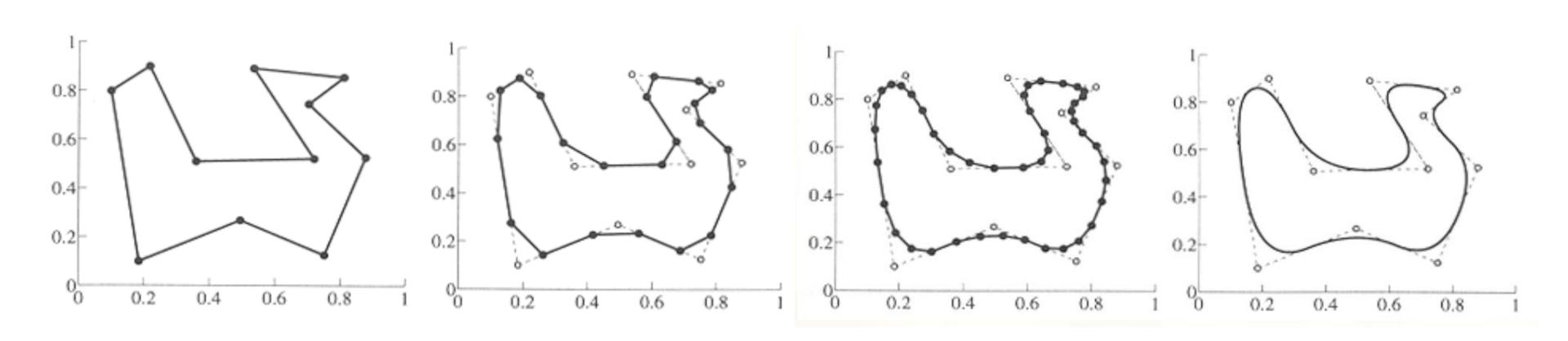
- There are many alternatives!
- NURBS, Gregory, Pm, polar...
- Tradeoffs:
  - degrees of freedom
  - continuity
  - difficulty of editing
  - cost of evaluation
  - generality
  - -
- As usual: pick the right tool for the job!





## Subdivision (Explicit or Implicit?)

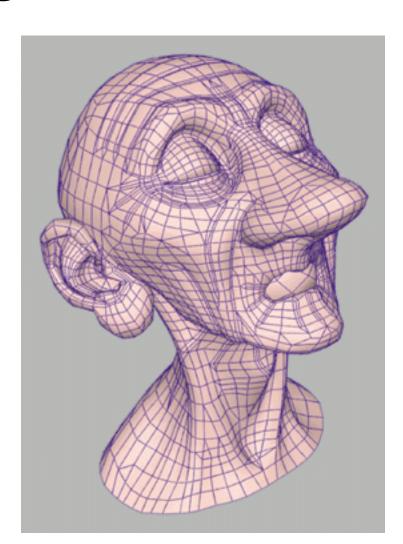
- Alternative starting point for curves/surfaces: subdivision
- Start with control curve
- Insert new vertex at each edge midpoint
- Update vertex positions according to fixed rule
- For careful choice of averaging rule, yields smooth curve
  - Some subdivision schemes correspond to well-known spline schemes!

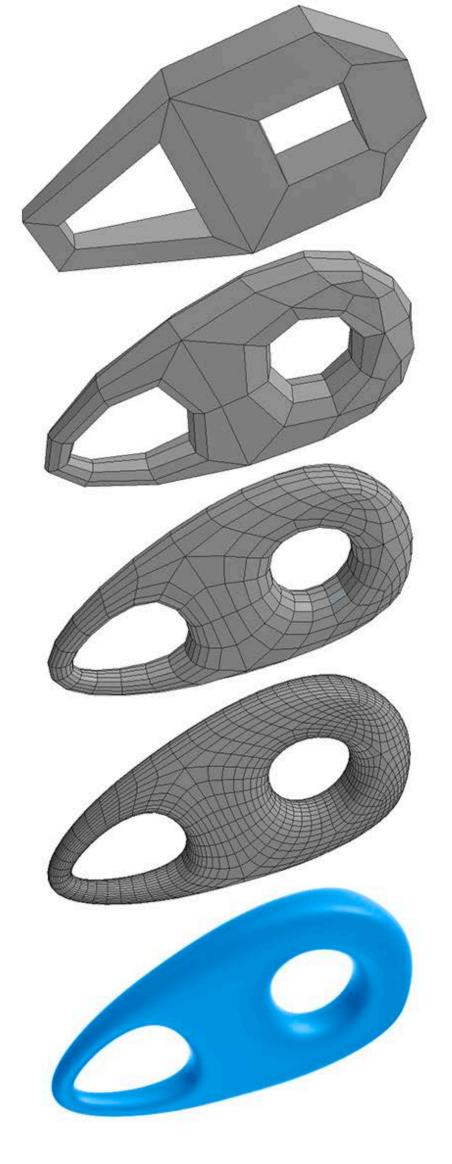


Slide cribbed from Don Fussell. CMU 15-462/662

## Subdivision Surfaces (Explicit)

- Start with coarse polygon mesh ("control cage")
- Subdivide each element
- Update vertices via local averaging
- Many possible rule:
  - Catmull-Clark (quads)
  - Loop (triangles)
  - -
- Common issues:
  - interpolating or approximating?
  - continuity at vertices?
- Easier than splines for modeling; harder to evaluate pointwise





## Subdivision in Action (Pixar's "Geri's Game")

#### Next time: Curves, Surfaces, & Meshes

